

Ikarus::NonLinearElastic
::calculateMatrix

Ikarus::NonLinearElastic
::calculateScalarImpl

Ikarus::NonLinearElastic
::calculateVectorImpl

Ikarus::NonLinearElastic
::strainFunction

```
graph LR; A["Ikarus::NonLinearElastic::calculateMatrix"] --> D["Ikarus::NonLinearElastic::strainFunction"]; B["Ikarus::NonLinearElastic::calculateScalarImpl"] --> D; C["Ikarus::NonLinearElastic::calculateVectorImpl"] --> D;
```

The diagram illustrates a dependency or call relationship. Three source functions on the left are connected by blue arrows to a single target function on the right. The target function, 'Ikarus::NonLinearElastic::strainFunction', is highlighted with a gray background, while the source functions have white backgrounds. The arrows originate from the bottom-right of the first box, the right side of the second box, and the top-right of the third box, all converging on the left side of the target box.