

Ikarus::LinearElastic
::calculateVectorImpl

Ikarus::NonLinearElastic
::calculateVectorImpl

Ikarus::KirchhoffLoveShell
::calculateVectorImpl

Ikarus::Traction::calculate
VectorImpl

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graph LR; A[Ikarus::LinearElastic::calculateVectorImpl] --> D[Ikarus::Traction::calculateVectorImpl]; B[Ikarus::NonLinearElastic::calculateVectorImpl] --> D; C[Ikarus::KirchhoffLoveShell::calculateVectorImpl] --> D;
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The diagram illustrates a function call or inheritance relationship. Three source functions on the left (Ikarus::LinearElastic::calculateVectorImpl, Ikarus::NonLinearElastic::calculateVectorImpl, and Ikarus::KirchhoffLoveShell::calculateVectorImpl) are shown in white boxes. Arrows from each of these boxes point to a single target function on the right (Ikarus::Traction::calculateVectorImpl), which is shown in a gray box. This suggests that the target function is a common interface or base function that is implemented or called by the three source functions.