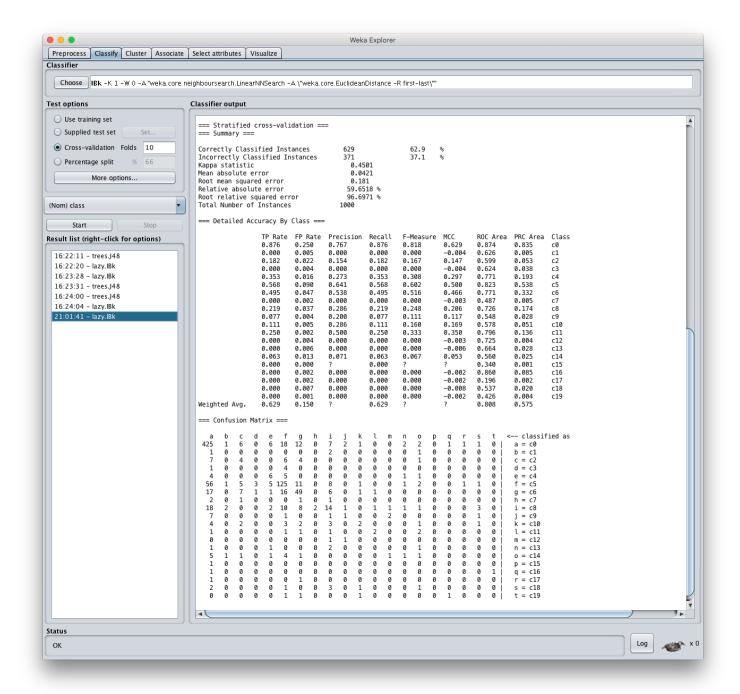
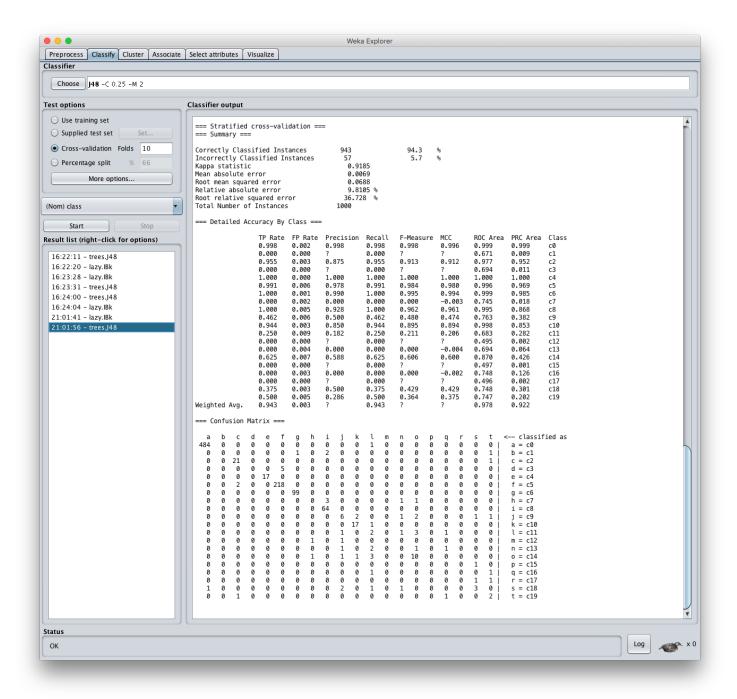
NOTE: ANSWERS IN RED

Part 1

1) Data set created through Weka. Here is the output, although the csv is also included in the submission:

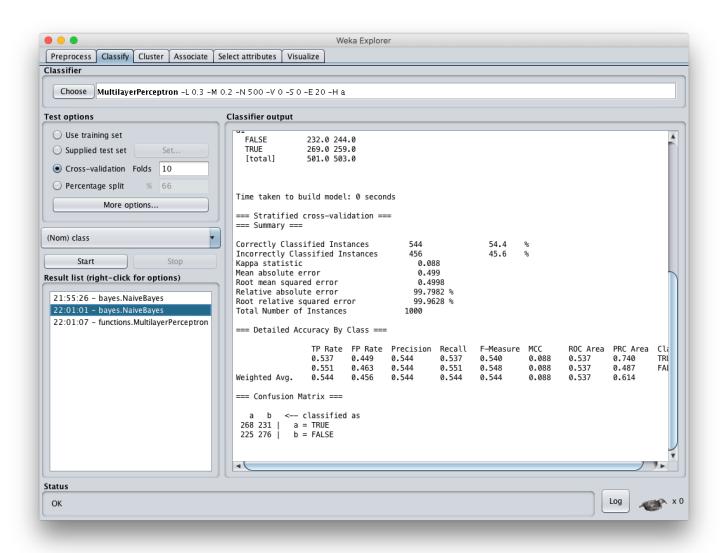




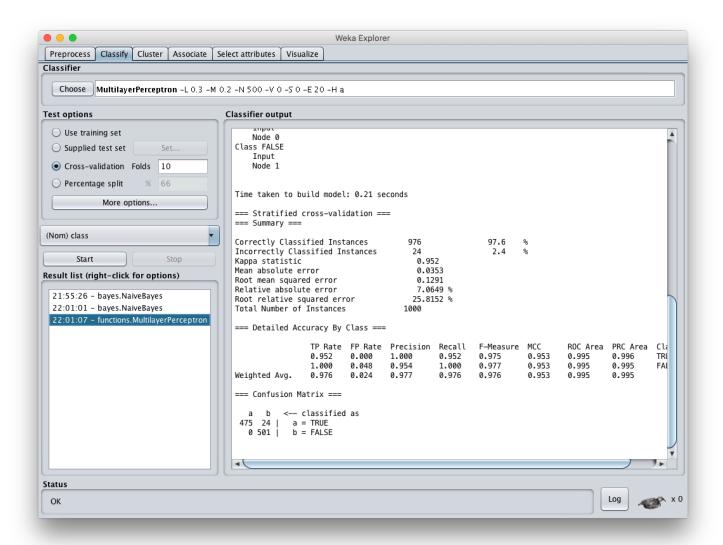
Decision Tree w/ accuracy 94.3%

- a. Absolute difference = |94.3% 62.9%| = 31.4%
- b. I generated the dataset through Weka itself. I spent a long time generating the data through Excel sheets but realized that wasn't necessary. Through Weka I generated randomly produced data by producing a decision list. In particular, I set the number of attributes to 30, number of classes to 20, kept 1000 examples as requested, and the number of irrelevant attributes to 10. The simple answer for why the classifiers perform so differently is that decision trees are eager learners that first build a classification model on the training dataset and predict a class for a given input vector. Nearest neighbor, however, does not build a classification model and instead learns directly from the training observations. It is coined a lazy learner and must use a distance metric. It lowers in accuracy as we add more dimensions (features).

2) Data set created through Weka. Here is the output, although the csv is also included in the submission:



Naïve Bayes w/ accuracy 54.4%



MLP w/ accuracy 97.6%

- a. Absolute difference = |97.6% 54.4%| = 43.2%
- b. I created the dataset without the help of Weka this time. While my two attributes were randomly true or false, my output was the XOR function. This enabled me to achieve such a low percentage with Naïve Bayes. Naïve Bayes classifiers work by making strong assumptions of conditional between attributes. As mentioned above, I specifically created the data set so that this wasn't the case at all. The MLP model had a better result because it iteratively changes the weights between each successive node to find a stronger correlation and thus classified with better accuracy.

3) Through Jupiter Notebook:

```
In [46]: import numpy as np
         from sklearn.naive bayes import BernoulliNB
         from sklearn.linear_model import LogisticRegression
         a = BernoulliNB()
         b = LogisticRegression(C=5)
In [47]: attributes = np.array([[1,1,1,1],[1,0,0,1],[1,1,0,1]])
         output = np.array([0,0,1])
In [48]: a.fit(attributes,output)
         b.fit(attributes,output)
Out[48]: LogisticRegression(C=5, class_weight=None, dual=False, fit_intercept=True,
                   intercept_scaling=1, max_iter=100, multi_class='ovr', n_jobs=1,
                   penalty='12', random_state=None, solver='liblinear', tol=0.0001,
                   verbose=0, warm_start=False)
In [49]: a.score(attributes,output)
Out[49]: 0.666666666666666
In [50]: b.score(attributes,output)
Out[50]: 1.0
```

Bernoulli's Model (Naïve Bayes) vs Logistic Regression

- a. For this question, while I worked alone for the most part, I asked Jack Richard for a little guidance (Downey allowed). He suggested I attempt this problem via the Jupiter Notebook. In it I used the Bernoulli Model for Naïve Bayes, and Logistic Regression to achieve a 1.0 and 2/3 training accuracy respectively, as depicted above. In order to achieve a 2/3 training accuracy, it was simpler to get 2 out of 3 example sets to train correctly, while still keeping true to 4 attributes in the matrix labeled 'attributes'. Because Naïve Bayes assumes conditional independence, it does not look for any relations between attributes. Logistic Regression can learn a function by a feature. As one of the example sets is classified differently, Naïve Bayes classifies it wrong (2/3). Logistic Regression measures the relationship between the output and one or more independent variables, and probabilistically predicted correctly, thus scoring a 1.0 accuracy.
- 4) Computing # of parameters
 - a. 9*3*3*3-1=242 independent parameters
 - b. 9*3*3*(3-1) = 162 independent parameters
 - c. (9-1)*3 + (3-1)*3 + (3-1)*3 + (3-1) = 38 independent parameters
- 5) Attached.
- 6) Simiarlity scores:
 - a. VGG Representation:
 - i. cat & mj1 = 15 %
 - ii. cat & mj2 = 14 %

 - iii. mj1 & mj2 = ~96%
 - b. Pixel Representation:
 - i. cat & mj1 = 47 %
 - ii. cat & mj2 = 62 %

- iii. mj1 & mj2 = ~37%
- c. In VGG representation, the most similar pair is MJ1.jpg and MJ2.jpg In Pixel representation, the most similar pair is Cat.jpg and MJ2.jpg
- 7) The main problem with pixel representation is that it is very sensitive to its position on the image. It does not extract any other features, it simply compares one pixel to another. Pixel representation is considered a "low-level presentation", and CNNs use an effective supervised learning solution, where the training process uses data that is labeled to close the semantic gap between low-level representations and higher-leveled ones.
- 8) I actually did something a little different I took the original image, cropped it a little, and returned used that new image to test. Here is the slightly cropped image:



Slightly cropped image of motorcycles. You can compare to the original

- a. VGG Representation provided a better summary of the image than Pixel Representation. They are defined below:
 - i. VGG: "A pair of motorcycles parked in a bike slot."
 - ii. Pixel: "a white red and gray boat some people a bird and some water"
- b. I didn't try a lot of examples, but for the most part, VGG was better, I think in part because it localizes where an image is in an object. I thought I could break that with cropping, but looks like the prediction worked out just fine for VGG.

9) 2 Images:



Bad VGG Representation: "A tall brown brick building next to a street with traffic"

Pretty sure that we used this example in class. While some elements do exist that are akin to both images (brick building, traffic, etc), the main idea of the images is not there. There is no *tall* brown brick building and there is nothing to represent a street. Still, very close.



Bad Pixel Representation: "Two men that are each trying to catch a Frisbee at the same time"

There are no similar elements to either two men, frisbee, or running around. Basically it's completely off, but when I looked for an image that did have people playing frisbee, I noticed that the largest similarity was the abundance of green grass in both images. I would imagine that color from both images creates a stronger chance for pixel representation to predict based off of these factors.