# AI Planning Exercise Sheet 11

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# Exercise 11.1

(a)

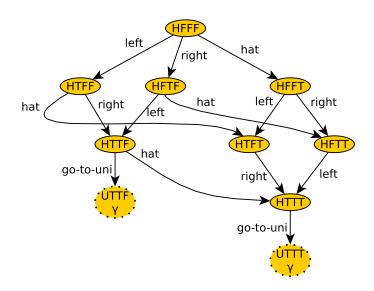


Figure 1: breadth-first search graph (with dublicate detection)

(b)

#### First Node Expansion

Possible initial disjunctive action landmarks are {wear-left-shoe}, {wear-right-shoe}, {go-to-university}. The last of those is not yet applicable. The tie break between the remaining two is decided in favor of  $L = \{\text{wear-left-shoe}\}$ .

## Compute $T_S$ :

- 1. Include wear-left-shoe in  $T_S$  as disjunctive action landmark
- 2. no other applicable operators interfere with wear-left-shoe
- 3. for go-to-university, which is not applicable yet  $T_S$  contains a necessary enabling set.

 $T_S = \{\text{wear-left-shoe}\}$ 

## Second Node Expansion

disjunctive action landmark:  $L = \{\text{wear-right-shoe}\}\ \text{Compute}\ T_S$ :

- 1. Include wear-right-shoe in  $T_S$  as disjunctive action landmark
- 2. no other applicable operators interfere with wear-right-shoe
- 3. for go-to-university, which is not applicable yet  $T_S$  contains a necessary enabling set.

 $T_S = \{\text{wear-right-shoe}\}$ 

#### Third Node Expansion

disjunctive action landmark:  $L = \{\text{go-to-university}\}\$ Compute  $T_S$ :

- 1. Include go-to-university in  $T_S$  as disjunctive action landmark
- 2. Include hat in  $T_S$  since it interferes with go-to-university (go-to-university disables hat)

 $T_S = \{\text{go-to-university, hat}\}\$ 

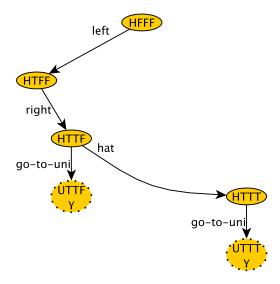


Figure 2: breadth-first search graph using strong stubborn set pruning

## Conclusion

We save 14 - 5 = 9 node expansions. The solution length in both cases is 3.

## Exercise 11.2

## **Preliminaries**

For every variable  $v \in prevars(o)$  (Only for  $o \in app(s)$ ?) we need to compute the Domain transition graph:

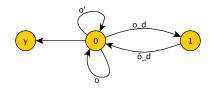


Figure 3: DTG(a)

All given operators are "Active Operators" (see lecture 13, slide 14), because of

- For every variable  $v \in prevars(o)$  there is a path in DTG(v) from s(v) to pre(o)(v).
- If v is goal-related, then there is also a path from pre(o)(v) to the goal value  $\gamma(v)$ .

# Disjunctive Action Landmark:

 $L = \{o, o'\}$  in initial state

## Strong Stubborn Sets

- 1. Include o (or o') in  $T_S$  as disjunctive action landmark.
- 2. Include  $o_d$  in  $T_S$  since it interferes with o ( $o_d$  disables o)
- 3. Include o' (or o) in  $T_S$  since it interferes with  $o_d$  ( $o_d$  disables o')
- 4. Include  $\overline{o_d}$  and  $o_i$  in  $T_S$  since both conflict with  $o_d$
- 5. Include  $\overline{o_i}$  in  $T_S$  since it conflicts with  $o_i$

$$T_S = \{o, o', o_d, \overline{o_d}, o_i, \overline{o_i}\}\$$

All six operators included in  $T_S$ , no pruning.

#### Weak Stubborn Sets

- 1. Include o (or o') in  $T_S$  as disjunctive action landmark.
- 2. there are no operators in s that have conflicting effects with o or that are disabled by o

$$T_S = \{o\}$$

Nice amount of pruning.

#### Conclusion

Weak stubborn sets admit exponentially more pruning than strong stubborn sets.

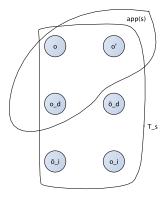


Figure 4: strongStubborn

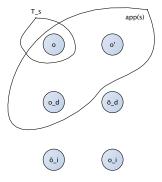


Figure 5: weakStubborn