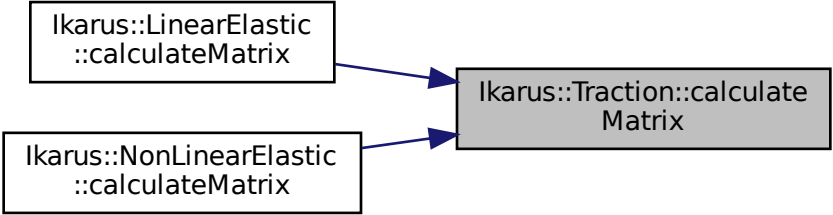


Ikarus::LinearElastic  
::calculateMatrix

Ikarus::NonLinearElastic  
::calculateMatrix

Ikarus::Traction::calculate  
Matrix



```
graph LR; A[Ikarus::LinearElastic::calculateMatrix] --> C[Ikarus::Traction::calculateMatrix]; B[Ikarus::NonLinearElastic::calculateMatrix] --> C;
```