AI Planning Exercise Sheet 5

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Exercise 5.1

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Proof by induction over the structure of \chi.
Base case \chi = \top: then s' \models \top.
Base case \chi = \bot: then s \not\models \bot.
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Base case $\chi = a \in A$: assume $s \models a$ and $on(s) \subseteq on(s')$. Wich $a \in on(s)$ we get $a \in on(s')$, hence $s' \models a$.

Inductive case
$$\chi = \chi_1 \wedge \chi_2$$

 $s \models \chi \iff s \models \chi_1 \wedge \chi_2$
 $\iff s \models \chi_1 \text{ and } s \models \chi_2$
 $\implies s' \models \chi_1 \text{ and } s' \models \chi_2$
 $\iff s' \models \chi$ and χ_2
 $\iff s' \models \chi$
Inductive case $\chi = \chi_1 \vee \chi_2$ (Analogous to previous case)
 $s \models \chi \iff s \models \chi_1 \vee \chi_2$
 $\iff s \models \chi_1 \text{ or } s \models \chi_2$
 $\implies s' \models \chi_1 \text{ or } s' \models \chi_2$
 $\iff s' \models \chi_1 \text{ or } \chi_2$
 $\iff s' \models \chi_1 \text{ or } \chi_2$
 $\iff s' \models \chi$

Exercise 5.2

```
(a) \Pi^{+} = \langle A, I, O, \gamma \rangle with A, I, \gamma unchanged and O = \{eatCake^{+}, bakeCake^{+}\} eatCake^{+} = \langle haveCake, \top \wedge haveNoCake \wedge eatenCake \rangle bakeCake^{+} = \langle haveNoCake, haveCake \wedge \top \rangle (b) \pi = bakeCake, eatCake \pi in \Pi results in \{haveCake \mapsto 0, eatenCake \mapsto 1, haveNoCake \mapsto 1\} \pi^{+} in \Pi^{+} results in \{haveCake \mapsto 1, eatenCake \mapsto 1, haveNoCake \mapsto 1\}
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Exercise 5.3

Considerations:

 $h^{Manhattan}(s)$ sums up distances of tiles to their target position.

 $h^+(s)$ considers the relaxed planning task with relaxed operators. This means when a tile is moved it moves to the new position but also "stays" at the old (at() for the old position is not negated). χ of each o^+ should be the same in Π and Π^+ though.

(a)

(b)
$$t_{0} \quad t_{1} \quad t_{2} \quad t_{3}$$

$$s = \begin{cases} t_{4} & t_{5} & t_{6} & t_{7} \\ t_{8} & t_{9} & t_{10} & t_{11} \\ t_{12} & t_{13} & t_{14} & - \end{cases}$$

$$h^{Manhattan}(s) = h^{+}(s) =$$