AI Planning Exercise Sheet 8

# AI Planning Exercise Sheet 8

Date: December 19, 2014

Students: Axel Perschmann, Tarek Saier

## Exercise 8.1

General idea: heuristic values are completely dependent on the chosen projection  $\pi_P$ . Example:

The heuristic value for the abstraction induced by  $\pi_{\{\text{truck A, truck B}\}}$  of I is 0:

 $h^{\{\text{truck A, truck B}\}}(LRR) = 0$ , as opposed to:

 $h^{\text{\{package, truck A\}}}(LRR) = 2$ 

 $h^{\{\text{package, truck B}\}}(LRR) = 2$ 

The above illustrates that it is important to choose the pattern wisely. Prune variables that are less significant, keep those that are most relevant for the goal formula.

### Exercise 8.2

Definitions/Notes:

- (1)  $\Pi = \langle V, I, O, \gamma \rangle$  (in FDR) is SAS<sup>+</sup> iff
  - $\forall o \in O$  have no conditional effects
  - $\forall \chi$  of  $o \in O$  and  $\gamma$  are conjunctions of atoms
- (2)  $\mathscr{T}(\Pi) = \langle S, L, T, s_0, S_{\star} \rangle$  is the induced transition system of  $\Pi = \langle V, I, O, \gamma \rangle$  where
  - S is the set of states over V
  - -L=O
  - $-T = \{ \langle s, o, t \rangle \in S \times L \times S | app_o(s) = t \}$
  - $s_0 = I$
  - $-S_{\star} = \{ s \in S | s \models \gamma \}$
- (3) For  $\mathscr{T} = \langle S, L, T, s_0, S_{\star} \rangle$  and  $\alpha : S \to S'$  (a surjective function),  $\mathscr{T}^{\alpha} = \langle S', L, T', s'_0, S'_{\star} \rangle$  is the abstraction of  $\mathscr{T}$  induced by  $\alpha$  where  $-S' = \{\alpha(s) | s \in S\}$   $-T = \{\langle \alpha(s), \ell, \alpha(t) \rangle | \langle s, \ell, t \rangle \in T\}$   $-s'_0 = \alpha(s_0)$   $-S'_{\star} = \{\alpha(s) | s \in S_{\star}\}$
- (4)  $P \subseteq V$  is a pattern,  $\Pi|_P$  denotes  $\Pi$  restricted to the variables in P

AI Planning Exercise Sheet 8

• (5)  $\pi_P$  is the projection  $S \to S'$  for P,  $\pi_P(s) := s|_P$ ,  $\mathscr{T}^{\pi_P}$  denotes the transition system induced by  $\pi_P$ 

- (6) two transition systems  $\mathscr{T}$  and  $\mathscr{T}'$  are graph-equivalent ( $\mathscr{T} \stackrel{G}{\sim} \mathscr{T}'$ ) if there exists a bijective function  $\phi: S \to S'$  such that
  - $-\phi(s_0) = s'_0$
  - $s \in S_{\star}$  iff  $\phi(s) \in S'_{\star}$
  - $\langle s, \ell, t \rangle \in T$  for some  $\ell \in L$  iff  $\langle \phi(s), \ell', \phi(t) \rangle \in T'$  for some  $\ell' \in L'$
- (a) to show:  $\mathscr{T}(\Pi|_P) \stackrel{G}{\sim} \mathscr{T}(\Pi)^{\pi_P}$  if  $\Pi$ 
  - is an SAS<sup>+</sup> planning task
  - is not trivially unsolvable
  - has no trivially inapplicable operators

In terms of the definitions/notes above: (6) holds between:

- -(4), then (2)
- and
- (2), then (5) the latter being a special case of (3)

## $\mathscr{T}(\Pi|_P)$ :

The difference to  $\mathscr{T}(\Pi)$  in this case is V of  $\Pi|_P$ , which affects S directly and T and  $S_{\star}$  indirectly. S will not include states over  $V \setminus P$ . T and  $S_{\star}$  will be restricted accordingly.

#### $\mathscr{T}(\Pi)^{\pi_P}$ :

The difference to  $\mathscr{T}(\Pi)$  in this case is that after getting  $\mathscr{T}$  the latter is abstracted by means of  $\pi_P$ . This means for all states  $s' \in S'$  of  $\mathscr{T}^{\pi_P}$ ,  $s \in S$  of  $\mathscr{T}$ :  $s' = s|_P$ . In other words, information about variables  $v \notin P$  will be discarded in all s'. Again, T and  $S_{\star}$  will be restricted accordingly.

In both cases all information about variables not in P is discarded. Performing this step by means of (4) before (2) or by means of (5) after (2) does not violate (6).

- (b) Replacing effect conditions in  $o \in O$  with  $\top$  causes problems with the third (see
- (6) above) condition of graph-equivalence that deals with transitions.