

Ikarus::NonLinearElastic  
::calculateMatrix

Ikarus::NonLinearElastic  
::calculateScalarImpl

Ikarus::NonLinearElastic  
::calculateVectorImpl

Ikarus::NonLinearElastic  
::strainFunction

```
graph LR; A["Ikarus::NonLinearElastic::calculateMatrix"] --> D["Ikarus::NonLinearElastic::strainFunction"]; B["Ikarus::NonLinearElastic::calculateScalarImpl"] --> D; C["Ikarus::NonLinearElastic::calculateVectorImpl"] --> D;
```

The diagram illustrates a dependency or call relationship. Three source functions on the left are connected by blue arrows to a single target function on the right. The source functions are 'Ikarus::NonLinearElastic::calculateMatrix', 'Ikarus::NonLinearElastic::calculateScalarImpl', and 'Ikarus::NonLinearElastic::calculateVectorImpl'. The target function is 'Ikarus::NonLinearElastic::strainFunction'. The target function box is shaded gray, while the source function boxes are white with black borders.