

Ikarus::NonLinearElastic
::calculateMatrix

Ikarus::NonLinearElastic
::calculateVectorImpl

Ikarus::NonLinearElastic
::getStress

```
graph LR; A["Ikarus::NonLinearElastic::calculateMatrix"] --> C["Ikarus::NonLinearElastic::getStress"]; B["Ikarus::NonLinearElastic::calculateVectorImpl"] --> C;
```

The diagram illustrates a dependency or call relationship. Two source functions, 'Ikarus::NonLinearElastic::calculateMatrix' and 'Ikarus::NonLinearElastic::calculateVectorImpl', are shown on the left. Arrows from both point to a target function, 'Ikarus::NonLinearElastic::getStress', on the right. The target function box is shaded gray, while the source boxes are white.