

Ikarus::NonLinearElastic
::calculateMatrix

Ikarus::NonLinearElastic
::calculateScalarImpl

Ikarus::NonLinearElastic
::calculateVectorImpl

Ikarus::NonLinearElastic
::strainFunction

```
graph LR; A["Ikarus::NonLinearElastic::calculateMatrix"] --> D["Ikarus::NonLinearElastic::strainFunction"]; B["Ikarus::NonLinearElastic::calculateScalarImpl"] --> D; C["Ikarus::NonLinearElastic::calculateVectorImpl"] --> D;
```

The diagram illustrates a dependency or inheritance relationship. Three source functions on the left (calculateMatrix, calculateScalarImpl, and calculateVectorImpl) all point via blue arrows to a single target function on the right (strainFunction). The target function box is shaded gray, while the source function boxes are white with black borders.