view frames Result Recorded at time: 1734639390.223139 odom Broadcaster: default authority Average rate: $\overline{10.5}$ Buffer length: 2.0 Most recent transform: 81.641 Oldest transform: 79.641 base footprint Broadcaster: default authority Average rate: 10000.0 Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 base link Broadcaster: default authority Average rate: $10\overline{0}00.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 left motor right motor body bottom panel caster circuit panel Broadcaster: default authority Average rate: 15.196 Average rate: 15.196 Average rate: 10000.0 Average rate: 10000.0 Average rate: 10000.0 Average rate: 10000.0 Buffer length: 2.04 Buffer length: 2.04 Buffer length: 0.0 Buffer length: 0.0 Buffer length: 0.0 Buffer length: 0.0 Most recent transform: 81.671 Most recent transform: 81.671 Most recent transform: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Oldest transform: 79.631 Oldest transform: 79.631 Oldest transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 wheel left link wheel_right_link lidar circuit_housing top_panel stand Broadcaster: default authority Broadcaster: default authority Average rate: $10\overline{0}00.0$ Average rate: $10\overline{0}00.0$ Buffer length: 0.0 Buffer length: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 realsense_housing pan_servo Broadcaster: default authority Broadcaster: default authority Broadcaster: default authority Average rate: $10\overline{0}00.0$ Average rate: $10\overline{0}00.0$ Average rate: $10\overline{0}00.0$ Buffer length: 0.0 Buffer length: 0.0 Buffer length: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 left realsense right_realsense pan_tilt_mount Broadcaster: default authority Average rate: $10\overline{0}00.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 tilt servo Broadcaster: default authority Average rate: $10\overline{0}00.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 mount Broadcaster: default authority Broadcaster: default authority Average rate: $10\overline{0}00.0$ Average rate: $10\overline{0}00.0$ Buffer length: 0.0 Buffer length: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 camera housing monitor Broadcaster: default authority Average rate: $10\overline{0}00.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 camera