

Ikarus::NonLinearElastic  
::calculateMatrix

Ikarus::NonLinearElastic  
::calculateScalarImpl

Ikarus::NonLinearElastic  
::calculateVectorImpl

Ikarus::NonLinearElastic  
::strainFunction

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graph LR; A[Ikarus::NonLinearElastic::calculateMatrix] --> D[Ikarus::NonLinearElastic::strainFunction]; B[Ikarus::NonLinearElastic::calculateScalarImpl] --> D; C[Ikarus::NonLinearElastic::calculateVectorImpl] --> D;
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The diagram illustrates a dependency or call relationship. Three source functions on the left are connected by blue arrows to a single target function on the right. The target function box is shaded gray, while the source boxes are white with black borders. The arrows originate from the bottom-right of the first box, the right side of the second box, and the top-right of the third box, all converging on the left side of the target box.