

# HW9

1.

- (a) If the two estimates of the mean are fairly similar, it is probably safe to use the pooled estimate. Otherwise, the researcher should use the unpooled estimate.

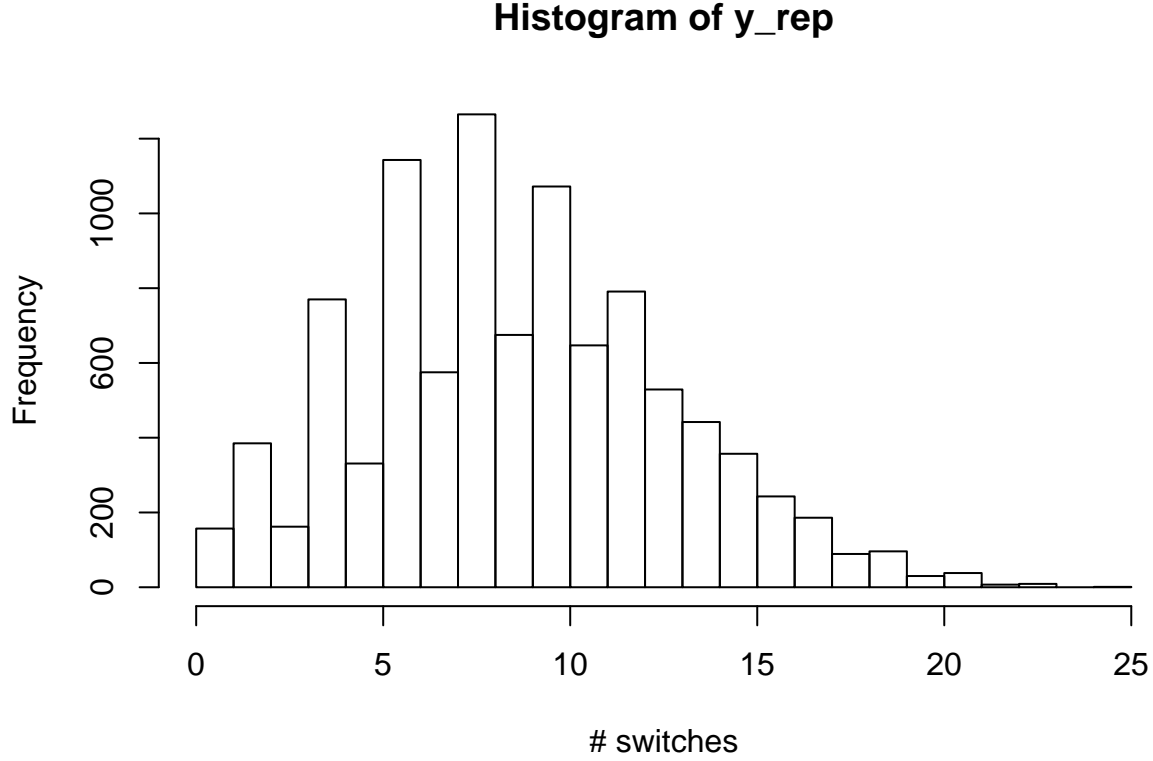
b.  $data_j \sim N(\mu_j, \sigma_j)$   
 $\mu_j \sim N(0, \tau_j)$

2.

- (a) Since we only have one experiment and the parameter  $\theta$  is only dependent on  $n$  and the number of zeros, the new data generation process doesn't change inference under this assumed model.
- (b) Under this data model we actually see more switches, presumably due to there often being more than 20 trials before 13 zeros are reached. This gives further evidence that a better model would include some autocorrelation

```
samples <- 10000
y_rep <- vector(mode = "numeric", length = samples)
for(s in 1:samples) {
  theta <- rbeta(1, 8, 14)
  nzeros <- 0
  nswitches <- 0
  n <- 0
  prev <- 0
  while(nzeros < 13) {
    samp <- rbinom(1, 1, theta)
    if(samp == 0){
      nzeros <- nzeros + 1
    }
    if(samp != prev & n > 0)
    {
      nswitches <- nswitches + 1
    }
    prev <- samp
    n <- n + 1
  }
  y_rep[s] <- nswitches
}

hist(y_rep, breaks = 20, freq = TRUE, xlab = "# switches")
```



3.

- (a) The numerator and denominator of the Bayes factor are essentially the normalization constant a product of gaussians. Thus  $p(H_1|y) = \prod_j \int N(\theta_j|y_j, \sigma_j^2)N(\theta_j|0, A^2) = \prod_j \frac{1}{\sqrt{2\pi\sigma_j^2+A^2}}e^{-\frac{y_j^2}{2(\sigma_j^2+A^2)}}$  and

$$p(H_2|y) = \int \prod_j (N(\theta|y_j, \sigma_j^2))N(\theta|0, A^2) = \frac{1}{2\pi^4} \sqrt{\frac{1}{\sum_j (\sigma_j^2)+A^2}} e^{-\frac{1}{2}(\sum_j \frac{y_j^2}{\sigma_j^2} - (\frac{\sum_j y_j}{\sum_j (\sigma_j^2)+A^2})^2)}$$

- (b) As A goes to infinity, the Bayes factor will go to infinity since the A in exponent term of  $p(H_2|y)$  will make the whole term get very large while  $p(H_1|y)$  will not. So regardless of the data, the pooled model will win. This also makes intuitive sense since the probability of choosing just one reasonable  $\theta$  is higher than the probability of choosing n reasonable  $\theta$ s under the noninformative prior.

- (c) As n gets really large, we can basically interpret this as A getting smaller in the prior and the prior mean getting close to  $\bar{y}$  since getting more data is equivalent to having a stronger prior. Thus, for each

additional data point  $y_j$ ,  $p(H_2|y_j, y) = \prod_j \frac{1}{\sqrt{2\pi\sigma_j^2}}e^{-\frac{(y_j-\bar{y})^2}{2(\sigma_j^2)}}$ . In contrast,  $p(H_1|y) = \frac{1}{\sqrt{2\pi\sigma_j^2+A^2}}e^{-\frac{y_j^2}{2(\sigma_j^2+A^2)}}$  since each data point is essentially independent. These will be the same when  $\bar{y} = 0$  and A equals the sampling variance of y. Otherwise, the pooled model will be preferred under the Bayes factor calculation.