



班级: 自11

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科目: 自动控制 第 1 页

1. 解: (a). $\frac{4}{25} \phi''(t) + \frac{2}{5} \phi'(t) + \phi = u(t)$ 阻尼系数 $\zeta = \frac{1}{2}$, 时间常数 $T = \frac{2}{5}$

$$\therefore s_{1,2} = -\frac{5}{4} \pm j\frac{5\sqrt{3}}{4} \quad \phi(t) = 1 - \frac{2\sqrt{3}}{3} e^{-\frac{5}{4}t} \sin\left(\frac{5\sqrt{3}}{4}t + \frac{\pi}{3}\right)$$

(b). $T = \frac{2}{5}$, $\zeta = \frac{1}{2}$, 无阻尼自然频率 $\omega_n = \frac{1}{T} = \frac{5}{2}$

(c). $t_s(5\%) = \frac{3T}{\zeta} = \frac{12}{5} s$. $\sigma = e^{-\frac{\zeta\pi}{\sqrt{1-\zeta^2}}} = e^{-\frac{\sqrt{3}\pi}{3}}$

$$t_r = \frac{\pi - \theta}{\omega_d} = \frac{8\sqrt{3}\pi}{45} s \quad \text{约 } 1.16s$$

$$\frac{1}{\sqrt{1-\zeta^2}} e^{-\frac{\zeta}{T}t_d} \sin(\omega_d t_d + \theta) = \frac{1}{2}, \quad \text{matlab 解得值为 } 0.5176.$$

$$\text{EP } t_d = 0.5176 s$$

$$t_p = \frac{\pi}{\omega_d} = \frac{4\sqrt{3}\pi}{15} s$$

2. 解: (a). $G_{\dot{z}_1}(s) = \frac{\frac{1}{5}}{1 + \frac{96.1}{s}} = \frac{1}{s + 96.1}$ $G_{\dot{z}_2}(s) = \frac{1}{(s+96.1)(s+6)}$

$$G_{\dot{z}_3}(s) = \frac{G_{\dot{z}_2}(s) \cdot \frac{1}{s+12}}{1 + \frac{6582.4}{s+12} G_{\dot{z}_2}(s)} = \frac{1}{(s+12)[(s+6)(s+96.1)-291.8] + 6582.4}$$

$$\therefore \frac{y(s)}{w(s)} = \frac{10000}{(s+12)[(s+6)(s+96.1)-291.8] + 6582.4} = \frac{10000}{(s+100)(s^2+14s+100)}$$

(b). 主导极点即为 $s^2+14s+100$ 的解:

$$s_1 = -7.05 + 7.09j \quad s_2 = -7.05 - 7.09j$$

(c). $\frac{y(s)}{w(s)} = \frac{100}{s^2+14s+100}$

