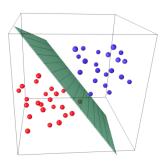
### Linear methods of classification

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- Classifiers
- Estimation of parameters
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## Multiclass general classifier

- Define discriminant functions  $g_c(x)$  for classes  $c = \overline{1, C}$ .
- General classifier:

$$\widehat{y}(x) = \underset{c}{\operatorname{arg max}} g_c(x)$$

Boundary between classes i and j:

$$\{x:g_i(x)=g_j(x)\}$$

• Margin (quality of classification):

$$M(x,y) = g_y(x) - \max_{c \neq y} g_c(x)$$

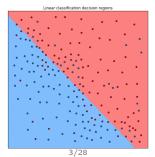
#### Linear classifier

- Include constant feature:  $x = [1, x^2, x^3, ... x^D]$ .
- Linear classifier:

$$g_c(x) = w_c^T x$$
,  $c = \overline{1, C}$ .

• Boundary between classes *i* and *j* is linear:

$$\left\{x: w_i^T x = w_j^T x\right\}$$



## Binary general classifier

- $y \in \{+1, -1\}$ . Discriminant functions:  $g_{+1}(x), g_{-1}(x)$ .
- Define  $g(x) = g_{+1}(x) g_{-1}(x)$  preference for class +1.
- Binary classifier:

$$\widehat{y}(x) = \underset{c \in \{+1,-1\}}{\arg \max} g_c(x) = \underset{c \in \{+1,-1\}}{\gcd} (g_{+1}(x) - g_{-1}(x)) = \underset{c \in \{+1,-1\}}{\gcd} (g(x))$$

• Margin:

$$M(x,y) = g_y(x) - g_{-y}(x) = y (g_{+1}(x) - g_{-1}(x)) = yg(x)$$

## Binary linear classifier

- Discriminant functions:  $w_{+1}^T x, w_{-1}^T x$ .
- Define  $w = w_{+1} w_{-1}$ .
- Binary linear classifier:

$$\widehat{y}(x) = \underset{c \in \{+1, -1\}}{\arg \max} \ w_c^T x = \operatorname{sign}\left(w_{+1}^T x - w_{-1}^T x\right) = \operatorname{sign}\left(w^T x\right)$$

Margin:

$$M(x,y) = w_y^T x - w_{-y}^T x = y \left( w_{+1}^T x - w_{-1}^T x \right) = y w^T x = w^T x y$$

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#### Estimation of w

• Select w to minimize # of misclassifications:

$$\sum_{n=1}^{N} \mathbb{I}\left[w^{T} x_{n} y_{n} < 0\right] \to \min_{w}$$

- Piecewise constant criterion, gradient=0 almost everywhere.
  - can't use optimization methods to find minimum!
- Use decreasing  $\mathcal L$  with non-trivial gradients:

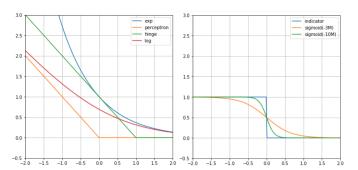
$$\sum_{n=1}^{N} \mathcal{L}\left(w^{T} x_{n} y_{n}\right) \to \min_{w}$$

For general binary classifier can use:

$$\sum_{n=1}^{N} \mathcal{L}\left(y_n g_w(x_n)\right) o \min_{w}, \quad w ext{-parameters of } g(x)$$

#### Common loss functions

$$\mathcal{L}_{exp}(M) = e^{-M} \quad \mathcal{L}_{perceptron}(M) = [-M]_+ \ \mathcal{L}_{hinge}(M) = [1-M]_+ \quad \mathcal{L}_{log}(M) = \ln\left(1+e^{-M}
ight)$$



Check properties: robustness to outliers, convexity, penalization for small positive margin.  $$_{8/28}$$ 

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### Regularization

• Insert additional requirement for regularizer  $R(\beta)$  to be small:

$$\sum_{n=1}^{N} \mathcal{L}\left(M(x_n, y_n|w) + \lambda R(w) \to \min_{\beta}$$

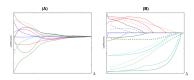
- $\lambda > 0$  hyperparameter.
- R(w) penalizes complexity of models.

$$\begin{array}{ll} R(\beta) = ||w||_1 & L_1 \text{ regularization} \\ R(\beta) = ||w||_2^2 & L_2 \text{ regularization} \\ R(\beta) = \alpha \left\|w\right\|_1 + (1 - \alpha) \left\|w\right\|_2^2 & \text{combination with } \alpha \in (0, 1) \end{array}$$

- Not only accuracy matters for the solution but also model simplicity!
- $\lambda$  controls complexity of the model:  $\uparrow \lambda \Leftrightarrow \text{complexity} \downarrow$ .

#### Comments

• Dependency of  $\beta$  from  $\lambda$  for  $L_2$  (A) and  $L_1$  (B) regularization:



- L<sub>2</sub> can be used for automatic feature selection.
- $\lambda$  is usually found using cross-validation on exponential grid, e.g.  $[10^{-6}, 10^{-5}, ... 10^{5}, 10^{6}]$ .
- It's always recommended to use regularization because
  - it gives smooth control over model complexity.
  - reduces ambiguity for multiple solutions case.

#### Different account for different features

• Traditional approach regularizes all features uniformly:

$$\sum_{n=1}^{N} \mathcal{L}\left(M(x_n, y_n|w)\right) + \lambda R(w) \to \min_{w}$$

• Suppose we have *K* groups of features with indices:

$$I_1, I_2, ... I_K$$

 We may control the impact of each feature group by minimizing:

$$\sum_{n=1}^{N} \mathcal{L}(M(x_n, y_n | w)) + \lambda_1 R(\{w_i | i \in I_1\}) + ... + \lambda_K R(\{w_i | i \in I_K\})$$

- $\lambda_1, \lambda_2, ... \lambda_K$  can be set using cross-validation
- In practice use common regularizer but with different feature scaling.

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# Orthogonal vector to hyperplane

#### Theorem 1

Vector w is orthogonal to hyperplane  $w^Tx + w_0 = 0$ 

*Proof.* Consider arbitrary  $x_A, x_B \in \{x : w^T x + w_0 = 0\}$ :

$$w^T x_A + w_0 = 0 \tag{1}$$

$$w^T x_B + w_0 = 0 (2)$$

By substracting (2) from (1), obtain  $w^T(x_A - x_B) = 0$ , so w is orthogonal to hyperplane.

## Distance from point to hyperplane

#### Theorem 2

Distance from point x to hyperplane  $w^Tx + w_0 = 0$  is equal to  $\frac{w^Tx + w_0}{\|\|w_0\|\|}$ .

*Proof.* Project x on the hyperplane, let the projection be p and complement h = x - p, orthogonal to hyperplane. Then

$$x = p + h$$

Since p lies on the hyperplane,

$$w^{T}p + w_{0} = 0$$

Since h is orthogonal to hyperplane and according to theorem 1

$$h=rrac{w}{||w||},\ r\in\mathbb{R}$$
 - distance to hyperplane.

## Distance from point to hyperplane

$$x = p + r \frac{w}{\|w\|}$$

After multiplication by w and addition of  $w_0$ :

$$w^{T}x + w_{0} = w^{T}p + w_{0} + r\frac{w^{T}w}{\|w\|} = r\|w\|$$

because  $w^T p + w_0 = 0$  and  $||w|| = \sqrt{w^T w}$ . So we get, that

$$r = \frac{w^T x + w_0}{\|w\|}$$

#### Comments:

- From one side of hyperplane  $r > 0 \Leftrightarrow w^T x + w_0 > 0$
- From the other side  $r < 0 \Leftrightarrow w^T x + w_0 < 0$ .
- Distance from hyperplane to origin 0 is  $\frac{w_0}{\|w\|}$ . So  $w_0$  accounts for hyperplane offset.

## Binary linear classifier geometric interpretation

Binary linear classifier:

$$\widehat{y}(x) = \operatorname{sign}\left(w^T x + w_0\right)$$

divides feature space by hyperplane  $w^T x + w_0 = 0$ .

- Confidence of decision is proportional to distance to hyperplane  $\frac{\left|w^Tx+w_0\right|}{\left|\left|w\right|\right|}$ .
- $w^T x + w_0$  is the confidence that class is positive.

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## Binary classification

Linear classifier:

$$score(y = 1|x) = w^T x$$

• +relationship between score and class probability is assumed:

$$p(y=1|x) = \sigma(w^T x)$$

where 
$$\sigma(z) = \frac{1}{1+e^{-z}}$$
 - sigmoid function

### Binary classification: estimation

Using the property  $1 - \sigma(z) = \sigma(-z)$  obtain that

$$p(y = +1|x) = \sigma(w^Tx) \Longrightarrow p(y = -1|x) = \sigma(-w^Tx)$$

So for  $y \in \{+1, -1\}$ 

$$p(y|x) = \sigma(y\langle w, x \rangle)$$

Therefore ML estimation can be written as:

$$\prod_{i=1}^N \sigma(\langle w, x_i \rangle y_i) \to \max_w$$

## Loss function for 2-class logistic regression

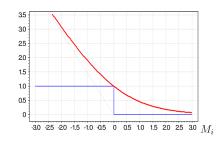
For binary classification 
$$p(y|x) = \sigma(\langle w, x \rangle y) \ w = [\beta'_0, \beta],$$
  
  $x = [1, x_1, x_2, ... x_D].$ 

#### Estimation with ML:

$$\prod_{i=1}^N \sigma(\langle w, x_i \rangle y_i) \to \max_w$$

which is equivalent to

$$\sum_{i=1}^N \ln(1+e^{-\langle w,x_i
angle y_i}) 
ightarrow \min_w$$



It follows that logistic regression is linear discriminant estimated with loss function  $\mathcal{L}(M) = \ln(1 + e^{-M})$ .

## Multiple classes

Multiple class classification:

$$\begin{cases} score(\omega_1|x) = w_1^T x \\ score(\omega_2|x) = w_2^T x \\ \dots \\ score(\omega_C|x) = w_C^T x \end{cases}$$

+relationship between score and class probability is assumed:

$$p(\omega_c|x) = softmax(w_c^T x | x_1^T x, ... x_C^T x) = \frac{exp(w_c^T x)}{\sum_i exp(w_i^T x)}$$

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## Multiclass classification with binary classifiers

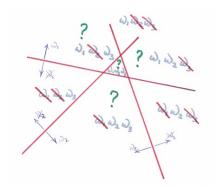
- Task make C-class classification using many binary classifiers.
- Approaches:
  - one-versus-all
    - for each c = 1, 2, ... C train binary classifier on all objects and output  $\mathbb{I}[y_n = c]$ ,
    - assign class, getting the highest score in resulting C classifiers.

#### one-versus-one

- for each  $i, j \in [1, 2, ... C]$ ,  $i \neq j$  learn on objects with  $y_n \in \{i, j\}$  with output  $y_n$
- assign class, getting the highest score in resulting C(C-1)/2 classifiers.
- error correcting codes

## One versus all - ambiguity

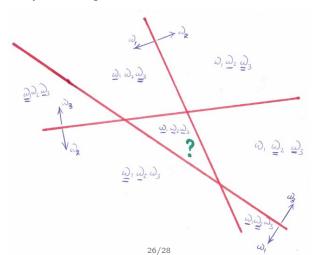
Classification among three classes:  $\omega_1, \omega_2, \omega_3$ 





# One versus one - ambiguity

Classification among three classes  $\omega_1, \omega_2, \omega_3$  depending only on halfspace may be ambiguous:



## Error correcting codes

- Used in classification
- Each class  $\omega_i$  is coded as a binary codeword  $W_i$  consisting of B bits:

class 
$$i \rightarrow W_i$$

- Minimum sufficient amount of bits to code C classes is  $\lceil \log_2 C \rceil$
- Given x, B binary classifiers predict each bit of the class codeword.
- Class is predicted as

$$\hat{c}(x) = \arg\min_{c} \sum_{b=1}^{B} |W_{cb} - \widehat{p}_b(x)|$$

- where  $W_{cb}$  is the b-th bit of codeword, corresponding to class c.
- More bits are used to make classification more robust to errors of individual binary classifiers.
- Codewords are selected to have maximum mutual Hamming distance or randomly.

## Summary

- Linear classifier classifier with linear discriminant functions.
- Binary linear classifier:  $\hat{y}(x) = \text{sign}(w^T x + w_0)$ .
- Perceptron, logistic, SVM linear classifiers estimated with different loss functions.
- Weights are selected to minimize total loss on margins.
- Regularization gives smooth control over model complexity.
- ullet  $L_1$  regularization automatically selects features.