AI Planning

Exercise Sheet 2

Date: 06.11.2014

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Exercise 2.1

(a) Transform the operator

```
original \langle \neg e \lor f, (a \rhd (b \rhd c)) \land (\neg d \rhd c) \land (\neg (\neg c \land \neg a) \rhd (d \land \neg d)) \land (d \rhd \neg e) \rangle (7) \langle \neg e \lor f, ((a \land b) \rhd c) \land (\neg d \rhd c) \land (\neg (\neg c \land \neg a) \rhd (d \land \neg d)) \land (d \rhd \neg e) \rangle (9) \langle \neg e \lor f, (((a \land b) \lor \neg d) \rhd c) \land (\neg (\neg c \land \neg a) \rhd (d \land \neg d)) \land (d \rhd \neg e) \rangle (8) \langle \neg e \lor f, (((a \land b) \lor \neg d) \rhd c) \land (\neg (\neg c \land \neg a) \rhd d) \land (\neg (\neg c \land \neg a) \rhd \neg e) \land (d \rhd \neg e) \rangle (9) \langle \neg e \lor f, (((a \land b) \lor \neg d) \rhd c) \land (\neg (\neg c \land \neg a) \rhd d) \land ((\neg (\neg c \land \neg a) \lor d) \rhd \neg e) \rangle 2x deMorgan \langle \neg e \lor f, (((a \land b) \lor \neg d) \rhd c) \land ((c \lor a) \rhd d) \land ((c \lor a \lor d) \rhd \neg e) \rangle
```

(b) Transform the ENF operator

```
original (\neg e \lor f, (((a \land b) \lor \neg d) \triangleright c) \land ((c \lor a) \triangleright d) \land ((c \lor a \lor d) \triangleright \neg e))
```

Exercise 2.2

(a)

Listing 1: set cover problem as a PDDL domain

(b)

Listing 2: set cover instance as a PDDL problem

(c)

Listing 3: solving set cover instance with fast-downward

```
$ ./fast-downward.py scprob.pddl --search "astar(blind())"
[...]
select-set s4 (1)
select-set s5 (1)
Plan length: 2 step(s).
Plan cost: 2
Initial state h value: 1.
Expanded 6 state(s).
Reopened O state(s).
Evaluated 16 state(s).
Evaluations: 16
Generated 21 state(s).
Dead ends: 0 state(s).
Expanded until last jump: 1 state(s).
Reopened until last jump: 0 state(s).
Evaluated until last jump: 6 state(s).
Generated until last jump: 5 state(s).
Number of registered states: 16
Search time: Os
Total time: Os
Solution found.
Peak memory: 2924 KB
$ cat sas_plan
(select-set s4)
(select-set s5)
```

; cost = 2 (unit cost)