view frames Result Recorded at time: 1734645777.821538 base footprint Broadcaster: default authority Average rate: $10\overline{0}00.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 base link Broadcaster: default authority Broadcaster: default authority Broadcaster: default authority Broadcaster: default_authority Broadcaster: default authority Broadcaster: default authority Average rate: $10\overline{0}00.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 left motor right motor body bottom panel circuit panel caster Broadcaster: default authority Average rate: 15.837 Average rate: $10\overline{0}00.0$ Average rate: $10\overline{0}00.0$ Average rate: 15.837 Average rate: $10\overline{0}00.0$ Average rate: $10\overline{0}00.0$ Buffer length: 0.884 Buffer length: 0.0 Buffer length: 0.884 Buffer length: 0.0 Buffer length: 0.0 Buffer length: 0.0 Most recent transform: 9.725 Most recent transform: 9.725 Most recent transform: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Oldest transform: 8.841 Oldest transform: 8.841 Oldest transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 wheel left link wheel right link top_panel lidar circuit housing stand Broadcaster: default authority Broadcaster: default authority Average rate: 10000.0 Average rate: 10000.0 Buffer length: 0.0 Buffer length: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 realsense housing pan servo Broadcaster: default authority Broadcaster: default authority Broadcaster: default authority Average rate: $10\overline{0}00.0$ Average rate: $10\overline{0}00.0$ Average rate: $10\overline{0}00.0$ Buffer length: 0.0 Buffer length: 0.0 Buffer length: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 $left_real sense$ $right_real sense$ pan_tilt_mount Broadcaster: default authority Average rate: $10\overline{0}00.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 tilt_servo Broadcaster: default authority Average rate: $10\overline{0}00.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 mount Broadcaster: default authority Broadcaster: default authority Average rate: 10000.0 Average rate: 10000.0 Buffer length: 0.0 Buffer length: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 camera housing monitor Broadcaster: default authority Average rate: $10\overline{0}00.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 camera