

1. 3.2d p.187

M_1 recognizes $B = \{w\#w \mid w \in \{0,1\}^*\}$ so the input, 10#11, should be rejected:

$q_1 10\#11$	$q_7 x0\#x1$
$xq_3 0\#11$	$xq_1 0\#x1$
$x0q_3\#11$	$xxq_2\#x1$
$x0\#q_5 11$	$xx\#q_4 x1$
$x0q_6\#x1$	$xx\#xq_4 1$
$xq_7 0\#x1$	$xx\#x1q_{\text{reject}}$

2. 3.2e p.187

M_1 recognizes $B = \{w\#w \mid w \in \{0,1\}^*\}$ so the input, 10#10, should be accepted:

$q_1 10\#10$	$xq_1 0\#x0$	$xxq_1\#xx$
$xq_3 0\#10$	$xxq_2\#x0$	$xx\#q_8 xx$
$x0q_3\#10$	$xx\#q_4 x0$	$xx\#xq_8 x$
$x0\#q_5 10$	$xx\#xq_4 0$	$xx\#xxq_8$
$x0q_6\#x0$	$xx\#q_6 xx$	$xx\#xxq_{\text{accept}}$
$xq_7 0\#x0$	$xxq_6\#xx$	
$q_7 x0\#x0$	$xq_7 x\#xx$	

4.

* = wildcard and therefore can be any symbol of $\Gamma = \{0, b, \#\}$.

$$\begin{aligned} \delta(q_0, \#) &= (q_1, \#, R) \\ \delta(q_1, 0) &= (q_1, 0, R) \\ \delta(q_1, b) &= (q_1, b, R) \\ \delta(q_1, \#) &= (q_2, \#, R) \\ \delta(q_2, b) &= (q_3, \#, L) \\ \delta(q_3, \#) &= (q_4, \#, L) \\ \delta(q_4, b) &= (q_5, b, R) \\ \delta(q_5, *) &= (q_7, b, L) \\ \delta(q_4, 0) &= (q_6, 0, R) \\ \delta(q_6, *) &= (q_7, 0, L) \\ \delta(q_7, 0) &= (q_4, 0, L) \\ \delta(q_7, b) &= (q_4, b, L) \\ \delta(q_4, \#) &= (q_8, \#, R) \\ \delta(q_8, *) &= (q_{\text{accept}}, b, L) \end{aligned}$$

5. 3.5d p.188

No, by definition a Turing machine has q_{accept} and q_{reject} where $q_{\text{accept}} \neq q_{\text{reject}}$. Additionally, the TM must have an initial state or the machine would immediately halt upon execution. Therefore, a TM requires a minimum of three states.