3 Control Transfer Instructions and Time Delay Generation

- There are 5 types of instructions
 - One of which is MOV, MOVC, MOVX
- No one uses JMP.
 - Because it's a bit difficult to work with as apposed to a long jump.
- NOP is literally do nothing
 - It's to kill time.
- Let's multiply 5×5

JZ Multiply By 5

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ORG 0
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MOV RO, #5

MOV R1, #0

MOV A, #0

LOOP: MOV A, R1

ADD A, #5

MOV R1, A

MOV A, RO

DEC A

JNZ A, LOOP

END

DJNZ Multiply By 5

ORG 0

MOV RO, #5 MOV A, #0

LOOP: ADD A, #5

DJNZ RO, Loop

END

Nested Loop

Load A with 5, add 10 for 300 times.

ORG 0

MOV A, #5

MOV RO, #3

LOOP2: MOV R1, #100 ; Runs 3 times LOOP1: ADD A, #10 ; Runs 100 times

3x100 = 300 times

DJNZ R1, LOOP1 DJNS R0, LOOP2

- 1 MC = $1.0852\mu s$ **KNOW THIS!**
- For slides, the values (in order) of the delay is

Machine Cycle	Times
1	1
1	∞
2	∞
1	∞
2	∞
1	∞
2	$200 \times \infty$
2	$1 \times \infty$

Delay Example

DELAY: MOV RO, #251

DL1: MOV R1, #182 DL2: DJNZ R1, DL2

DJNZ RO, DL1

RET