

Ikarus::LinearElastic  
::calculateScalarImpl

Ikarus::NonLinearElastic  
::calculateScalarImpl

Ikarus::KirchhoffLoveShell  
::calculateScalarImpl

Ikarus::Volume::calculate  
ScalarImpl

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graph LR; A[Ikarus::LinearElastic::calculateScalarImpl] --> D[Ikarus::Volume::calculateScalarImpl]; B[Ikarus::NonLinearElastic::calculateScalarImpl] --> D; C[Ikarus::KirchhoffLoveShell::calculateScalarImpl] --> D;
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The diagram illustrates a dependency or inheritance relationship. Three source functions on the left (Ikarus::LinearElastic::calculateScalarImpl, Ikarus::NonLinearElastic::calculateScalarImpl, and Ikarus::KirchhoffLoveShell::calculateScalarImpl) are shown in white boxes. Arrows from each of these boxes point to a single target function on the right (Ikarus::Volume::calculateScalarImpl), which is shown in a gray box. This suggests that the target function is a base or a common implementation that the three source functions inherit from or depend on.