

# Chapter 15: Vector Calculus

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## 15.1 Vector Fields

### Vector Fields in Two Dimensions

Let  $f$  and  $g$  be defined on a region  $R$  of  $\mathbb{R}^2$ . A **vector field** in  $\mathbb{R}^2$  is a function  $\mathbf{F}$  that assigns to each point in  $R$  a vector  $\langle f(x, y), g(x, y) \rangle$ . The vector field is written as

$$\mathbf{F}(x, y) = \langle f(x, y), g(x, y) \rangle \quad \text{or} \quad \mathbf{F}(x, y) = f(x, y)\hat{\mathbf{i}} + g(x, y)\hat{\mathbf{j}} \quad (1)$$

A vector field  $\mathbf{F} = \langle f, g \rangle$  is continuous or differentiable on a region  $R$  of  $\mathbb{R}^2$  if  $f$  and  $g$  are continuous or differentiable on  $R$ , respectively.

### Radial Vector Fields in $\mathbb{R}^2$

Let  $\mathbf{r} = \langle x, y \rangle$ . A vector field of the form  $\mathbf{F} = f(x, y)\mathbf{r}$ , where  $f$  is a scalar-valued function, is a **radial vector field**. Of specific interest are the radial vector field

$$\mathbf{F}(x, y) = \frac{\mathbf{r}}{|\mathbf{r}|^p} = \frac{\langle x, y \rangle}{|\mathbf{r}|^p} \quad (2)$$

where  $p$  is a real number. At every point (except the origin), the vectors of this field are directed outward from the origin with the magnitude of  $|\mathbf{F}| = \frac{1}{|\mathbf{r}|^{p-1}}$ .

### Vector Fields in Three Dimensions

Let  $f$ ,  $g$ , and  $h$  be defined on a region  $D$  of  $\mathbb{R}^3$ . A **vector field** in  $\mathbb{R}^3$  is a function  $\mathbf{F}$  that assigns to each point in  $D$  a vector  $\langle f(x, y, z), g(x, y, z), h(x, y, z) \rangle$ . The vector field is written as

$$\mathbf{F}(x, y, z) = \langle f(x, y, z), g(x, y, z), h(x, y, z) \rangle \quad \text{or} \quad (3)$$

$$\mathbf{F}(x, y, z) = f(x, y, z)\hat{\mathbf{i}} + g(x, y, z)\hat{\mathbf{j}} + h(x, y, z)\hat{\mathbf{k}} \quad (4)$$

A vector field  $\mathbf{F} = \langle f, g, h \rangle$  is continuous or differentiable on a region  $D$  of  $\mathbb{R}^3$  if  $f$ ,  $g$ ,  $h$  are continuous or differentiable on  $R$ , respectively. Of particular importance are the **radial vector fields**

$$\mathbf{F}(x, y, z) = \frac{\mathbf{r}}{|\mathbf{r}|^p} = \frac{\langle x, y, z \rangle}{|\mathbf{r}|^p} \quad (5)$$

where  $p$  is a real number.

### **Gradient Fields and Potential Functions**

Let  $z = \varphi(x, y)$  and  $w = \varphi(x, y, z)$  be differentiable functions on regions of  $\mathbb{R}^2$  and  $\mathbb{R}^3$ , respectively. The vector field  $\mathbf{F} = \nabla\varphi$  is **gradient field**, and the function  $\varphi$  is a **potential function** for  $\mathbf{F}$ .

## 15.2 Line Integrals

### Scalar Line Integral in the Plane, Arc Length Parameter

Suppose the scalar-valued function  $f$  is defined on the smooth curve  $C : \mathbf{r}(s) = \langle x(s), y(s) \rangle$ , parameterized by the arc length  $s$ . The **line integral of  $f$  over  $C$**  is

$$\int_C f(x(s), y(s)) ds = \lim_{\Delta \rightarrow 0} \sum_{k=1}^n f(x(s_k^*), y(s_k^*)) \Delta s_k, \quad (6)$$

provided this limit exists over all partitions of  $C$ . When the limit exists,  $f$  is said to be **integrable** on  $C$ .

### Evaluating Scalar Line Integrals in $\mathbb{R}^2$

Let  $f$  be continuous on a region containing a smooth curve  $C : \mathbf{r}(t) = \langle x(t), y(t) \rangle$ , for  $a \leq t \leq b$ . Then

$$\int_C f ds = \int_a^b f(x(t), y(t)) |\mathbf{r}'(t)| dt \quad (7)$$

$$= \int_a^b f(x(t), y(t)) \sqrt{x'(t)^2 + y'(t)^2} dt \quad (8)$$

### Evaluating the Line Integral $\int_C f ds$

1. Find a parametric description of  $C$  in the form  $\mathbf{r}(t) = \langle x(t), y(t) \rangle$ , for  $a \leq t \leq b$
2. Computer  $|\mathbf{r}'(t)| = \sqrt{x'(t)^2 + y'(t)^2}$
3. Make substitutions for  $x$  and  $y$  in the integrand and evaluate an ordinary integral

$$\int_C f ds = \int_a^b f(x(t), y(t)) |\mathbf{r}'(t)| dt \quad (9)$$

### Evaluating Scalar Line Integrals in $\mathbb{R}^3$

Let  $f$  be continuous on a region containing a smooth curve  $C : \mathbf{r}(t) = \langle x(t), y(t), z(t) \rangle$ , for  $a \leq t \leq b$ . Then

$$\int f \, ds = \int_a^b f(x(t), y(t), z(t)) |\mathbf{r}'(t)| \, dt \quad (10)$$

$$= \int_a^b f(x(t), y(t), z(t)) \sqrt{x'(t)^2 + y'(t)^2 + z'(t)^2} \, dt \quad (11)$$

### Line Integral of a Vector Field

Let  $\mathbf{F}$  be a vector field that is continuous on a region containing a smooth oriented curve  $C$  parameterized by arc length. Let  $\mathbf{T}$  be the unit tangent vector at each point of  $C$  consistent with the orientation. The line integral of  $\mathbf{F}$  over  $C$  is  $\int_C \mathbf{F} \cdot \mathbf{T} \, ds$ .

### Different Forms of Line Integrals of Vector Fields

The line integral  $\int_C \mathbf{F} \cdot \mathbf{T} \, ds$  may be expressed in the following forms, where  $\mathbf{F} = \langle f, g, h \rangle$ , for  $a \leq t \leq b$ :

$$\int_a^b \mathbf{F} \cdot \mathbf{r}'(t) \, dt = \int_a^b (f x'(t), g y'(t), h z'(t)) \, dt \quad (12)$$

$$= \int_C f \, dx + g \, dy + h \, dz \quad (13)$$

$$= \int_C \mathbf{F} \cdot d\mathbf{r} \quad (14)$$

For line integrals in the plane, we let  $\mathbf{F} = \langle f, g \rangle$  and assume  $C$  is parameterized in the form  $\mathbf{r}(t) = \langle x(t), y(t) \rangle$ , for  $a \leq t \leq b$ . Then

$$\int_C \mathbf{F} \cdot \mathbf{T} \, ds = \int_a^b (f x'(t) + g y'(t)) \, dt = \int_C f \, dx + g \, dy = \int_C \mathbf{F} \cdot d\mathbf{r} \quad (15)$$

### Work Done in a Force Field

Let  $\mathbf{F}$  be a continuous force field in a region  $D$  of  $\mathbb{R}^3$  and let  $C : \mathbf{r}(t) = \langle x(t), y(t), z(t) \rangle$ , for  $a \leq t \leq b$ , be a smooth curve in  $D$  with a unit tangent vector  $\mathbf{T}$  consistent with the orientation. The work done in moving an object  $C$  in the positive direction is

$$W = \int_C \mathbf{F} \cdot \mathbf{T} \, ds = \int_a^b \mathbf{F} \cdot \mathbf{r}'(t) \, dt \quad (16)$$

### Circulation

Let  $\mathbf{F}$  be a continuous vector field on a region  $D$  of  $\mathbb{R}^3$  and let  $C$  be a closed smooth oriented curve in  $D$ . The **circulation** of  $\mathbf{F}$  on  $C$  is  $\int_C \mathbf{F} \cdot \mathbf{T} \, ds$ , where  $\mathbf{T}$  is the unit vector tangent to  $C$  consistent with the orientation.

### Flux

Let  $F = \langle f, g \rangle$  be continuous vector field on a region  $R$  of  $\mathbb{R}^2$ . Let  $C : \mathbf{r}(t) = \langle x(t), y(t) \rangle$ , for  $a \leq t \leq b$ , be a smooth oriented curve in  $R$  that does not intersect itself. The **flux** of the vector field across  $C$  is

$$\int_C \mathbf{F} \cdot \mathbf{n} \, ds = \int_a^b (f y'(t) - g x'(t)) \, dt, \quad (17)$$

where  $\mathbf{n} = \mathbf{T} \times \hat{\mathbf{k}}$  is the unit normal vector and  $\mathbf{T}$  is the unit tangent vector consistent with the orientation. If  $C$  is a closed curve with counterclockwise orientation,  $\mathbf{n}$  is the outward normal vector and the flux integral gives the **outward flux** across  $C$ .

## 15.3 Conservative Vector Fields

### Simple and Closed Curves

Suppose a curve  $C$  (in  $\mathbb{R}^2$  and  $\mathbb{R}^3$ ) is described parametrically by  $\mathbf{r}(t)$ , where  $a \leq t \leq b$ . Then  $C$  is a **simple curve** if  $\mathbf{r}(t_1) \neq \mathbf{r}(t_2)$  for all  $t_1$  and  $t_2$ , with  $a < t_1 < t_2 < b$ ; that is,  $C$  never intersects itself between its endpoints. The curve  $C$  is **closed** if  $\mathbf{r}(a) = \mathbf{r}(b)$ ; that is, the initial and terminal points of  $C$  are the same.

### Connected and Simply Connected Regions

An open region  $R$  in  $\mathbb{R}^2$  (or  $D$  in  $\mathbb{R}^3$ ) is **connected** if it is possible to connect any two points of  $R$  by a continuous curve lying in  $R$ . An open region  $R$  is **simply connected** if every closed simple curve in  $R$  can be deformed and contracted to a point in  $R$ .

### Conservative Vector Field

A vector field  $F$  is said to be **conservative** on a region (in  $\mathbb{R}^2$  or  $\mathbb{R}^3$ ) if there exists a scalar function  $\varphi$  such that  $\mathbf{F} = \nabla\varphi$  on that region.

### Test for Conservative Vector Fields

Let  $\mathbf{F} = \langle f, g, h \rangle$  be a vector field defined on a connected and simply connected region  $D$  of  $\mathbb{R}^3$ , where  $f$ ,  $g$ , and  $h$  have continuous first partial derivatives on  $D$ . Then  $\mathbf{F}$  is a conservative vector field on  $D$  (there is a potential function  $\varphi$  such that  $\mathbf{F} = \nabla\varphi$ ) if and only if

$$\frac{\partial f}{\partial y} = \frac{\partial g}{\partial x}, \quad \frac{\partial f}{\partial z} = \frac{\partial h}{\partial x}, \quad \text{and} \quad \frac{\partial g}{\partial z} = \frac{\partial h}{\partial y} \quad (18)$$

For vector fields in  $\mathbb{R}^2$ , we have the single condition  $\frac{\partial f}{\partial y} = \frac{\partial g}{\partial x}$ .

### Finding Potential Functions in $\mathbb{R}^3$

Suppose  $\mathbf{F} = \langle f, g, h \rangle$  is a conservative vector field. To find  $\varphi$  such that  $\mathbf{F} = \nabla\varphi$ , take the following steps:

1. Integral  $\varphi_x = f$  with respect to  $x$  to obtain  $\varphi$ , which includes an arbitrary function  $c(y, z)$ .

2. Compute  $\varphi_y$  and equate it to  $g$  to obtain an expression for  $c_y(y, z)$ .
3. Integrate  $c_y(y, z)$  with respect to  $y$  to obtain  $c(y, z)$ , including an arbitrary function  $d(z)$ .
4. Compute  $\varphi_z$  and equate it to  $h$  to get  $d(z)$ .

Beginning the procedure with  $\varphi_y = g$  or  $\varphi_z = h$  maybe be easier in some cases.

### Fundamental Theorem for Line Integrals

Let  $\mathbf{F}$  be a continuous vector field on an open connected region  $R$  in  $\mathbb{R}^2$  (or  $D$  in  $\mathbb{R}^3$ ). There exists a potential function  $\varphi$  with  $\mathbf{F} = \nabla\varphi$  (which means that  $\mathbf{F}$  is conservative) if and only if

$$\int_C \mathbf{F} \cdot \mathbf{T} \, ds = \int_C \mathbf{F} \cdot d\mathbf{r} = \varphi(B) - \varphi(A) \quad (19)$$

for all points  $A$  and  $B$  in  $R$  and all smooth oriented curves  $C$  from  $A$  to  $B$ .

### Line Integrals on Closed Curves

Let  $R$  in  $\mathbb{R}^2$  (or  $D$  in  $\mathbb{R}^3$ ) be an open region. Then  $\mathbf{F}$  is a conservative vector field on  $R$  if and only if  $\oint_C \mathbf{F} \cdot d\mathbf{r} = 0$  on all simple closed smooth oriented curves  $C$  in  $R$ .



## 15.4 Green's Theorem

Let  $C$  be a simple closed smooth curve, oriented counterclockwise, that encloses a connected and simply connected region  $R$  in the plane. Assume  $\mathbf{F} = \langle f, g \rangle$ , where  $f$  and  $g$  have continuous first partial derivatives in  $R$ . Then

$$\oint_C \mathbf{F} \cdot d\mathbf{r} = \oint_C f dx + g dy = \iint_R \left( \frac{\partial g}{\partial x} - \frac{\partial f}{\partial y} \right) dA. \quad (20)$$

### Two-Dimensional Curl

The **two-dimensional curl** of the vector field  $\mathbf{F} = \langle f, g \rangle$  is  $\frac{\partial g}{\partial x} - \frac{\partial f}{\partial y}$ . If the curl is zero throughout a region, the vector field is said to be **irrotational** on that region.

### Area of a Plane Region by Line Integrals

Under the conditions of Green's Theorem, the area of a region  $R$  enclosed by a curve  $C$  is

$$\oint_C x dy = - \oint_C y dx = \frac{1}{2} \oint_C (x dy - y dx) \quad (21)$$

### Green's Theorem, Flux Form

Let  $C$  be a simple closed smooth curve, oriented counterclockwise, that encloses a connected and simply connected region  $R$  in the plane. Assume  $\mathbf{F} = \langle f, g \rangle$ , where  $f$  and  $g$  have continuous first partial derivatives in  $R$ . Then

$$\oint_C \mathbf{F} \cdot \mathbf{n} ds = \oint_C f dy - g dx = \iint_R \left( \frac{\partial f}{\partial x} + \frac{\partial g}{\partial y} \right) dA \quad (22)$$

where  $\mathbf{n}$  is the outward unit normal vector on the curve.

## Two-Dimensional Divergence

The **two-dimensional divergence** of the vector field  $\mathbf{F} = \langle f, g \rangle$  is  $\frac{\partial f}{\partial x} + \frac{\partial g}{\partial y}$ . If the divergence is zero throughout a region, the vector field is said to be **source free** on that region.

## 15.5 Divergence and Curl

### Divergence of a Vector Field

The **divergence** of a vector field  $\mathbf{F} = \langle f, g, h \rangle$  that is differentiable on a region of  $\mathbb{R}^3$  is

$$\operatorname{div} \mathbf{F} = \nabla \cdot \mathbf{F} = \frac{\partial f}{\partial x} + \frac{\partial g}{\partial y} + \frac{\partial h}{\partial z} \quad (23)$$

If  $\nabla \cdot \mathbf{F} = 0$ , the vector field is **source free**.

### Divergence of Radial Vector Fields

For a real number  $p$ , the divergence of the radial vector field

$$\mathbf{F} = \frac{\mathbf{r}}{|\mathbf{r}|^p} = \frac{\langle x, y, z \rangle}{(x^2 + y^2 + z^2)^{\frac{p}{2}}} \text{ is } \nabla \cdot \mathbf{F} = \frac{3-p}{|\mathbf{r}|^p} \quad (24)$$

### Curl of a Vector Field

The **curl** of a vector field  $\mathbf{F} = \langle f, g, h \rangle$  that is differentiable on a region of  $\mathbb{R}^3$  is

$$\nabla \times \mathbf{F} = \operatorname{curl} \mathbf{F} = \left( \frac{\partial h}{\partial y} - \frac{\partial g}{\partial z} \right) \hat{\mathbf{i}} + \left( \frac{\partial f}{\partial z} - \frac{\partial h}{\partial x} \right) \hat{\mathbf{j}} + \left( \frac{\partial g}{\partial x} - \frac{\partial f}{\partial y} \right) \hat{\mathbf{k}} \quad (25)$$

If  $\nabla \times \mathbf{F} = \mathbf{0}$ , the vector field is **irrotational**.

### Curl of a Conservative Vector Field

The **general rotation vector field** is  $\mathbf{F} = \mathbf{a} \times \mathbf{r}$ , where the nonzero constant vector  $\mathbf{a} = \langle a_1, a_2, a_3 \rangle$  is the axis of rotation and  $\mathbf{r} = \langle x, y, z \rangle$ . For all nonzero choices of  $\mathbf{a}$ ,  $|\nabla \times \mathbf{F}| = 2|\mathbf{a}|$  and  $\nabla \cdot \mathbf{F} = 0$ . The constant angular speed of the vector field is

$$\omega = |\mathbf{a}| = \frac{1}{2} |\nabla \times \mathbf{F}| \quad (26)$$

### Curl of a Conservative Vector Field

Suppose that  $\mathbf{F}$  is a conservative vector field on an open region  $D$  of  $\mathbb{R}^3$ . Let  $\mathbf{F} = \nabla\varphi$ , where  $\varphi$  is a potential function with continuous second partial derivatives on  $D$ . Then  $\nabla \times \mathbf{F} = \nabla \times \nabla\varphi = \mathbf{0}$ ; that is, the curl of the gradient is the zero vector and  $\mathbf{F}$  is irrotational.

### Divergence of the Curl

Suppose that  $\mathbf{F} = \langle f, g, h \rangle$ , where  $f$ ,  $g$ , and  $h$  have continuous second partial derivatives. Then  $\nabla \cdot (\nabla \times \mathbf{F}) = 0$ : The divergence of the curl is zero.

### Product Rule for the Divergence

Let  $u$  be a scalar-valued function that is differentiable on a region  $D$  and let  $\mathbf{F}$  be a vector field that is differentiable on  $D$ . Then

$$\nabla \cdot (u\mathbf{F}) = \nabla u \cdot \mathbf{F} + u(\nabla \cdot \mathbf{F}) \quad (27)$$

### Properties of a Conservative Vector Field

Let  $\mathbf{F}$  be a conservative vector field whose components have continuous second partial derivatives on an open connected region  $D$  in  $\mathbb{R}^3$ . Then  $\mathbf{F}$  has the following equivalent properties.

1. There exists a potential function  $\varphi$  such that  $\mathbf{F} = \nabla\varphi$
2.  $\int_C \mathbf{F} \cdot d\mathbf{r} = \varphi(B) - \varphi(A)$  for all points  $A$  and  $B$  in  $D$  and all smooth oriented curves  $C$  from  $A$  and  $B$ .
3.  $\oint_C \mathbf{F} \cdot d\mathbf{r} = 0$  on all simple smooth closed oriented curves  $C$  in  $D$ .
4.  $\nabla \times \mathbf{F} = \mathbf{0}$  at all points of  $D$ .

## 15.6 Surface Integrals

### Surface Integrals of Scalar-Valued Functions on Parameterized Surface

Let  $f$  be a continuous function on a smooth surface  $S$  given parametrically by  $\mathbf{r}(u, v) = \langle x(u, v), y(u, v), z(u, v) \rangle$ , where  $R = \{(u, v) : a \leq u \leq b, c \leq v \leq d\}$ . Assume also that the tangent vectors  $\mathbf{t}_u = \frac{\partial \mathbf{r}}{\partial u} = \langle \frac{\partial x}{\partial u}, \frac{\partial y}{\partial u}, \frac{\partial z}{\partial u} \rangle$ , and  $\mathbf{t}_v = \frac{\partial \mathbf{r}}{\partial v} = \langle \frac{\partial x}{\partial v}, \frac{\partial y}{\partial v}, \frac{\partial z}{\partial v} \rangle$  are continuous on  $R$  and the normal vectors  $\mathbf{n} = \mathbf{t}_u \times \mathbf{t}_v$  is nonzero on  $R$ . Then the **surface integral** of the scalar-valued function  $f$  over  $S$  is

$$\iint_S f(x, y, z) dS = \iint_R f(x(u, v), y(u, v), z(u, v)) |\mathbf{t}_u \times \mathbf{t}_v| dA \quad (28)$$

If  $f(x, y, z) = 1$ , the integral equals the surface area of  $S$ .

### Evaluation of Surface Integrals of Scalar-Valued Functions on Explicitly Defined Surfaces

Let  $f$  be a continuous function on a smooth surfaces  $S$  given by  $z = g(x, y)$ , for  $(x, y)$  in a region  $R$ . The surface integral of  $f$  over  $S$  is

$$\iint_S f(x, y, z) dS = \iint_R f(x, y, g(x, y)) \sqrt{z_x^2 + z_y^2 + 1} dA \quad (29)$$

If  $f(x, y, z) = 1$ , the surface integral equals the area of the surface.

### Surface Integral of a Vector Field

Suppose  $\mathbf{F} = \langle f, g, h \rangle$  is a continuous vector field on a region of  $\mathbb{R}^3$  containing a smooth oriented surface  $S$ . If  $S$  is defined parametrically as  $\mathbf{r}(u, v) = \langle x(u, v), y(u, v), z(u, v) \rangle$ , for  $(u, v)$  is a region  $R$ , then

$$\iint_S \mathbf{F} \cdot \mathbf{n} dS = \iint_R \mathbf{F} \cdot (\mathbf{t}_u \times \mathbf{t}_v) dA \quad (30)$$

where  $\mathbf{t}_u = \frac{\partial \mathbf{r}}{\partial u} = \langle \frac{\partial x}{\partial u}, \frac{\partial y}{\partial u}, \frac{\partial z}{\partial u} \rangle$  and  $\mathbf{t}_v = \frac{\partial \mathbf{r}}{\partial v} = \langle \frac{\partial x}{\partial v}, \frac{\partial y}{\partial v}, \frac{\partial z}{\partial v} \rangle$  are continuous on  $R$ , the normal vector  $\mathbf{n} = \mathbf{t}_u \times \mathbf{t}_v$  is nonzero on  $R$ , and the direction of  $\mathbf{n}$  is

consistent with the orientation of  $S$ . If  $S$  is defined in the form  $z = g(x, y)$ , for  $(x, y)$  in a region  $R$ , then

$$\iint_S \mathbf{F} \cdot \mathbf{n} \, dS = \iint_R (-f z_x - g z_y + h) \, dA \quad (31)$$

## 15.7 Stokes' Theorem

Let  $S$  be a smooth oriented surface in  $\mathbb{R}^3$  with a smooth closed boundary  $C$  whose orientation is consistent with that of  $S$ . Assume that  $\mathbf{F} = \langle f, g, h \rangle$  is a vector field whose components have continuous first partial derivatives on  $S$ . Then

$$\oint_C \mathbf{F} \cdot d\mathbf{r} = \iint_S (\nabla \times \mathbf{F}) \cdot \mathbf{n} \, dS \quad (32)$$

where  $\mathbf{n}$  is the unit vector normal to  $S$  determined by the orientation of  $S$ .

### Curl $\mathbf{F} = \mathbf{0}$ Implies $\mathbf{F}$ is Conservative

Suppose that  $\nabla \times \mathbf{F} = \mathbf{0}$  throughout an open simply connected region  $D$  of  $\mathbb{R}^3$ . Then  $\oint_C \mathbf{F} \cdot d\mathbf{r} = 0$  on all closed simple smooth curves  $C$  in  $D$  and  $\mathbf{F}$  is a conservative vector field on  $D$ .

## 15.8 Divergence Theorem

Let  $\mathbf{F}$  be a vector field whose components have continuous first partial derivatives in a connected and simply connected region  $D$  in  $\mathbb{R}^3$  enclosed by a smooth oriented surface  $S$ . Then

$$\iint_S \mathbf{F} \cdot \mathbf{n} \, dS = \iiint_D \nabla \cdot \mathbf{F} \, dV \quad (33)$$

where  $\mathbf{n}$  is the unit outward normal vector on  $S$ .

### Divergence Theorem for Hollow Regions

Suppose the vector field  $\mathbf{F}$  satisfies the conditions of the Divergence Theorem on a region  $D$  bounded by two smooth oriented surfaces  $S_1$  and  $S_2$ , where  $S_1$  lies within  $S_2$ . Let  $S$  be the entire boundary of  $D$  ( $S = S_1 \cup S_2$ ) and let  $\mathbf{n}_1$  and  $\mathbf{n}_2$  be the outward unit normal vectors for  $S_1$  and  $S_2$ , respectively. Then

$$\iiint_D \nabla \cdot \mathbf{F} \, dV = \iint_S \mathbf{F} \cdot \mathbf{n} \, dS = \iint_{S_2} \mathbf{F} \cdot \mathbf{n}_2 \, dS + \iint_{S_1} \mathbf{F} \cdot \mathbf{n}_1 \, dS \quad (34)$$