

Objective Chart

Objective

1,400
1,300
1,200
1,100
1,000
900
800
700
600
500
400
300
200
100
0

0

10

20

30

40

50

60

70

N

- GRASP{maxIterations=1000; alpha=0.3; GreedyLocalSearch{firstImprovement=true; strategy=REASSIGNMENT}}
- GRASP{maxIterations=1000; alpha=0.5; GreedyLocalSearch{firstImprovement=true; strategy=REASSIGNMENT}}
- GRASP{maxIterations=1000; alpha=0.65; GreedyLocalSearch{firstImprovement=true; strategy=REASSIGNMENT}}
- GRASP{maxIterations=1000; alpha=0.85; GreedyLocalSearch{firstImprovement=true; strategy=REASSIGNMENT}}
- GRASP{maxIterations=1000; alpha=1.0; GreedyLocalSearch{firstImprovement=true; strategy=REASSIGNMENT}}