

Ikarus::NonLinearElastic
::calculateMatrixImpl

Ikarus::NonLinearElastic
::calculateVectorImpl

Ikarus::NonLinearElastic
::getStress

```
graph LR; A["Ikarus::NonLinearElastic::calculateMatrixImpl"] --> C["Ikarus::NonLinearElastic::getStress"]; B["Ikarus::NonLinearElastic::calculateVectorImpl"] --> C;
```

The diagram illustrates a dependency or call relationship. Two source functions on the left, 'Ikarus::NonLinearElastic::calculateMatrixImpl' and 'Ikarus::NonLinearElastic::calculateVectorImpl', both have arrows pointing to a single target function on the right, 'Ikarus::NonLinearElastic::getStress'. The target function box is shaded gray, while the source function boxes are white with black borders.