

Ikarus::LinearElastic  
::calculateScalarImpl

Ikarus::NonLinearElastic  
::calculateScalarImpl

Ikarus::KirchhoffLoveShell  
::calculateScalarImpl

Ikarus::Traction::calculate  
ScalarImpl

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graph LR; A[Ikarus::LinearElastic::calculateScalarImpl] --> D[Ikarus::Traction::calculateScalarImpl]; B[Ikarus::NonLinearElastic::calculateScalarImpl] --> D; C[Ikarus::KirchhoffLoveShell::calculateScalarImpl] --> D;
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The diagram illustrates a dependency or inheritance relationship. Three source functions on the left (Ikarus::LinearElastic::calculateScalarImpl, Ikarus::NonLinearElastic::calculateScalarImpl, and Ikarus::KirchhoffLoveShell::calculateScalarImpl) are connected by blue arrows to a single target function on the right (Ikarus::Traction::calculateScalarImpl). The target function is highlighted with a gray background, while the source functions have white backgrounds.