

# Ijtihed Kilani

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## EDUCATION

### Aalto University

*MSc in Pure Mathematics, Minor in Algorithms & Theoretical Computer Science*

Aug 2026 - Jun 2028

Incoming

### Aalto University

*BSc in Computational Engineering, Minor in Computer Science*

Aug 2024 - June 2026

Graduating in 2 years instead of 3

## EXPERIENCE

### Founding Software Engineer (Systems & Autonomy)

*Kova Labs*

Nov 2025 – Present

Helsinki, Finland

- #2 Hire leading simulations & digital-twin at a Lifeline VC-backed startup building drone autonomy.
- Managing autonomy and perception pipelines in C++/Rust, integrating into a Unity/TS sim with ROS2 interfaces.
- Deployed to a physical drone and cut localization error 0.35 m → 0.12 m and failures 2.0/min → 0.8/min with math optimization.

### Software Engineer (Systems)

*Sensofusion*

Mar 2025 – Nov 2025

Helsinki, Finland

- Joined at age 17 the fastest growing anti-drone startup in Europe as lead simulations engineer.

- Shipped an end-to-end drone simulator (TS + Three.js, Python/C++ backend) with hand-optimized 3D assets.
- Reduced cold start from 15 s → 2.5 s and improved FPS 30 → 60 via lazy loading/reducing per-frame allocations.

### Research Assistant, Physical AI

*Aalto University, Computational Behavior Lab*

Nov 2025 – Present

Espoo, Finland

- Reproducing NeurIPS 2024 CoHoI baselines in NVIDIA Isaac Gym (GPU accelerated simulation).

- Developing a Unity OpenXR ↔ Isaac Gym bridge to stream a VR human agent for human-in-the-loop evaluation.

### Teaching Assistant (CS-C3150, Software Engineering)

*Aalto University*

Sep 2025 – Dec 2025

Espoo, Finland

### Research Intern (Algorithms)

*Bulgarian Institute of Mathematics and Informatics*

Jun 2023 – Aug 2023

Varna, Bulgaria

- Accepted to a research program (5% acceptance); mentored by the international math olympiad team's coach.
- Implemented DP and graph-based search in Python/C++ (state modeling + pruning) for math-olympiad problems.

## PROJECTS

### Real-Time Physics (Dynamics) Engine | C++, ROS2, Unity, gRPC/WebSockets

- Built a custom C++ terrain / vehicle dynamics simulator (rigid-body contact, friction, slopes) w/ deterministic scenarios.

### Scribe (HackMIT '25) | Next.js, Python, Wispr Flow, OpenAI API, SQLite, TS/JS

- Accepted to HackMIT '25 (6% acceptance), fully compensated for travel to Boston.
- Built a real-time clinical scribe using Next.js + Tailwind and a FastAPI/WebSockets backend.

### ”The Yappin’ Spirit” | C#, Python, Unity

- Built a real-time vision pipeline (OpenCV + DeepFace) via Flask, streaming computer vision model output into Unity at 60 FPS.

## AWARDS AND ACHIEVEMENTS

### National Olympiad for Programming (KSA), #1 / 280,000 participants

2024

1st round; Featured on local + national news. Speaker at events.

### World Robotics Olympiad (WRO '22 & '23), 2x Silver + 1x Bronze (#2, #4 & #5 / 2,500+)

Built fully custom PCB board used by AI-powered autonomous physical health assistant (mobile robot).

### Y Combinator AI Startup School, San Francisco

2025

Selected participant (10% Acceptance); travel flight paid/covered by organizers; talked 1 on 1 with 2 YC partners.

## PUBLICATIONS

### Analysis of Complete Blood Count Between High-Altitude and Sea-Level Residents, Cureus Journal 2023

## TECHNICAL SKILLS

**Languages:** Python, C#, C++, TypeScript, Rust

**Tools/Tech:** React, Node.js, Flask, SQL, WebSockets, PostgreSQL, Docker, GitHub Actions, Linux, Git, AWS, Google Cloud

**Coursework:** Data Structures and Algorithms, Parallel Computing, Discrete Math, Linear Algebra, Databases