

Computational Methods for Astrophysical Applications

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Lesson 2 :

Finite Difference Approximation for linear hyperbolic PDE

- **Spatial discretization**

Mesh and data collocation

Discrete equations

- **Time advance**

Von Neumann stability analysis

Explicit linear schemes

- 1 Preliminary concepts
 - Mesh and data collocation
 - Consistency
 - Stability

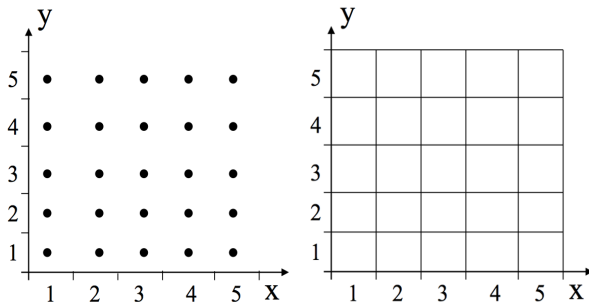
- 2 Spatial discretization
 - Discretized function
 - Discretized first order derivatives
 - Discretized second order derivatives

- 3 Temporal discretization
 - Explicit methods
 - Implicit methods

- 4 Time advance
 - Von Neumann stability analysis
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Mesh

- Numerical schemes require spatial and temporal discretization



Data collocation

- Finite difference (FD): values are located at points, not necessarily regularly distributed. There is no cell.
 - ⇒ Intuitive & computationally fast but not conservative and no straightforward refinement strategy
- Finite volume (FV): values are associated to the whole cell : the value of the function is constant over the cell. Conservative by Gauss' law (a.k.a Green-Ostrogradsky).
 - ⇒ Reconstruction at interfaces required => slower

Consistency of a method

- A FD approximation of a PDE is *consistent* if and only if

$$\text{FD} \xrightarrow{\Delta t, \Delta x \rightarrow 0} \text{PDE}$$

\Rightarrow Balsara 2.4

- Empirical order of convergence (EOC) : u analytic solution and \tilde{u}_i numerical solution on 1D uniform grid x_i with $i \in [1, N_\nu = 2^\nu]$. Compute the maximal error $\epsilon_\nu = \|u - \tilde{u}\|_\infty$ and deduce EOC :

$$\text{EOC}_\nu = \frac{\log(\epsilon_\nu / \epsilon_{\nu-1})}{\log(N_{\nu-1} / N_\nu)}$$

\Rightarrow quantify the overall quality of a method, on analytic test-cases

\Rightarrow see [Project# 1](#) of Köln school

\Rightarrow see Balsara chapter 2, slides# 27-32

Von Neumann stability analysis

- round-off errors should not grow during time progression
 - \Rightarrow numerical solution = exact + round-off error $\epsilon(x, t)$
 - \Rightarrow represent $\epsilon(x, t)$ in Fourier series, analyse Fourier term

$$\epsilon_i^n(k) = \hat{\epsilon}_k e^{\lambda t^n} e^{ikx_i}$$

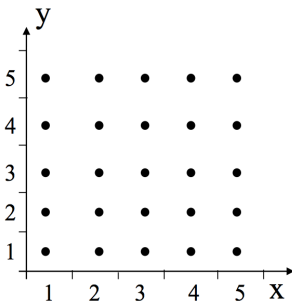
- numerically stable scheme \forall spatial wavenumbers k if

$$\left| \frac{\epsilon_i^{n+1}(k)}{\epsilon_i^n(k)} \right| = |e^{\lambda \Delta t}| \leq 1$$

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Discretized function

- Balsara 2.3
- We now want to obtain a FD discretized form of the equations to solve



⇒ variables evaluated at the points

Discretized spatial derivatives

- Assume $N + 1$ points regularly spaced by Δx and u_i the associated values
- Key-question: how to get a FD approximation of the spatial derivatives $u'_i, u''_i \dots$?
 - \Rightarrow Use Taylor series expansions

Backward, forward & central FD

- For instance, to 1st order accuracy in Δx , we have the *1st order forward difference* :

$$u'_i \sim \frac{u_{i+1} - u_i}{\Delta x}$$

\Rightarrow but we also have the *1st order backward difference* :

$$u'_i \sim \frac{u_i - u_{i-1}}{\Delta x}$$

\Rightarrow or the *2nd order central difference* :

$$u'_i \sim \frac{u_{i+1} - u_{i-1}}{2\Delta x}$$

- Which one to choose? Properties (e.g. stencil, accuracy)?

Truncation error and order of accuracy

- Taylor expansions linking u_i to the continuous function u :

$$u_{i+1} = u(0) + u'(0) \Delta x + u''(0) \frac{(\Delta x)^2}{2!} + u^{(3)}(0) \frac{(\Delta x)^3}{3!} + \dots \quad (1)$$

$$u_i = u(0) \quad (2)$$

$$u_{i-1} = u(0) - u'(0) \Delta x + u''(0) \frac{(\Delta x)^2}{2!} - u^{(3)}(0) \frac{(\Delta x)^3}{3!} + \dots \quad (3)$$

$$\Rightarrow (1)-(3) : u'(0) = \frac{u_{i+1} - u_{i-1}}{2\Delta x} + \underbrace{O((\Delta x)^2)}_{\text{truncation error}}$$

- Order of accuracy (o.a.) = order of first truncated term
 $\Rightarrow (\Delta x \rightarrow \Delta x/2) \Rightarrow \text{accuracy improved by } 2^{\text{o.a.}}$
- Stencil : points required, increases with o.a.

2nd order derivative

- Same principle

$$(1)+(3)-2\times(2) : u''(0) = \frac{u_{i+1}-2u_i+u_{i-1}}{(\Delta x)^2} + O((\Delta x)^2)$$

⇒ O.a.? Stencil?

- Exo

⇒ 3rd, 4th & 5th order central difference representations of u'_i ?

⇒ 2nd order forward/backward differences?

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Principle

- Consider the 1D linear advection equation with constant speed v

$$\partial_t \rho + v \partial_x \rho = 0$$

- Explicit time integration: values at t^{n+1} computed from available information on time level $t^n = t^{n+1} - \Delta t$

Principle

- Example: explicit forward 2nd order central difference

$$\frac{u^{n+1} - u^n}{\Delta t} = -v \frac{u_{i+1}^n - u_{i-1}^n}{2\Delta x}$$

⇒ rearrange to

$$u_i^{n+1} = u_i^n - v \frac{\Delta t}{\Delta x} \frac{u_{i+1}^n - u_{i-1}^n}{2} \quad (4)$$

⇒ 1st order accurate in time, 2nd order in space

⇒ Is this FD approximation consistent?

- Sandbox: Write your 1st solver using the explicit forward 2nd order central difference above. Apply it to the Riemann problem (advection of a step function). Is the numerical solution stable?

Von Neumann stability analysis

- Von Neumann stability analysis

$$e^{\lambda \Delta t} = 1 - \frac{v \Delta t}{\Delta x} \frac{e^{ik\Delta x} - e^{-ik\Delta x}}{2} = 1 - i \frac{v \Delta t}{\Delta x} \sin(k\Delta x)$$

\Rightarrow scheme is unconditionally unstable since for all k

$$\left| \frac{\epsilon_k^{n+1}}{\epsilon_k^n} \right| > 1$$

- 3 possible solutions to stabilize
 - \Rightarrow add numerical diffusivity to damp nonphysical instability
 - \Rightarrow impose same space-time symmetry as original PDE
 - \Rightarrow use implicit scheme (next section)

Numerical diffusivity

- adding diffusion: advection-diffusion equation has form

$$\frac{\partial u}{\partial t} = -v \frac{\partial u}{\partial x} + \mathcal{D} \frac{\partial^2 u}{\partial x^2} \quad \text{with } \mathcal{D} \text{ a diffusion coefficient}$$

- Lax-Friedrichs scheme : in (4), if we replace u_i^n by spatial average between $i-1$ and $i+1$, we get :

$$u_i^{n+1} = \frac{u_{i+1}^n + u_{i-1}^n}{2} - v \frac{\Delta t}{\Delta x} \frac{u_{i+1}^n - u_{i-1}^n}{2}$$

which can be rearranged to form

$$\frac{u_i^{n+1} - u_i^n}{\Delta t} = -v \frac{u_{i+1}^n - u_{i-1}^n}{2\Delta x} + \frac{(\Delta x)^2}{2\Delta t} \frac{u_{i+1}^n - 2u_i^n + u_{i-1}^n}{(\Delta x)^2}$$

\Rightarrow numerical dissipation with $\mathcal{D} \equiv (\Delta x)^2 / 2\Delta t$

\Rightarrow 1st order accurate in time, 2nd order in space

CFL condition

- perform von Neumann stability analysis for Lax-Friedrichs

$$e^{\lambda \Delta t} = \cos(k \Delta x) - i \frac{v \Delta t}{\Delta x} \sin(k \Delta x)$$

⇒ conditional stability requiring Courant number C

$$C \equiv \frac{|v| \Delta t}{\Delta x} \leq 1$$

⇒ limitation of the time step Δt for a given resolution Δx

⇒ Courant-Friedrichs-Lewy condition (1928)

⇒ necessary condition for stability

- Rk: see stencil of Lax-Friedrichs scheme in Table on slide 23

The Lax-Wendroff scheme

- Lax-Friedrichs has different o.a. in space (2nd) and time (1st)
⇒ Taylor expansion in time suggests :

$$u_i^{n+1} = u_i^n - \frac{1}{2} \frac{\Delta t}{\Delta x} v (u_{i+1}^n - u_{i-1}^n) + \frac{1}{2} \frac{(\Delta t)^2}{(\Delta x)^2} v^2 (u_{i+1}^n - 2u_i^n + u_{i-1}^n)$$

⇒ 2nd order in space and in time

- Conditionally stable
⇒ for $\Delta t = \Delta x/v$, we retrieve the Lax-Friedrichs scheme

Space-time symmetry

- How to maintain the space-time symmetry of the PDE in the FD approximation?
 - ⇒ use central discretisation for both time and space
 - ⇒ leapfrog scheme

$$u_i^{n+1} = u_i^{n-1} - v \frac{\Delta t}{\Delta x} \frac{u_{i+1}^n - u_{i-1}^n}{2}$$

- ⇒ conditionally stable and second-order accurate
 - ⇒ multiple time levels involved: $n-1$, n , $n+1$
 - ⇒ potential problem: even/odd time levels may 'decouple'
- stencil of leapfrog on slide 23

Examples

- Overview of explicit FD methods (from Leveque1 chapter 10)








Name	Difference Equations	Stencil
Backward Euler	$U_j^{n+1} = U_j^n - \frac{k}{2h} A(U_{j+1}^n - U_{j-1}^n)$	
One-sided	$U_j^{n+1} = U_j^n - \frac{k}{h} A(U_j^n - U_{j-1}^n)$	
One-sided	$U_j^{n+1} = U_j^n - \frac{k}{h} A(U_{j+1}^n - U_j^n)$	
Lax-Friedrichs	$U_j^{n+1} = \frac{1}{2}(U_{j-1}^n + U_{j+1}^n) - \frac{k}{2h} A(U_{j+1}^n - U_{j-1}^n)$	
Leapfrog	$U_j^{n+1} = U_j^{n-1} - \frac{k}{2h} A(U_{j+1}^n - U_{j-1}^n)$	
Lax-Wendroff	$U_j^{n+1} = U_j^n - \frac{k}{2h} A(U_{j+1}^n - U_{j-1}^n) + \frac{k^2}{2h^2} A^2(U_{j+1}^n - 2U_j^n + U_{j-1}^n)$	
Beam-Warming	$U_j^{n+1} = U_j^n - \frac{k}{2h} A(3U_j^n - 4U_{j-1}^n + U_{j-2}^n) + \frac{k^2}{2h^2} A^2(U_j^n - 2U_{j-1}^n + U_{j-2}^n)$	

TABLE 10.1

Finite difference methods for the linear problem $u_t + Au_x = 0$.

$h=dx$
 $k=dt$

Central FD method

Truncation error and order of accuracy

- for second order wave equation

$$\frac{\partial^2 u}{\partial t^2} - v^2 \frac{\partial^2 u}{\partial x^2} = 0$$

⇒ factorizes to

$$\left(\frac{\partial}{\partial t} - v \frac{\partial}{\partial x} \right) \left(\frac{\partial}{\partial t} + v \frac{\partial}{\partial x} \right) u = 0$$

⇒ general solution has left and right going wave with

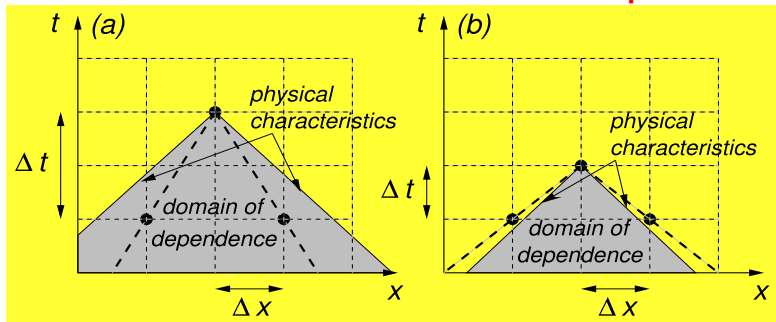
$$u = f(x - vt) + g(x + vt)$$

⇒ initial shapes $f(x)$, $g(x)$ combine

⇒ 2 characteristics $\frac{dx}{dt} = \pm v$

Consistency of a FDA w/ respect to its PDE

- illustrate CFL for second order wave equation:
the domain of dependence of the differential equation should be contained in the DOD of the discretised equations



⇒ stability means physical DOD contained in stencil bounds (numerical DOD), hence Δt small enough (right case)

- note: linear advection + wave equation: DOD only involves 1 or 2 points from $t = 0 \leftrightarrow$ HD: DOD bounds set by $v \pm c_s$ with c_s

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Principle and necessary stability condition

- von Neumann stability analysis for BTCS scheme

$$|e^{\lambda \Delta t}| = \frac{1}{|1 + i \frac{v \Delta t}{\Delta x} \sin(k \Delta x)|} < 1 \quad \text{for all } k$$

\Rightarrow **unconditionally stable**, any (large) time step Δt allowed

- note: **stability does not imply accuracy**

\Rightarrow large Δt affects accuracy, defines time resolution:
behavior may involve physical timescale that needs to be resolved!

- implicit backward Euler: first order in time

Convergence : Lax-Richtmeyer theorem

- von Neumann stability analysis for BTCS scheme

$$|e^{\lambda \Delta t}| = \frac{1}{|1 + i \frac{v \Delta t}{\Delta x} \sin(k \Delta x)|} < 1 \quad \text{for all } k$$

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Lax-Friedrichs

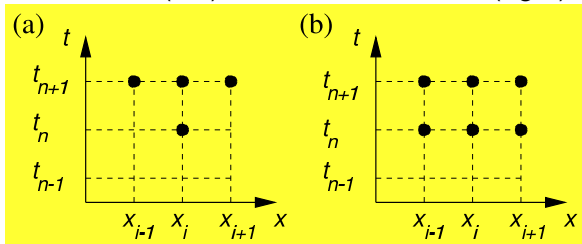
- spatial differences as average of n -th and $(n+1)$ -th time step

$$u_i^{n+1} = u_i^n - \frac{1}{4}v \frac{\Delta t}{\Delta x} (u_{i+1}^{n+1} + u_{i+1}^n - u_{i-1}^{n+1} - u_{i-1}^n)$$

⇒ second order **Crank–Nicolson method**

⇒ **Exercise**: show that this scheme is unconditionally stable,
2nd order accurate

- stencils for BTCS (left) and Crank-Nicolson (right)



Lax-Wendroff

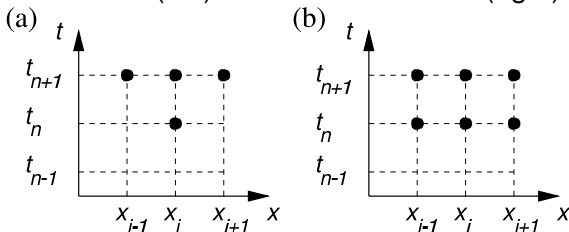
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\Rightarrow second order **Crank–Nicolson method**

\Rightarrow **Exercise**: show that this scheme is unconditionally stable,
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Runge-Kutta

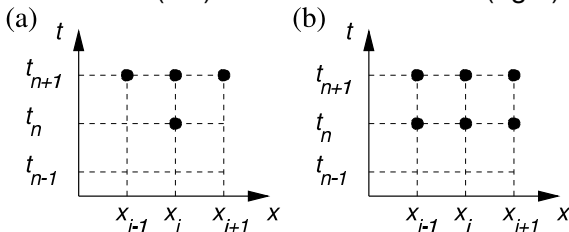
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⇒ second order **Crank–Nicolson method**

⇒ **Exercise**: show that this scheme is unconditionally stable,
2nd order accurate

- stencils for BTCS (left) and Crank-Nicolson (right)



Upwind FD scheme

- spatial differences as average of n -th and $(n+1)$ -th time step

$$u_i^{n+1} = u_i^n - \frac{1}{4}v \frac{\Delta t}{\Delta x} (u_{i+1}^{n+1} + u_{i+1}^n - u_{i-1}^{n+1} - u_{i-1}^n)$$

⇒ second order **Crank–Nicolson method**

⇒ **Exercise**: show that this scheme is unconditionally stable,
2nd order accurate

- stencils for BTCS (left) and Crank-Nicolson (right)

