AI Planning Exercise Sheet 7

AI Planning Exercise Sheet 7

Date: December 12, 2014

Students: Axel Perschmann, Tarek Saier

Exercise 7.1

(a) $\Pi' = \{V, I, O, \gamma\}$ with

- $V = \{above-a, above-b, above-c, below-a, below-b, below-c\}$ $\mathcal{D}_{above-\Upsilon} = \{A, B, C, n\} \setminus \{\Upsilon\}$ $\mathcal{D}_{below-\Upsilon} = \{A, B, C, t\} \setminus \{\Upsilon\}$ where $\Upsilon \in \{A, B, C\}$
- I(a) = 1 for $a \in \{below b = t, above b = A, above a = n, below c = t, above c = n\}$ I(a) = 0 else
- $O = \{move-X-Y-Z, move-X-Table-Z, move-X-Y-Table\}$ $move-X-Y-Z = \langle (below-X=Y) \land (above-X=n) \land (above-Z=n),$ $(above-Y:=n) \land (below-X:=Z) \rangle$ $move-X-Table-Z = \langle (below-X=t) \land (above-X=n) \land (above-Z=n),$ $(below-X:=Z) \rangle$ $move-X-Y-Table = \langle (below-X=Y) \land (above-X=n),$ $(above-Y:=n) \land (below-X:=t) \rangle$ for pair-wise distinct $X, Y, Z \in \{A, B, C\}$
- $\bullet \ \gamma = (above{-}c = B) \land (above{-}a = C)$

And the addition¹ that every $above|below[:]=\Upsilon$ with $\Upsilon \in \{A, B, C\}$ implies its counterpart (e.g. above-A[:]=B also tests/sets below-B[:]=A).

(b)
$$\Pi'' = \Pi$$

The induced propositional planning task Π'' is the (regular) planning task $\Pi'' = \langle A', I', O', \gamma \rangle$, where

 $\begin{array}{l} \bullet \ A' = \{(above-a,B), (abova-a,C), (above-a,n), (above-b,A), (above-b,C), (above-b,n), (above-c,A), (above-c,B), (above-c,n), (below-a,B), (below-a,C), (below-a,t), (below-b,A), (below-b,C), (below-b,t), (below-c,A), (below-c,B), (below-c,t)\} \end{array}$

¹to make this a bit less verbose and better readable

AI Planning Exercise Sheet 7

AI Planning Exercise Sheet 7

Exercise 7.2

(a) Since both h_1 and h_2 include the blank tile, $h_1 + h_2$ is not admissible. Proof by counterexample:

(b) Basic approach: Goal awareness: for every goal state s_{γ} of the full puzzle, $h_3(s_{\gamma}) = 0$ and $h_4(s_{\gamma}) = 0$. Consistency: since a tile is accounted for in at most one of $\{h_3, h_4\}$, each step necessary to reach the goal counts as either 1 or 0 in $h_3 + h_4$.