

# Domain Adversarial Learning for Reducing Training Bias in ttH(bb) search at ATLAS

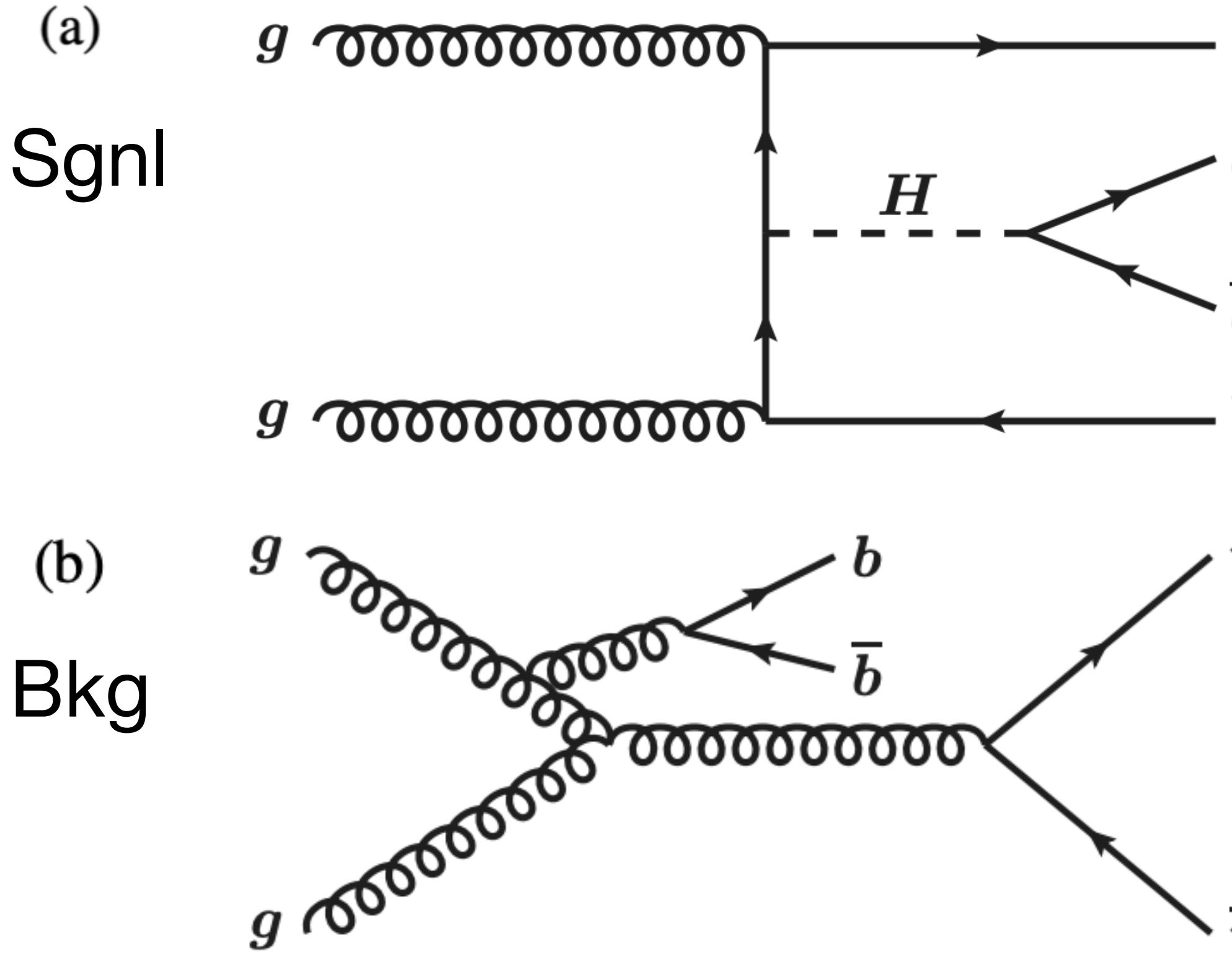
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*Supervisors: Glaysher P., Katzy J., Pollard C.*

*ATLAS, DESY*  
2019

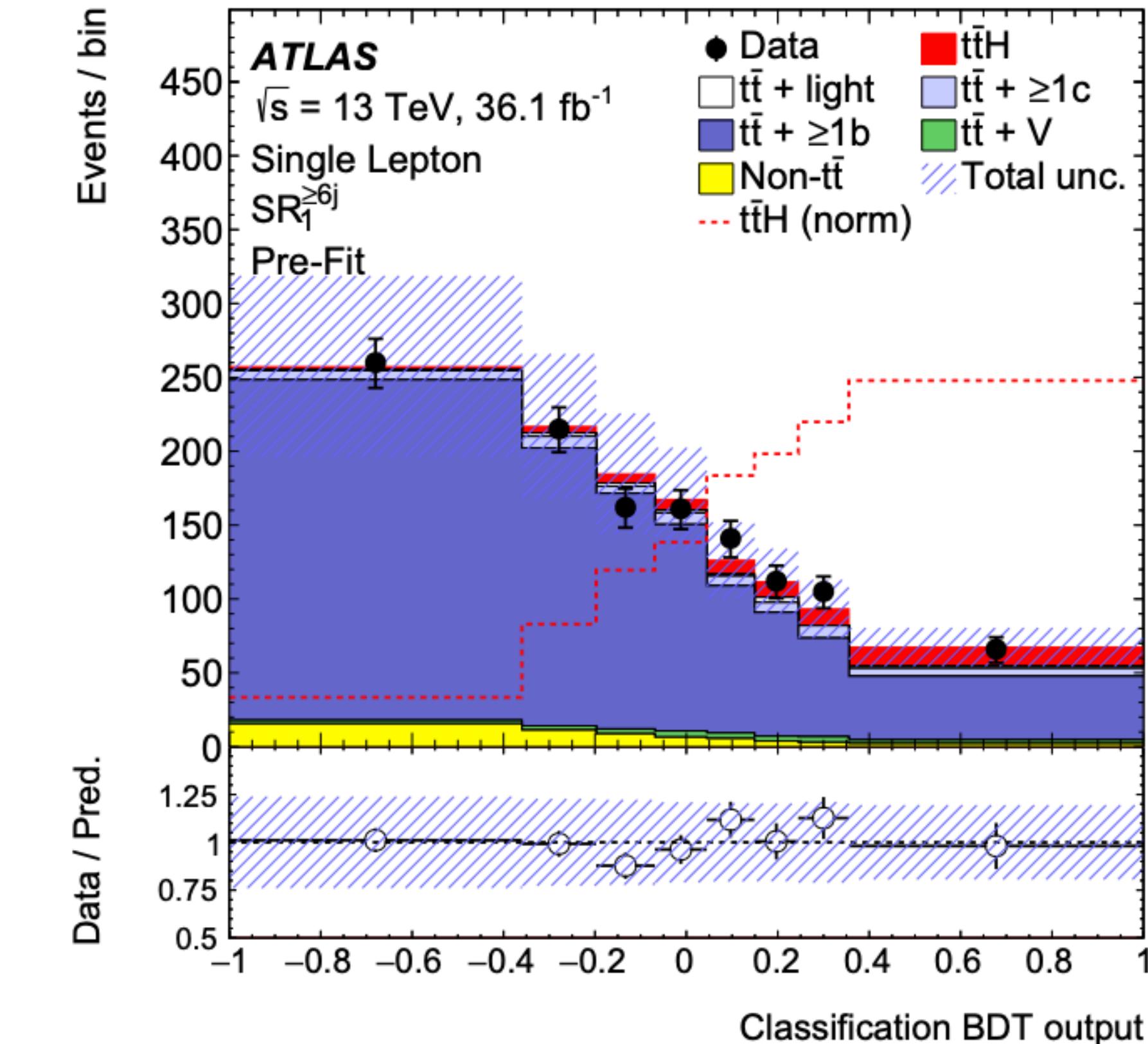
# Outline

- Introduction
- Classification of  $t\bar{t}H(bb)$  vs  $t\bar{t}bb$  bkg
- Idea of Adversarial Domain Adaptation
- Results

# ttH(bb) Production Search



Feynman diagrams for a) ttH(bb) production b) tt+bb background



- Systematic uncertainties come because of different simulations
- The goal is to minimise this uncertainty while preserving good classification performance

# Domain Adaptation

GTA V

What we do

GTA Vice  
City



Source 1

Source 2

Future perspectives ?

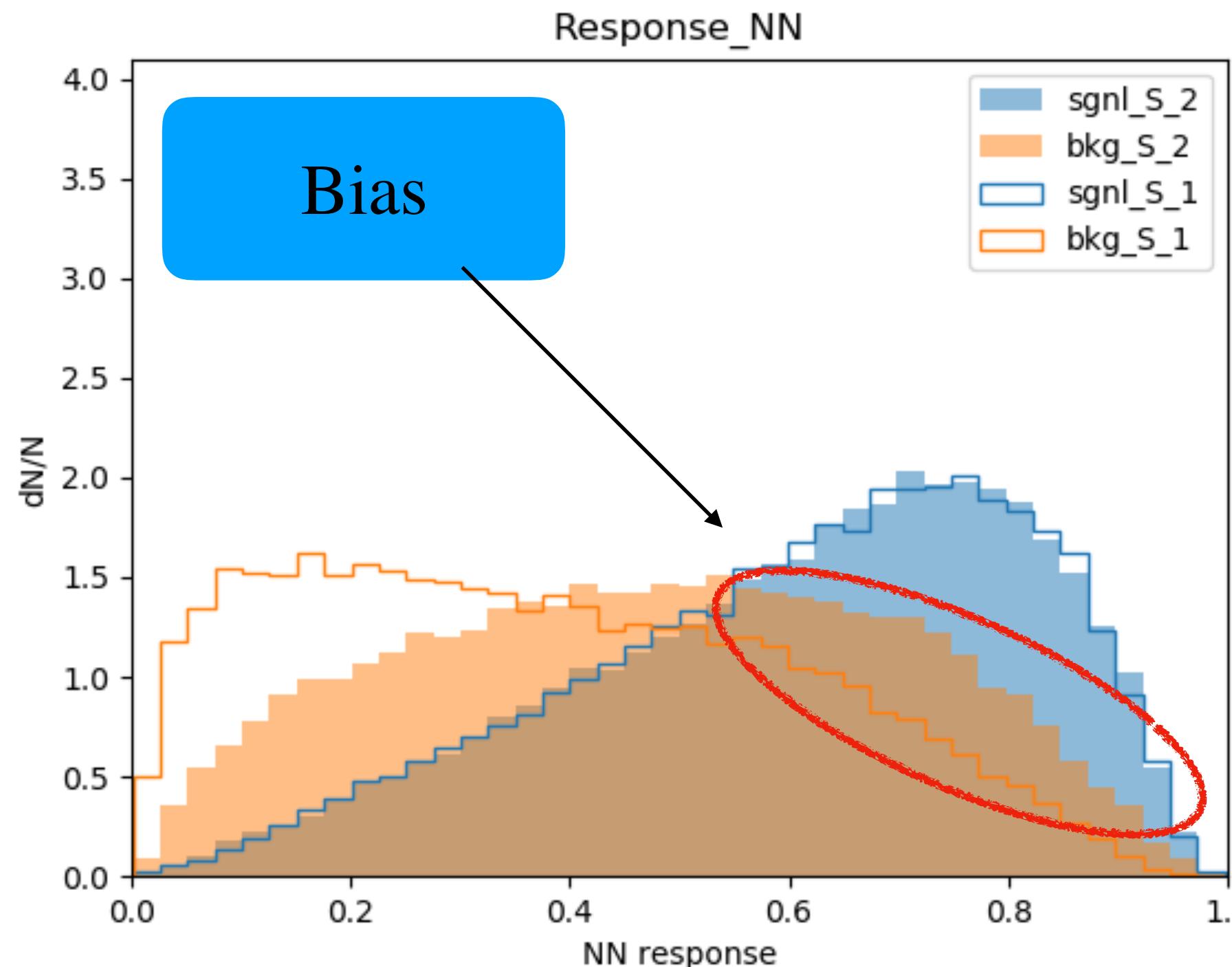


Bike

House



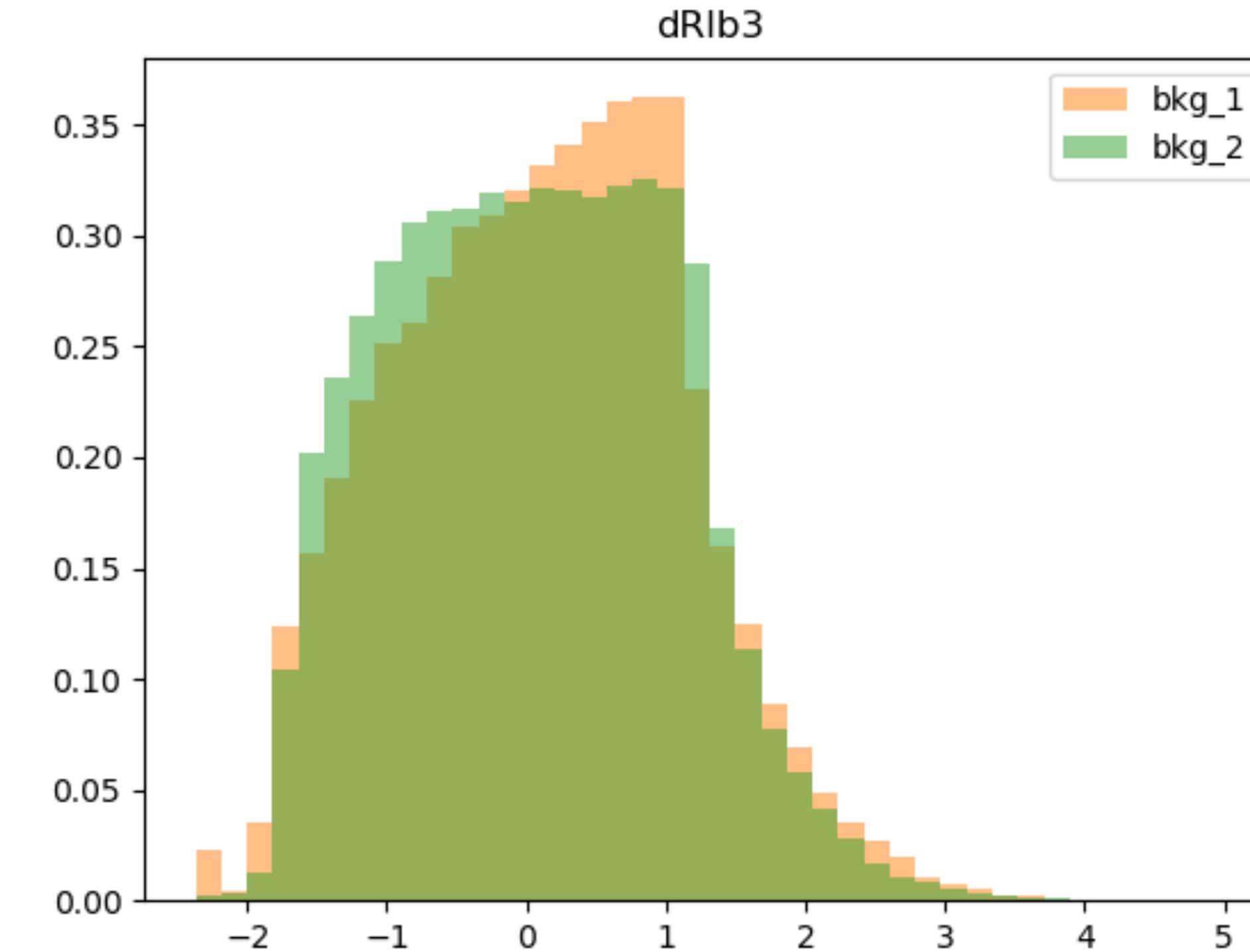
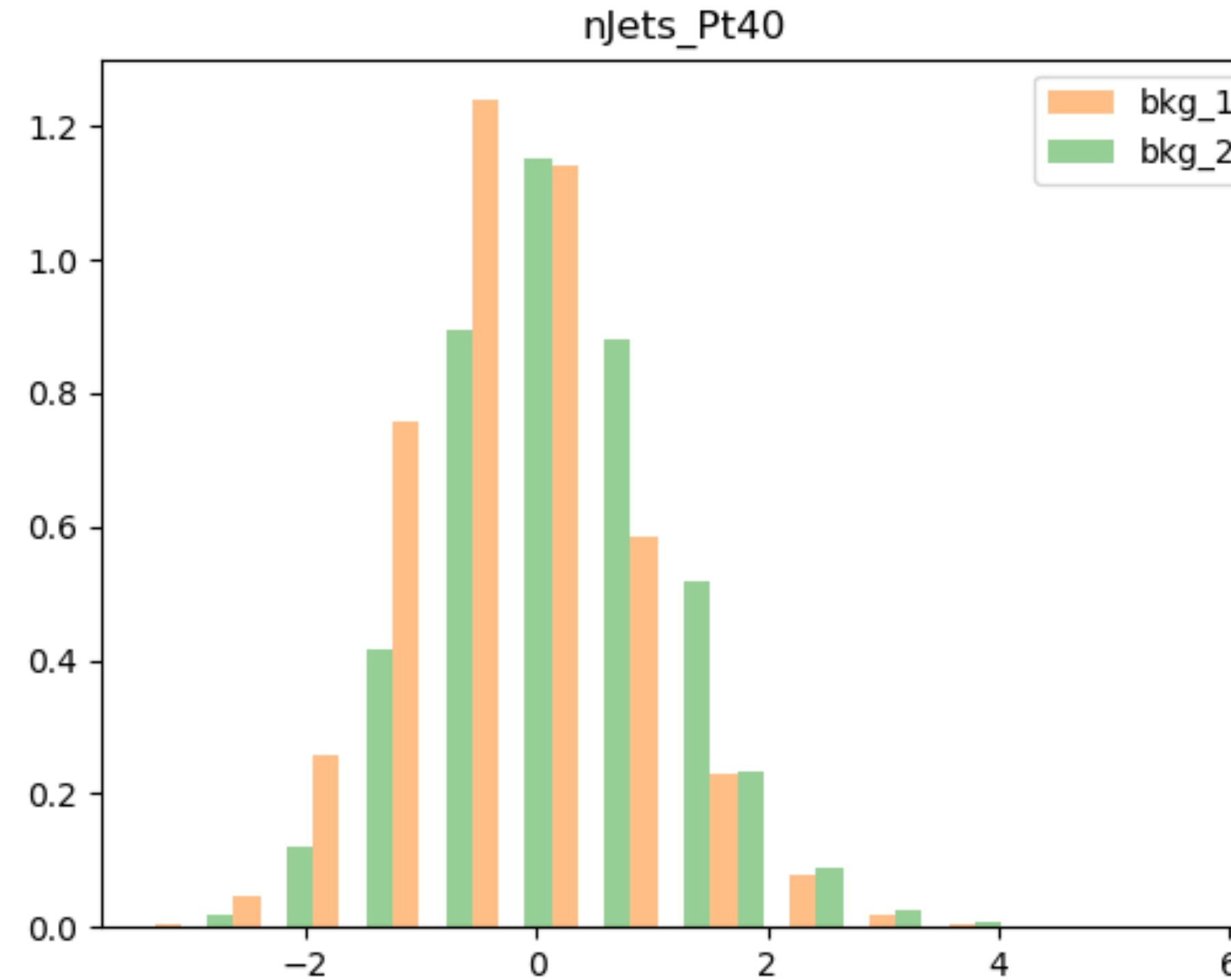
# Motivation



Performance of baseline Feed Forward NN with 3 hidden layers

- We have one signal and two different background simulations
- It's been noted that if we train NN classifier on data with one background simulation and apply it to the test data with another background, its performance is reduced significantly
- This happens because backgrounds are slightly different
- Domain adaptation techniques [1] are hoped to reduce the training bias of NN and show good performance

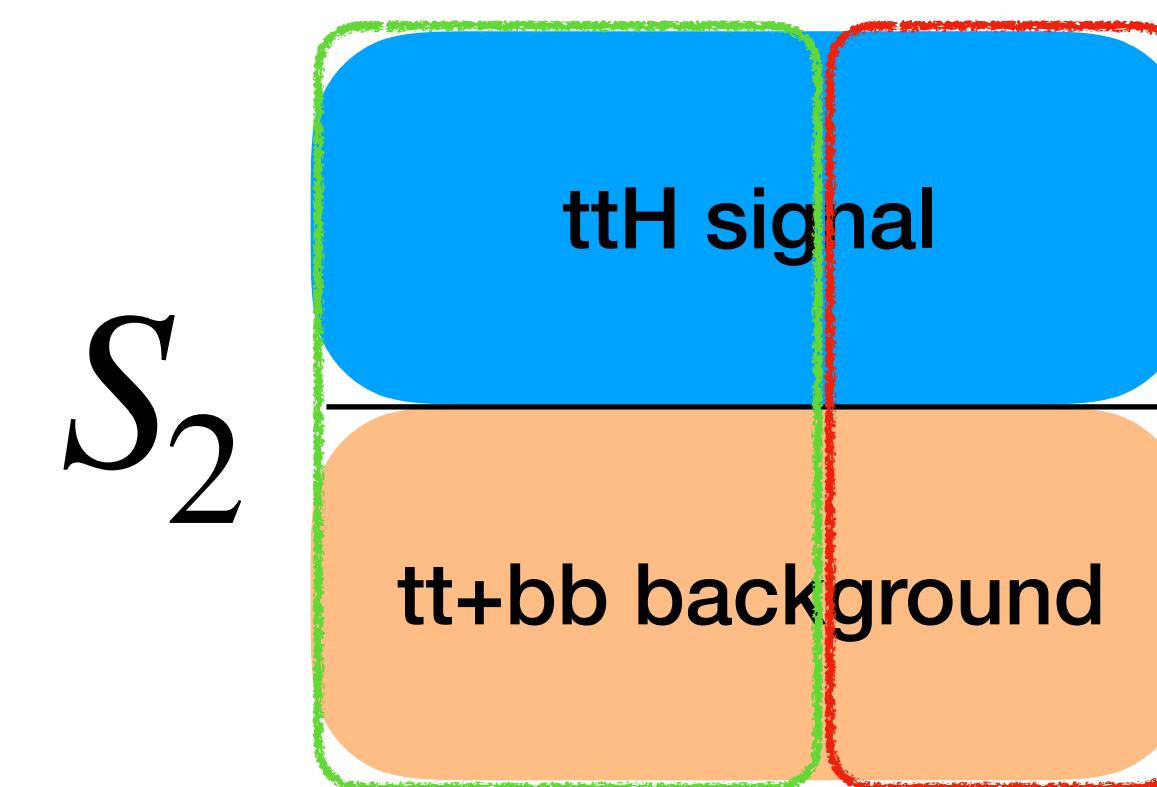
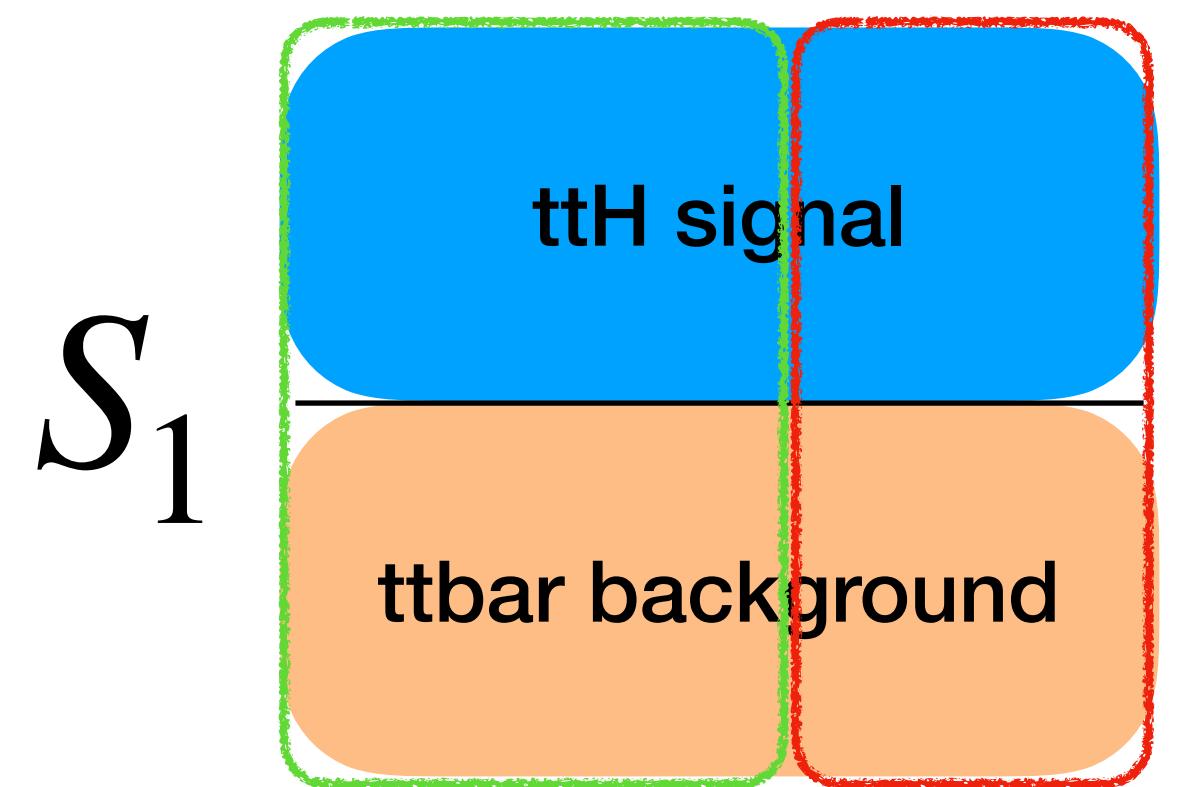
# Background distributions



- $bkg\_1 = ttbar$  background: *MadGraph / Pythia6*
- $bkg\_2 = tt+bb$  background: *Powheg Pythia8*
- *Two background simulations are similar in distribution shapes, but there is some difference.*

# Notations

- $\mathcal{X}$  an input space (40 variables)
- $\mathcal{Y} = \{0,1\}$  a set of classes (if an event comes from signal or background)
- We define domain as a pair  $\langle \mathcal{D}, f \rangle$  consisting of distribution  $\mathcal{D}$  on  $\mathcal{X}$  and a labelling function  $f$  on  $\mathcal{X} \times \mathcal{Y}$ .
- $S_1$  and  $S_2$  denote two datasets obtained from domains Source 1  $\langle \mathcal{D}_{S_1}, f_{S_1} \rangle$  and Source 2  $\langle \mathcal{D}_{S_1}, f_{S_1} \rangle$

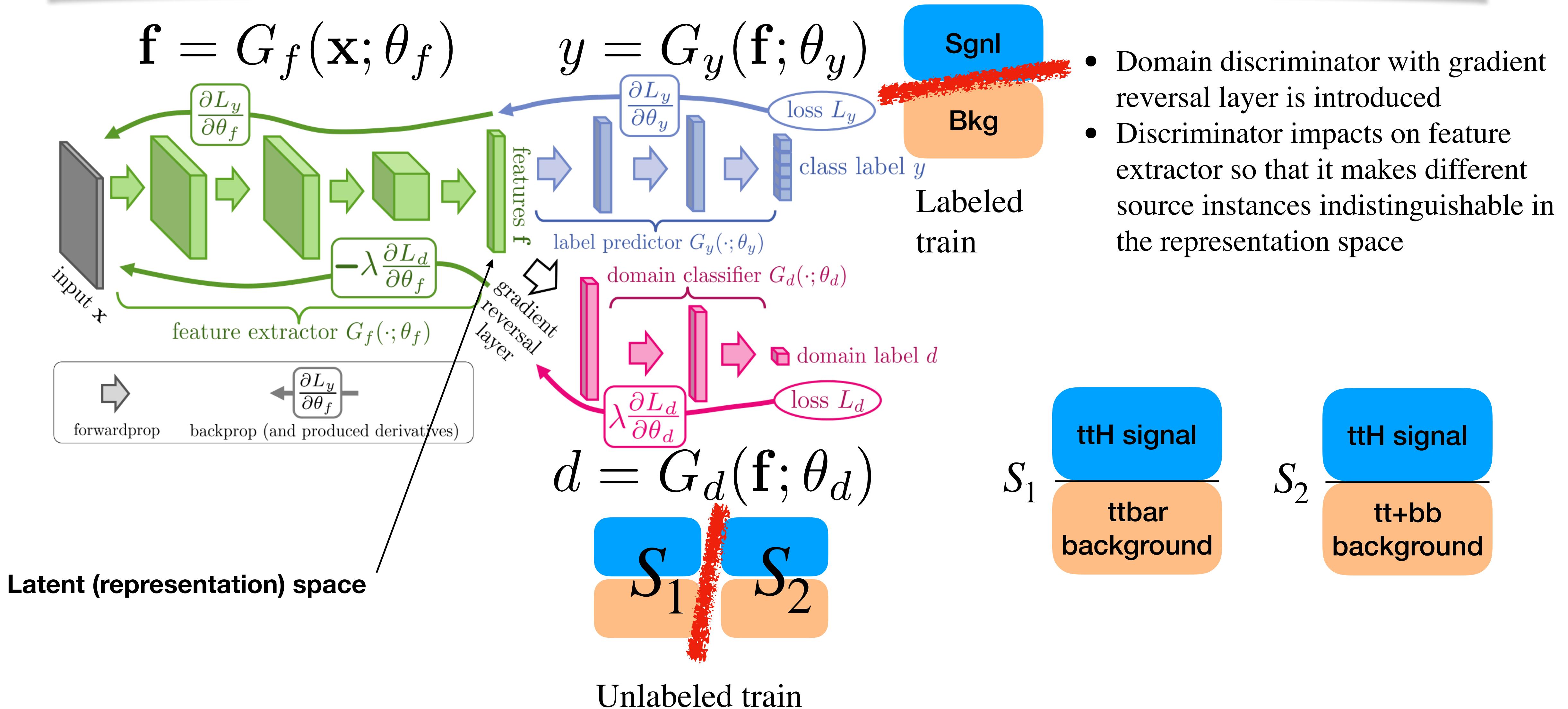


*Source 1*

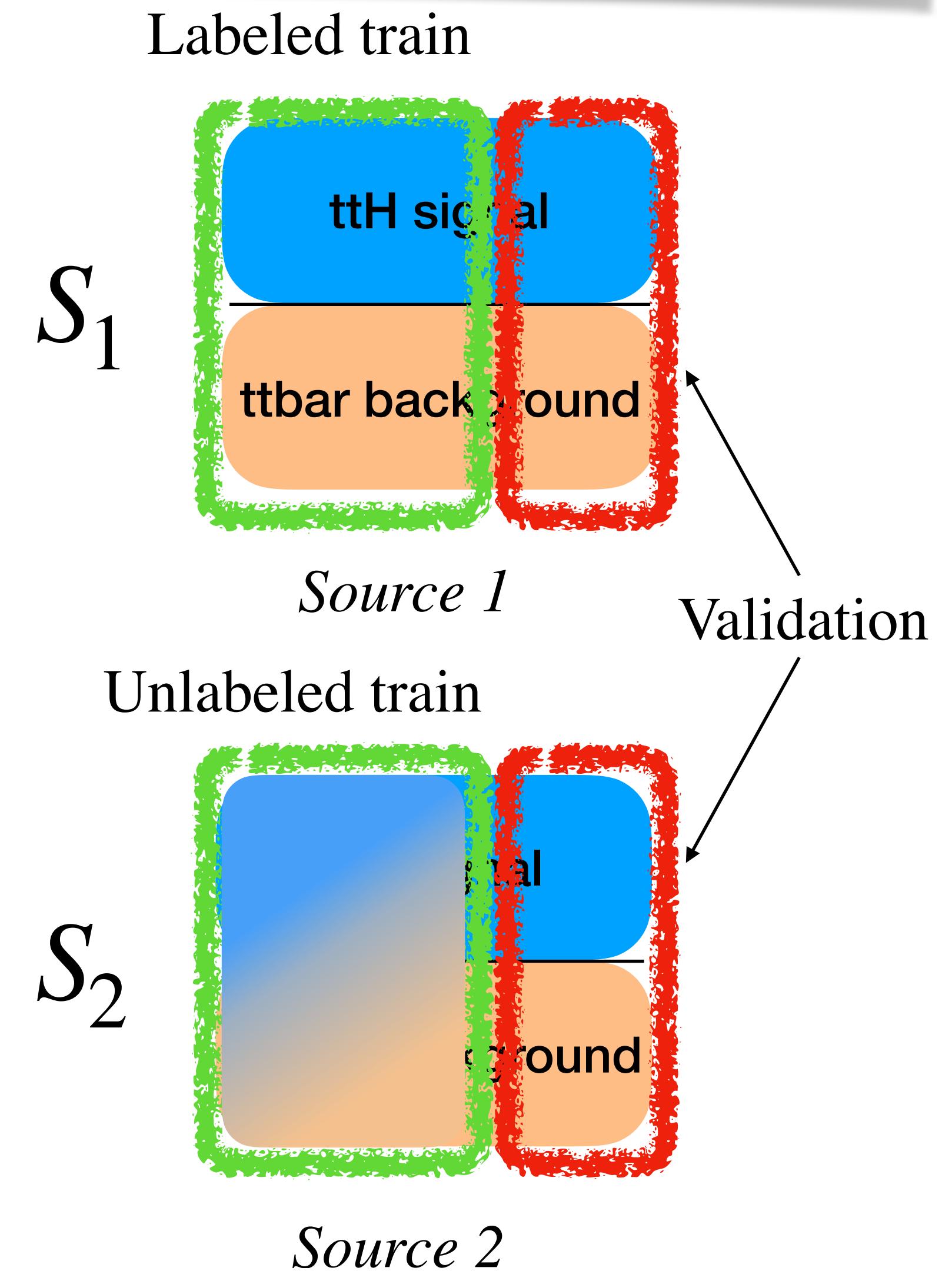
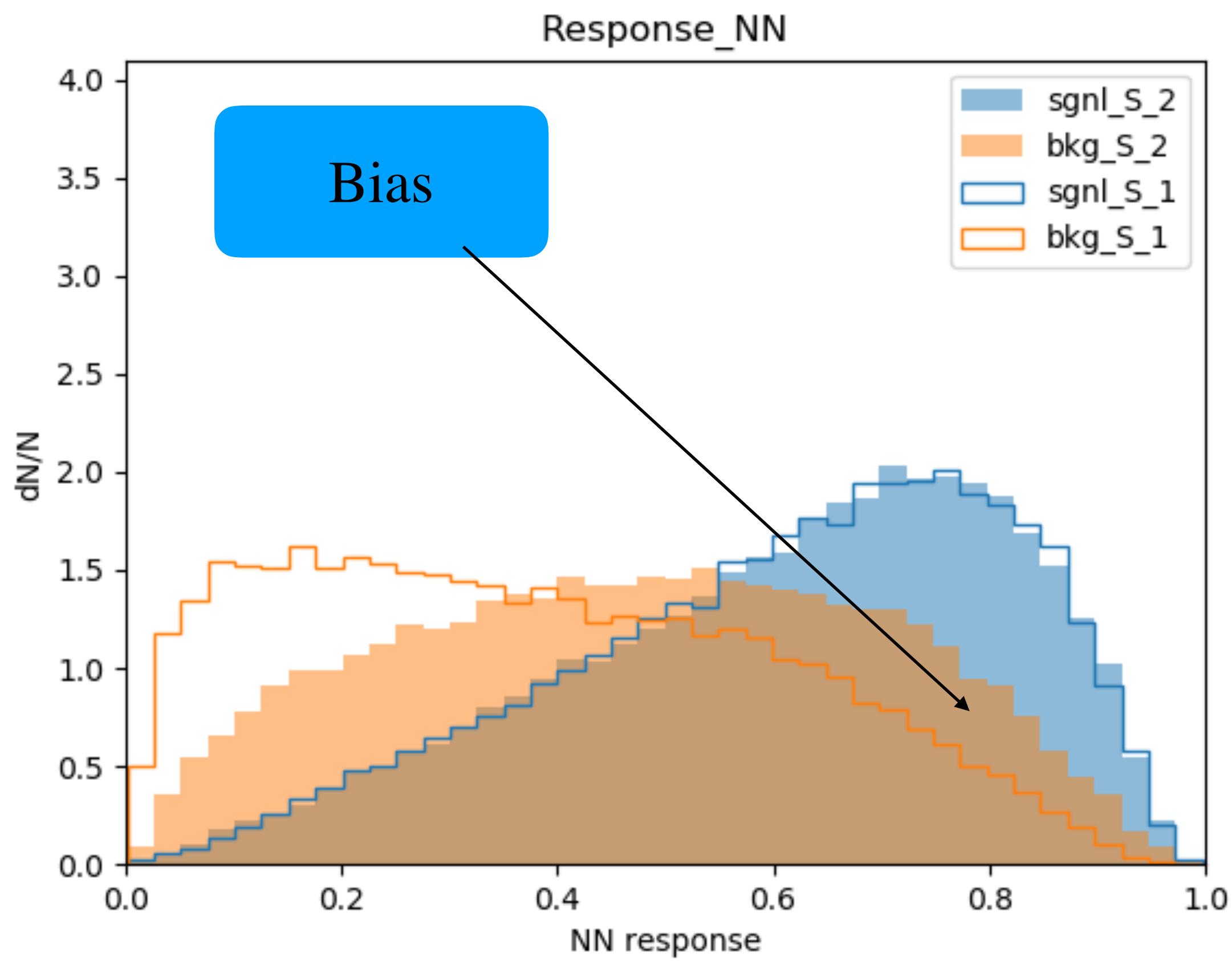
*Source 2*

- ttH signal: MadGraph/Herwig6
- ttbar background: MadGraph/Pythia6
- tt+bb background: Powheg Pythia8

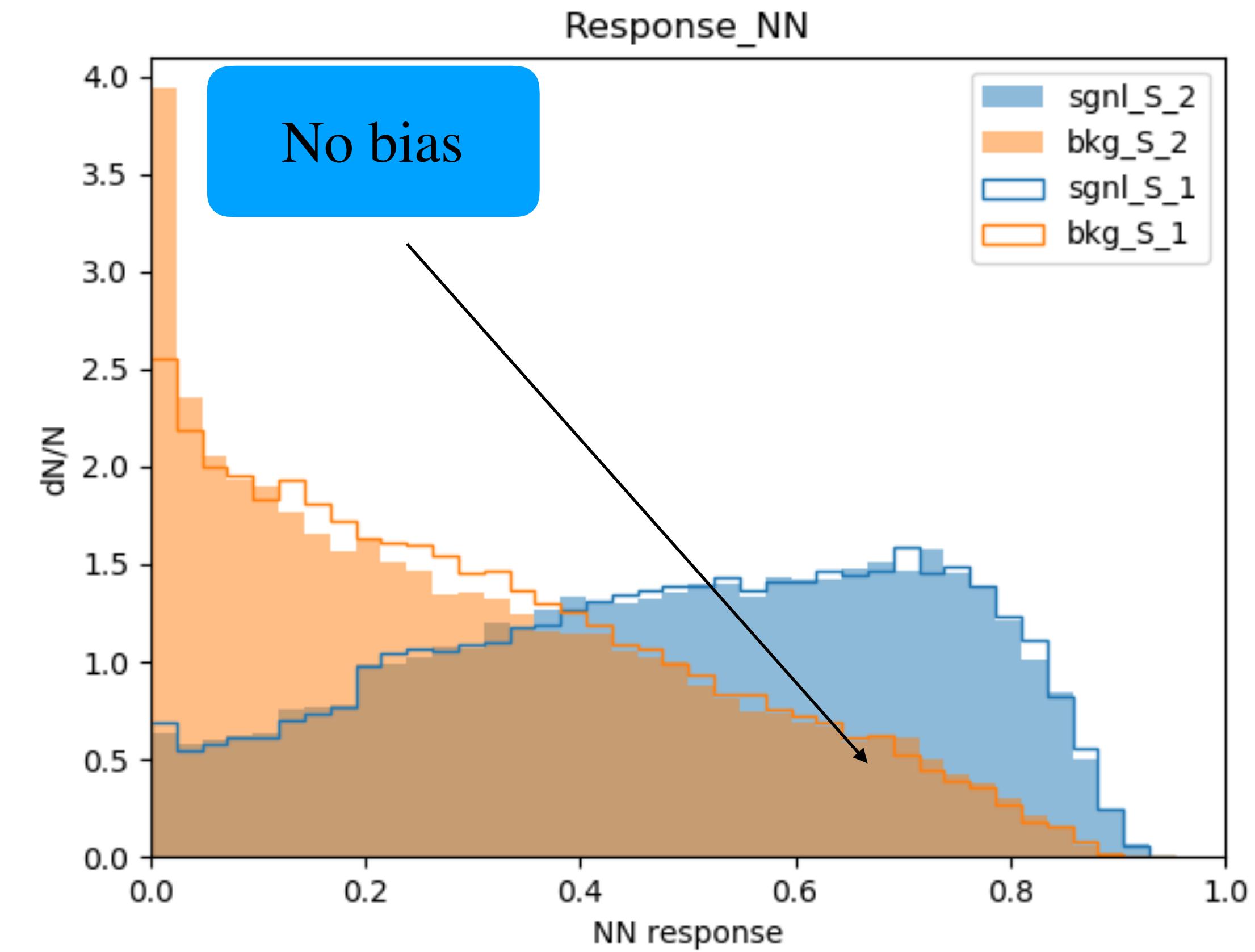
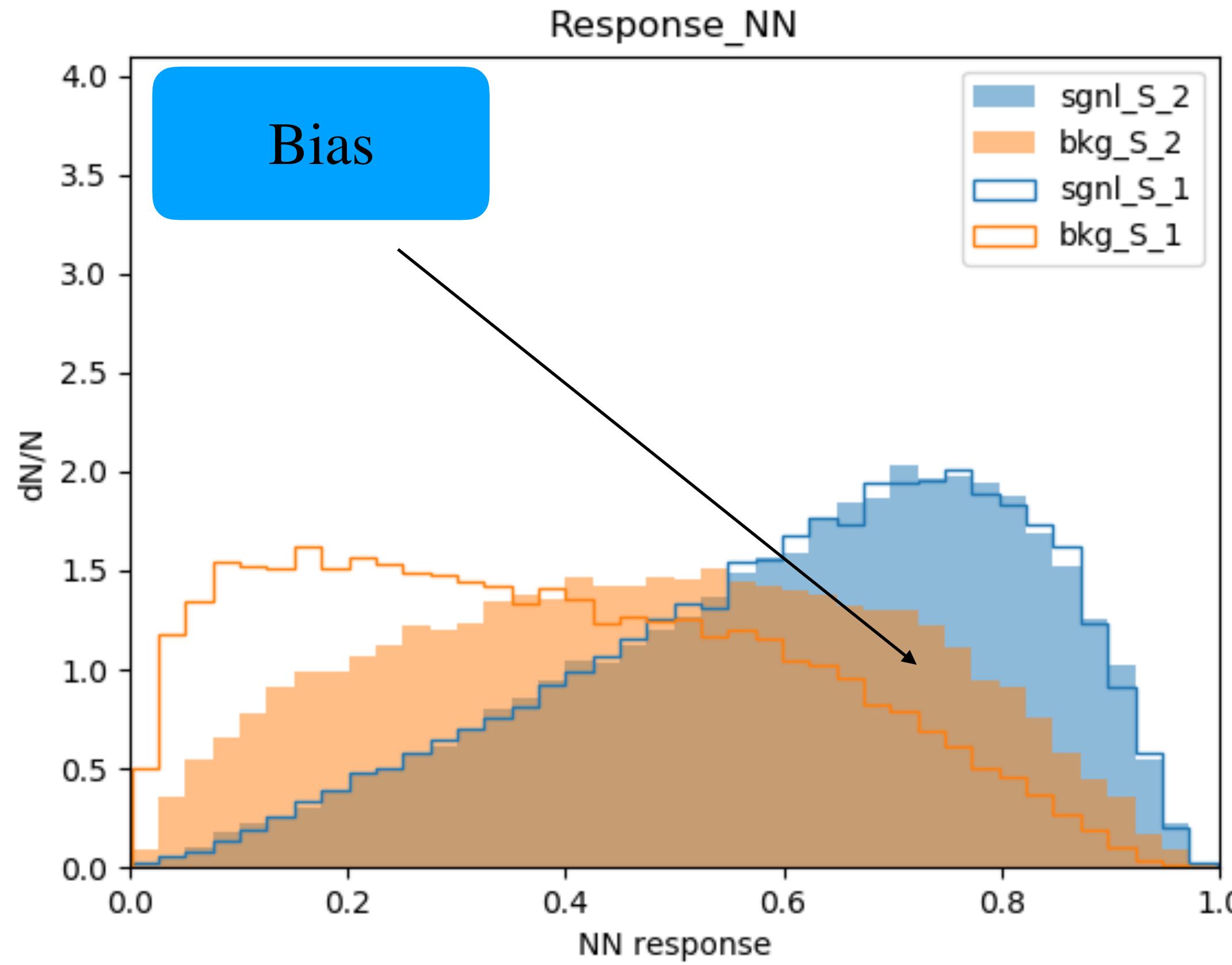
# Main Idea



# Results



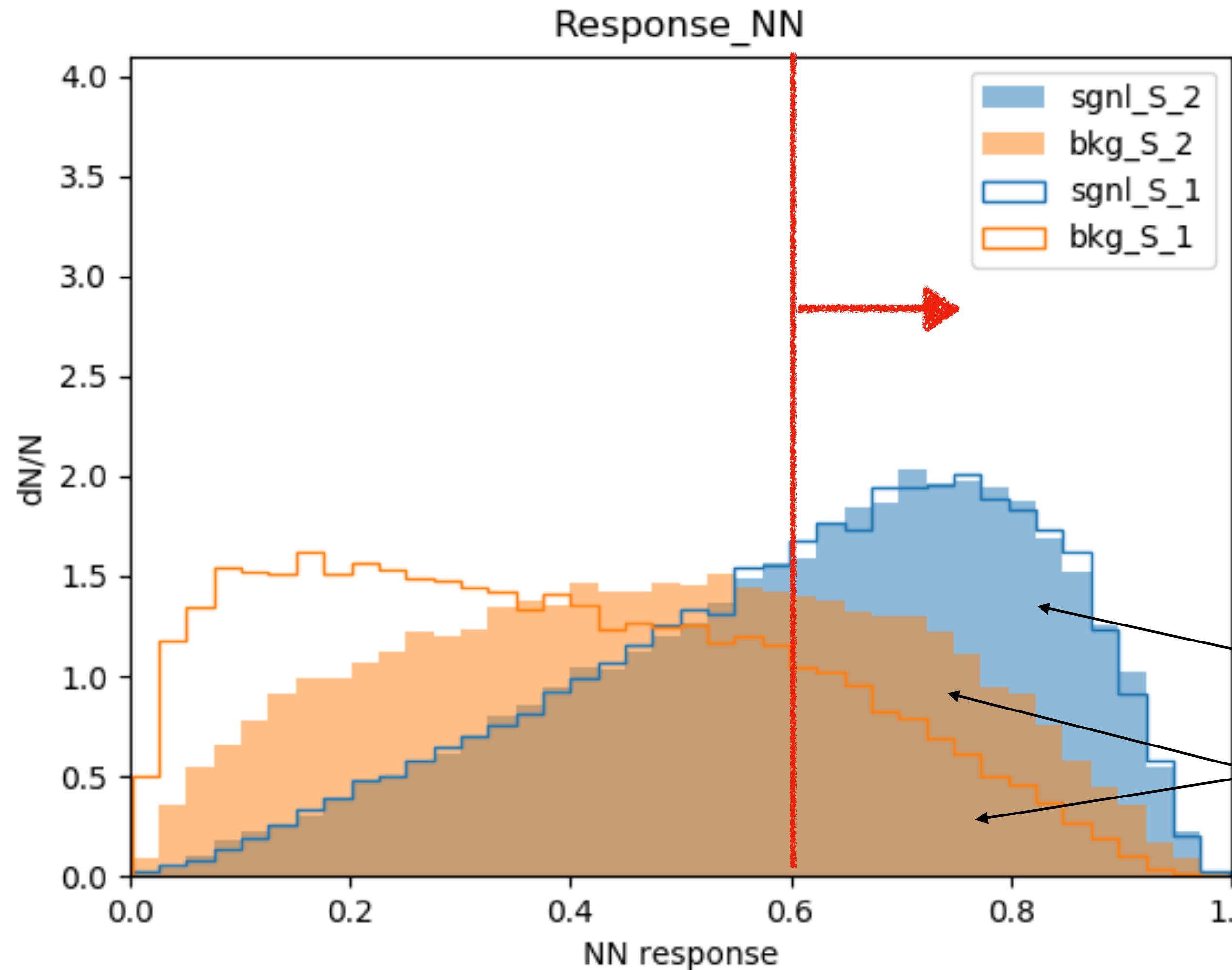
# Results



- Discriminator importance parameter  $\lambda = 0$

- Discriminator importance parameter  $\lambda = 1.3$

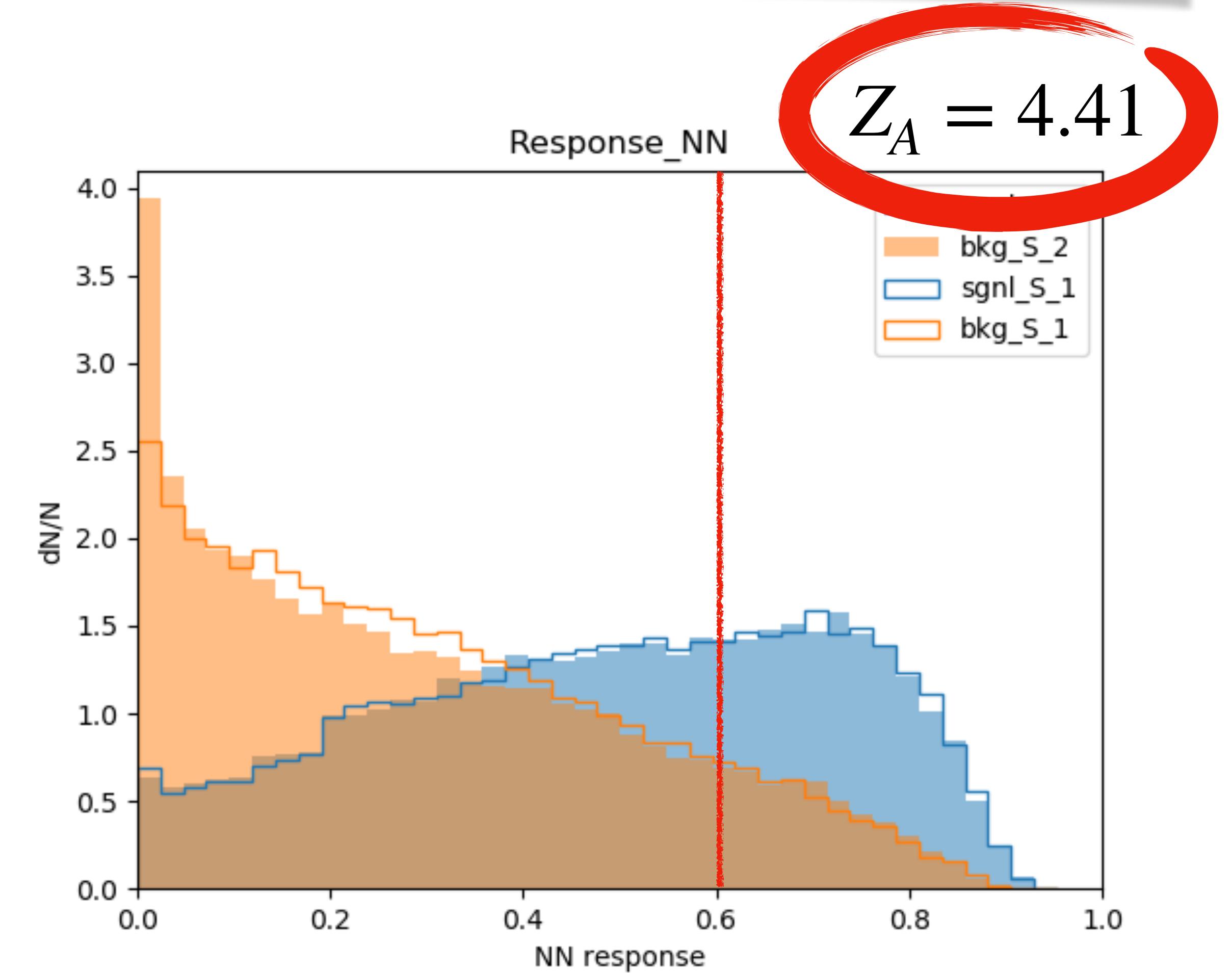
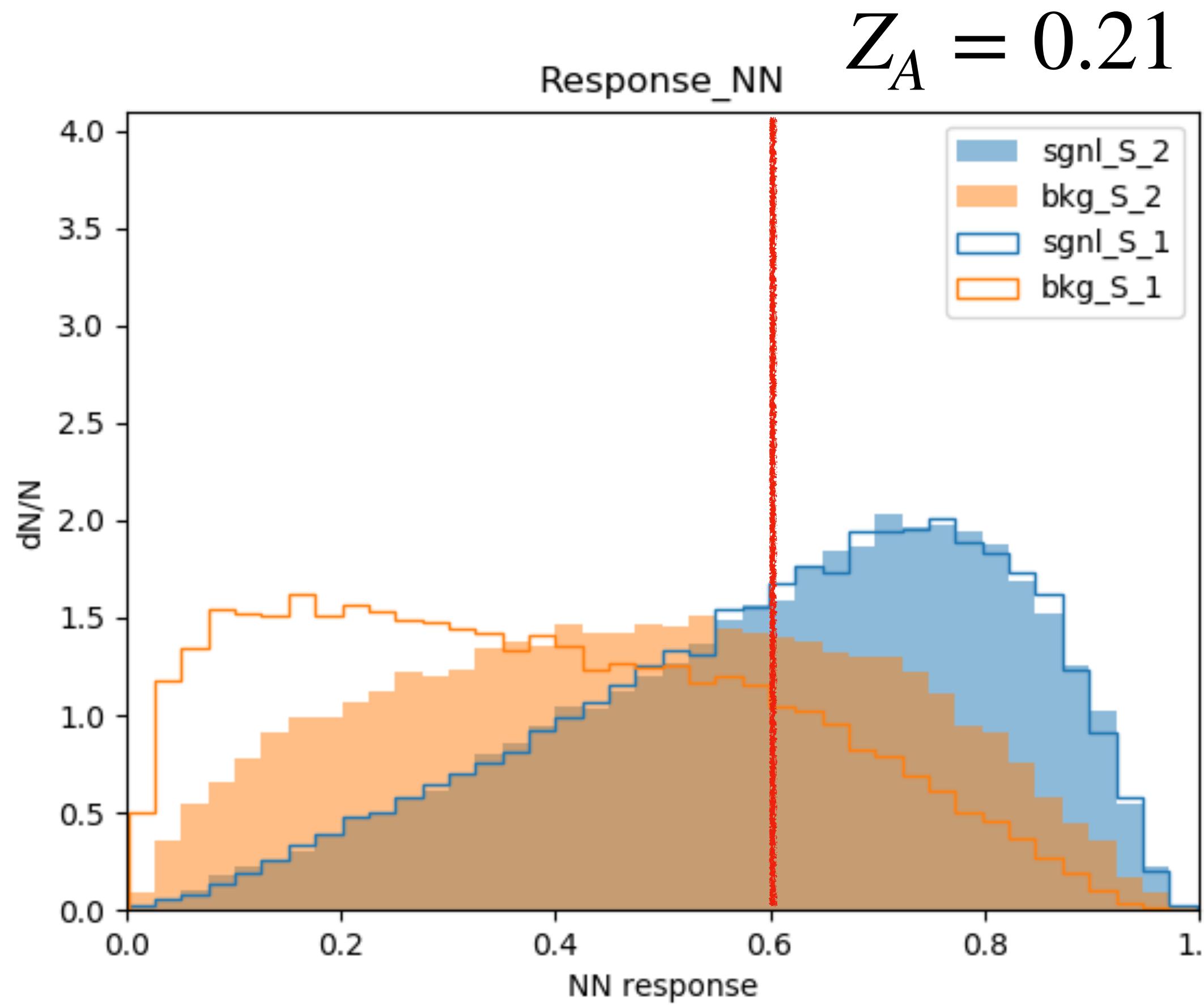
# Significance Calculation



$$Z_A = \frac{s}{\sqrt{b + \sigma_b^2}}$$

- $s$  - signal events in the cut
- $b$  - test bkg events in the cut
- $\sigma_b^2$  - difference btw test and train bkg

# Significance and Response

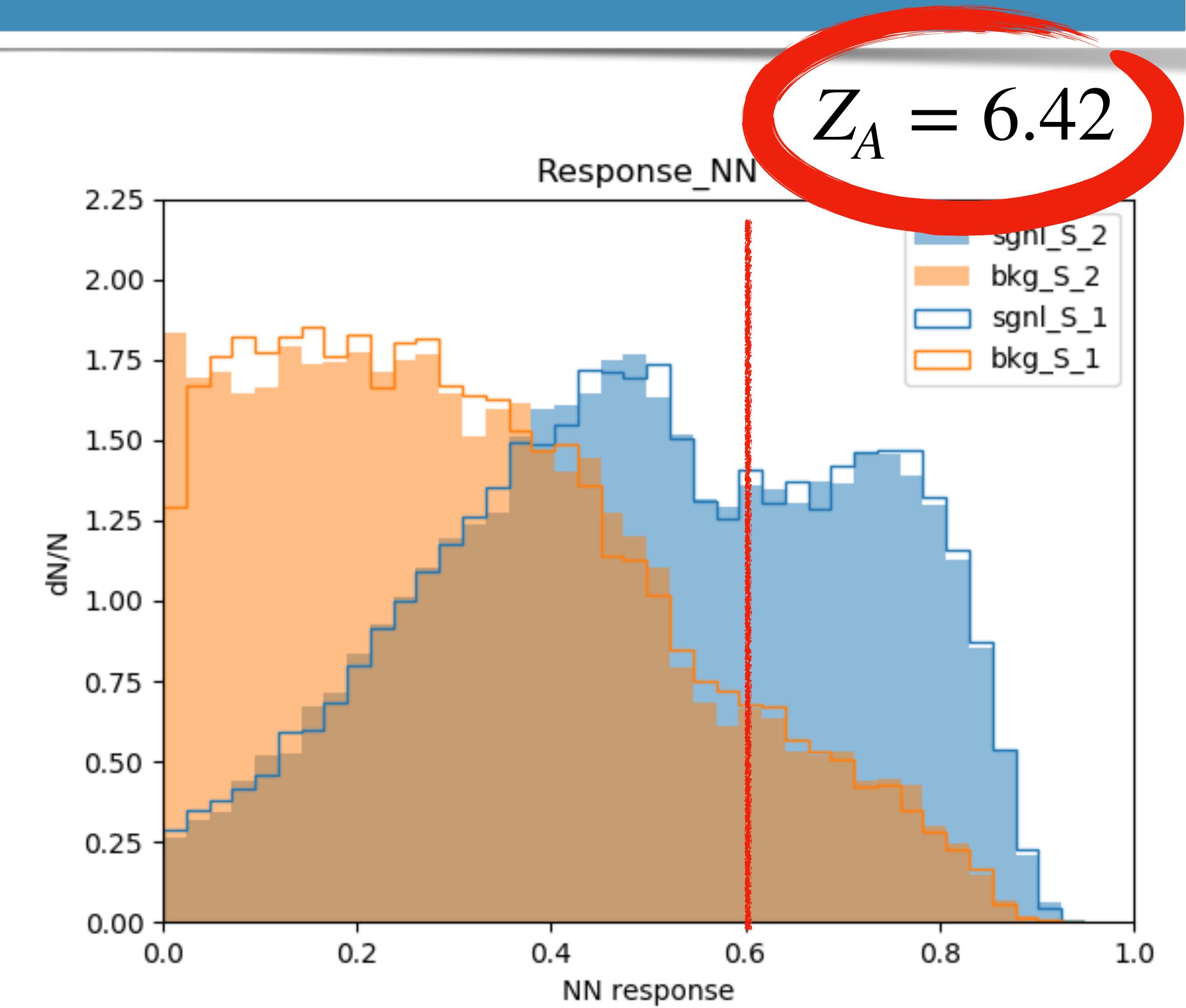
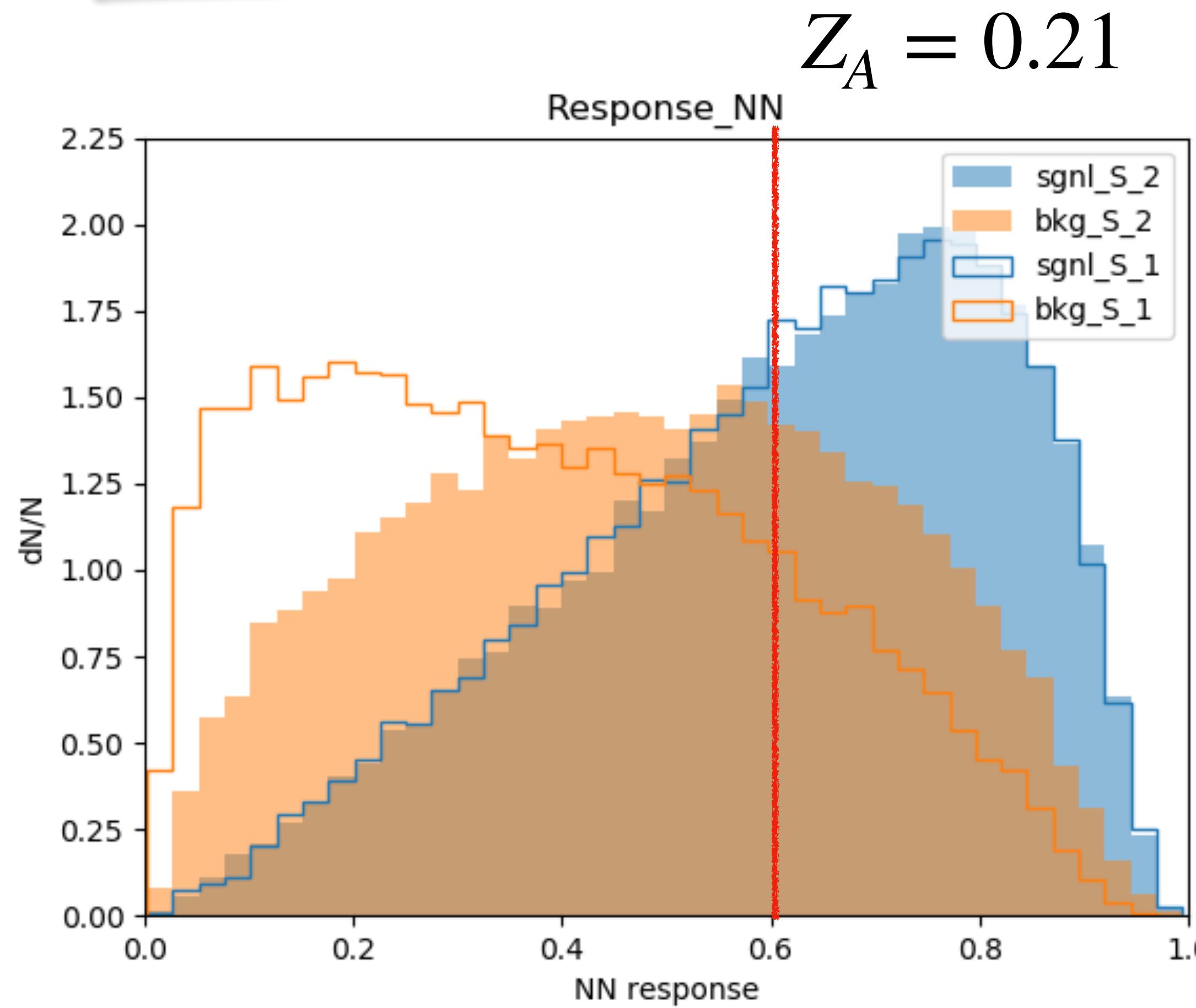


- Discriminator importance parameter  $\lambda = 0$

- Discriminator importance parameter  $\lambda = 1.3$

# **Testing on different NN settings**

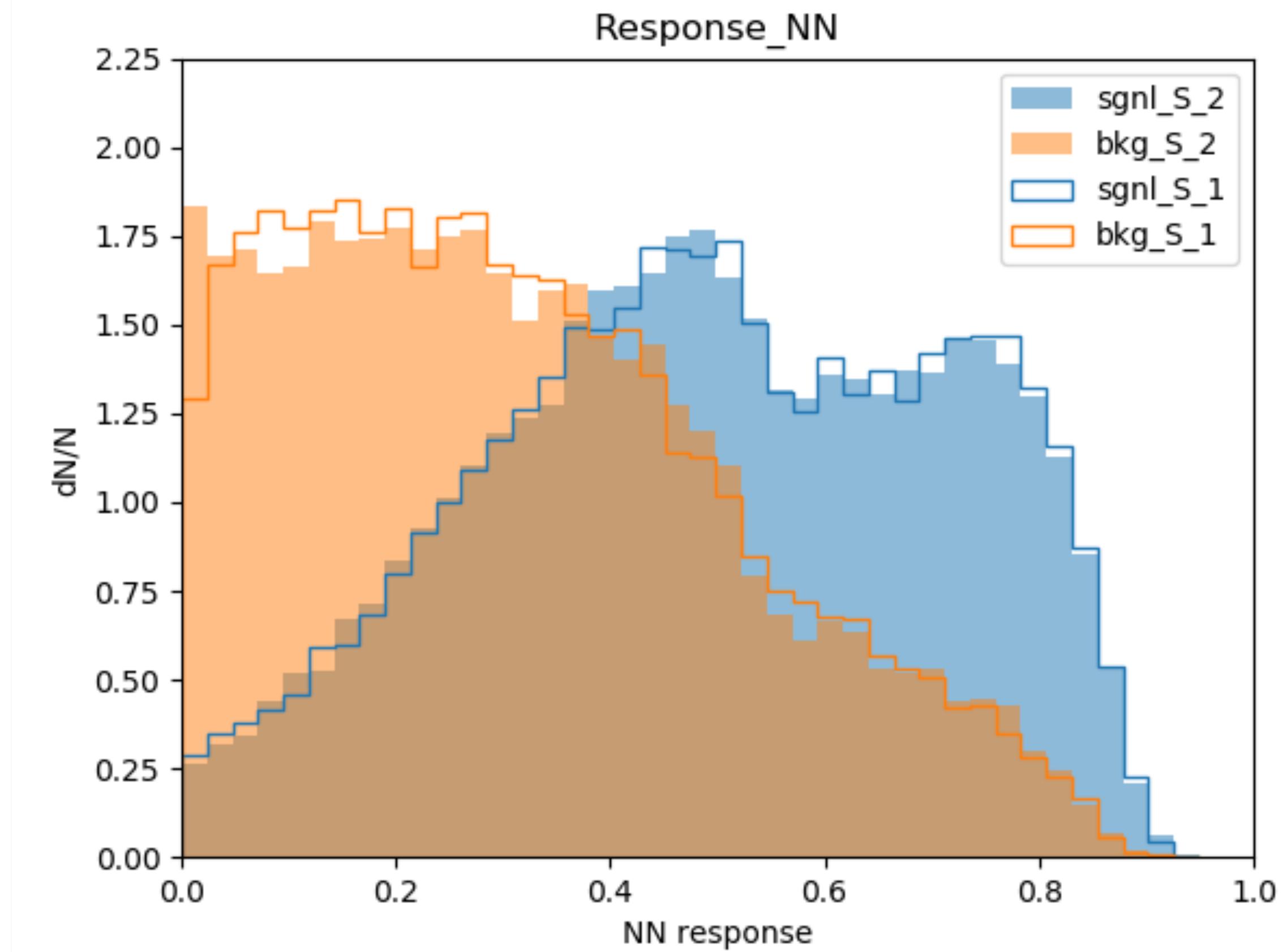
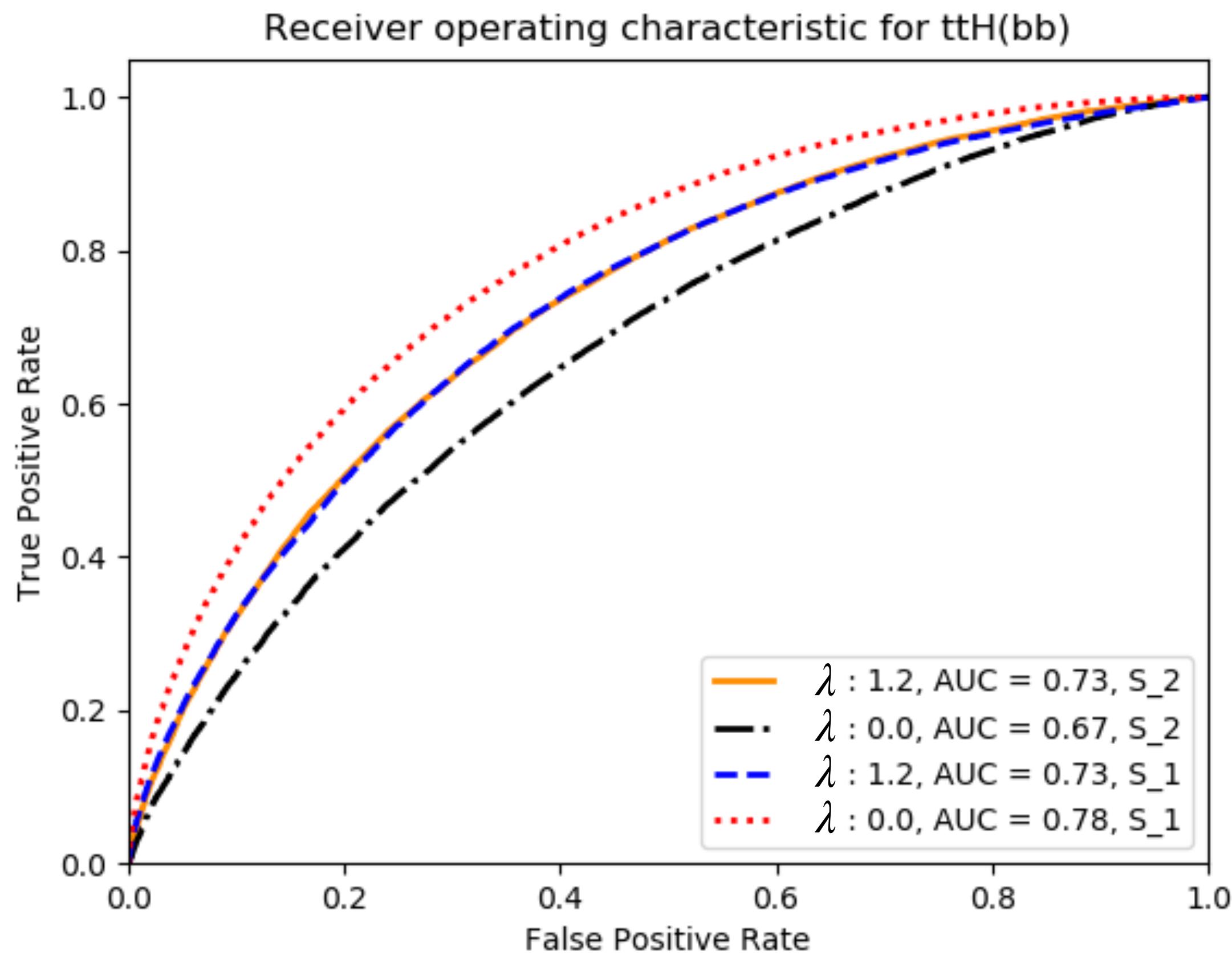
# Significance and Response



- Discriminator importance parameter  $\lambda = 0$

- Discriminator importance parameter  $\lambda = 1.2$

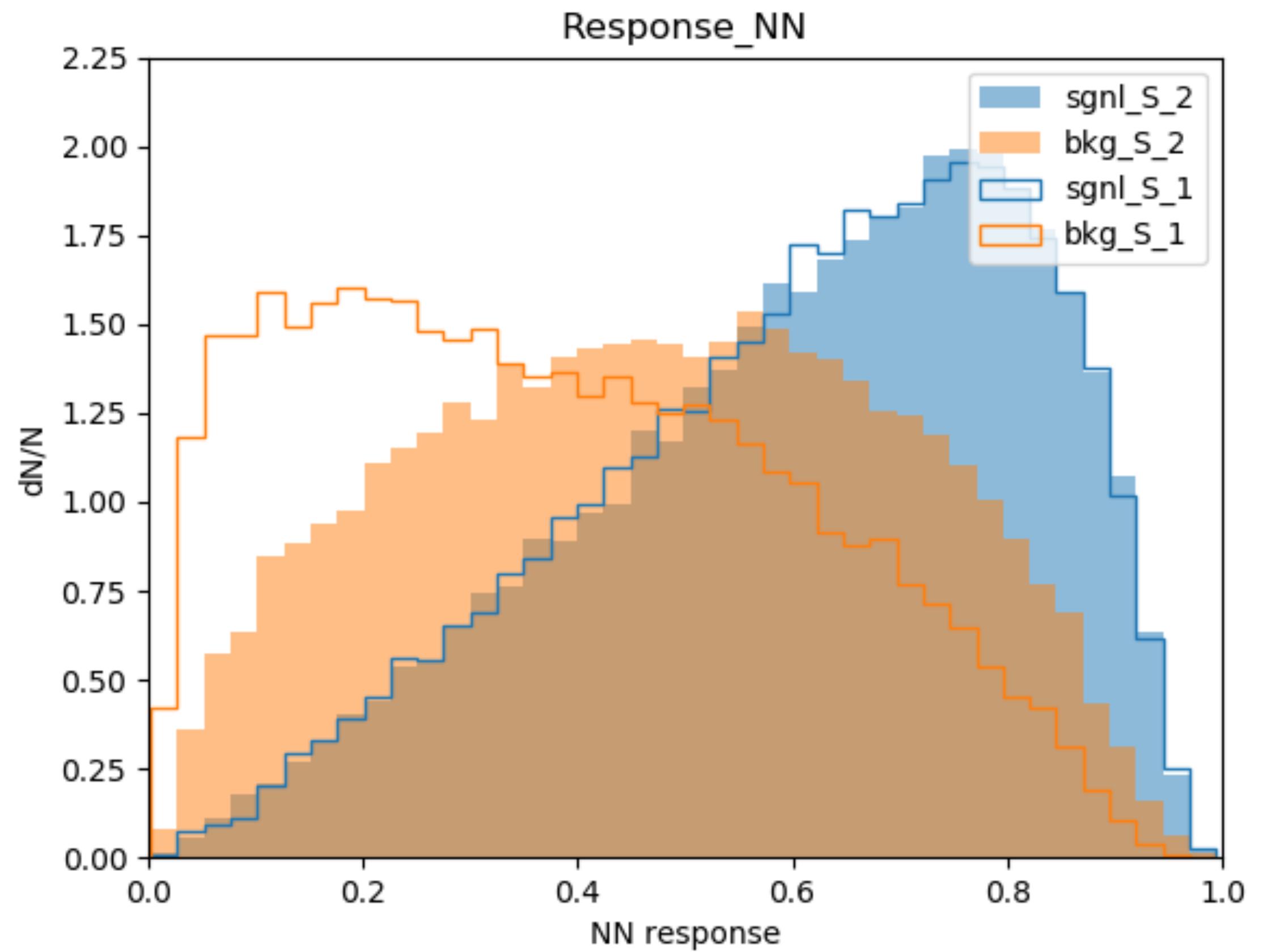
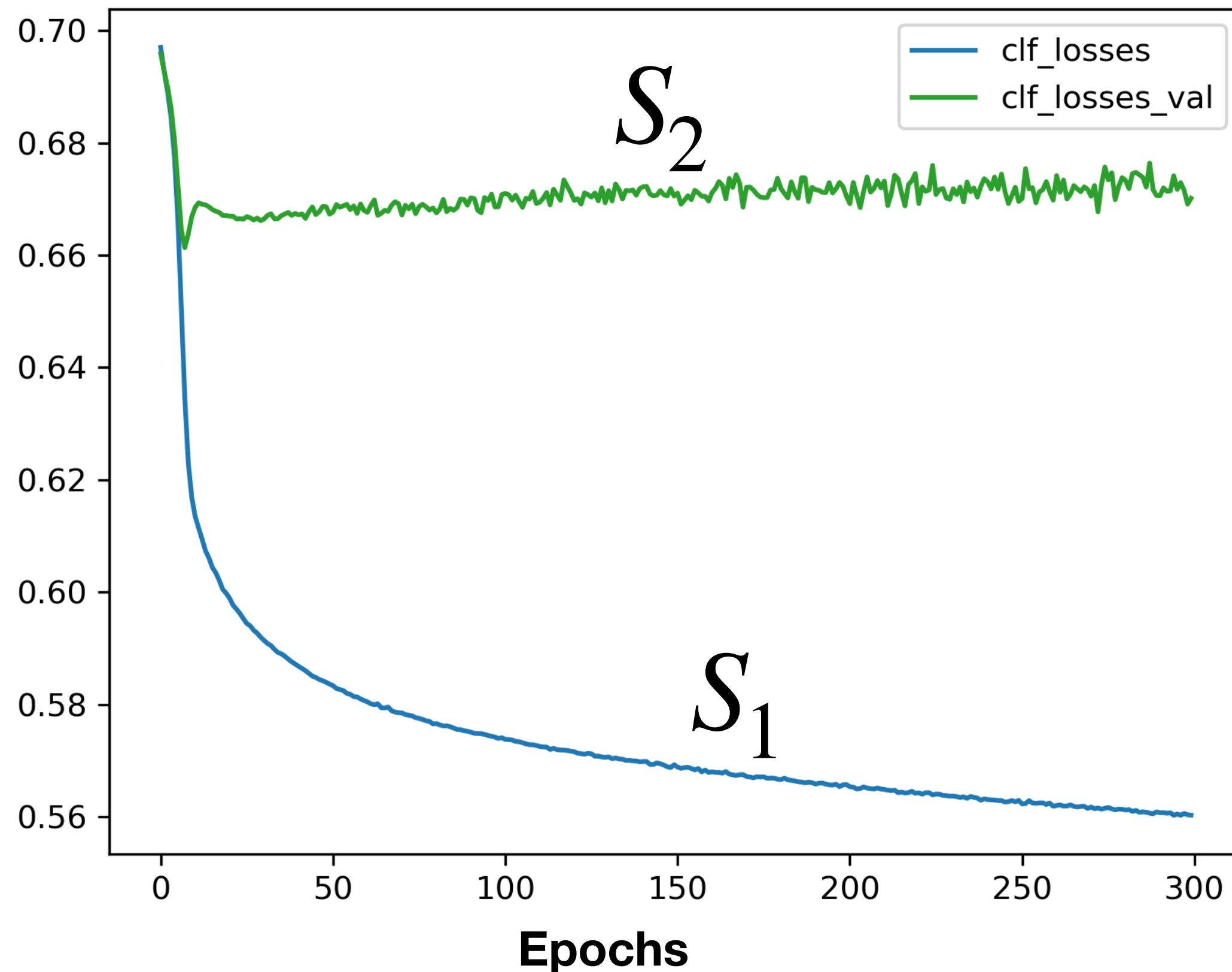
# Results



# Training

- $\lambda = 0$

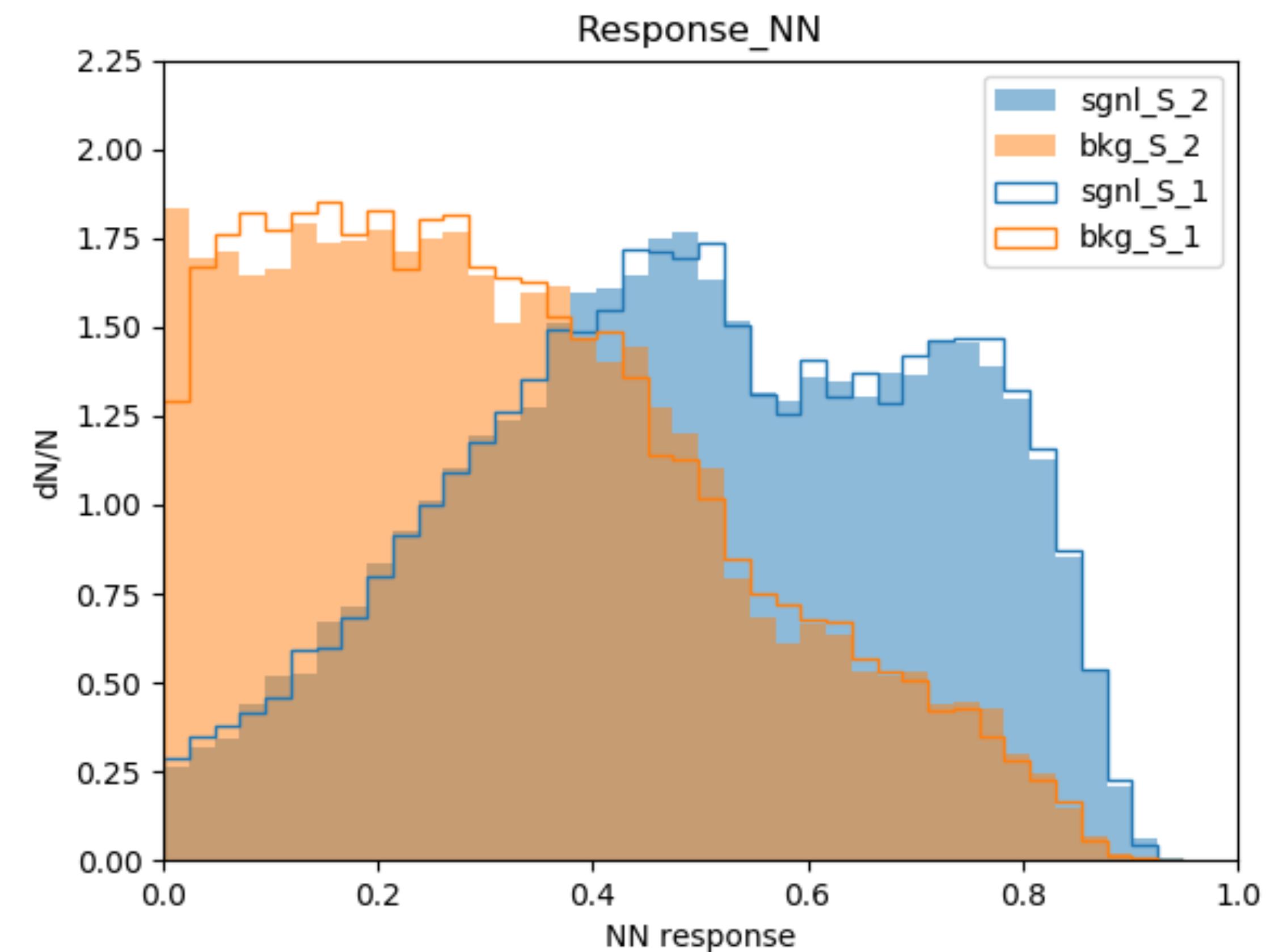
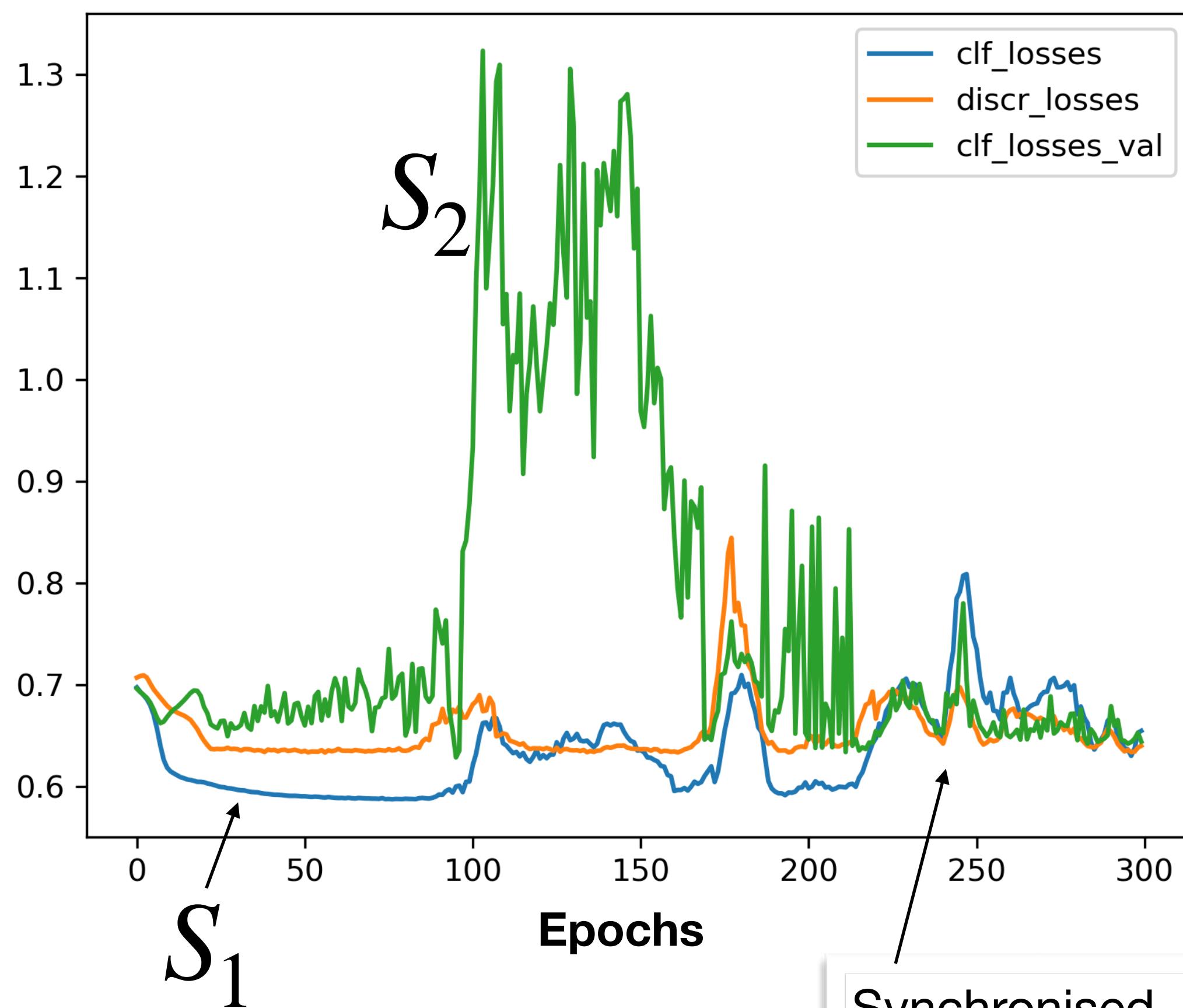
Training plot



# Training

- $\lambda = 1.20$

Training plot



# Results

Table 1

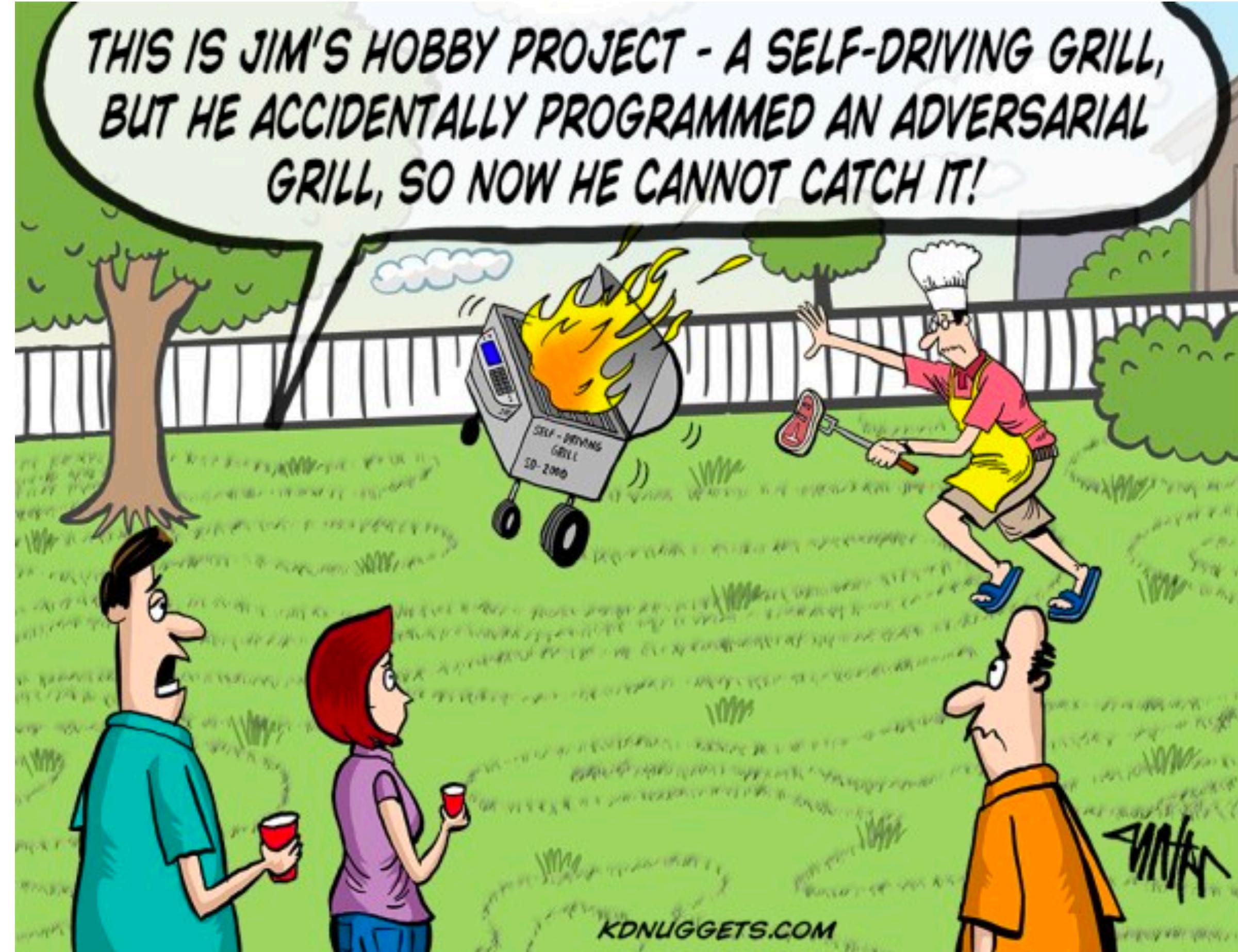
#Neurons in hidden layer	\lambda	Accuracy (test)	AUCROC (test)	Significance
[35, 30, 15]	0.000	0.621	0.668	0.212
[35, 30, 15]	1.300	0.652	0.729	<u>4.408</u>
[40, 25, 25]	0.000	0.623	0.671	0.215
[40, 25, 25]	1.245	0.642	0.729	<u>3.953</u>
[45, 30, 25]	0.000	0.622	0.671	0.214
[45, 30, 25]	1.201	0.649	0.729	<u>6.417</u>

- Adadelta optimiser with 300 epochs and batch size of 5000 events

# Future work

- Develop an appropriate stopping criterion
- Understand how the network architecture and discriminator importance parameter  $\lambda$  result on the performance
  - Add additional layers to discriminator part
- Play with signal/bkg ratio

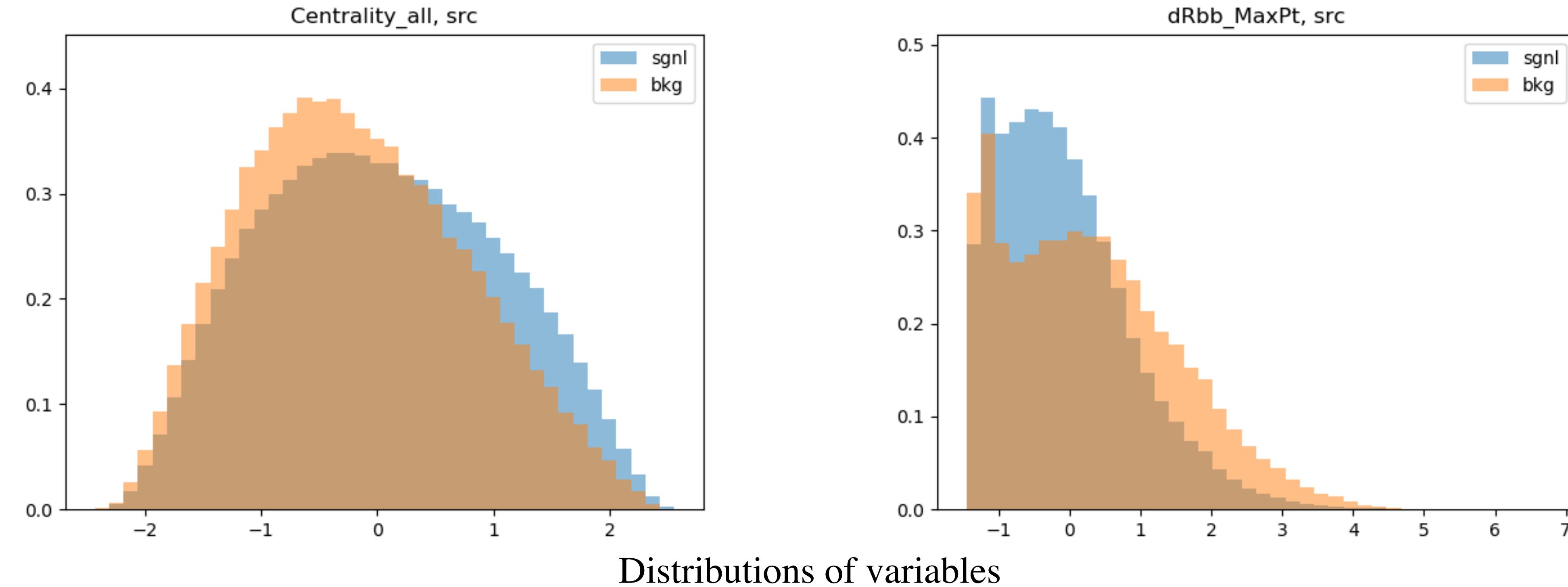
# Questions?



# Variables description

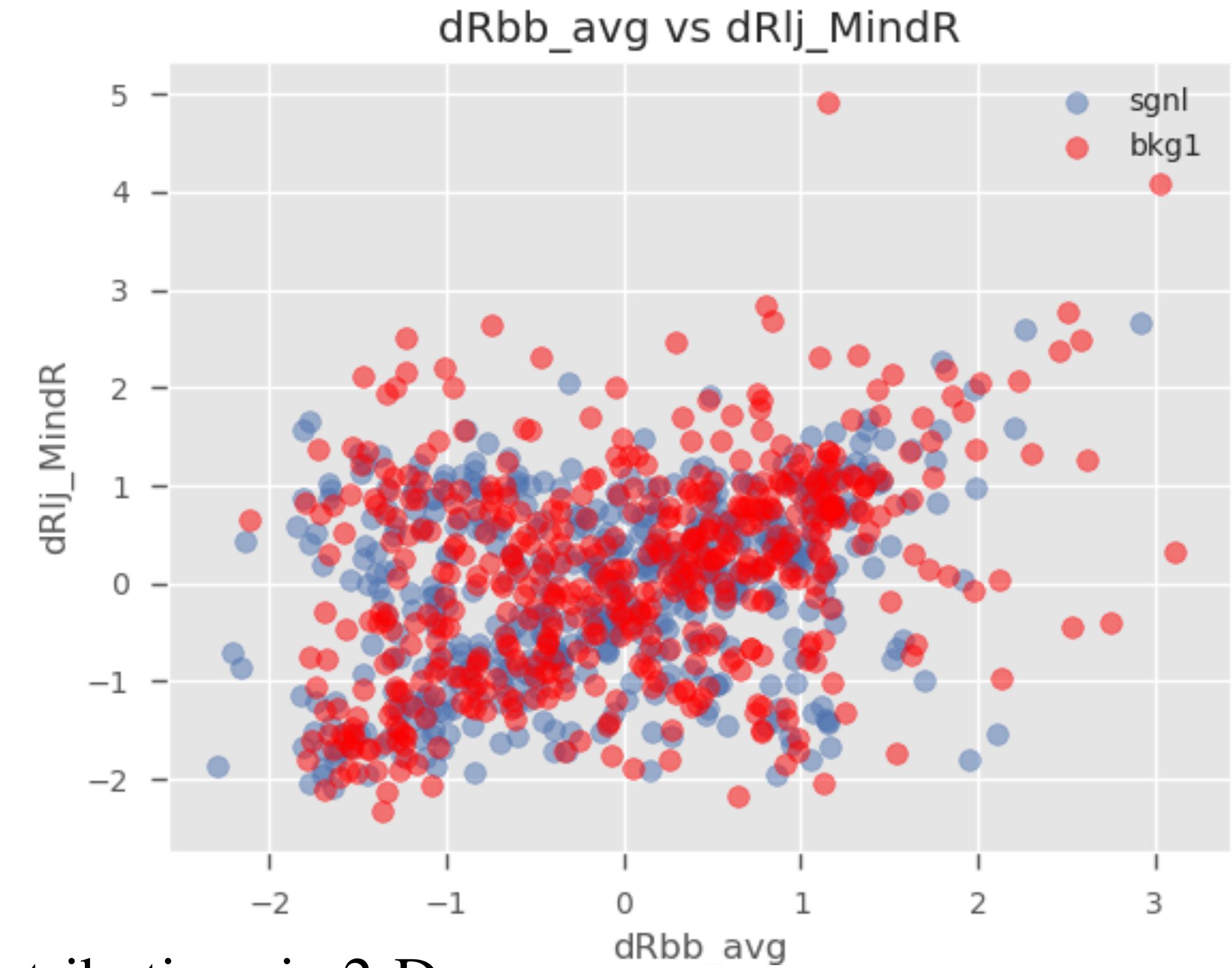
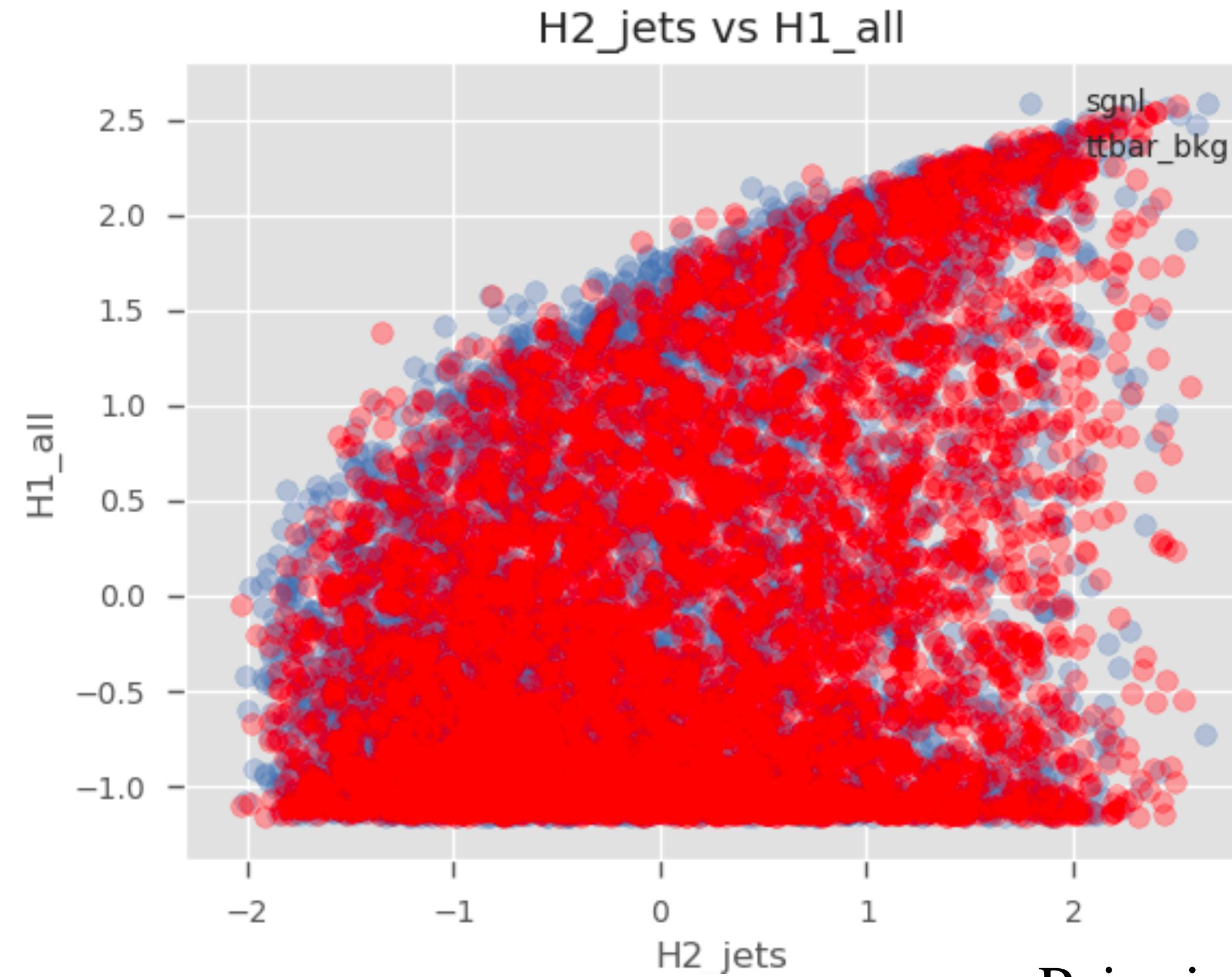
dRbb_avg	average dR of all $b$ -jet pairs
dRbb_MaxPt	dR of the $b$ -jet pair with the highest sum of $p_T$
dRbb_MaxM	dR of the $b$ -jet pair with the highest invariant mass
dRlb1-dRlb3	dR of the charged lepton and the $b$ -jet with the 1st-3rd largest $p_T$
dRlbb_MindR	dR of the charged lepton and total $b$ -jet pair system which has the smallest dR
dRlj_MindR	minimum dR between the charged lepton and any jet
Mbb_MaxM	maximum invariant mass of any $b$ -jet pair
Mbb_MindR	invariant mass of $b$ -jet pair which has the smallest dR
Mbj_MaxPt	invariant mass of two jets with the largest $p_T$ sum, where exactly one of the jets is a $b$ -jet
Mjjj_MaxPt	invariant mass of any three jets with the largest $p_T$ sum
pT_lep	transverse momentum of the charged lepton
HT_jets	sum of transverse momentum of all jets
HT_all	sum of transverse momentum of all jets and the charged lepton
nJets_Pt40	number of jets with $p_T \geq 40$ GeV
nbTag	number of $b$ -jets
nHiggsbb30	number of $b$ -jet pairs with an invariant mass within 30 GeV of the Higgs boson mass of 125 GeV
MET	missing transverse energy
dEtajj_MaxdEta	largest difference in longitudinal angle $\eta$ of any two jets
Centrality_all	ratio of momentum sum over the energy sum of all objects
Hi_all, H2_jets	1st-5th Fox Wolfram transverse moment [9] of all objects

# Signal vs Background classification is hard task



- The problem is hard in terms of classification
- Distributions most of the variables look similar for signal and background
- One cannot separate them neither in one nor in two dimensions

# Signal vs Background classification is hard task



Pairwise distributions in 2-D

- One cannot separate signal vs background in two dimensions as well
- Principal Component Analysis (PCA) and Linear Discriminate Analysis (LDA) transforms into 2D were unsuccessful