AI Planning Exercise Sheet 11

# AI Planning Exercise Sheet 11

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## Exercise 11.1

blubb

## Exercise 11.2

#### **Preliminaries**

For every variable  $v \in prevars(o)$  (Only for  $o \in app(s)$ ?) we need to compute the Domain transition graph:

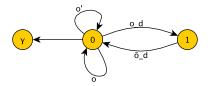


Figure 1: DTG(a)

All given operators are "Active Operators" (see lecture 13, slide 14), because of

- For every variable  $v \in prevars(o)$  there is a path in DTG(v) from s(v) to pre(o)(v).
- If v is goal-related, then there is also a path from pre(o)(v) to the goal value  $\gamma(v)$ .

## Disjunctive Action Landmark:

 $L = \{o, o'\}$  in initial state

## Strong Stubborn Sets

- 1. Include o (or o') in  $T_S$  as disjunctive action landmark.
- 2. Include  $o_d$  in  $T_S$  since it interferes with o ( $o_d$  disables o)
- 3. Include o' (or o) in  $T_S$  since it interferes with  $o_d$  ( $o_d$  disables o')
- 4. Include  $\overline{o_d}$  and  $o_i$  in  $T_S$  since both conflict with  $o_d$

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5. Include  $\overline{o_i}$  in  $T_S$  since it conflicts with  $o_i$ 

$$T_S = \{o, o', o_d, \overline{o_d}, o_i, \overline{o_i}\}$$

All six operators included in  $T_S$ , no pruning.

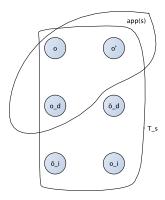


Figure 2: strongStubborn

## Weak Stubborn Sets

- 1. Include o (or o') in  $T_S$  as disjunctive action landmark.
- 2. there are no operators in s that have conflicting effects with o or that are disabled by o

$$T_S = \{o\}$$

Nice amount of pruning.

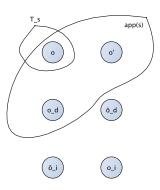


Figure 3: weakStubborn

Conclusion: Weak stubborn sets admit exponentially more pruning than strong stubborn sets.