

Ikarus::NonLinearElastic  
::calculateMatrix

Ikarus::NonLinearElastic  
::calculateScalarImpl

Ikarus::NonLinearElastic  
::calculateVectorImpl

Ikarus::NonLinearElastic  
::strainFunction

```
graph LR; A[Ikarus::NonLinearElastic::calculateMatrix] --> D[Ikarus::NonLinearElastic::strainFunction]; B[Ikarus::NonLinearElastic::calculateScalarImpl] --> D; C[Ikarus::NonLinearElastic::calculateVectorImpl] --> D;
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The diagram illustrates a dependency or inheritance relationship. Three source functions on the left (calculateMatrix, calculateScalarImpl, and calculateVectorImpl) all point via blue arrows to a single target function on the right (strainFunction). The target function box is shaded gray, while the source function boxes are white with black borders.