

Ikarus::LinearElastic  
::calculateMatrix

Ikarus::NonLinearElastic  
::calculateMatrix

Ikarus::Traction::calculate  
Matrix

```
graph LR; A[Ikarus::LinearElastic::calculateMatrix] --> C[Ikarus::Traction::calculateMatrix]; B[Ikarus::NonLinearElastic::calculateMatrix] --> C;
```

The diagram illustrates a flow where two separate calculation methods, 'Ikarus::LinearElastic::calculateMatrix' and 'Ikarus::NonLinearElastic::calculateMatrix', both point to a common target box labeled 'Ikarus::Traction::calculateMatrix'. The arrows indicate a dependency or a shared output for the traction calculation.