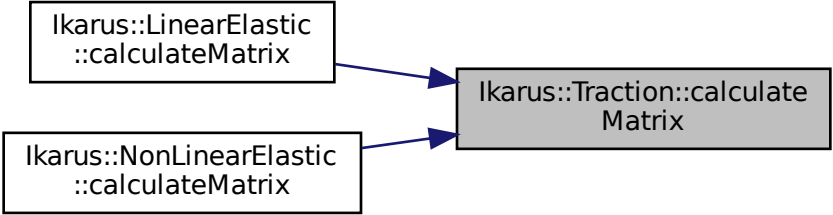


Ikarus::LinearElastic
::calculateMatrix

Ikarus::NonLinearElastic
::calculateMatrix

Ikarus::Traction::calculate
Matrix



```
graph LR; A[Ikarus::LinearElastic::calculateMatrix] --> C[Ikarus::Traction::calculate Matrix]; B[Ikarus::NonLinearElastic::calculateMatrix] --> C;
```