

Ikarus::NonLinearElastic  
::calculateMatrixImpl

Ikarus::NonLinearElastic  
::calculateVectorImpl

Ikarus::NonLinearElastic  
::getStress

```
graph LR; A["Ikarus::NonLinearElastic::calculateMatrixImpl"] --> C["Ikarus::NonLinearElastic::getStress"]; B["Ikarus::NonLinearElastic::calculateVectorImpl"] --> C;
```

The diagram illustrates a dependency or call relationship. Two source functions, 'Ikarus::NonLinearElastic::calculateMatrixImpl' and 'Ikarus::NonLinearElastic::calculateVectorImpl', are shown on the left. Arrows from both of these functions point to a single target function, 'Ikarus::NonLinearElastic::getStress', which is highlighted with a gray background on the right.