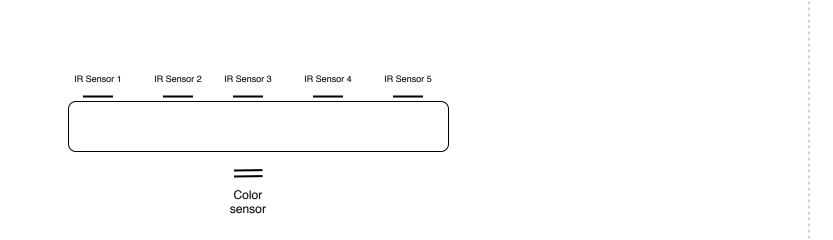
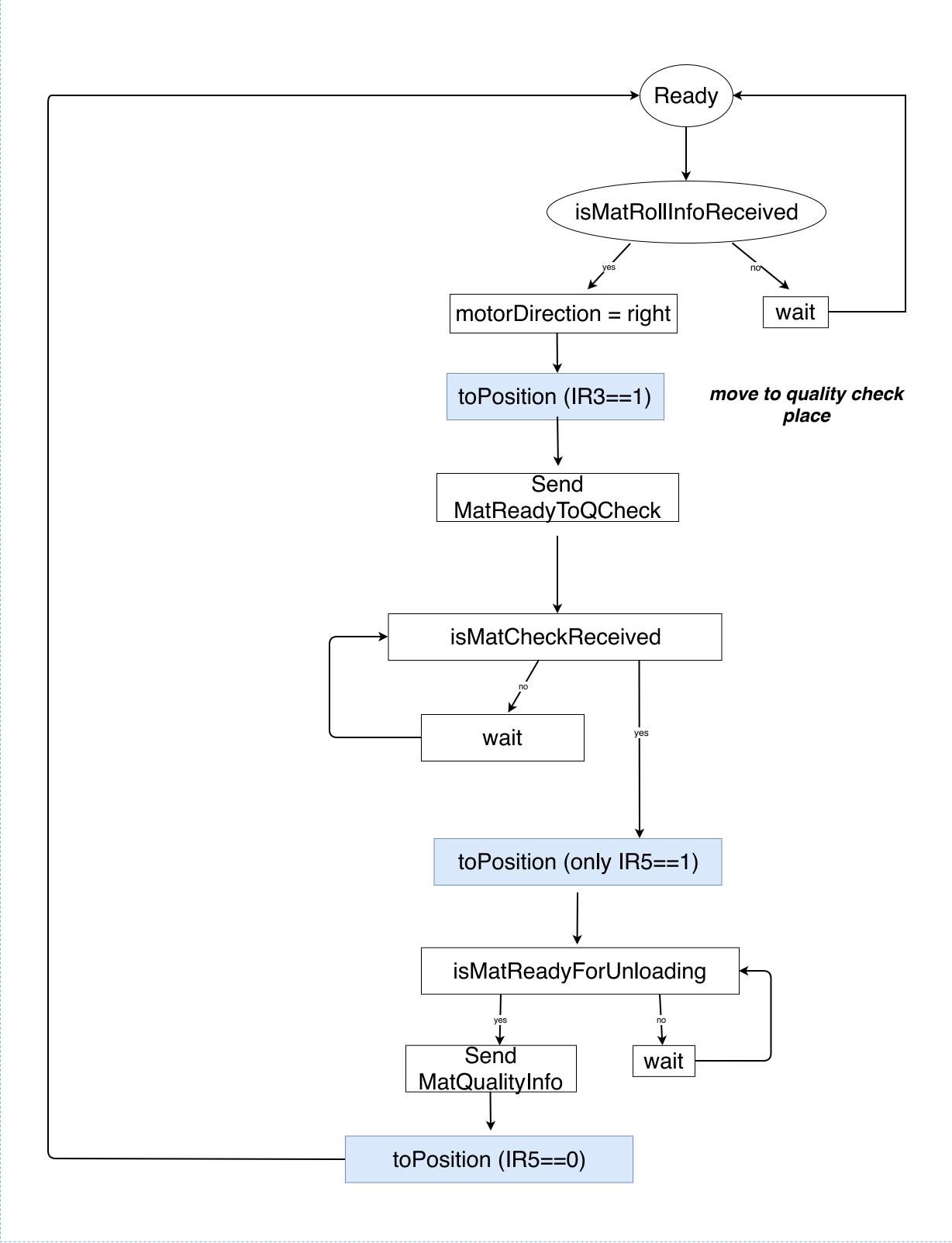
3) Quality





Motor run Check IR Send position condition isPositionChanged Motor stop