

Ikarus::KirchhoffLoveShell  
::calculateScalarImpl

Ikarus::LinearElastic  
::calculateScalarImpl

Ikarus::NonLinearElastic  
::calculateScalarImpl

Ikarus::Traction::calculate  
ScalarImpl

```
graph LR; A[Ikarus::KirchhoffLoveShell::calculateScalarImpl] --> D[Ikarus::Traction::calculateScalarImpl]; B[Ikarus::LinearElastic::calculateScalarImpl] --> D; C[Ikarus::NonLinearElastic::calculateScalarImpl] --> D;
```

The diagram illustrates a dependency or inheritance relationship. Three source boxes on the left, each containing a function name with a namespace, have arrows pointing to a single target box on the right. The target box also contains a function name with a namespace. The target box is shaded gray, while the source boxes are white with black borders. The arrows are blue.