

Ex  $f(x,y) = (x+2y^3)^2$   $\nabla f(x,y) = \begin{bmatrix} \frac{\partial f(x,y)}{\partial x} & \frac{\partial f(x,y)}{\partial y} \end{bmatrix}$

$$= \begin{bmatrix} 2(x+2y^3) & 2(x+2y^3)6y^2 \end{bmatrix} = \begin{bmatrix} 2(x+2y^3) & 12y^2(x+2y^3) \end{bmatrix}$$

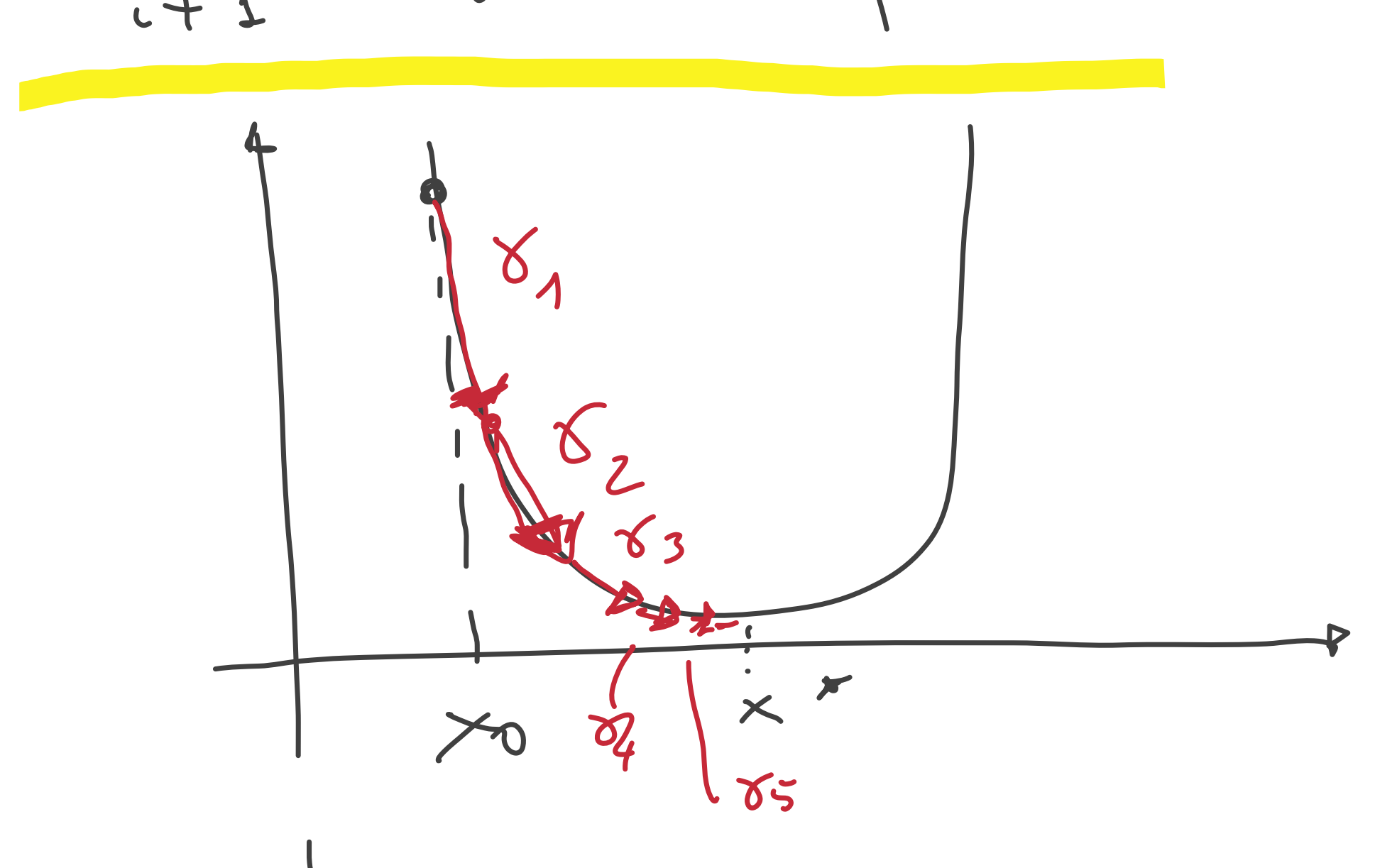
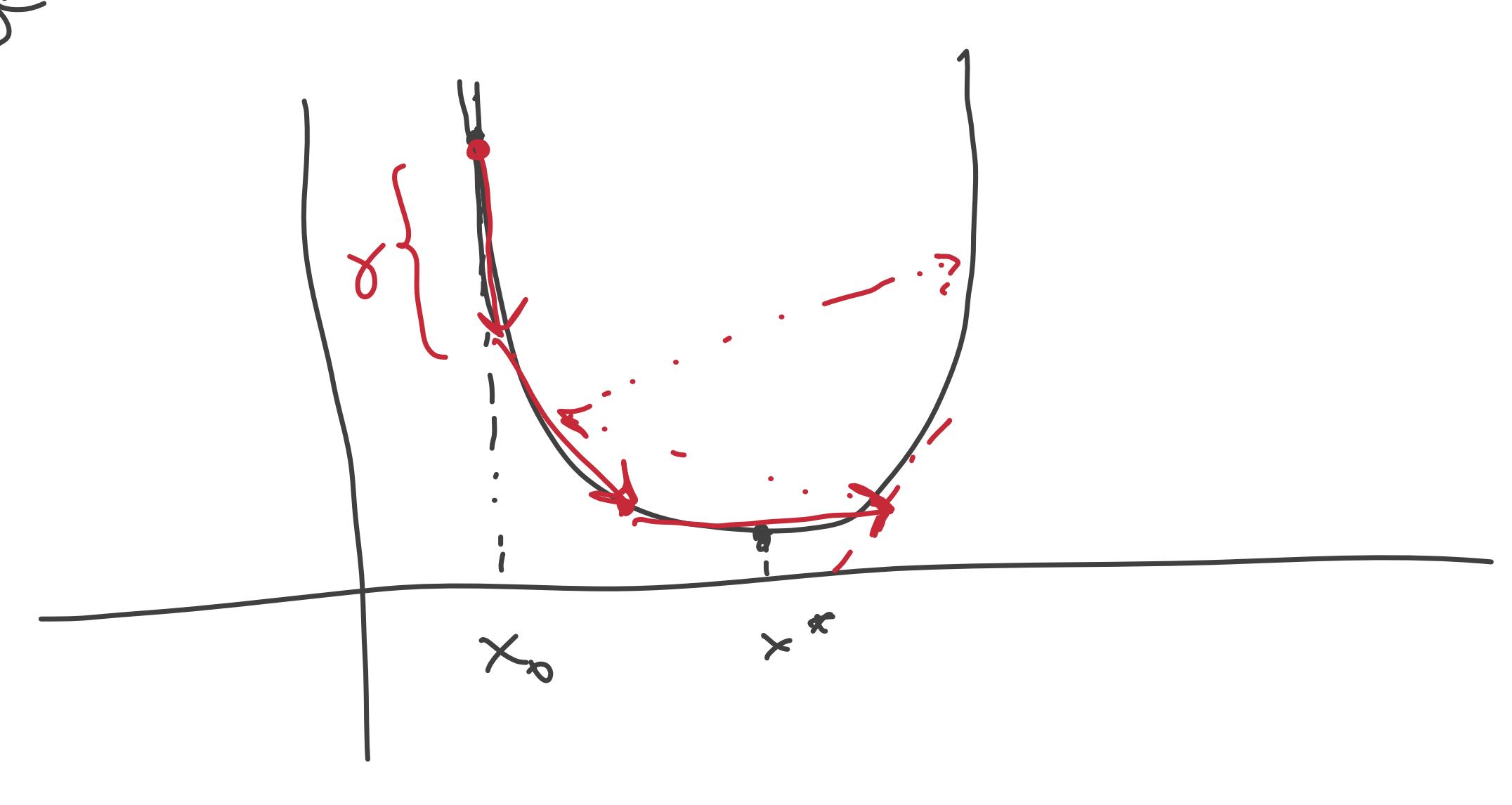
### GRADIENT DESCENT

If we want to find a local optimum  $f(x^*)$  of a function  $f: \mathbb{R}^n \rightarrow \mathbb{R}$  we start with an initial guess  $x_0$  of the parameters we wish to optimize and then iterate according to

$$x_{i+1} = x_i - \gamma \nabla f(x_i) \quad (*)$$

where  $\gamma$  dictates how far to move along the gradient descent curve.

The choice of  $\gamma$  is critical for the performance -  
If  $\gamma$  is too small the process might take too long and  
if  $\gamma$  is too large we are in danger of overshooting.  
In  $(*)$   $\gamma$  is a fixed step size but it may also change at each iteration i.e.  $x_{i+1} = x_i - \gamma_i \nabla f(x_i)$



Ex  $(*)$   $x_0$  ,  $x_{i+1} = x_i - \gamma \nabla f(x_i)$

$i=0$	$x_1 = x_0 - \gamma \nabla f(x_0)$
$i=1$	$x_2 = x_1 - \gamma \nabla f(x_1)$
$i=2$	$x_3 \dots$
$i=3$	$x_4 \dots$
$\vdots$	$\vdots$

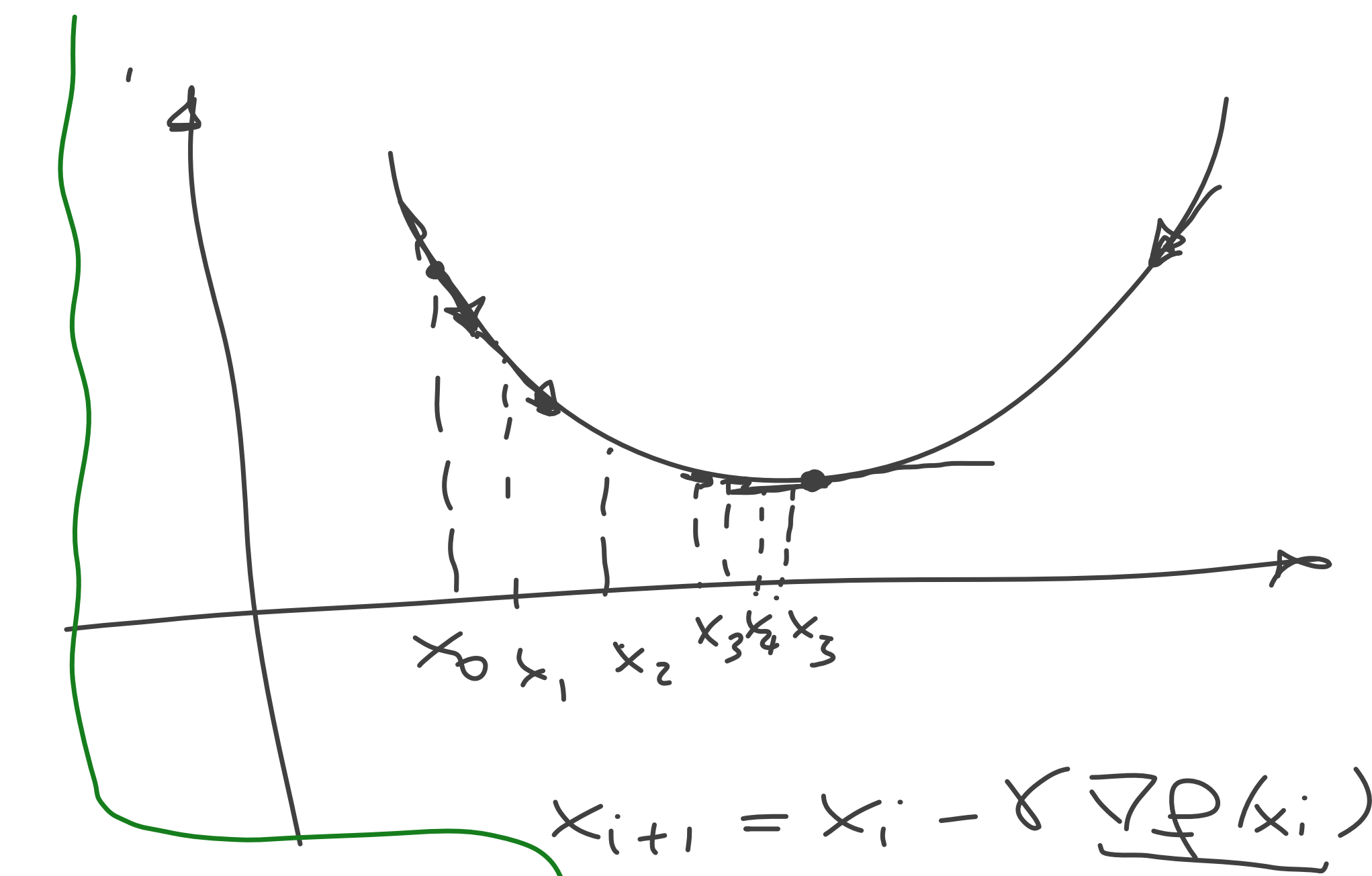
INPUT:  $x_0, \nabla f, \gamma, itMax$   
OUTPUT:  $x_{fin} \quad x_{fin} \approx x^*$

Matlab code

```
i = 0, 1, 2, 3, ... if
    if ||x_{i+1}|| > ||x_i|| (2) NO
    stop
    x_{fin} = x_{i+1}
```

STOPPING CRITERIA  $\epsilon$  tolerance ( $10^{-5}$ )

- 1)  $\|\nabla f(x_{i+1})\| \leq \epsilon$
- 2)  $\|x_{i+1} - x_i\| < \epsilon$  ✓
- 3)  $i < itMax$  ✓



$x_i = x_0; x_{i+1} = x_i - \gamma * \nabla f(x_i); i = 0;$   
while  $(\|x_{i+1} - x_i\| > \epsilon) \&\& (i < itMax) \&\& \|\nabla f(x_{i+1})\| > \epsilon$   
     $i = i + 1; x_i = x_{i+1};$   
     $x_{i+1} = x_i - \gamma * \nabla f(x_i)$   
end

$x_{i+1} = x_i - \gamma \nabla f(x_i)$   
small  
 $x_{i+1} \sim x_i$   
 $x_0 \rightarrow x_1 \rightarrow x_2 \rightarrow x_3$   
 $i = 0$   
while  
     $x_1 = x$   
     $x_2 = x_1 - \gamma \dots$

Example •  $f(x,y) = x^2 + 2y^2$  ,  $x_0 = [4 \ 3]$  ,  $\gamma = 0.1$  ( $x^* = [0 \ 0]$ )

$x_1 = x_0 - \gamma \nabla f(x_0) = [4 \ 3] - 0.1 [8 \ 12] = [3.2 \ 1.8]$

$\nabla f(x,y) = [2x \ 4y]$

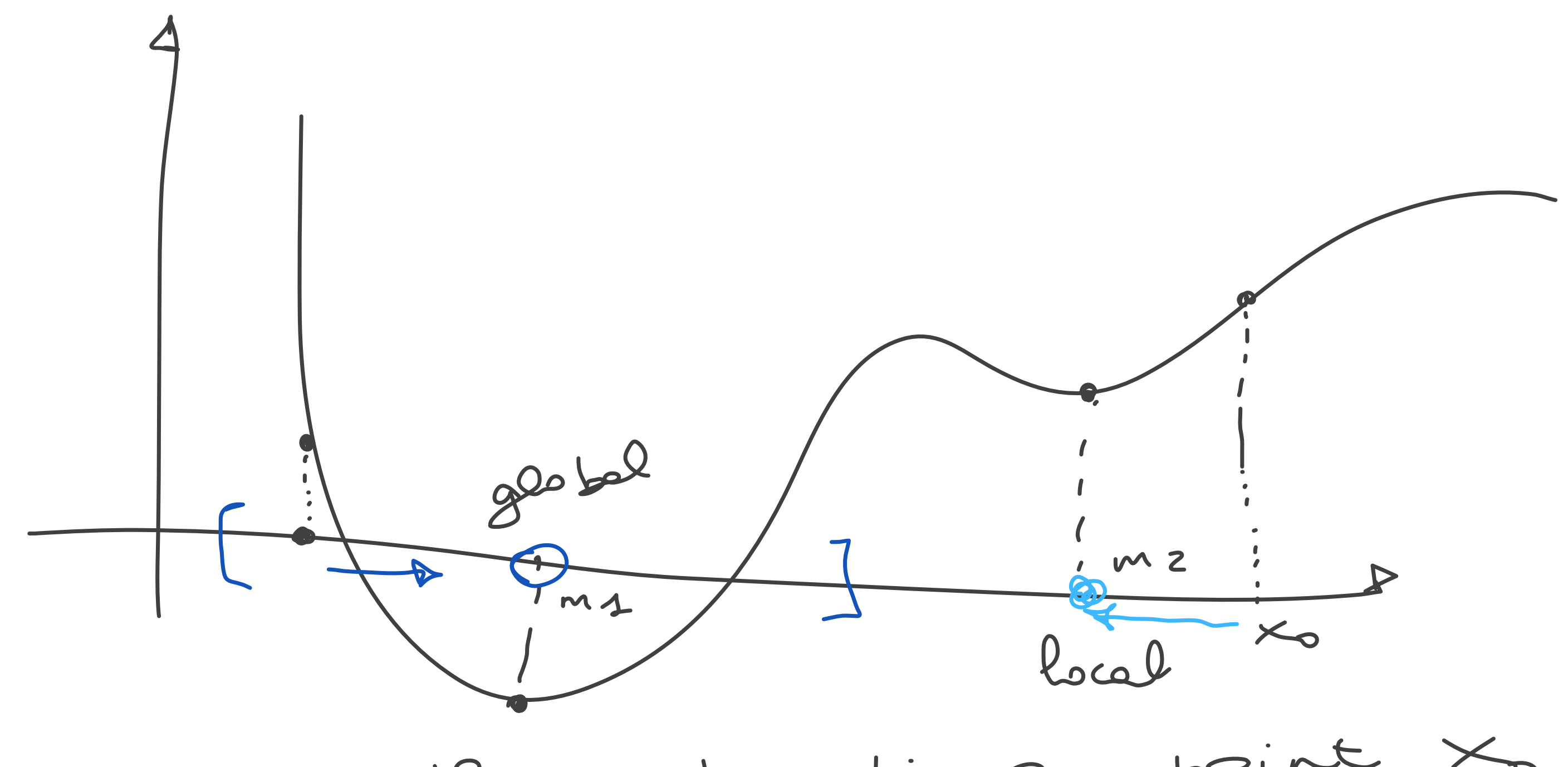
$\nabla f(x_0) = [2x_0(1) \ 4x_0(2)]$

$x_2 = x_1 - \gamma \nabla f(x_1) = [3.2 \ 1.8] - 0.1 [6.4 \ 7.2] = [2.56 \ 1.08]$

$\times [8 \cdot 10^{-4} \ 1 \cdot 10^{-8}]$

•  $\gamma = 0.5 \rightarrow$  no convergence

Rk



Depending on the starting point  $x_0$  we may reach  $m_1$  or  $m_2$

For CONVEX functions all local minima are global minima  
So these functions do not exhibit the tricky dependence on the starting point of the optimization algorithm.