Sivan Syed



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EDUCATION

The University of Texas at Austin (GPA: 3.8/4.0)

May 2027

Bachelor of Science, **Electrical and Computer Engineering**

Bachelor of Science, Physics

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Certificate, German

Minor, Materials Science and Engineering

Relevant Coursework: Circuit Theory, Electromagnetic Engineering, Computational Physics, Fluid Dynamics, Solid-State Electronic Devices, Thermodynamics and Statistical Mechanics, Mechanics of Solids, Embedded Systems, Fundamental Electronic Circuits, Dynamics

EXPERIENCE

Adom Industries Inc. / R&D Design Engineer / Electrical and Robotics Engineering

May 2025 - August 2025

- Designed the mechanical and electrical systems for robotic shuttle drivetrain to pick up and deliver circuit boards autonomously
- Applied FEA methods to analyze stress, strain, and deformation, reducing material usage by 88%

Sandia National Laboratories / R&D Computational Engineer / Pulsed Power Physics

May 2024 - August 2024

- Analyzed fluid RTIs and RMIs to diagnose inaccuracies in ALEGRA simulations
- Built a fast current-pulse generator to synthesize 10k+ waveforms for ML-aided surrogate modeling and UQ pipelines
- Wrote ODE/trajectory solvers to track radial liner implosions and compare ALEGRA predictions and observed instability spectra

FSAE Longhorn Racing / Dynamics + Vehicle Modeling Engineer / Steering Lead, Member

September 2022 – August 2025

- Designed an anti-Ackermann geometry with compliance modeling to tune slip-angle behavior; verified through Python simulation and track feedback loops
- Re-engineered steering column using carbon-fiber layups, cutting system weight ≈68% while maintaining torsional rigidity
- Created a modular gearbox CAD stack (GD&T, CNC and composite fab) with fast-swap adjustability for testing days

Large Enriched Germanium for Neutrinoless Double-beta Decay – Karol Lang / High Energy Particle Detectors November 2022 – Present

- Analyzing scintillating and wavelength shifting fibers to detect the neutrinoless double-beta decay
- Visualized and analyzed positional and intensity variation from Fermilab's Hadron Monitor for preparation to be repaired
- Simulating through a Docker supported codebase, MaGe, photon emissions from scintillating fibers

Projects

Surrogate ML Model for Magneto-Hydrodynamics Radial Trajectory Prediction

Relevant Skills: Neural Network, MATLAB

- Implemented an FNN Machine Learning model to replicate Magneto-Hydrodynamics simulations with >98% fidelity
- Utilized for rapid High Energy Density simulations and iterative design of future tests

Vehicle Dynamics and Modeling

Relevant Skills: Vehicle Modeling, Computational Dynamics, Simulation, Python, C++

- Created a kinematic model of the vehicle to optimize car performance and stability
- Designing compliance model to simulate stress of vehicle parts and implement collision detection through FEM

Weather-Damage Forecasting Relevant Skills: Python, XGBoost, PyTorch, Predictive Analysis, Data Visualization, Data Analysis, LSTM

- Predicted damage with an LSTM model with >98% accuracy to set optimal insurance prices and maximize profits
- Explored numerous time analysis approaches such as ARIMA, LSTMs, and a Transformer model, comparing and optimizing each

Plasma Physics Fusion Reactor Anomaly Detector Relevant Skills: Python, XGBoost, sklearn, PCA, Kaggle, Anomaly Detection, RNN

- Developed and compared PCA + Random Forest anomaly detection models for when MIT's tokamak fusion reactor was unstable
- Simulated with time series analysis models such as RNNs for fusion reactor conditions during runtime

Transformer Model for Pulse Shape Discrimination

Relevant Skills: Transformer Theory, Neural Network

- Developing Pulse Shape Discrimination Methods of radioactive sources and incorporating a Transformer model for optimization
- Cleaning data for input use into the Transformer and achieving >98% accuracy as reported

Steering Gearbox

Relevant Skills: CAD, SOLIDWORKS, ANSYS, Manufacturing, CNC, Manual Mill, Lathe

- Performed stress analyses of various parts with finite element analysis from Ansys and SOLIDWORKS
- Calculated by hand steering efforts and ratios with high level vehicle modeling and computational verification

Ping Pong Ball Equilibrium Robot

Relevant Skills: Mechatronics, Robotics, Controls, C, C++

- **Developing inverse kinematics and PID control** of a **robotic platform** for precise movement correction within ±0.5 mm accuracy.
- Programming firmware for motor control, and microcontrollers in C/C++ to interface with IMUs, encoders, and servo motors.

SKILL

Software Language Proficiencies: Rust, C, C++, ARM, Python, MATLAB, Bash, JS, HTML, CSS, LaTeX **Simulation/Modeling Software**: Fusion360, KiCAD, LTSpice, FLASH, MaGe, SOLIDWORKS, VCarve, Inventor, Ansys