# Chapter 12: Vectors and Vector Valued Functions

# Illya Starikov

June 30, 2025

# Contents

12.1	Vectors in the Plane
12.2	Vectors in Three Dimensions
12.3	Dot Product
12.4	Cross Product
12.5	Lines and Curves in Space
12.6	Calculus of Vector-Valued Functions
12.7	Motion In Space
12.8	Length of Curves
12.9	Curvature and Normal Vectors

## 12.1 Vectors in the Plane

#### Vectors, Equal Vectors, Scalars, Zero Vector

**Vectors** are quantities that have both **length** (or **magnitude**) and **direction**. Two vectors are **equal** if they have the same magnitude and direction. Quantities having magnitude but no direction are called **scalars**. One exception is the **zero** vector, denoted **0**: It has length 0 and no direction.

#### Scalar Multiples and Parallel Vectors

Given a scalar c and a vector  $\mathbf{u}$ , the scalar multiple  $c\mathbf{v}$  is a vector whose magnitude is |c| multiplied by the magnitude of  $\mathbf{v}$ . If c>0, then  $c\mathbf{v}$  has the same direction as  $\mathbf{v}$ . If c<0, then  $c\mathbf{v}$  and  $\mathbf{v}$  point in opposite directions. Two vectors are **parallel** if they are scalar multiples of each other.

#### Position Vectors and Vector Components

A vector  $\mathbf{v}$  with its tail at the origin and head at the point  $(v_1, v_2)$  is called a **position vector** (or is said to be in **standard position**) and is written  $\langle v_1, v_2 \rangle$ . The real numbers  $v_1$  and  $v_2$  are the x- and y-components of  $\mathbf{v}$ , respectively. The position vectors  $\mathbf{u} = \langle v_1, v_2 \rangle$  and  $\mathbf{v} = \langle v_1, v_2 \rangle$  are equal if and only if  $u_1 = v_1$  and  $u_2 = v_2$ .

#### Magnitude of a Vector

Given the points  $P(x_1, y_1)$  and  $Q(x_2, y_2)$ , the **magnitude**, or **length**, of  $\overrightarrow{PQ} = \langle x_2 - x_1, y_2 - y_1 \rangle$ , denoted  $|\overrightarrow{PQ}|$ , is the distance between P and Q:

$$|\vec{PQ}| = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2}$$
 (1)

The magnitude of the position vector  $\mathbf{v} = \langle v_1, v_2 \rangle$  is  $|\mathbf{v}| = \sqrt{v_1^2 + v_2^2}$ 

#### **Vector Operations**

Suppose c is a scalar,  $\mathbf{u} = \langle u_1, u_2 \rangle$  and  $\mathbf{v} = \langle v_1, v_2 \rangle$ .

$$\mathbf{u} + \mathbf{v} = \langle u_1 + v_1, u_2 + v_2 \rangle$$
 Vector addition (2)

$$\mathbf{u} - \mathbf{v} = \langle u_1 - v_1, u_2 - v_2 \rangle$$
 Vector subtraction (3)

$$c\mathbf{u} = \langle cu_1, cu_2 \rangle$$
 Scalar multiplication (4)

# Unit Vectors and Vectors of a Specified Length

A unit vector is any vector with length 1. Given a nonzero vector  $\mathbf{v}, \pm \frac{\mathbf{v}}{|\mathbf{v}|}$  are unit vectors parallel to  $\mathbf{v}$ . For a scalar c > 0, the vectors  $\pm \frac{c\mathbf{v}}{|v|}$  are vectors of length c parallel to  $\mathbf{v}$ .

### **Properties of Vector Operations**

Suppose  $\mathbf{u}, \mathbf{v}$ , and  $\mathbf{w}$  are vectors and a and c are scalars. Then the following properties hold (for vectors in any number of dimensions).

$\mathbf{u} + a = \mathbf{v} + \mathbf{u}$	Commutative property of addition	(5)
$(\mathbf{u} + \mathbf{v}) + \mathbf{w} = \mathbf{u} + (\mathbf{v} + \mathbf{w})$	Associative property of addition	(6)
$\mathbf{v} + 0 = \mathbf{v}$	Additive identity	(7)
$\mathbf{v} + (-\mathbf{v}) = 0$	Additive identity	(8)
$c(\mathbf{u} + \mathbf{v}) = c\mathbf{u} + c\mathbf{v}$	Distributive property 1	(9)
$(a+c)\mathbf{v} = a\mathbf{v} + c\mathbf{v}$	Distributive property 2	(10)
$0\mathbf{v} = 0$	Multiplication by zero scalar	(11)
c <b>0</b> = <b>0</b>	Multiplication by zero vector	(12)
$1\mathbf{v} = \mathbf{v}$	Multiplicative identity	(13)
$a(c\mathbf{v}) = (ac)\mathbf{v}$	Associative property of scalar multiplication	
		(14)

#### 12.2 Vectors in Three Dimensions

#### Distance Formula in xyz-Space

The distance between the points  $P(x_1, y_1, z_1)$  and  $Q(x_2, y_2, z_2)$  is

$$\sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2} \tag{15}$$

#### Spheres and Balls

A **sphere** centered at (a, b, c) with radius r is the set of points satisfying the equation

$$(x-a)^{2} + (y-b)^{2} + (z-c)^{2} = r^{2}$$
(16)

A ball centered at (a, b, c) with radius r is the set of points satisfying the inequality

$$(x-a)^2 + (y-b)^2 + (z-c)^2 \le r^2 \tag{17}$$

#### Vector Operations in $\mathbb{R}$

Let c be a scalar,  $\mathbf{u} = \langle u_1, u_2, u_3 \rangle$  and  $\mathbf{v} = \langle v_1, v_2, v_3 \rangle$ .

$$\mathbf{u} + \mathbf{v} = \langle u_1 + v_1, u_2 + v_2, u_3 + v_3 \rangle \qquad \text{Vector addition}$$
 (18)

$$\mathbf{u} - \mathbf{v} = \langle u_1 - v_1, u_2 - v_2, u_3 - v_3 \rangle \qquad \text{Vector subtraction}$$
 (19)

$$c\mathbf{u} = \langle cu_1, \, cu_2, \, c_3 \rangle \tag{20}$$

#### Magnitude of a Vector

The **magnitude** (or **length**) of the vector  $\vec{PQ} = \langle x_2 - x_1, y_2 - y_1, z_2 - z_1 \rangle$  is the distance from  $P(x_1, y_1, z_1)$  to  $Q(x_2, y_2, z_2)$ 

$$|\vec{PQ}| = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2}$$
 (21)

#### 12.3 Dot Product

#### **Dot Product**

Given two nonzero vectors  $\mathbf{u}$  and  $\mathbf{v}$  in two or three dimensions, their  $\mathbf{dot}$  product is

$$\mathbf{u} \cdot \mathbf{v} = |\mathbf{u}||\mathbf{v}|\cos\theta \tag{22}$$

where  $\theta$  is the angle between  $\mathbf{u}$  and  $\mathbf{v}$  with  $0 \le \theta \le \pi$ . If  $\mathbf{u} = \mathbf{0}$  or  $\mathbf{v} = \mathbf{0}$ , then  $\mathbf{u} \cdot \mathbf{v} = 0$ , and  $\theta$  is undefined.

#### Orthogonal Vectors

Two vectors  $\mathbf{u}$  and  $\mathbf{v}$  are **orthogonal** if and only if  $\mathbf{u} \cdot \mathbf{v} = 0$ . The zero vector is orthogonal to all vectors. In two or three dimensions, two nonzero orthogonal vectors are perpendicular to each other.

#### **Dot Product**

Given two vectors  $\mathbf{u} = \langle u_1, u_2, u_3 \rangle$  and  $\mathbf{v} = \langle v_1, v_2, v_3 \rangle$ ,

$$\mathbf{u} \cdot \mathbf{v} = u_1 v_1 + u_2 v_2 + u_3 v_3 \tag{23}$$

#### Properties of the Dot Product

Suppose  $\mathbf{u}$ ,  $\mathbf{v}$ , and  $\mathbf{w}$  are vectors and let c be a scalar.

$$\mathbf{u} \cdot \mathbf{v} = \mathbf{v} \cdot \mathbf{u}$$
 Commutative property (24)

$$c(\mathbf{u} \cdot \mathbf{v}) = (c\mathbf{u}) \cdot \mathbf{v} = \mathbf{u} \cdot (c\mathbf{v})$$
 Associative property (25)

$$\mathbf{u} \cdot (\mathbf{v} + \mathbf{w}) = \mathbf{u} \cdot \mathbf{v} + \mathbf{u} \cdot \mathbf{w} \tag{26}$$

#### (Orthogonal) Projection of u onto v

The orthogonal projection of u onto v , denoted  $\operatorname{proj}_{\mathbf{v}}\mathbf{u}$ , where  $\mathbf{v} \neq \mathbf{0}$ , is

$$\operatorname{proj}_{\mathbf{v}}\mathbf{u} = |\mathbf{u}|\cos\theta\left(\frac{\mathbf{v}}{|\mathbf{v}|}\right) \tag{27}$$

The orthogonal projection may also be computed with the formulas

$$\operatorname{proj}_{\mathbf{v}}\mathbf{u} = \operatorname{scal}_{\mathbf{v}}\mathbf{u} \left( \frac{\mathbf{v}}{|\mathbf{v}|} \right) = \left( \frac{\mathbf{u} \cdot \mathbf{v}}{\mathbf{v} \cdot \mathbf{v}} \right) \mathbf{v}$$
 (28)

where the scalar component of u in the direction of v is

$$\operatorname{scal}_{\mathbf{v}}\mathbf{u} = |\mathbf{u}|\cos\theta = \frac{\mathbf{u}\cdot\mathbf{v}}{|\mathbf{v}|}$$
 (29)

#### Work

Let a constant force  $\mathbf{F}$  be applied to an object, producing a displacement  $\mathbf{d}$ . If the angle between  $\mathbf{F}$  and  $\mathbf{d}$  is  $\theta$ , then the **work** done by the force is

$$W = |\mathbf{F}||\mathbf{d}|\cos\theta = \mathbf{F} \cdot \mathbf{d} \tag{30}$$

#### 12.4 Cross Product

Given two nonzero vectors  $\mathbf{u}$  and  $\mathbf{v}$  in  $\mathbb{R}^3$ , the **cross product**  $\mathbf{u} \times \mathbf{v}$  is a vector with magnitude

$$|\mathbf{u} \times \mathbf{v}| = |\mathbf{u}||\mathbf{v}|\sin\theta \tag{31}$$

where  $0 \le \theta \le \pi$  is the angle between  $\mathbf{u}$  and  $\mathbf{v}$ . The direction of  $\mathbf{u} \times \mathbf{v}$  is given by the **right-hand rule**: When you put the vectors tail to tail and let the fingers of your right hand curl from  $\mathbf{u}$  to  $\mathbf{v}$  the direction of  $\mathbf{u} \times \mathbf{v}$  is the direction of your thumb, orthogonal to both  $\mathbf{u}$  and  $\mathbf{v}$ . When  $\mathbf{u} \times \mathbf{v} = 0$ , the direction of  $\mathbf{u} \times \mathbf{v}$  undefined.

#### Geometry of the Cross Product

Let **u** and **v** be two nonzero vectors in  $\mathbb{R}^3$ .

- 1. The vectors  $\mathbf{u}$  and  $\mathbf{v}$  are parallel ( $\theta = 0$  or  $\theta = \pi$ ) if and only if  $\mathbf{u} \times \mathbf{v} = 0$ .
- 2. If  $\mathbf{u}$  and  $\mathbf{v}$  are two sides of a parallelogram, then the area of the parallelogram is

$$|\mathbf{u} \times \mathbf{v}| = |\mathbf{u}||\mathbf{v}|\sin\theta \tag{32}$$

#### Properties of the Cross Product

Let  $\mathbf{u}$ ,  $\mathbf{v}$ , and  $\mathbf{w}$  be nonzero vectors in  $\mathbb{R}^3$ , and let a and b be scalars.

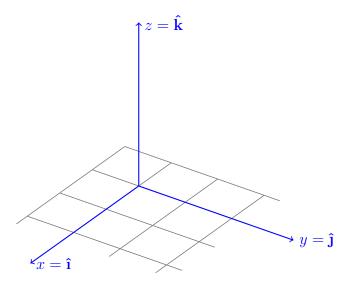
$$\mathbf{u} \times \mathbf{v} = -(\mathbf{v} \times \mathbf{u})$$
 Anticommutative property (33)

$$(a\mathbf{u}) \times (b\mathbf{v}) = ab(\mathbf{u} \times \mathbf{v})$$
 Associative property (34)

$$\mathbf{u} \times (\mathbf{v} + \mathbf{w}) = (\mathbf{u} \times \mathbf{v}) + (\mathbf{u} \times \mathbf{w})$$
 Distributive property (35)

$$(\mathbf{u} + \mathbf{v}) \times \mathbf{w} = (\mathbf{u} \times \mathbf{w}) + (\mathbf{v} \times \mathbf{w})$$
 Distributive property (36)

#### **Cross Products of Coordinate Unit Vectors**



$$\hat{\mathbf{i}} \times \hat{\mathbf{j}} = -(\hat{\mathbf{j}} \times \hat{\mathbf{i}}) = \hat{\mathbf{k}} \tag{37}$$

$$\hat{\mathbf{j}} \times \hat{\mathbf{k}} = -(\hat{\mathbf{k}} \times \hat{\mathbf{j}}) = \hat{\mathbf{i}} \tag{38}$$

$$\hat{\mathbf{k}} \times \hat{\mathbf{i}} = -(\hat{\mathbf{i}} \times \hat{\mathbf{k}}) = \hat{\mathbf{j}} \tag{39}$$

$$\hat{\mathbf{i}} \times \hat{\mathbf{i}} = \hat{\mathbf{j}} \times \hat{\mathbf{j}} = \hat{\mathbf{k}} \times \hat{\mathbf{k}} = 0 \tag{40}$$

# **Evaluating the Cross Product**

Let  $\mathbf{u} = u_1 \hat{\mathbf{i}} + u_2 \hat{\mathbf{j}} + u_3 \hat{\mathbf{k}}$  and  $\mathbf{v} = v_1 \hat{\mathbf{i}} + v_2 \hat{\mathbf{j}} + v_3 \hat{\mathbf{k}}$ . Then

$$\mathbf{u} \times \mathbf{v} = \begin{vmatrix} \hat{\mathbf{i}} & \hat{\mathbf{j}} & \hat{\mathbf{k}} \\ u_1 & u_2 & u_3 \\ v_1 & v_2 & v_3 \end{vmatrix} = \begin{vmatrix} u_2 & u_3 \\ v_2 & v_3 \end{vmatrix} \hat{\mathbf{i}} - \begin{vmatrix} u_1 & u_3 \\ v_1 & v_3 \end{vmatrix} \hat{\mathbf{j}} + \begin{vmatrix} u_1 & u_2 \\ v_1 & v_2 \end{vmatrix} \hat{\mathbf{k}}$$
(41)

# 12.5 Lines and Curves in Space

## Equation of a Line

An equation of the line passing through the point  $P_0(x_0, y_0, z_0)$  in the direction of the vector  $\mathbf{v} = \langle a, b, c \rangle$  is  $\mathbf{r} = r_0 + t\mathbf{v}$ , or

$$\langle x, y, z \rangle = \langle x_0, y_0, z_0 \rangle + t \langle a, b, c \rangle, \quad \text{for} \quad -\infty < t < \infty$$
 (42)

Equivalently, the parametric equations of the line are

$$x = x_0 + at$$
,  $y = y_0 + bt$ ,  $z = z_0 + ct$ , for  $-\infty < t < \infty$  (43)

#### Limit of a Vector-Valued Function

A vector-valued function  $\mathbf{r}$  approaches the limit  $\mathbf{L}$  as t approaches a, written  $\lim_{t\to a} \mathbf{r}(t) = \mathbf{L}$ , provided  $\lim_{t\to a} |\mathbf{r}(t) - \mathbf{L}| = 0$ 

#### 12.6 Calculus of Vector-Valued Functions

#### **Derivative and Tangent Vector**

Let  $\mathbf{r}(t) = f(t)\hat{\mathbf{i}} + g(t)\hat{\mathbf{j}} + h(t)\hat{\mathbf{k}}$ , where f, g, and h are differentiable functions on (a b). Then  $\mathbf{r}$  has a **derivative** (or is **differentiable**) on (a b) and

$$\mathbf{r}'(t) = f'(i)\hat{\mathbf{i}} + g'(t)\hat{\mathbf{j}} + h'(t)\hat{\mathbf{k}}$$
(44)

Provided  $\mathbf{r}'(t) \neq \mathbf{0}, \mathbf{r}'(t)$  is a **tangent vector** (or velocity vector) at the point corresponding to  $\mathbf{r}$ .

### Unit Tangent Vector

Let  $\mathbf{r} = f(t)\mathbf{\hat{i}} + g(t)\mathbf{\hat{j}} + h(t)\mathbf{\hat{k}}$  be a smooth parameterized curve, for  $a \le t \le b$ . The **unit tangent vector** for a particular value of t is

$$\mathbf{T}(t) = \frac{\mathbf{r}'(t)}{|\mathbf{r}'(t)|} \tag{45}$$

#### **Derivative Rules**

Let  $\mathbf{u}$  and  $\mathbf{v}$  be differentiable vector-valued functions and let f be a differentiable scalar-valued function, all at a point t. Let  $\mathbf{c}$  be a constant vector. The following rules apply.

$$\frac{d}{dt}(\mathbf{c}) = \mathbf{0}$$
 Constant Rule (46)

$$\frac{d}{dt}(\mathbf{u}(t) + \mathbf{v}(t)) = \mathbf{u}'(t) + \mathbf{v}'(t) \quad \text{Sum Rule}$$
 (47)

$$\frac{d}{dt}(f(t)\mathbf{u}(t)) = f'(t)\mathbf{u}(t) + f(t)\mathbf{u}'(t) \quad \text{Product Rule}$$
 (48)

$$\frac{d}{dt}(\mathbf{u}(f(t))) = \mathbf{u}'(f(t))f'(t) \quad \text{Chain Rule}$$
 (49)

$$\frac{d}{dt}(\mathbf{u}(t)\cdot\mathbf{v}(t)) = \mathbf{u}'(t)\cdot\mathbf{v}(t) + \mathbf{u}(t)\cdot\mathbf{v}'(t) \quad \text{Dot Product Rule}$$
 (50)

$$\frac{d}{dt}(\mathbf{u}(t) \times \mathbf{v}(t)) = \mathbf{u}'(t) \times \mathbf{v}(t) + \mathbf{u}(t) \times \mathbf{v}'(t) \quad \text{Cross Product Rule} \quad (51)$$

#### Indefinite Integral of a Vector-Valued Function

Let  $\mathbf{r} = f\hat{\mathbf{i}} + g\hat{\mathbf{j}} + h\hat{\mathbf{k}}$  be a vector function and let  $\mathbf{R} = F\hat{\mathbf{i}} + G\hat{\mathbf{j}} + H\hat{\mathbf{k}}$ , where F, G, and H are antiderivatives of f, g, and h, respectively. The **indefinite** integral of  $\mathbf{r}$  is

$$\int \mathbf{r}(t) dt = \mathbf{R}(t) + \mathbf{C}$$
 (52)

where C is an arbitrary constant vector.

#### Definite Integral of a Vector-Valued Function

Let  $\mathbf{r}(t) = f(t)\mathbf{\hat{i}} + g(t)\mathbf{\hat{j}} + h(t)\mathbf{\hat{k}}$ , where f, g, and h are integrable on the interval [a, b].

$$\int \mathbf{r}(t) dt = \left[ \int_{a}^{b} f(t) dt \right] \hat{\mathbf{i}} + \left[ \int_{a}^{b} g(t) dt \right] \hat{\mathbf{j}} + \left[ \int_{a}^{b} h(t) dt \right] \hat{\mathbf{k}}$$
 (53)

# 12.7 Motion In Space

#### Position, Velocity, Speed, Acceleration

Let the position of an object moving in three-dimensional space be given by  $\mathbf{r}(t) = \langle x(t), y(t), z(t) \rangle$ , for  $t \geq 0$ . The **velocity** of the object is

$$\mathbf{v}(t) = \mathbf{r}'(t) = \langle x'(t), y'(t), z'(t) \rangle \tag{54}$$

The **speed** of the object is the scalar function

$$|\mathbf{v}(t)| = \sqrt{x'(t)^2 + y'(t)^2 + z'(t)^2}$$
(55)

The acceleration of the object is  $\mathbf{a}(t) = \mathbf{v}'(t) = \mathbf{r}''(t)$ .

#### Motion with Constant |r|

Let  $\mathbf{r}$  describe a path on which  $|\mathbf{r}|$  is constant (motion on a circle or sphere centered at the origin). Then,  $\mathbf{r} \cdot \mathbf{v} = 0$ , which means the position vector and the velocity vector are orthogonal at all times for which the functions are defined.

#### Two-Dimensional Motion in a Gravitational Field

Consider an object moving in a plane with horizontal x-axis and a vertical y-axis, subject only to the force of gravity. Given the initial velocity  $\mathbf{v}(0) = \langle u_0, v_0 \rangle$  and the initial position  $\mathbf{r}(0) = \langle x_0, y_0 \rangle$ , the velocity of the object, for  $t \geq 0$ , is

$$\mathbf{v}(t) = \langle x'(t), y'(t) \rangle = \langle u_0, -gt + v_0 \rangle$$
 (56)

and the position is

$$\mathbf{r}(t) = \langle x(t), y(t) \rangle = \left\langle u_0 \ t + x_0, -\frac{1}{2}gt^2 + v_0t + y_0 \right\rangle$$
 (57)

#### Two-Dimensional Motion

Assume an object traveling over horizontal ground, acted on only by the gravitational force, has an initial position  $\langle x_0, y_0 \rangle = \langle 0, 0 \rangle$  and initial velocity

 $\langle u_0, v_0 \rangle = \langle |\mathbf{v}_0| \cos \alpha, |\mathbf{v}_0| \sin \alpha \rangle$ . The trajectory, which is a segment or a parabola, has the following properties.

time of flight = 
$$T = \frac{2|\mathbf{v}_0|\sin\alpha}{g}$$
 (58)  
range =  $\frac{|\mathbf{v}_0|\sin 2\alpha}{g}$  (59)

$$range = \frac{|\mathbf{v}_0|\sin 2\alpha}{q} \tag{59}$$

maximum height = 
$$y\left(\frac{T}{2}\right) = \frac{(|\mathbf{v}_0|\sin\alpha)^2}{2g}$$
 (60)

# 12.8 Length of Curves

Consider the parameterized curve  $\mathbf{r}(t) = \langle f(t), g(t), h(t) \rangle$ , where f', g', and h' are continuous, and the curve is traversed once for  $a \leq t \leq b$ . The **arc** length of the curve between (f(a), g(a), h(a)) and (f(b), g(b), h(b)) is

$$L = \int_{a}^{b} \sqrt{f'(t)^{2} + g'(t)^{2} + h'(t)^{2}} dt = \int_{a}^{b} |\mathbf{r}'(\mathbf{t})| dt$$
 (61)

#### Arc Length of a Polar Curve

Let f have a continuous derivative on the interval  $[\alpha, \beta]$ . The **arc length** of the polar curve  $r = f(\theta)$  on  $[\alpha, \beta]$  is

$$L = \int_{\alpha}^{\beta} \sqrt{f(\theta)^2 + f'(\theta)^2} \, d\theta. \tag{62}$$

#### Arc Length as a Function of a Parameter

Let  $\mathbf{r}(t)$  describe a smooth curve, for  $t \geq a$ . The arc length is given by

$$s(t) = \int_{0}^{t} |\mathbf{v}(u)| \, du,\tag{63}$$

where  $|\mathbf{v}| = |\mathbf{r}'|$ . Equivalently,  $\frac{ds}{dt} = |\mathbf{v}t| > 0$ . If  $|\mathbf{v}(t)| = 1$ , for all  $t \ge a$ , then the parameter t corresponds to arc length.

#### Arc Length as a Function of a Parameter

Let  $\mathbf{r}(t)$  describe a smooth curve, for  $t \geq a$ . The arc length is given by

$$s(t) = \int_{a}^{t} |\mathbf{v}(u)| \, du, \tag{64}$$

where  $|\mathbf{v}| = |\mathbf{r}'|$ . Equivalently,  $\frac{ds}{dt} = \mathbf{v}(t) > 0$ . If  $|\mathbf{v}(\mathbf{t})| = 1$ , for all  $t \ge a$ , then the parameter t corresponds to arc length.

#### 12.9 Curvature and Normal Vectors

#### Curvature

Let **r** describe a smooth parameterized curve. If s denotes arc length and  $\mathbf{T} = \frac{\mathbf{r}'}{|\mathbf{r}'|}$  is the unit tangent vector, the **curvature** is  $\kappa(s) = \left|\frac{d\mathbf{T}}{ds}\right|$ 

#### Curvature Formula

Let  $\mathbf{r}(t)$  describes a smooth parameterized curve, where t is any parameter. If  $\mathbf{v} = \mathbf{r}'$  is the velocity and  $\mathbf{T}$  is the unit tangent vector, then the curvature is

$$\kappa(t) = \frac{1}{|\mathbf{v}|} \left| \frac{d\mathbf{T}}{dt} \right| = \left| \frac{\mathbf{T}'(t)}{\mathbf{r}'(t)} \right|$$
 (65)

#### Alternative Curvature Formula

Let  $\mathbf{r}$  be the position of an object moving on a smooth curve. The **curvature** at a point on the curve is

$$\kappa = \frac{|\mathbf{v} \times \mathbf{a}|}{|\mathbf{v}|^3},\tag{66}$$

where  $\mathbf{v} = \mathbf{r}'$  is the velocity and  $\mathbf{a} = \mathbf{v}'$  is the acceleration.

#### Principal Unit Normal Vector

Let **r** describe a smooth parameterized curve. The **principal unit normal vector** at a point P on the curve at which  $\kappa \neq 0$  is

$$\mathbf{N}(s) = \frac{d\mathbf{T}/ds}{|d\mathbf{T}/ds|} = \frac{1}{\kappa} \frac{d\mathbf{T}}{ds}$$
 (67)

In practice, we use the equivalent formula

$$\mathbf{N}(t) = \frac{d\mathbf{T}/dt}{|d\mathbf{T}/dt|} \tag{68}$$

evaluated at the value of t corresponding to P.

#### Properties of the Principal Unit Normal Vector

Let  $\mathbf{r}$  describe a smooth parameterized curve with unit tangent vector  $\mathbf{T}$  and principal unit normal vector  $\mathbf{N}$ .

- 1. **T** and **N** are orthogonal at all points of the curve; that is,  $\mathbf{T}(t) \cdot \mathbf{N}(t) = 0$ , at all points where **N** is defined.
- 2. The principal unit normal vector points to the inside of the curve—in the direction that the curve is turning.

#### Tangential and Normal Components of the Acceleration

The acceleration vector of an object moving in space along a smooth curve has the following representation in terms of its **tangential component**  $a_T$  (in the direction of  $\mathbf{T}$ ) and its normal component  $a_N$  (in the direction of  $\mathbf{N}$ ):

$$\mathbf{a} = a_N \mathbf{N} + a_T \mathbf{T},\tag{69}$$

where  $a_N = \kappa |\mathbf{v}|^2 = \frac{|\mathbf{v} \times \mathbf{a}|}{|\mathbf{v}|}$  and  $a_T = \frac{d^2s}{dt^2}$ .

#### Unit Binormal Vector and Torsion

Let C be a smooth parameterized curve with unit tangent and principal unit normal vectors  $\mathbf{T}$  and  $\mathbf{N}$ , respectively. Then, at each point of the curve at which the curvature is nonzero, the **unit binormal vector** is

$$\mathbf{B} = \mathbf{T} \times \mathbf{N} \tag{70}$$

and the **torsion** is

$$\tau = -\frac{d\mathbf{B}}{ds} \cdot \mathbf{N} \tag{71}$$

#### Formulas for Curves in Space

1. Position function:  $\mathbf{r}(t) = \langle x(t), y(t), z(t) \rangle$ 

2. Velocity:  $\mathbf{v} = \mathbf{r}'$ 

3. Acceleration:  $\mathbf{a} = \mathbf{v}'$ 

- 4. Unit tangent vector:  $\mathbf{T} = \frac{\mathbf{v}}{|\mathbf{v}|}$
- 5. Principal unit normal vector:  $\mathbf{N} = \frac{d^{\mathbf{T}}/dt}{|d^{\mathbf{T}}/dt|}$  (provided  $d^{\mathbf{T}}/dt \neq \mathbf{0}$ )
- 6. Curvature:  $\kappa = \frac{d\mathbf{T}}{ds} = \frac{1}{|\mathbf{v}|} \left| \frac{d\mathbf{T}}{dt} \right| = \left| \frac{\mathbf{T}'(t)}{\mathbf{r}'(t)} \right| = \frac{|\mathbf{v} \times \mathbf{a}|}{|\mathbf{v}|^3}$
- 7. Components of acceleration:  $\mathbf{a} = a_N \mathbf{N} + a_T \mathbf{T}$ , where  $a_N = \kappa |\mathbf{v}|^2 = \frac{|\mathbf{v} \times \mathbf{a}|}{|\mathbf{v}|}$  and  $a_T = \frac{d^2s}{dt^2} = \frac{\mathbf{v} \cdot \mathbf{a}}{|\mathbf{v}|}$
- 8. Unit binormal vector:  $\mathbf{B} = \mathbf{B} \times \mathbf{N} = \frac{\mathbf{v} \times \mathbf{a}}{|\mathbf{v} \times \mathbf{a}|}$
- 9. Torsion  $\tau = -\frac{d\mathbf{B}}{ds} \cdot \mathbf{N} = \frac{(\mathbf{v} \times \mathbf{a}) \cdot \mathbf{a}'}{|\mathbf{v} \times \mathbf{a}|^2} = \frac{(\mathbf{r}' \times \mathbf{r}'') \cdot \mathbf{r}'''}{(\mathbf{r}' \times \mathbf{r}'')^2}$