# Computational and Statistical Challenges in High Dimensional Statistical Models

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PhD Thesis Defense

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June 12, 2019

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Many open challenging theoretical questions even for *simple high dimensional statistical models!* 

#### Thesis Overview: The Models

#### Two Long-Studied Stylized High Dimensional Models:

(1) High Dimensional Linear Regression Model (HDLR), [Tibshirani '96] Recover vector of coefficients from few noisy linear samples.

Motivation: Fit linear models in high dimensional data.



(2) Planted Clique Model (PC) [Jerrum '92]
Recover planted clique from a large observed network.
Motivation: Community detection in large networks.



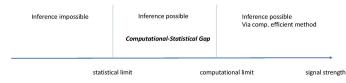
#### Thesis Overview: Contributions

### $\mathsf{HDLR}$ (signal strength = sample size), $\mathsf{PC}$ (signal strength = clique size):



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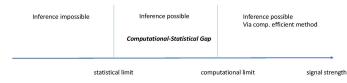
- Compute the exact statistical limit of the HDLR model ("All-to-Nothing Phase Transition")
- Explain computational-statistical gaps of HDLR and PC models, through statistical-physics based methods. ("Overlap Gap Property")
- Improved computational limit for noiseless HDLR model using lattice basis reduction ("One Sample Suffices")

#### Papers:

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#### Outline of the Talk

- (1) Introduction and Thesis Overview
- (2) High Dimensional Linear Regression Model
  - Background
  - Statistical Limit: All-or-Nothing Phenomenon
  - Computational-Statistical Gap and Overlap Gap Property
- (3) Planted Clique Model and Overlap Gap Property

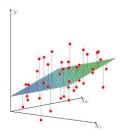
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### High Dimensional Linear Regression

Let (unknown)  $\beta^* \in \mathbb{R}^p$ . p number of features. For **data matrix**  $X \in \mathbb{R}^{n \times p}$ , and **noise**  $W \in \mathbb{R}^n$ , **observe** n noisy linear samples of  $\beta^*$ ,  $Y = X\beta^* + W$ .

**Goal:** Given (Y, X), **recover**  $\beta^*$  with minimum n possible.

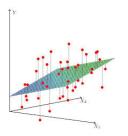


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# High Dimensional Linear Regression

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**Goal:** Given (Y, X), **recover**  $\beta^*$  with minimum n possible.



High-dimensional regime:  $n \ll p, p \to +\infty$ . n < p implies assumptions on  $\beta^*$  are necessary.

*Reason:* even if W = 0,  $Y = X\beta^*$  underdetermined.

### Assumptions on $\beta^*$ and X, W

#### Assumptions on $\beta^*$ :

- (1)  $\beta^*$  is k-sparse: k non-zero coordinates, k/p  $\to$  0, as p  $\to$  + $\infty$ . (A lot of research, e.g. *Compressed Sensing, Genomics, MRI.*)
- (2)  $\beta^*$  is binary valued:  $\beta^* \in \{0, 1\}^p$ . (†)

(†) (non-trivial) simplification of **well-studied**  $\beta_{\min}^* := \min_{\beta_i^* \neq 0} |\beta_i^*| = \Theta(1) > 0$  and support recovery task.

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#### Distributional Assumptions on X, W:

- (1)  $X \in \mathbb{R}^{n \times p}$  has i.i.d.  $\mathcal{N}(0,1)$  entries.
- (2)  $W \in \mathbb{R}^n$  has i.i.d.  $\mathcal{N}(0, \sigma^2)$  entries.
- (†) (non-trivial) simplification of **well-studied**  $\beta_{\min}^* := \min_{\beta_i^* \neq 0} |\beta_i^*| = \Theta(1) > 0$  and support recovery task.

#### The Model

#### Setup

Let  $\beta^* \in \{0,1\}^p$  be a **binary** k-sparse vector,  $k/p \to 0$ , as  $p \to +\infty$ . For

- $X \in \mathbb{R}^{n \times p}$  consisting of i.i.d  $\mathcal{N}(0,1)$  entries
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#### Goal: Statistical and Computational Limit

**Minimum** n so that given (Y, X),  $\beta^*$  is (efficiently) recoverable with probability tending to 1 as n, k, p  $\to +\infty$  (w.h.p.).



### Computational Results ([Wainwright '09],[Fletcher et al '11])

Set  $n_{alg} = 2k \log p$ . Assume  $SNR = \frac{k}{\sigma^2} \to +\infty$ . If

$$\mathsf{n} > (1+\epsilon)\mathsf{n}_{\mathsf{alg}}$$

LASSO (convex relaxation) and OMP (greedy algorithm) succeed w.h.p.

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#### **Statistical Results**

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# Pictorial Representation



Figure: Computational-Statistical Gap

### Pictorial Representation



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#### Contributions

- (1)  $n^* = 2k \log \frac{p}{k} / \log \left( \frac{k}{\sigma^2} + 1 \right)$  is the **exact statistical limit** (All-or-Nothing Phase Transition).
- (2)  $n_{alg} = 2k \log p$  is the **phase transition point** for (landscape) hardness (Overlap Gap Property Phase Transition).

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# Maximum Likelihood Estimator (MLE)

 $Y = X\beta^* + W$  with W iid  $N(0, \sigma^2)$  entries.

#### The MLE

 $\hat{eta}_{\mathsf{MLE}}$  is the optimal solution of least-squares

(LS): 
$$\min_{\beta \in \{0,1\}^p, \|\beta\|_0 = k} \|Y - X\beta\|_2$$

[Rad '11]: success with Cn\* samples.

### All or Nothing Phenomenon- Result

#### **Definition**

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# Theorem ("All or Nothing Phase Transition" (GZ '17), (RXZ '19))

Let  $\epsilon > 0$  be arbitrary. Assume  $k \ll p$  and  $k/\sigma^2 \ge C(\epsilon) > 0$ ,

• If  $n > (1 + \epsilon) n^*$ , then

$$\frac{1}{\mathsf{k}}\mathsf{overlap}\left(\hat{\beta}_{\mathsf{MLE}}\right) \to \mathsf{1}, \textit{whp, as } \mathsf{n}, \mathsf{p}, \mathsf{k} \to +\infty.$$

• If  $n < (1 - \epsilon) n^*$ , and  $k \ll \sqrt{p}$ , then  $\forall \hat{\beta} = \hat{\beta} (Y, X)$ 

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#### An "All or Nothing" phase transition!

- With n ≥ (1 + ε)n\*,
   MLE recovers all but o(1)-fraction of the support.
- With n ≤ (1 − ε)n\*,
   every estimator recovers at most o(1)-fraction of the support.

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, as  $\mathsf{p} \to +\infty$ .

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"Impossibility of Testing" implies "Impossibility of Estimation".

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• Step 2:

"Impossibility of Testing" implies "Impossibility of Estimation". We show that for any estimator  $\hat{\beta} = \hat{\beta}(Y, X)$ :

overlap 
$$(\hat{\beta})/k \le (1 + \sigma^2/k) D_{\mathsf{KL}}(\mathsf{P}||\mathsf{Q})$$
.

### Summary for n\* contribution



#### Sharp Information-Theoretic Limit n\*

 $(1+\epsilon)$ n\* samples MLE (asymptotically) succeeds.

 $(1-\epsilon)n^*$  samples all estimators (asymptotically) strongly fail.

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## Computational-Statistical Gap



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## Computational-Statistical Gap



### Contribution through Landscape Analysis

 $n_{alg}$  is a **phase transition point** for certain Overlap Gap Property (OGP) on the space of binary k-sparse vectors (origin in *spin glass theory*).

Conjecture computational hardness!

Computational gaps appear frequently in random environments

- (1) randoms CSPs, such as random-k-SAT (e.g. [MMZ '05], [ACORT '11])
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## (Vague) Strategy of Studying the Geometry

Study **realizable overlap sizes** between "near-optimal" solutions.

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Overlap Gap Property, Shattering, Clustering, Free Energy Wells etc

## The Overlap Gap Property (OGP) for Linear Regression

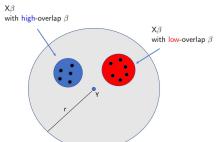
"Near-optimal solutions"  $\{\beta \in \{0,1\}^p : \|\beta\|_0 = \mathsf{k}, \text{ "small" } \|\mathsf{Y} - \mathsf{X}\beta\|_2\}.$ 

## The Overlap Gap Property (OGP) for Linear Regression

"Near-optimal solutions"  $\{\beta \in \{0,1\}^p : \|\beta\|_0 = k$ , "small"  $\|Y - X\beta\|_2\}$ . *Idea:* Study overlaps between  $\beta$  and  $\beta^*$ . overlap $(\beta) = |\mathsf{Support}(\beta) \cap \mathsf{Support}(\beta^*)|$ .

## The OGP (informally)

The set of  $\beta'$ s with "small"  $\|Y - X\beta\|_2$  partitions in one group where  $\beta$  have **low** overlap with the ground truth  $\beta^*$  and the other group where  $\beta$  have **high** overlap with the ground truth  $\beta^*$ .



# The Overlap Gap Property for Linear Regression-definition

For 
$$r > 0$$
, set  $S_r := \{ \beta \in \{0, 1\}^p : \|\beta\|_0 = k, n^{-\frac{1}{2}} \|Y - X\beta\|_2 < r \}.$ 

## Definition (The Overlap Gap Property)

The linear regression problem satisfies OGP if there exists r>0 and  $0<\zeta_1<\zeta_2<1$  such that

(a) For every  $\beta \in S_r$ ,

$$\frac{1}{\mathsf{k}}\mathsf{overlap}\left(\beta\right)<\zeta_1 \text{ or } \frac{1}{\mathsf{k}}\mathsf{overlap}\left(\beta\right)>\zeta_2.$$

(b) Both the sets

$$\mathsf{S_r} \cap \{\beta: \frac{1}{\mathsf{k}} \mathsf{overlap}\left(\beta\right) < \zeta_1\} \text{ and } \mathsf{S_r} \cap \{\beta: \frac{1}{\mathsf{k}} \mathsf{overlap}\left(\beta\right) > \zeta_2\}$$

are non-empty.

# OGP Phase Transition at $\Theta(n_{alg})$

## Theorem (GZ '17a), (GZ '17b)

Suppose  $k \le exp(\sqrt{\log p})$ . There exists C > 1 > c > 0 such that,

- If  $n^* < n < cn_{alg}$  then w.h.p. OGP holds.
- If n > Cn<sub>alg</sub> then w.h.p. OGP does not hold.

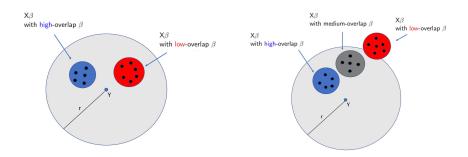


Figure: n < cn<sub>alg</sub>

Figure:  $n > Cn_{alg}$ 

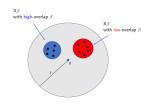
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# OGP coincides with the failure of **convex relaxation** and **compressed sensing** methods!

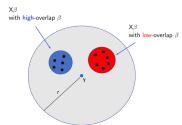


 $\begin{array}{c} \text{XJ} \\ \text{with medium-overlap } \beta \\ \text{With high-overlap } \beta \\ \text{with high-overlap } \beta \end{array}$ 

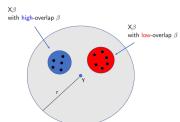
Figure:  $n^* < n < cn_{alg}$ 

Figure:  $n > Cn_{alg}$ 

Local Step: 
$$\beta \to \beta'$$
 if  $d_H(\beta, \beta') = 2$ . E.g.  $\begin{bmatrix} * \\ 0 \\ 1 \\ * \end{bmatrix} \to \begin{bmatrix} * \\ 1 \\ 0 \\ * \end{bmatrix}$ 



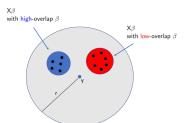
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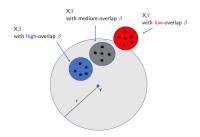
## Corollary: Local Search Barrier [GZ'17a]

Under OGP, there are **low-overlap local minima** in (LS). If  $n < cn_{alg}$ , greedy local-search algorithm **fails** (worst-case) w.h.p.



## Theorem (GZ '17b)

If n > Cn<sub>alg</sub>, the **only local minimum** in (LS) is  $\beta^*$  whp and greedy local search algorithm **succeeds** in  $O(k/\sigma^2)$  iterations whp.



## Summary of Contribution

	Lit: Impossible to exactly recover	Lit: Possible but hard??	Lit: Possible and Easy (LASSO, OMP)
[RXZ1	(19): All estimators strongly fail with n<(1-ε)n*	[GZ17a]: MLE succeeds with n>(1+ε)n*	[GZ17b]: OGP disappears and
		[GZ17a]: OGP appears [GZ17b]: LS has low overlap local min	greedy local search works [GZ17b]: LS has only the trivial local min
	0	$(n^*)$ $\Theta(n^*)$	n

### Sharp Information-Theoretic Limit n\*

 $(1+\epsilon)$ n\* samples MLE (asymptotically) succeeds.

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## OGP Phase Transition at nalg

 $n < cn_{alg}$  OGP holds and  $n > Cn_{alg}$  OGP does not hold.

Computational Hardness conjectured!



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## The Planted Clique Model

## The Planted Clique Model [Jerrum '92]

#### **Graph Generating Assumptions:**

- Stage 1: G<sub>0</sub> is an Erdos-Renyi G(n, 1/2):
   n-vertex undirected graph, each edge appears w.p. 1/2.
- Stage 2: k out of the n vertices of  $\mathcal{G}_0$  are chosen u.a.r. to form a k-vertex clique,  $\mathcal{PC}$ . Call  $\mathcal{G}$  the final graph.

**Goal:** Recover  $\mathcal{PC}$  from observing  $\mathcal{G}$ .

**Question:** For how small  $k = k_n$  can we recover?

Statistical limit + Computational limit.

$$n=7, k=3, \ \mathcal{G}_0 \ (left) \ and \ \mathcal{G} \ (right)$$
 :





## The Planted Clique Model-Literature



#### Literature:

- Statistical Limit (unique k-clique):  $k = (2 + \epsilon) \log_2 n$ , for any  $\epsilon > 0$ .
- (Apparent) Computational Limit:  $k = c\sqrt{n}$ , for any c > 0. [AKS'98],[FR'10],[DM'13],[DGGP'14]





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**Long-studied comp-stats gap** [BR'13], [BHK+'16], [BBH'18] *Question: Is there an OGP phase transition around*  $k = \sqrt{n}$ ?





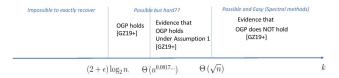
## The Overlap Gap Property for Planted Clique: Results



• Focus on subgraphs of  $\mathcal G$  of fixed vertex size ("k-sparse binary  $\beta$ ") with many edges, dense, ("small error  $\|\mathbf Y - \mathbf X\beta\|_2$ ") and study their overlap with  $\mathcal {PC}$  ("overlap with  $\beta^*$ ").

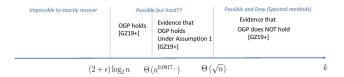
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- Proof OGP appears if  $k \le n^{0.0917}$ .

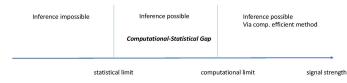
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- Proof OGP appears if  $k \le n^{0.0917}$ .
- Assumption 1: Concentration of the value of k-densest subgraph problem of  $G(n, \frac{1}{2})$ . Known for  $k = \Theta(\log n)$  [BBSV'18], proven for  $k \le n^{0.0917..}$  [GZ'19], conjectured for all  $k = o(\sqrt{n})$ .

### Thesis Overview: Contributions

HDLR (signal strength = sample size), PC (signal strength = clique size):



#### Under assumptions,

- Compute the exact statistical limit of the HDLR model ("All-to-Nothing Phase Transition")
- Explain computational-statistical gaps of HDLR and PC models, through statistical-physics based methods. ("Overlap Gap Property")
- Improved computational limit for noiseless HDLR model using lattice basis reduction ("One Sample Suffices")

#### Papers:

```
(Gamarnik, Z. COLT '17, AOS (major rev.) '18+)
(Gamarnik, Z. AOS (major rev.) '18+), (Gamarnik, Z. NeurIPS '18)
(Reeves, Xu, Z. COLT '19), (Gamarnik, Z. '19+)
```