

Singular value decomposition

Victor Kitov

v.v.kitov@yandex.ru

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SVD decomposition

Every matrix $X \in \mathbb{R}^{N \times D}$, $\text{rank } X = R$, can be decomposed into the product of three matrices:

$$X = U \Sigma V^T$$

where

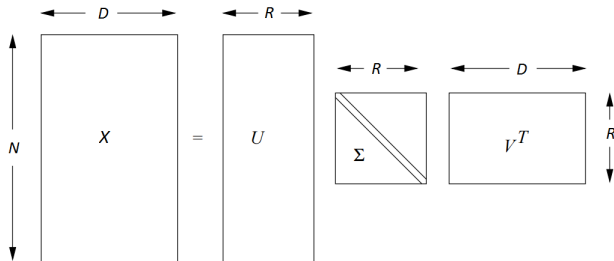
- $U \in \mathbb{R}^{N \times R}$, $\Sigma \in \mathbb{R}^{R \times R}$, $V^T \in \mathbb{R}^{R \times D}$
- $\Sigma = \text{diag}\{\sigma_1, \sigma_2, \dots, \sigma_R\}$, $\sigma_1 \geq \sigma_2 \geq \dots \geq \sigma_R \geq 0$
- $U^T U = I$, $V^T V = I$, where $I \in \mathbb{R}^{R \times R}$ is identity matrix.

Equivalent:

$$X = \sum_{i=1}^R u_i \sigma_i v_i^T$$

where u_i - i -th column of U and v_i^T - i -th row of V^T .

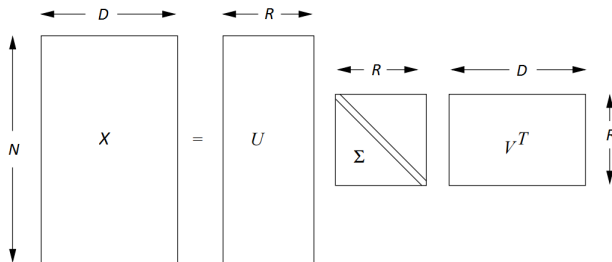
Interpretation of SVD



For X_{ij} let i denote objects and j denote properties.

- Columns of U - orthonormal basis of columns of X
- Rows of V^T - orthonormal basis of rows of X
- Σ - scaling.
- Efficient representations of low-rank matrix!

Interpretation of SVD



For X_{ij} let i denote objects and j denote properties.

- Rows of U are normalized coordinates of rows in V^T
- $\Sigma = \text{diag}\{\sigma_1, \dots, \sigma_R\}$ shows the magnitudes of presence of each row from V^T .

Finding V

$$X^T X = \left(U \Sigma V^T \right)^T U \Sigma V^T = (V \Sigma U^T) U \Sigma V^T = V \Sigma^2 V^T$$

It follows that¹

$$X^T X V = V \Sigma^2 V^T V = V \Sigma^2 \quad (1)$$

So V consists of eigenvectors of $X^T X$ with corresponding eigenvalues $\sigma_1^2, \sigma_2^2, \dots, \sigma_R^2$ - **these are top R principal components!**

¹Singular values for matrix X are square roots of eigenvalues of $X^T X$. From (1) it follows that $\sigma_1, \dots, \sigma_R$ are singular values of X .

Finding U

$$XX^T = U\Sigma V^T (U\Sigma V^T)^T = U\Sigma V^T V \Sigma U^T = U\Sigma^2 U^T$$

It follows that

$$XX^T U = U\Sigma^2 U^T U = U\Sigma^2.$$

So U consists of eigenvectors of XX^T with corresponding eigenvalues $\sigma_1^2, \sigma_2^2, \dots, \sigma_R^2$.

SVD: existence & uniqueness

Theorem 1

For any matrix $X \in \mathbb{R}^{N \times D}$ SVD decomposition exists.

Theorem 2

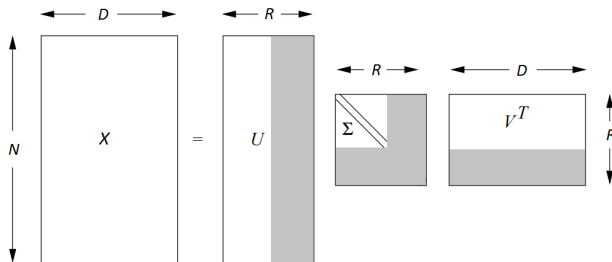
SVD decomposition is unique up to sign $\Leftrightarrow X^T X \in \mathbb{R}^{D \times D}$ has a set of D unique eigenvalues.

Unique up to sign means that we can always simultaneously change signs of u_i and v_i^T for $\forall i = 1, 2, \dots, R$.

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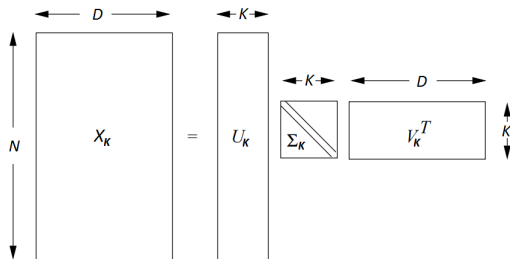
Truncated SVD decomposition



- Truncation: remove least important columns of U and rows of V^T .
- Importance measures by $\sigma_1, \sigma_2, \dots, \sigma_R$.
- So replace

$$\text{diag}\{\sigma_1, \sigma_2, \dots, \sigma_K, \sigma_{K+1}, \dots, \sigma_R\} \longrightarrow \text{diag}\{\sigma_1, \sigma_2, \dots, \sigma_K, 0, 0, \dots, 0\}$$

Truncated SVD decomposition



Simplification to rank $K \leq R$:

$$X_K = U_K \Sigma_K V_K \approx X$$

$$\Sigma = \text{diag}\{\sigma_1, \sigma_2, \dots, \sigma_K, \sigma_{K+1}, \dots, \sigma_R\} \longrightarrow \text{diag}\{\sigma_1, \sigma_2, \dots, \sigma_K\} = \Sigma_K$$

$$U = [u_1, u_2, \dots, u_K, u_{K+1}, \dots, u_R] \longrightarrow [u_1, u_2, \dots, u_K] = U_K$$

$$V = [v_1, v_2, \dots, v_K, v_{K+1}, \dots, v_R] \longrightarrow [v_1, v_2, \dots, v_K] = V_K$$

Properties of truncated SVD decomposition

Frobenius norm of matrix

$$\|X\|_F^2 = \sum_{n=1}^N \sum_{d=1}^D x_{nd}^2$$

- For matrix X and its approximation \hat{X} we can measure

$$\text{approximation error} = \|\hat{X} - X\|_F^2$$

Theorem 3

Suppose $X \in \mathbb{R}^{N \times D}$, is approximated with $\hat{X}_K = U_K \Sigma_K V_K$. Then:

- 1 rank $X_K = K$.
- 2 $X_K = \arg \min_{B: \text{rank } B \leq K} \|X - B\|_F^2$

Which K to choose for approximation?

Theorem 4

For any matrix X and its SVD decomposition $X = U\Sigma V^T$, $\Sigma = \text{diag}\{\sigma_1, \dots, \sigma_R\}$:

$$\|X\|_F^2 = \sum_{i=1}^R \sigma_i^2$$

- Suppose $X = U\Sigma V^T$, $\Sigma = \text{diag}\{\sigma_1, \dots, \sigma_R\}$
- Approximation $\hat{X}_K = U\Sigma_K V^T$,
 $\Sigma_K = \text{diag}\{\sigma_1, \dots, \sigma_K, 0, 0, \dots, 0\}$.
- Then error $X - \hat{X}_K = U\tilde{\Sigma}V^T$, where
 $\tilde{\Sigma} = \text{diag}\{0, 0, \dots, \sigma_{K+1}, \dots, \sigma_R\}$, so

$$\|X - \hat{X}_K\|_F^2 = \sum_{i=K+1}^R \sigma_i^2$$

Which K to choose for approximation?

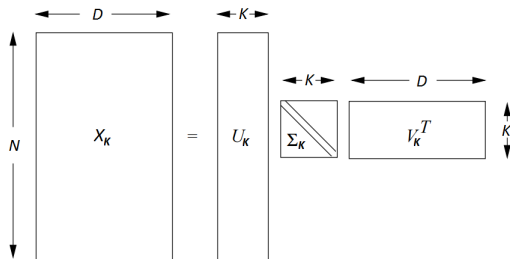
Using theorem 4, we can select K giving relative error below some threshold t :

$$K = \arg \min_K \left\{ \frac{\|X - \hat{X}_K\|_F^2}{\|X\|_F^2} = \frac{\sum_{i=K+1}^R \sigma_i^2}{\sum_{i=1}^R \sigma_i^2} < t \right\}$$

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Dimensionality reduction



- rows of U give truncated representation of rows of X .
- $x_n \in \mathbb{R}^D \longrightarrow u_n \in \mathbb{R}^K, \quad K \leq D$.

Memory efficiency

Storage costs of $X \in \mathbb{R}^{N \times D}$, assuming $N \geq D$ and each element taking 1 byte:

Memory storage costs

representation of X	memory requirements
original X	?
fully SVD decomposed	?
truncated SVD to rank K	?

Performance efficiency

- Multiplication Xq
 - X - normalized documents representation
 - q - normalized search query

representation of X	Xq complexity
original X	?
truncated SVD to rank K	?

Finding similar objects and similar features

- Similar objects have co-appearing features.
- Similar features co-appear in objects.
- Example: text analysis.
 - LSA gives compact representations, invariant to synonyms
 - can compare documents
 - can compare words

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Example

	Terminator	Gladiator	Rambo	Titanic	Love story	A walk to remember
Andrew	4	5	5	0	0	0
John	4	4	5	0	0	0
Matthew	5	5	4	0	0	0
Anna	0	0	0	5	5	5
Maria	0	0	0	5	5	4
Jessica	0	0	0	4	5	4

Example

$$U = \begin{pmatrix} 0. & 0.6 & -0.3 & 0. & 0. & -0.8 \\ 0. & 0.5 & -0.5 & 0. & 0. & 0.6 \\ 0. & 0.6 & 0.8 & 0. & 0. & 0.2 \\ 0.6 & 0. & 0. & -0.8 & -0.2 & 0. \\ 0.6 & 0. & 0. & 0.2 & 0.8 & 0. \\ 0.5 & 0. & 0. & 0.6 & -0.6 & 0. \end{pmatrix}$$

$$\Sigma = \text{diag}\{(14. \quad 13.7 \quad 1.2 \quad 0.6 \quad 0.6 \quad 0.5)\}$$

$$V^T = \begin{pmatrix} 0. & 0. & 0. & 0.6 & 0.6 & 0.5 \\ 0.5 & 0.6 & 0.6 & 0. & 0. & 0. \\ 0.5 & 0.3 & -0.8 & 0. & 0. & 0. \\ 0. & 0. & 0. & -0.2 & 0.8 & -0.6 \\ -0. & -0. & -0. & 0.8 & -0.2 & -0.6 \\ 0.6 & -0.8 & 0.2 & 0. & 0. & 0. \end{pmatrix}$$

Example (excluded insignificant concepts)

$$U_2 = \begin{pmatrix} 0. & 0.6 \\ 0. & 0.5 \\ 0. & 0.6 \\ 0.6 & 0. \\ 0.6 & 0. \\ 0.5 & 0. \end{pmatrix}$$

$$\Sigma_2 = \text{diag}\{(14. \quad 13.7)\}$$

$$V_2^T = \begin{pmatrix} 0. & 0. & 0. & 0.6 & 0.6 & 0.5 \\ 0.5 & 0.6 & 0.6 & 0. & 0. & 0. \end{pmatrix}$$

Concepts may be

- patterns among movies (along j) - action movie / romantic movie
- patterns among people (along i) - boys / girls

Dimensionality reduction case: patterns along j axis.

Applications

- Example: new movie rating by new person

$$x = (5 \ 0 \ 0 \ 0 \ 0 \ 0)$$

- **Dimensionality reduction:** map x into concept space:

$$y = V_2^T x = (0 \ 2.7)$$

- **Recommendation system:** map y back to original movies space:

$$\hat{x} = yV_2^T = (1.5 \ 1.6 \ 1.6 \ 0 \ 0 \ 0)$$

Summary

- SVD decomposition $X = U\Sigma V^T$, $U^T U = I$, $V^T V = I$, $\Sigma = \text{diag}\{\sigma_1, \dots, \sigma_R\}$ exists $\forall X$.
- Reduced SVD decomposition of order K solves:

$$X_K = \arg \min_{B: \text{rank } B \leq K} \|X - B\|_F^2$$

- SVD (reduced SVD) extracts structure of large matrices with small (close to small) rank
 - gives intuitive representation
 - efficient representations
 - fast matrix multiplications
- Helpful in recommendation engines
 - pitfall: treats 0 (no vote) as real vote.