

Ijtihed Kilani

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EDUCATION

Aalto University <i>MSc in Pure Mathematics, Minor in Algorithms & Theoretical Computer Science</i>	Aug 2026 - Jun 2028 <i>Incoming</i>
Aalto University <i>BSc in Computational Engineering, Minor in Computer Science</i>	Aug 2024 - June 2026 <i>Graduating in 2 years instead of 3</i>

EXPERIENCE

Founding Software Engineer (Systems & Autonomy) <i>Kova Labs</i> <ul style="list-style-type: none">• #2 Hire leading simulations & digital-twin at a Lifeline VC-backed startup building drone autonomy.• Managing autonomy and perception pipelines in C++/Rust, integrating into a Unity/TS sim with ROS2 interfaces.• Deployed to a physical drone and cut localization error 0.35 m→0.12 m and failures 2.0/min→0.8/min with math optimization.	Nov 2025 – Present <i>Helsinki, Finland</i>
Software Engineer (Systems) <i>Sensofusion</i> <ul style="list-style-type: none">• Joined at age 17 the fastest growing anti-drone startup in Europe as lead simulations engineer.• Shipped an end-to-end drone simulator (TS + Three.js, Python/C++ backend) with hand-optimized 3D assets.• Reduced cold start from 15 s→2.5 s and improved FPS 30→60 via lazy loading/reducing per-frame allocations.	Mar 2025 – Nov 2025 <i>Helsinki, Finland</i>
Research Assistant, Physical AI <i>Aalto University, Computational Behavior Lab</i> <ul style="list-style-type: none">• Reproducing NeurIPS 2024 CoHoI baselines in NVIDIA Isaac Gym (GPU accelerated simulation).• Developing a Unity OpenXR ↔ Isaac Gym bridge to stream a VR human agent for human-in-the-loop evaluation.	Nov 2025 – Present <i>Espoo, Finland</i>
Teaching Assistant (CS-C3150, Software Engineering) <i>Aalto University</i>	Sep 2025 – Dec 2025 <i>Espoo, Finland</i>
Research Intern (Algorithms) <i>Bulgarian Institute of Mathematics and Informatics</i> <ul style="list-style-type: none">• Accepted to a research program (5% acceptance); mentored by the international math olympiad team’s coach.• Implemented DP and graph-based search in Python/C++ (state modeling + pruning) for math-olympiad problems.	Jun 2023 – Aug 2023 <i>Varna, Bulgaria</i>

PROJECTS

Real-Time Physics (Dynamics) Engine <i>C++, ROS2, Unity, gRPC/WebSockets</i> <ul style="list-style-type: none">• Built a custom C++ terrain / vehicle dynamics simulator (rigid-body contact, friction, slopes) w/ deterministic scenarios.	
Skribe (HackMIT '25) <i>Next.js, Python, Wispr Flow, OpenAI API, SQLite, TS/JS</i> <ul style="list-style-type: none">• Accepted to HackMIT '25 (6% acceptance), fully compensated for travel to Boston.• Built a real-time clinical scribe using Next.js + Tailwind and a FastAPI/WebSockets backend.	
”The Yappin’ Spirit” <i>C#, Python, Unity</i> <ul style="list-style-type: none">• Built a real-time vision pipeline (OpenCV + DeepFace) via Flask, streaming computer vision model output into Unity at 60 FPS.	

AWARDS AND ACHIEVEMENTS

National Olympiad for Programming (KSA), #1 / 280,000 participants <i>1st round; Featured on local + national news. Speaker at events.</i>	2024
World Robotics Olympiad (WRO '22 & '23), 2x Silver + 1x Bronze (#2, #4 & #5 / 2,500+) <i>Built fully custom PCB board used by AI-powered autonomous physical health assistant (mobile robot).</i>	
Y Combinator AI Startup School, San Francisco <i>Selected participant (10% Acceptance); travel flight paid/covered by organizers; talked 1 on 1 with 2 YC partners.</i>	2025

PUBLICATIONS

Analysis of Complete Blood Count Between High-Altitude and Sea-Level Residents , Cureus Journal	2023
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TECHNICAL SKILLS

Languages: Python, C#, C++, TypeScript, Rust
Tools/Tech: React, Node.js, Flask, SQL, WebSockets, PostgreSQL, Docker, GitHub Actions, Linux, Git, AWS, Google Cloud
Coursework: Data Structures and Algorithms, Parallel Computing, Discrete Math, Linear Algebra, Databases