Supplement + max length & FOV

frame rate > <u>speed</u> supplement

FOV = sensor width = tgd

resolution  $(mm/px) = \frac{length}{m^{\circ}pixel} = \frac{speed}{frequency} = \frac{1}{resolution}$ 

FOV\_ X = resolution · m° pixel

sensor width = mo pixel · pixel size

shulter time = speed = blur frequency

bit rate = m° pixel . frequency

max\_x (y) . m° pixel\_y (x) = length > max\_y (x)

m° pixel(y)

smallest size defect: correct processing · resolution