

Ikarus::KirchhoffLoveShell
::calculateScalarImpl

Ikarus::LinearElastic
::calculateScalarImpl

Ikarus::NonLinearElastic
::calculateScalarImpl

Ikarus::Traction::calculate
ScalarImpl

```
graph LR; A[Ikarus::KirchhoffLoveShell::calculateScalarImpl] --> D[Ikarus::Traction::calculateScalarImpl]; B[Ikarus::LinearElastic::calculateScalarImpl] --> D; C[Ikarus::NonLinearElastic::calculateScalarImpl] --> D;
```

The diagram illustrates a dependency or inheritance structure. Three boxes on the left, each containing a function name with a namespace, have arrows pointing to a single box on the right. The boxes on the left are: 'Ikarus::KirchhoffLoveShell::calculateScalarImpl', 'Ikarus::LinearElastic::calculateScalarImpl', and 'Ikarus::NonLinearElastic::calculateScalarImpl'. The box on the right is 'Ikarus::Traction::calculateScalarImpl'. The arrows indicate that the three left-hand functions are related to or depend on the right-hand function.