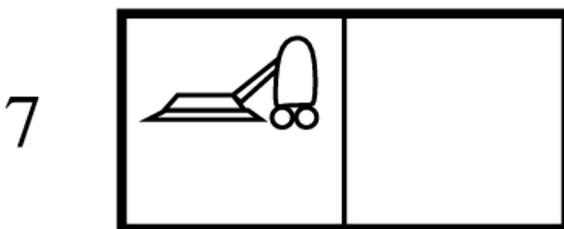
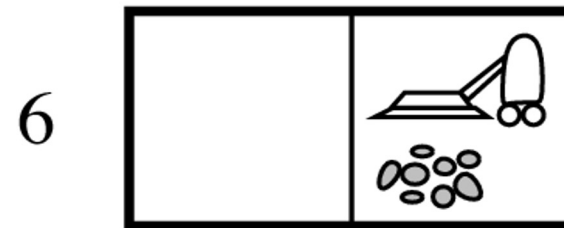
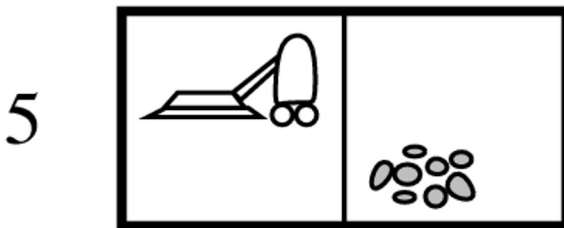
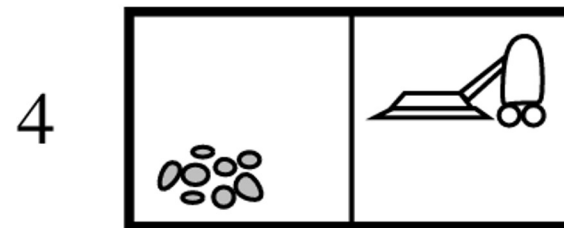
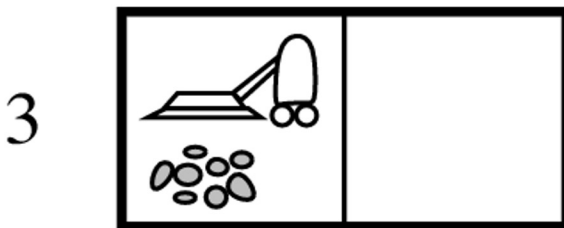
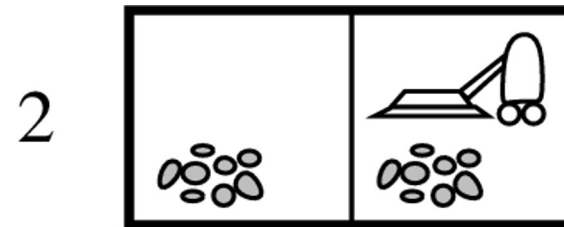
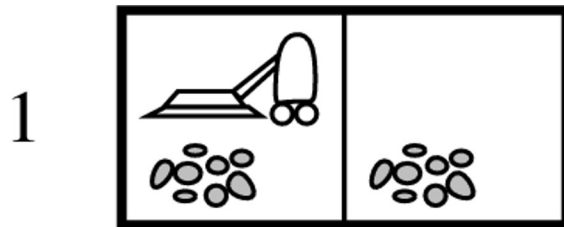


# Searching with nondeterministic actions

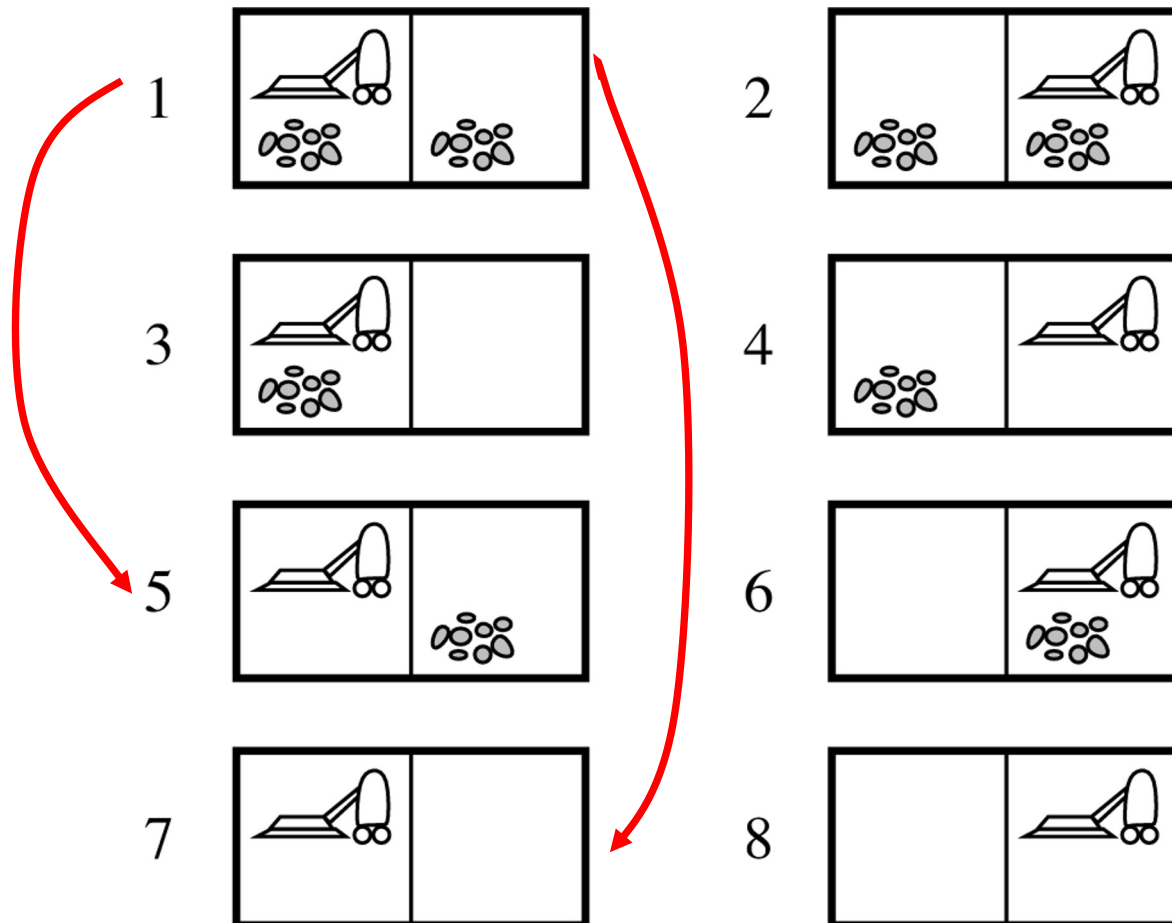


# Searching with nondeterministic action: erratic vacuum world

The *Suck* action works as follows:

- When applied to a dirty square the action cleans the square and sometimes cleans up dirt in an adjacent square, too
- When applied to a clean square the action sometimes deposit dirt on the carpet

# Contingency plan 1/2



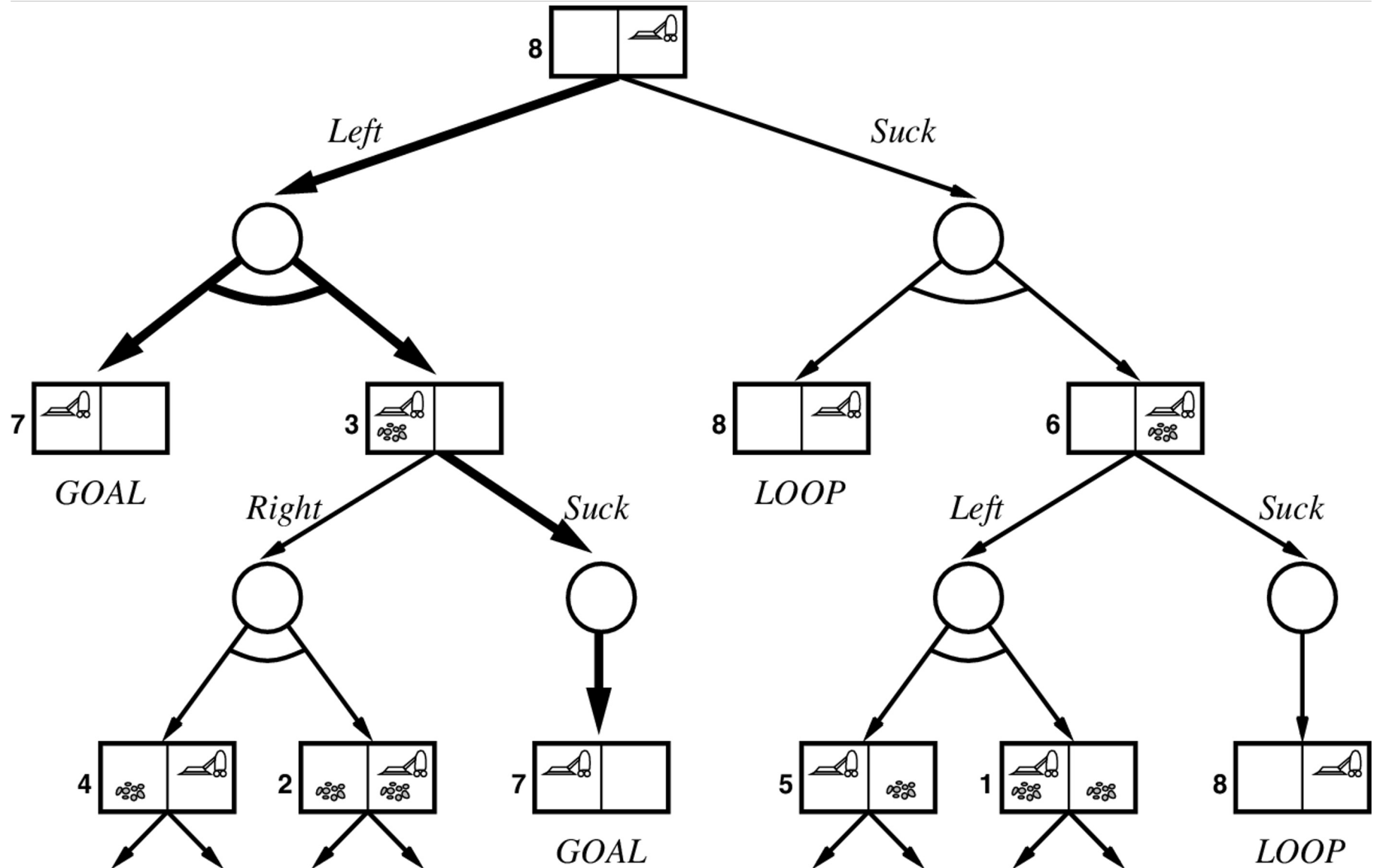
# Contingency plan 2/2

Interleaving between search and execution

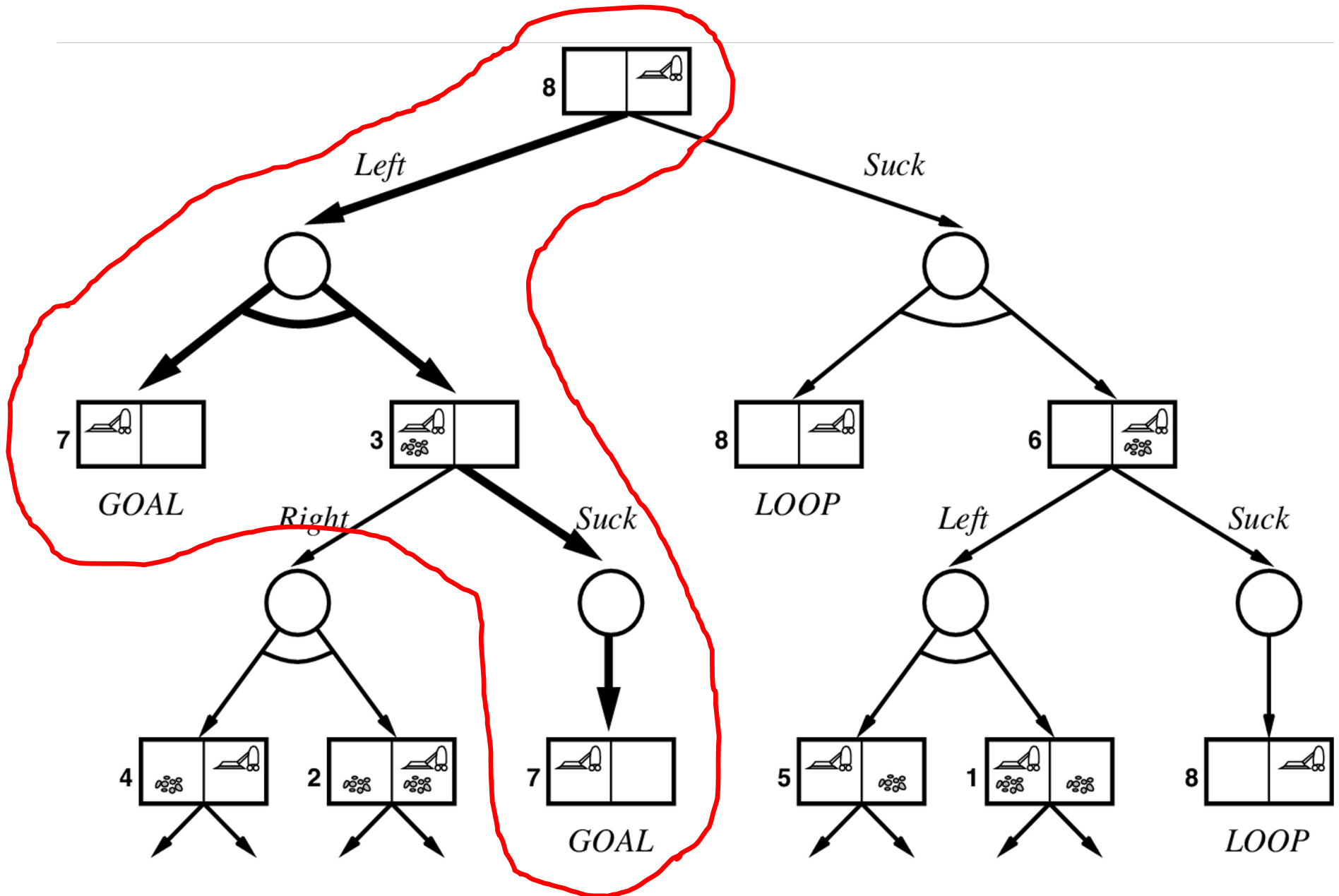
Given the vacuum cleaner in state = 7

**[*Suck*, if state = 5 then [*Right*, *Suck*] else []]**

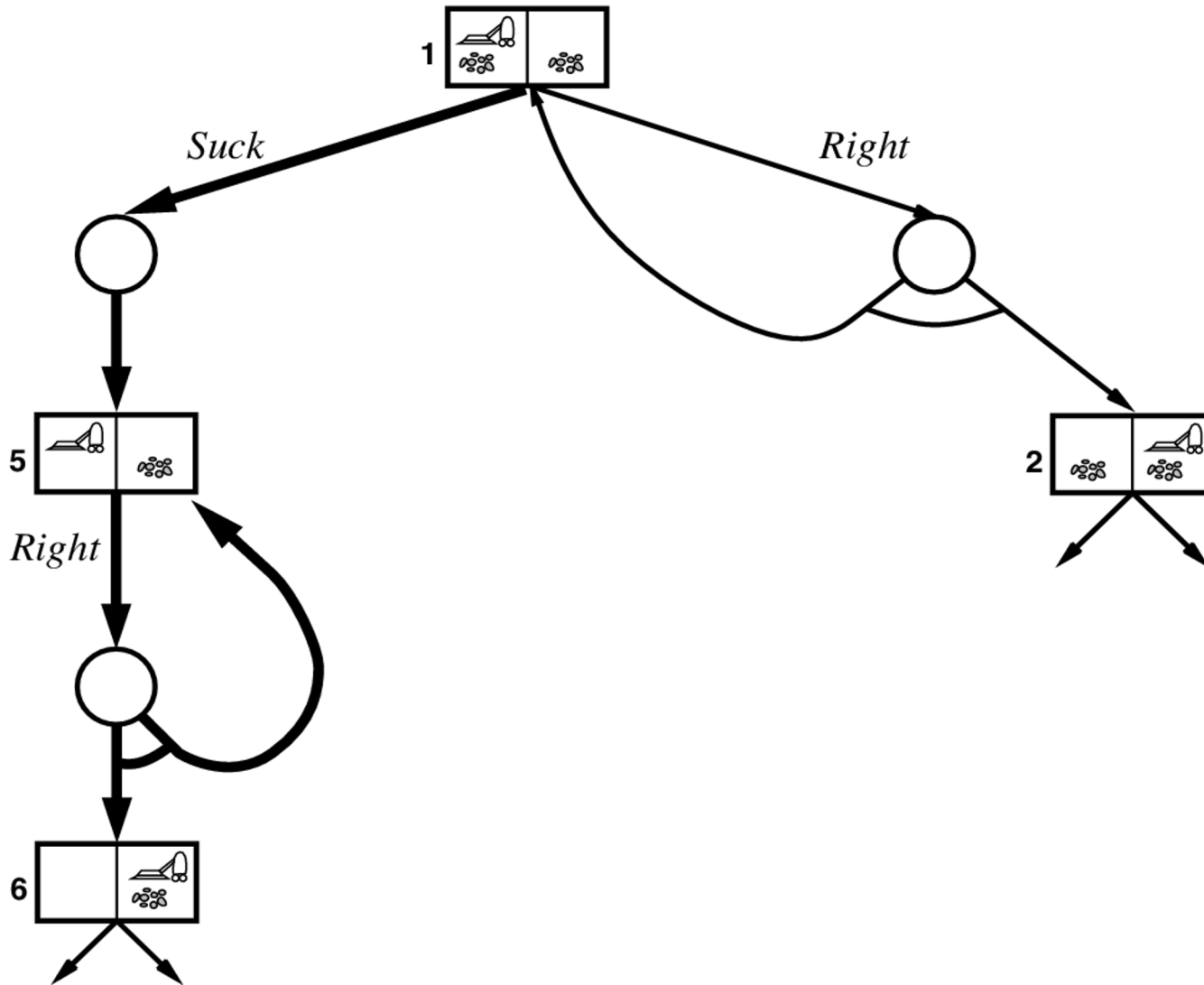
# AND-OR search trees



# AND-OR trees



# Slippery vacuum world



# Slippery vacuum world

[*Suck*, **while** state = 5 **do** *Right* , *Suck*]



# Searching with no observations

