view frames Result Recorded at time: 23.156 world Broadcaster: /world2odom broadcaster Broadcaster: /simulate node Average rate: $100\overline{0}0.0$ Average rate: 71.486 Buffer length: 0.0 Buffer length: 4.966 Most recent transform: 23.126 Most recent transform: 0.0 Oldest transform: 0.0 Oldest transform: 18.16 ground truth pose odom Broadcaster: /gazebo Average rate: 500.2 Buffer length: 4.994 Most recent transform: 23.142 Oldest transform: 18.148 base footprint Broadcaster: /robot state publisher Average rate: 10000.0 Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 base link Broadcaster: /robot state publisher Broadcaster: /robot state publisher Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: $1000\overline{0}.0$ Average rate: $50.\overline{201}$ Average rate: $50.\overline{201}$ Average rate: $50.\overline{201}$ Buffer length: 0.0 Buffer length: 4.98 Buffer length: 4.98 Buffer length: 4.98 Most recent transform: 0.0 Most recent transform: 23.132 Most recent transform: 23.132 Most recent transform: 23.132 Oldest transform: 18.152 Oldest transform: 18.152 Oldest transform: 0.0 Oldest transform: 18.152 left wheel link laser frame rear caster base right wheel link Broadcaster: /robot state publisher Average rate: $50.\overline{201}$ Buffer length: 4.98 Most recent transform: 23.132 Oldest transform: 18.152 rear caster link