

# Chapter 13: Functions of Several Variables

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## 13.1 Planes and Surfaces

### Plane in $\mathbb{R}^3$

Given a fixed point  $P_0$  and a nonzero **normal vector**  $\mathbf{n}$ , the set of points  $P$  in  $\mathbb{R}^3$  for which  $\vec{P_0P}$  is orthogonal to  $\mathbf{n}$  is called a **plane**.

### General Equation of a Plane in $\mathbb{R}^3$

The plane passing through the point  $P_0(x_0, y_0, z_0)$  with a nonzero normal vector  $\mathbf{n} = \langle a, b, c \rangle$  is described by the equation

$$a(x - x_0) + b(y - y_0) + c(z - z_0) = 0 \quad \text{or} \quad ax + by + cz = d \quad (1)$$

where  $d = ax_0 + by_0 + cz_0$ .

### Parallel and Orthogonal Planes

Two distinct planes are **parallel** if their respective normal vectors are parallel (that is, the normal vectors are scalar multiples of each other). Two planes are **orthogonal** if their respective normal vectors are orthogonal (that is, the dot product of the normal vectors is zero).

### Cylinder

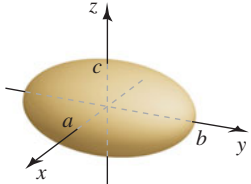
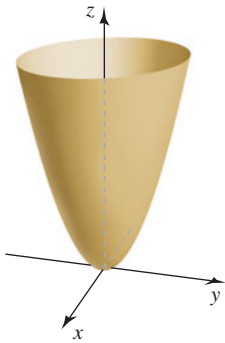
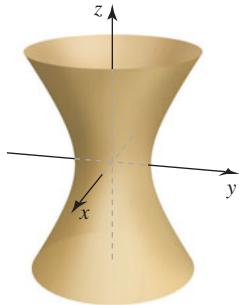
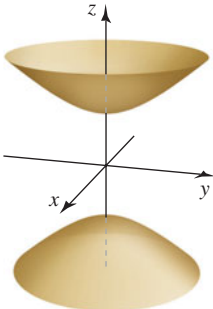
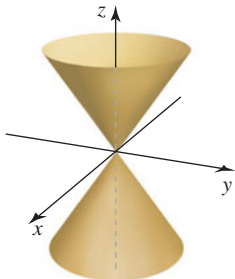
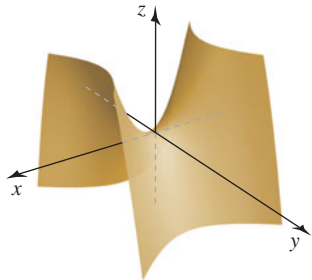
Given a curve  $C$  in a plane  $P$  and a line  $\ell$  not in  $P$ , a **cylinder** is the surface consisting of all lines parallel to  $\ell$  that pass through  $C$ .

### Trace

A **trace** of a surface is the set of points at which the surface intersects a plane that is parallel to one of the coordinate planes. The trace in the coordinate planes are called **xy-trace**, the **xz-trace**, and the **yz-trace**.

## Quadratic Surfaces

Name	Standard Equation	Features
Ellipsoid	$\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1$	All traces are ellipses.
Elliptic paraboloid	$z = \frac{x^2}{a^2} + \frac{y^2}{b^2}$	Traces with $z = z_0 > 0$ are ellipses. Traces with $x = x_0$ or $y = y_0$ are parabolas.
Hyperboloid of one sheet	$\frac{x^2}{a^2} + \frac{y^2}{b^2} - \frac{z^2}{c^2} = 1$	Traces with $z = z_0$ are ellipses for all $z_0$ . Traces with $x = x_0$ or $y = y_0$ are hyperbolas.
Hyperboloid of two sheets	$-\frac{x^2}{a^2} - \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1$	Traces with $z = z_0$ with $ z_0  >  c $ are ellipses. Traces with $x = x_0$ and $y = y_0$ are hyperbolas.
Elliptic cone	$-\frac{x^2}{a^2} + \frac{y^2}{b^2} = \frac{z^2}{c^2}$	Traces with $z = z_0 \neq 0$ are ellipses. Traces with $x = x_0$ or $y = y_0$ are hyperbolas or intersecting lines.
Hyperbolic paraboloid	$z = \frac{x^2}{a^2} - \frac{y^2}{b^2}$	Traces with $z = z_0 \neq 0$ are hyperbolas. Traces with $x = x_0$ or $y = y_0$ are parabolas.

Name	Standard Equation	Features	Graph
Ellipsoid	$\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1$	All traces are ellipses.	
Elliptic paraboloid	$z = \frac{x^2}{a^2} + \frac{y^2}{b^2}$	Traces with $z = z_0 > 0$ are ellipses. Traces with $x = x_0$ or $y = y_0$ are parabolas.	
Hyperboloid of one sheet	$\frac{x^2}{a^2} + \frac{y^2}{b^2} - \frac{z^2}{c^2} = 1$	Traces with $z = z_0$ are ellipses for all $z_0$ . Traces with $x = x_0$ or $y = y_0$ are hyperbolas.	
Hyperboloid of two sheets	$-\frac{x^2}{a^2} - \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1$	Traces with $z = z_0$ with $ z_0  >  c $ are ellipses. Traces with $x = x_0$ and $y = y_0$ are hyperbolas.	
Elliptic cone	$\frac{x^2}{a^2} + \frac{y^2}{b^2} = \frac{z^2}{c^2}$	Traces with $z = z_0 \neq 0$ are ellipses. Traces with $x = x_0$ or $y = y_0$ are hyperbolas or intersecting lines.	
Hyperbolic paraboloid	$z = \frac{x^2}{a^2} - \frac{y^2}{b^2}$	Traces with $z = z_0 \neq 0$ are hyperbolas. Traces with $x = x_0$ or $y = y_0$ are parabolas.	

## 13.2 Graphs and Level Curves

### Function, Domain, and Range with Two Independent Variables

A **function**  $z = f(x, y)$  assigns to each point  $(x, y)$  in a set  $D$  in  $\mathbb{R}^2$  a unique real number  $z$  in a subset of  $\mathbb{R}$ . The set  $D$  is the **domain** of  $f$ . The **range** of  $f$  is the set of real numbers  $z$  that are assumed as the points  $(x, y)$  vary over the domain.

### Function, Domain, and Range with n Independent Variables

The **function**  $y = f(x_1, x_2, \dots, x_n)$  assigns a unique real number  $y$  to each point  $(x_1, x_2, \dots, x_n)$  in a set  $D$  in  $\mathbb{R}^n$ . The set  $D$  is the **domain** of  $f$ . The **range** is the set of real numbers  $y$  that are assumed as the points  $(x_1, x_2, \dots, x_n)$  vary over the domain.

## 13.3 Limits and Continuity

### Limit of a Function of Two Variables

The function  $f$  has the **limit**  $L$  as  $P(x, y)$  approaches  $P_0(a, b)$  written

$$\lim_{(x, y) \rightarrow (a, b)} f(x, y) = L \quad (2)$$

if, given any  $\varepsilon > 0$ , there exists a  $\delta > 0$  such that

$$|f(x, y) - L| < \varepsilon \quad (3)$$

whenever  $(x, y)$  is in the domain of  $f$  and

$$0 < |PP_0| = \sqrt{(x - a)^2 + (y - b)^2} < \delta \quad (4)$$

### Limits of Constant and Linear Functions

Let  $a, b$ , and  $c$  be real numbers.

1. Constant functions  $f(x, y) = c : \lim_{(x, y) \rightarrow (a, b)} c = c$
2. Linear function  $f(x, y) = x : \lim_{(x, y) \rightarrow (a, b)} x = a$
3. Linear function  $f(x, y) = y : \lim_{(x, y) \rightarrow (a, b)} y = b$

### Limit Laws and Functions of Two Variables

Let  $L$  and  $M$  be real numbers and suppose that  $\lim_{(x, y) \rightarrow (a, b)} f(x, y) = L$  and  $\lim_{(x, y) \rightarrow (a, b)} g(x, y) = M$ . Assume  $c$  is a constant, and  $\forall m, n \in \mathbb{Z}$ .

**1 Sum**  $\lim_{(x, y) \rightarrow (a, b)} (f(x, y) + g(x, y)) = L + M$

**2 Difference**  $\lim_{(x, y) \rightarrow (a, b)} (f(x, y) - g(x, y)) = L - M$

**3 Constant multiple**  $\lim_{(x, y) \rightarrow (a, b)} cf(x, y) = cL$

**4 Product**  $\lim_{(x, y) \rightarrow (a, b)} f(x, y) \cdot g(x, y) = L \cdot M$

**5 Quotient**  $\lim_{(x, y) \rightarrow (a, b)} \left[ \frac{f(x, y)}{g(x, y)} \right] = \frac{L}{M}$

**6 Power**  $\lim_{(x,y) \rightarrow (a,b)} (f(x, y))^n = L^n$

**7  $m/n$  Power** If  $m$  and  $n$  have no common factors and  $n \neq 0$ , then  $\lim_{(x,y) \rightarrow (a,b)} [f(x, y)]^{m/n} = L^{m/n}$ , where we assume  $L > 0$  if  $n$  is even.

## Interior and Boundary Points

Let  $R$  be a region in  $\mathbb{R}^2$ . An **interior point**  $P$  of  $R$  lies entirely within  $R$ , which means it is possible to find a disk centered at  $P$  that contains only points of  $R$ .

A **boundary point**  $Q$  of  $R$  lies on the edge of  $R$  in the sense that *every* disk centered at  $Q$  contains at least one point in  $R$  and at least one point not in  $R$ .

## Open and Closed Sets

A region is **open** if it consists entirely of interior points. A region is **closed** if it contains all its boundary points.

## Two-Path Test for Nonexistence of Limits

If  $f(x, y)$  approaches two different values as  $(x, y)$  approaches  $(a, b)$  along two different paths in the domain of  $f$ , then  $\lim_{(x,y) \rightarrow (a,b)} f(x, y)$  does not exist.

## Continuity

A function  $f$  is continuous at the point  $(a, b)$  provided

1.  $f$  is defined at  $(a, b)$ .
2.  $\lim_{(x,y) \rightarrow (a,b)} f(x, y)$  exists.
3.  $\lim_{(x,y) \rightarrow (a,b)} f(x, y) = f(a, b)$ .

## Continuity of Composite Functions

If  $u = g(x, y)$  is continuous at  $(a, b)$  and  $z = f(u)$  is continuous at  $g(a, b)$ , then the composite function  $z = f(g(x, y))$  is continuous at  $(a, b)$ .

## 13.4 Partial Derivatives

The **partial derivative of  $f$  with respect to  $x$  at the point  $(a, b)$**  is

$$f_x(a, b) = \lim_{h \rightarrow 0} \frac{f(a + h, b) - f(a, b)}{h}. \quad (5)$$

The **partial derivative of  $f$  with respect to  $y$  at the point  $(a, b)$**  is

$$f_y(a, b) = \lim_{h \rightarrow 0} \frac{f(a, b + h) - f(a, b)}{h}. \quad (6)$$

provided these limits exists.

### Equality of Mixed Partial Derivatives

Assume that  $f$  is defined on an open set  $D$  of  $\mathbb{R}^2$ , and  $f_{xy}$  and  $f_{yx}$  are continuous throughout  $D$ . Then  $f_{xy} = f_{yx}$  at all points of  $D$ .

### Differentiability

The function  $z = f(x, y)$  is **differentiable at  $(a, b)$**  provided  $f_x(a, b)$  and  $f_y(a, b)$  exist and the change  $\Delta z = f(a + \Delta x, b + \Delta y) - f(a, b)$  equals

$$\Delta z = f_x(a, b)\Delta x + f_y(a, b)\Delta y + \varepsilon_1\Delta x + \varepsilon_2\Delta y, \quad (7)$$

where for fixed  $a$  and  $b$ ,  $\varepsilon_1$  and  $\varepsilon_2$  are functions that depend only on  $\Delta x$  and  $\Delta y$ , with  $(\varepsilon_1, \varepsilon_2) \rightarrow (0, 0)$  as  $(\Delta x, \Delta y) \rightarrow (0, 0)$ . A function is **differentiable** on an open set  $R$  if it is differentiable at every point on  $R$ .

### Conditions for Differentiability

Suppose the function  $f$  has partial derivatives  $f_x$  and  $f_y$  defined on an open set containing  $(a, b)$ , with  $f_x$  and  $f_y$  continuous  $(a, b)$ . Then  $f$  is differentiable at  $(a, b)$ .

### Differentiability Implies Continuity

If a function  $f$  is differentiable at  $(a, b)$ , then it is continuous at  $(a, b)$



## 13.5 The Chain Rule

### Chain Rule (One Independent Variable)

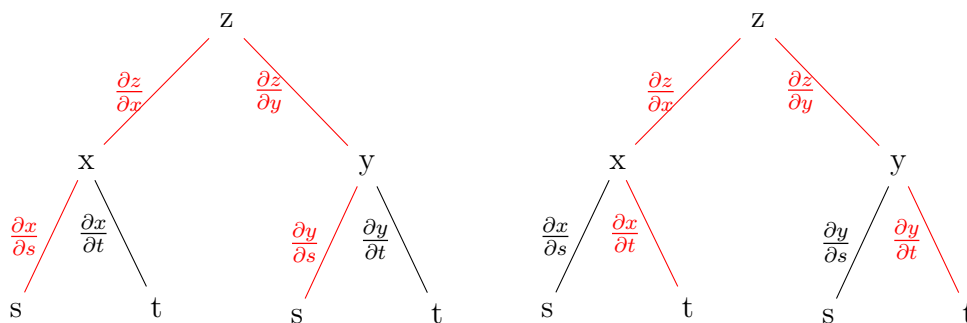
Let  $z$  be a differentiable function of  $x$  and  $y$  on its domain, where  $x$  and  $y$  are differentiable functions of  $t$  on an interval  $I$ . Then

$$\frac{dz}{dt} = \frac{\partial z}{\partial x} \frac{dx}{dt} + \frac{\partial z}{\partial y} \frac{dy}{dt}. \quad (8)$$

### Chain Rule (Two Independent Variables)

Let  $z$  be a differentiable function of  $x$  and  $y$ , where  $x$  and  $y$  are differentiable functions of  $s$  and  $t$ . Then

$$\frac{dz}{ds} = \frac{\partial z}{\partial x} \frac{\partial x}{\partial s} + \frac{\partial z}{\partial y} \frac{\partial y}{\partial s} \quad \text{and} \quad \frac{dz}{dt} = \frac{\partial z}{\partial x} \frac{\partial x}{\partial t} + \frac{\partial z}{\partial y} \frac{\partial y}{\partial t} \quad (9)$$



### Implicit Differentiation

Let  $F$  be differentiable on its domain and suppose that  $F(x, y) = 0$  defines  $y$  as a differentiable function of  $x$ . Provided  $F_y \neq 0$ .

$$\frac{dy}{dx} = -\frac{F_x}{F_y} \quad (10)$$

## 13.6 Directional Derivatives and the Gradient

### Directional Derivative

Let  $f$  be differentiable at  $(a, b)$  and let  $\mathbf{u} = \langle \cos \theta, \sin \theta \rangle$  be a unit vector in the  $xy$ -plane. The **directional derivatives of  $f$  at  $(a, b)$  in the direction of  $\mathbf{u}$**  is

$$D_{\mathbf{u}}f(a, b) = \lim_{h \rightarrow 0} \frac{f(a + h \cos \theta, b + h \sin \theta) - f(a, b)}{h} \quad (11)$$

provided the limit exists.

### Directional Derivative

Let  $f$  be differentiable on  $(a, b)$  and let  $\mathbf{u} = \langle u_1, u_2 \rangle$  be a unit vector in the  $x, y$ -plane. The **directional derivative of  $f$  at  $(a, b)$  in the direction of  $\mathbf{u}$**  is

$$D_{\mathbf{u}}f(a, b) = \langle f_x(a, b), f_y(a, b) \rangle \cdot \langle u_1, u_2 \rangle \quad (12)$$

### Gradient (Two Dimensions)

Let  $f$  be differentiable at the point  $(x, y)$ . The **gradient of  $f$  at  $(x, y)$**  is the vector-valued function

$$\nabla f(x, y) = \langle f_x(x, y), f_y(x, y) \rangle = f_x(x, y)\mathbf{i} + f_y(x, y)\mathbf{j} \quad (13)$$

### Directions of Change

Let  $f$  be differentiable at  $(a, b)$  with  $\nabla f(a, b) \neq \mathbf{0}$

1.  $f$  has its maximum rate of increase at  $(a, b)$  in the direction of the gradient  $\nabla f(a, b)$ . The rate of increase in this direction is  $|\nabla f(a, b)|$
2.  $f$  has its maximum rate of decrease at  $(a, b)$  in the direction of  $-\nabla f(a, b)$ . The rate of decrease in this direction is  $-|\nabla f(a, b)|$ .
3. The directional derivative is zero in any direction orthogonal to  $\nabla f(a, b)$ .

## The Gradient and Level Curves

Given a function  $f$  differentiable at  $(a, b)$ , the line tangent to the level curve of  $f$  at  $(a, b)$  is orthogonal to the gradient  $\nabla f(a, b)$ , provided  $\nabla f(a, b) \neq \mathbf{0}$ .

## Gradient and Directional Derivative in Three Dimensions

Let  $f$  be differentiable at the point  $(x, y, z)$ . The **gradient** of  $f$  at  $(x, y, z)$  is the vector-valued function

$$\nabla f(x, y, z) = \langle f_x(x, y, z), f_y(x, y, z), f_z(x, y, z) \rangle \quad (14)$$

$$= f_x(x, y, z)\hat{\mathbf{i}} + f_y(x, y, z)\hat{\mathbf{j}} + f_z(x, y, z)\hat{\mathbf{k}} \quad (15)$$

The **directional derivative** of  $f$  in the direction of the unit vector  $\mathbf{u} = \langle u_1, u_2, u_3 \rangle$  at the point  $(a, b, c)$  is  $D_{\mathbf{u}}f(a, b, c) = \nabla f(a, b, c) \cdot \mathbf{u}$

## 13.7 Tangent Planes and Linear Approximation

Let  $F$  be differentiable at the point  $P_0(a, b, c)$  with  $\nabla F(a, b, c) \neq \mathbf{0}$ . The plane tangent to the surface  $F(x, y, z) = 0$  at  $P_0$ , called the **tangent plane**, is the plane passing through  $P_0$  orthogonal  $\nabla F(a, b, c)$ . An equation of the tangent plane is

$$F_x(a, b, c)(x - a) + F_y(a, b, c)(y - b) + F_z(a, b, c)(z - c) = 0. \quad (16)$$

### Tangent Plane for $z = f(x, y)$

Let  $f$  be differentiable at the point  $(a, b)$ . An equation of the plane tangent to the surface  $z = f(x, y)$  at the point  $(a, b, f(a, b))$  is

$$z = f_x(a, b)(x - a) + f_y(a, b)(y - b) + f(a, b) \quad (17)$$

### Linear Approximation

Let  $f$  be differentiable at  $(a, b)$ . The linear approximation to the surface  $z = f(x, y)$  at the point  $(a, b, f(a, b))$  is the tangent plane at that point, given by the equation

$$L(x, y) = f_x(a, b)(x - a) + f_y(a, b)(y - b) + f(a, b) \quad (18)$$

### The Differential $dz$

Let  $f$  be differentiable at the point  $(a, b)$ . The change in  $z = f(x, y)$  as the independent variables change from  $(a, b)$  to  $(a + dx, b + dy)$  is denoted by the differential  $dz$ :

$$\Delta z \approx dz = f_x(a, b)dx + f_y(a, b)dy \quad (19)$$

## 13.8 Maximum/Minimum Problems

### Local Maximum/Minimum Values

A function  $f$  has a **local maximum value** at  $(a, b)$  if  $f(x, y) \leq f(a, b)$  for all  $(x, y)$  in the domain of  $f$  in some open disk centered at  $(a, b)$ . A function  $f$  has a **local minimum value** at  $(a, b)$  if  $f(x, y) \geq f(a, b)$  for all  $(x, y)$  in the domain of  $f$  in some open disk centered at  $(a, b)$ . Local maximum and local minimum values are also called **local extreme values** or **local extrema**.

### Derivatives and Local Maximum/Minimum Values

If  $f$  has a local maximum or minimum value at  $(a, b)$  and the partial derivatives  $f_x$  and  $f_y$  exist at  $(a, b)$  then  $f_x(a, b) = f_y(a, b) = 0$ .

### Critical Point

An interior point  $(a, b)$  in the domain of  $f$  is a **critical point** of  $f$  if either

1.  $f_x(a, b) = f_y(a, b) = 0$ , or
2. one (or both) of  $f_x$  or  $f_y$  does not exist at  $(a, b)$

### Saddle Point

A function  $f$  has a **saddle point** at a critical point  $(a, b)$  if, in every open disk centered at  $(a, b)$ , there are points  $(x, y)$  for which  $f(x, y) > f(a, b)$  and points for which  $f(x, y) < f(a, b)$

### Second Derivative Test

Suppose that the second partial derivative of  $f$  are continuous throughout an open disk centered at the point  $(a, b)$ , where  $f_x(a, b) = f_y(a, b) = 0$ . Let  $D(x, y) = f_{xx}(x, y)f_{yy}(x, y) - (f_{xy}(x, y))^2$ .

1. If  $D(a, b) > 0$  and  $f_{xx}(a, b) < 0$ , then  $f$  has a local maximum value at  $(a, b)$ .
2. If  $D(a, b) > 0$  and  $f_{xx}(a, b) > 0$ , then  $f$  has a local minimum value at  $(a, b)$ .

3. If  $D(a, b) < 0$ , then  $f$  has a saddle point at  $(a, b)$ .
4. If  $D(a, b) = 0$ , then the test is inconclusive.

### **Absolute Maximum/Minimum Values**

If  $f(x, y) \leq f(a, b)$  for all  $(x, y)$  in the domain of  $f$ , then  $f$  has an **absolute maximum value** at  $(a, b)$ . If  $f(x, y) \geq f(a, b)$  for all  $(x, y)$  in the domain of  $f$ , then  $f$  has an **absolute minimum value** at  $(a, b)$ .

### **Finding Absolute Maximum/Minimum Values on Closed, Bounded Sets**

Let  $f$  be continuous on a closed bounded set  $R$  in  $\mathbb{R}^2$ . To find the absolute maximum and minimum values of  $f$  on  $R$ :

1. Determine the values of  $f$  at all critical points in  $R$ .
2. Find the maximum and minimum values of  $f$  on the boundary of  $R$ .
3. The greatest function values found in Step 1 and 2 is the absolute maximum value of  $f$  on  $R$ , and the least function value found in Steps 1 and 2 is the absolute minimum value of  $f$  on  $R$ .

## 13.9 Lagrange Multipliers

### Parallel Gradients (Ball Park Theorem)

Let  $f$  be a differentiable function in a region of  $\mathbb{R}^2$  that contains the smooth curve  $C$  given by  $g(x, y) = 0$ . Assume that  $f$  has a local extreme value (relative to values of  $f$  on  $C$ ) at a point  $P(a, b)$  on  $C$ . Then  $\nabla f(a, b)$  is orthogonal to the line tangent to  $C$  at  $P$ . Assuming  $\nabla g(a, b) \neq 0$ , it follows that there is a real number  $\lambda$  (called a **Lagrange multiplier**) such that  $\nabla f(a, b) = \lambda \nabla g(a, b)$ .

### Method of Lagrange Multipliers in Two Variables

Let the objective function  $f$  and the constraint function  $g$  be differentiable on a region of  $\mathbb{R}^2$  with  $\nabla g(x, y) \neq 0$  on the curve  $g(x, y) = 0$ . To locate the maximum and minimum values of  $f$  subject to the constraint  $g(x, y) = 0$ , carry out the following steps.

1. Find the values of  $x, y$  and  $\lambda$  (if they exist) that satisfy the equations

$$\nabla f(x, y) = \lambda \nabla g(x, y) \quad \text{and} \quad g(x, y) = 0 \quad (20)$$

2. Among the values  $(x, y)$  found in Step 1, select the largest and smallest corresponding function values, which are the maximum and minimum values of  $f$  subject to the constraint.

### Method of Lagrange Multipliers in Three Variables

Let  $f$  and  $g$  be differentiable on a region of  $\mathbb{R}^3$  with  $\nabla g(x, y, z) \neq 0$  on the surface  $g(x, y, z) = 0$ . To locate the maximum and minimum values of  $f$  subject to the constraint  $g(x, y, z) = 0$ , carry out the following steps.

1. Find the values of  $x, y, z$  and  $\lambda$  that satisfy the equations

$$\nabla f(x, y, z) = \lambda \nabla g(x, y, z) \quad \text{and} \quad g(x, y, z) = 0 \quad (21)$$

2. Among the points  $(x, y, z)$  found in Step 1, select the largest and smallest corresponding values of the objective function. These values are the maximum and minimum values of  $f$  subject to the constraint.