## Sivan Syed



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## **EDUCATION**

The University of Texas at Austin (GPA: 3.8/4.0)

May 2027

Bachelor of Science, Electrical and Computer Engineering

Bachelor of Science, **Physics** 

Certificate, German

Minor, Materials Science and Engineering

**Relevant Coursework:** Circuit Theory, Electromagnetic Engineering, Computational Physics, Fluid Dynamics, Solid-State Electronic Devices, Thermodynamics and Statistical Mechanics, Mechanics of Solids, Embedded Systems, Fundamental Electronic Circuits, Dynamics

## **EXPERIENCE**

Adom Industries Inc. / R&D Design Engineer / Electrical and Robotics Engineering

May 2025 - August 2025

- Designed the mechanical and electrical systems for robotic shuttle drivetrain to pick up and deliver circuit boards autonomously
- Applied FEA methods to analyze stress, strain, and deformation, reducing material usage by 88%

Sandia National Laboratories / R&D Computational Engineer / Pulsed Power Physics

May 2024 – August 2024

- Analyzed fluid RTIs and RMIs to diagnose inaccuracies in ALEGRA simulations
- Created an electrical current pulse generation model to rapidly deploy >10000 datasets for use in a training algorithm
- Programmed a model to track radial implosion trajectories on the Z-Machine by numerically solving differential equations

FSAE Longhorn Racing / Dynamics + Vehicle Modeling Engineer / Steering Lead, Member

September 2022 - August 2025

- Modelled vehicle kinematics to optimize car performance and stability in Python
- Designed the steering system for ideal Anti-Ackermann and dynamics characteristics validated through simulation
- Reduced weight with carbon fiber columns of Steering system by 68%

Large Enriched Germanium for Neutrinoless Double-beta Decay – Karol Lang / High Energy Particle Detectors November 2022 – Present

- Analyzing scintillating and wavelength shifting fibers to detect the neutrinoless double-beta decay
- Visualized and analyzed positional and intensity variation from Fermilab's Hadron Monitor for preparation to be repaired
- Simulating through a Docker supported codebase, MaGe, photon emissions from scintillating fibers

## **Projects**

Surrogate ML Model for Magneto-Hydrodynamics Radial Trajectory Prediction

Relevant Skills: Neural Network, MATLAB

- Implemented an FNN Machine Learning model to replicate Magneto-Hydrodynamics simulations with >98% fidelity
- Utilized for rapid High Energy Density simulations and iterative design of future tests

**Vehicle Dynamics and Modeling** 

Relevant Skills: Vehicle Modeling, Computational Dynamics, Simulation, Python, C++

- Created a kinematic model of the vehicle to optimize car performance and stability
- Designing compliance model to simulate stress of vehicle parts and implement collision detection through FEM

Weather-Damage Forecasting Relevant Skills: Python, XGBoost, PyTorch, Predictive Analysis, Data Visualization, Data Analysis, LSTM

- Predicted damage with an LSTM model with >98% accuracy to set optimal insurance prices and maximize profits
- Explored numerous time analysis approaches such as ARIMA, LSTMs, and a Transformer model, comparing and optimizing each

Plasma Physics Fusion Reactor Anomaly Detector Relevant Skills: Python, XGBoost, sklearn, PCA, Kaggle, Anomaly Detection, RNN

- Developed and compared PCA + Random Forest anomaly detection models for when MIT's tokamak fusion reactor was unstable
- Simulated with time series analysis models such as RNNs for fusion reactor conditions during runtime

**Transformer Model for Pulse Shape Discrimination** 

Relevant Skills: Transformer Theory, Neural Network

- Developing Pulse Shape Discrimination Methods of radioactive sources and incorporating a Transformer model for optimization
- Cleaning data for input use into the Transformer and achieving >98% accuracy as reported

**Steering Gearbox** 

Relevant Skills: CAD, SOLIDWORKS, ANSYS, Manufacturing, CNC, Manual Mill, Lathe

- Performed stress analyses of various parts with finite element analysis from Ansys and SOLIDWORKS
- Calculated by hand steering efforts and ratios with high level vehicle modeling and computational verification

**Ping Pong Ball Equilibrium Robot** 

Relevant Skills: Mechatronics, Robotics, Controls, C, C++

- **Developing inverse kinematics and PID control** of a **robotic platform** for precise movement correction within ±0.5 mm accuracy.
- Programming firmware for motor control, and microcontrollers in C/C++ to interface with IMUs, encoders, and servo motors.

**SKILLS** 

**Software Language Proficiencies**: Rust, C, C++, ARM, Python, MATLAB, Bash, JS, HTML, CSS, LaTeX **Simulation/Modeling Software**: Fusion360, KiCAD, LTSpice, FLASH, MaGe, SOLIDWORKS, VCarve, Inventor, Ansys