

# AI Planning

## Exercise Sheet 7

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 Students: Axel Perschmann, Tarek Saier

### Exercise 7.1

(a)  $\Pi' = \{V, I, O, \gamma\}$  with

- $V = \{above-a, above-b, above-c, below-a, below-b, below-c\}$   
 $\mathcal{D}_{above-\Upsilon} = \{A, B, C, n\} \setminus \{\Upsilon\}$   
 $\mathcal{D}_{below-\Upsilon} = \{A, B, C, t\} \setminus \{\Upsilon\}$   
 where  $\Upsilon \in \{A, B, C\}$
- $I(a) = 1$  for  $a \in \{below-b = t, above-b = A, above-a = n, below-c = t, above-c = n\}$   
 $I(a) = 0$  else
- $O = \{move-X-Y-Z, move-X-Table-Z, move-X-Y-Table\}$   
 $move-X-Y-Z = \langle (below-X = Y) \wedge (above-X = n) \wedge (above-Z = n), (above-Y := n) \wedge (below-X := Z) \rangle$   
 $move-X-Table-Z = \langle (below-X = t) \wedge (above-X = n) \wedge (above-Z = n), (below-X := Z) \rangle$   
 $move-X-Y-Table = \langle (below-X = Y) \wedge (above-X = n), (above-Y := n) \wedge (below-X := t) \rangle$   
 for pair-wise distinct  $X, Y, Z \in \{A, B, C\}$
- $\gamma = (above-c = B) \wedge (above-a = C)$

And the addition<sup>1</sup> that every  $above|below[:]=\Upsilon$  with  $\Upsilon \in \{A, B, C\}$  implies its counterpart (e.g.  $above-A[:]=B$  also tests/sets  $below-B[:]=A$ ).

(b)  $\Pi'' = \Pi$

(c)

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<sup>1</sup>to make this a bit less verbose and better readable

## Exercise 7.2

(a) Since both  $h_1$  and  $h_2$  include the blank tile,  $h_1 + h_2$  is not admissible.

Proof by counterexample:

$n = 1, m = 2$

	$t_0$	$t_1$	$t_2$	$t_3$		$t_0$	—	—	—		—	$t_1$	$t_2$	$t_3$
$s =$	$t_4$	$t_5$	$t_6$	$t_7$	$\alpha_2$ -view :	—	—	—	—	$\alpha_1$ -view :	$t_4$	$t_5$	$t_6$	$t_7$
	$t_8$	$t_9$	$t_{10}$	$t_{11}$		—	—	—	—		$t_8$	$t_9$	$t_{10}$	$t_{11}$
	$t_{12}$	$t_{13}$	$b$	$t_{14}$		—	—	$b$	—		$t_{12}$	$t_{13}$	$b$	$t_{14}$

$$h^*(s) = 1$$

$$h_1(s) + h_2(s) = 1 + 1 = 2$$

$2 > 1$ , therefore  $h_1 + h_2$  is not admissible.

(b) Basic approach: Goal awareness: for every goal state  $s_\gamma$  of the full puzzle,  $h_3(s_\gamma) = 0$  and  $h_4(s_\gamma) = 0$ . Consistency: since a tile is accounted for in at most one of  $\{h_3, h_4\}$ , each step necessary to reach the goal counts as either 1 or 0 in  $h_3 + h_4$ .