



班级: 自11

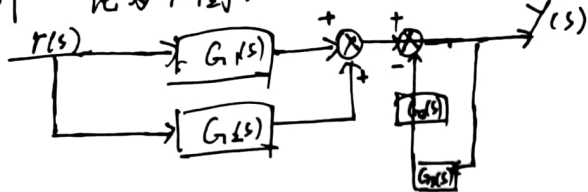
姓名: 孙捷

编号: 2021013444

科目: 自动控制

第 1 页

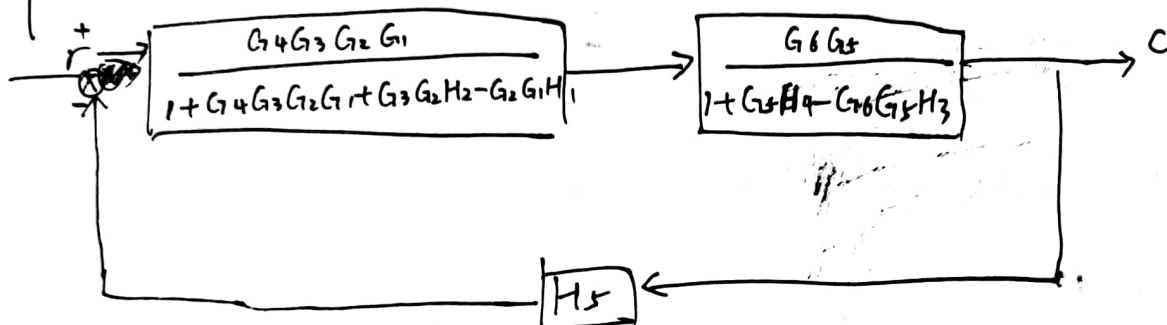
1. 解: 化为下图:



$$\begin{aligned} Y(s) &= \frac{1}{1 + G_2 G_3} \cdot (G_1 + G_2) r(s) \\ &= \frac{G_1 + G_2}{1 + G_2 G_3} r(s) \end{aligned}$$

$$\therefore G(s) = \frac{G_1 + G_2}{1 + G_2 G_3}$$

2. 解: 经化简, 可得下图.



$$\therefore G(s) =$$

$$1 + \frac{G_6 G_5 G_4 G_3 G_2 G_1 H_5}{(1 + G_5 H_4 - G_6 G_5 H_3)(1 + G_4 G_3 G_2 G_1 + G_3 G_2 H_2 - G_2 G_1 H_1)}$$

=

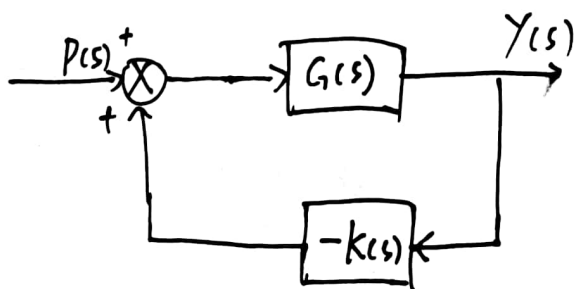
$$\frac{G_6 G_5 G_4 G_3 G_2 G_1}{G_6 G_5 G_4 G_3 G_2 G_1 H_5 + (1 + G_5 H_4 - G_6 G_5 H_3)(1 + G_4 G_3 G_2 G_1 + G_3 G_2 H_2 - G_2 G_1 H_1)}$$

3. 解:

$$\therefore r(s) = 0 \quad \therefore e(s) = -Y(s)$$

$$\therefore \frac{e(s)}{p(s)} = G'(s) = -\frac{Y(s)}{p(s)}$$

原框图可化为



$$\therefore \frac{Y(s)}{p(s)} = \frac{G(s)}{1 + G(s)K(s)}$$

$$\therefore \frac{e(s)}{p(s)} = \frac{-G(s)}{1 + G(s)K(s)}$$





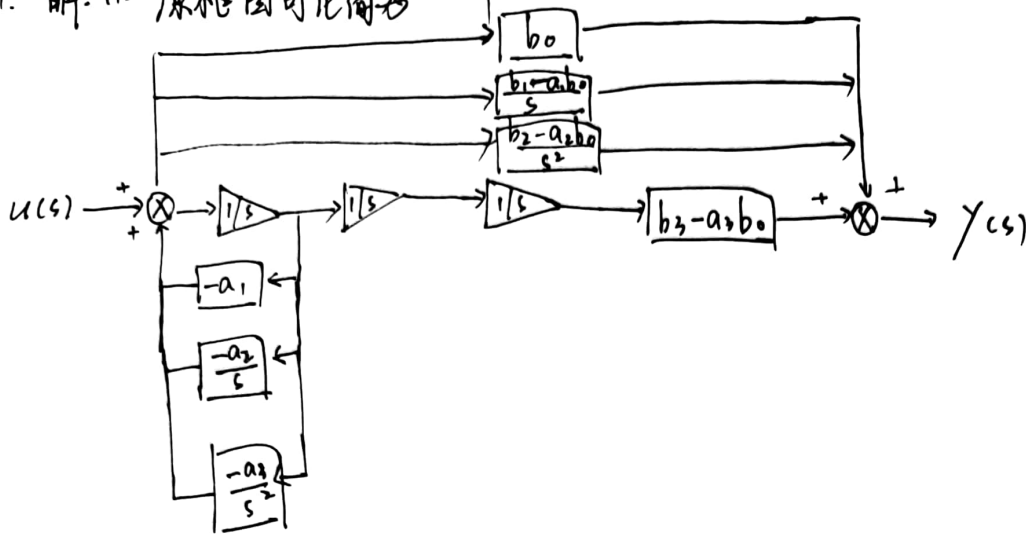
班级: 自11

姓名: 孙捷

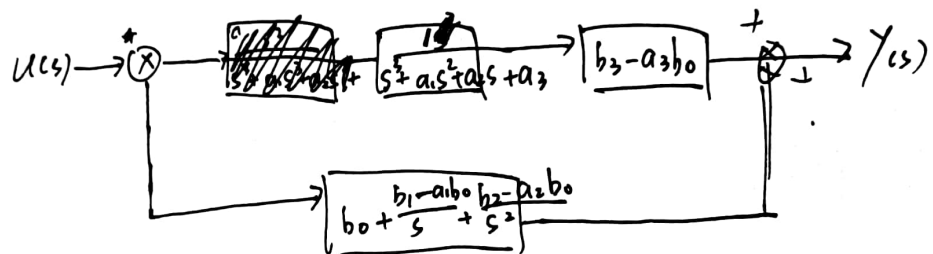
编号: 2021013444 科目: 自动控制

第 2 页

4. 解: (1) 原框图可化简为



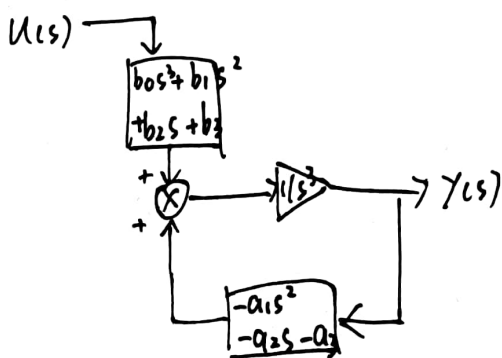
再化简可得:



$$\therefore \frac{Y(s)}{U(s)} = \frac{b_3 - a_3 b_0}{s^3 + a_1 s^2 + a_2 s + a_3} + b_0 + \frac{b_1 - a_1 b_0}{s} + \frac{b_2 - a_2 b_0}{s^2}$$

(2)  $\begin{cases} \dot{x}_1 = x_2 \\ \dot{x}_2 = x_3 \\ \dot{x}_3 = -a_3 x_1 - a_2 x_2 - a_1 x_3 + u \\ y = (b_3 - a_3 b_0) x_1 + (b_2 - a_2 b_0) x_2 + (b_1 - a_1 b_0) x_3 \end{cases}$

解: 原框图可化为



$$\begin{aligned} \therefore \frac{Y(s)}{U(s)} &= \frac{(b_0 s^3 + b_1 s^2 + b_2 s + b_3)}{1 + \frac{a_1 s^2 + a_2 s + a_3}{s^3}} \\ &= \frac{b_0 s^3 + b_1 s^2 + b_2 s + b_3}{s^3 + a_1 s^2 + a_2 s + a_3} \end{aligned}$$





班级: 自11

姓名: 孙捷

编号: 201013444

科目: 自动控制

第 3 页

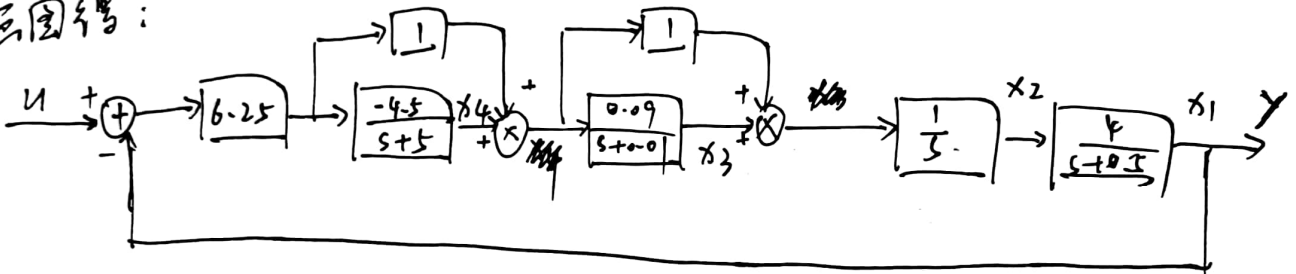
(2)

$$\begin{cases} \dot{x}_1 = -a_3 x_3 + (b_3 - a_3 b_0) u \\ \dot{x}_2 = x_1 - a_2 x_3 + (b_2 - a_2 b_0) u \\ \dot{x}_3 = x_2 - a_1 x_3 + (b_1 - a_1 b_0) u \\ y = x_3 + b_0 u \end{cases}$$

6. 解: 根据题设可得  $G_c(s) = 6.25 \cdot (1 - \frac{4.5}{s+5}) \cdot (1 + \frac{0.09}{s+0.1})$

$$G_p(s) = \frac{1}{s} \cdot \frac{4}{s+0.5}$$

画方块图:



则系统状态空间表达式为:

$$\begin{cases} \dot{x}_1 = -0.5 x_1 + 4 x_2 \\ \dot{x}_2 = -6.25 x_1 + x_3 + x_4 + 6.25 u \\ \dot{x}_3 = -0.5625 x_1 - 0.01 x_3 + 0.09 x_4 + 0.5625 u \\ \dot{x}_4 = -6.25 x_1 + 6.25 u \\ y = x_1 \end{cases}$$

