



# Khanh Nguyen (He/Him)

Email: [nkhanh1895@gmail.com](mailto:nkhanh1895@gmail.com)

Website: <https://imkhanhnguyen.github.io/>

Google scholar: [Khanh Nguyen](#)

LinkedIn: [Khanh-Nguyen-11b0a919b](#)

Research gate: [Khanh-Nguyen-259](#)

## EDUCATION

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### Ph.D. in Smart Vehicle Engineering (Expected in February 2026)

Konkuk University, Seoul, Republic of Korea

Thesis: [From Wings to Fins: Bioinspired Robotics in Flying and Swimming Systems](#)

Outcome (as of April 2025): One co-authored paper on a fast-swimming robot (2023). Two first-author papers on flapping-wing stability (2023) and on gliding feasibility of the flying-fish-like robot (2024).

Relevant courses: Robot Kinematics, Numerical Analysis, Optimal Control Theory.

(GPA: 4.00/4.00)

### M.S. in Smart Vehicle Engineering (February 2021)

Konkuk University, Seoul, Republic of Korea

Thesis: [Investigation of stability and aerodynamic performance of a flapping-wing micro air vehicle in hover using three-dimensional computational fluid dynamics analyses](#)

Outcome: Two first-author papers on stability and aerodynamic analyses of the flapping-wing robot (2021)

Relevant courses: Finite Element Method, Advanced Finite Element Method, Structural Analysis.

(GPA: 3.89/4.00)

### B.S. in Mechanical and Aerospace Engineering (August 2018)

Ho Chi Minh City University of Technology, Vietnam

5-year Vietnam-France Excellent Engineer Training Program (PFIEV) is accredited by Engineering Degree Commission (CTI) in France and is eligible for the EUR-ACE (European Accredited Engineer) Masters label, issued by European Network for Accreditation of Engineering Education (ENAAE). Total ECTS: 274.

Thesis: [Computational approach on the aerodynamics of UAV combining fixed wing and three propellers](#) (Graded: 9.07/10)

Outcome: One first-author conference paper (2018)

Relevant courses: Aerodynamics, Aircraft Propulsion, Combustion, Computational Fluid Dynamics, Aircraft Design, Helicopters, Aerospace Materials, Flight Mechanics, Strength of Materials.

(GPA: 3.18/4.00)

## HONORS AND AWARDS

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Doctoral Fellowship, KU, Republic of Korea (2022 – 2026)

Research Assistant Fellowship, KU, Republic of Korea (2019 – 2021)

Research Assistant Fellowship, University of Ulsan, Republic of Korea (2019)

Research Assistant Fellowship, HCMUT, Vietnam (2018 – 2019)

Best Paper Award, 18th International Conference on Intelligent Unmanned Systems (ICIUS), Japan (2022)

Merits for Exceptional Academic Students, KU, Republic of Korea (50%, 2019 – 2021 & 2022 – 2024)

Excellent Student of HCMUT, Vietnam (120% tuition waiver in 2018)

Outstanding Scholar Tuition Grant, HCMUT, Vietnam (100% in 2014 and 110% in 2017)

## PROFESSIONAL SERVICES

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Reviewer, Journal of Aeronautics Astronautics and Aviation

Reviewer, International Journal of Intelligent Unmanned Systems

## UNIVERSITY SERVICES

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### Teaching Assistant

Assisted in grading assignments (KU): *Basics of mechanics* (Fall, 2020), *Finite Element Method* (Spring, 2025).

Facilitated students understanding assignments during lectures (HCMUT): *Fluid Mechanics* (delivered in English, 2018).

### Research Assistant

Co-supervised two junior students on their capstone projects during Spring & Fall, 2018 (HCMUT).

*Aerodynamic analyses of a hybrid design UAV in forward flight using OpenFOAM.*

*Numerical simulation of a tricopter in a forward flight using virtual blade element theory with OpenFOAM.*

Outcome: Two co-authored conference papers (2019 & 2023), and two peer-reviewed journal publications (2020 & 2024).

## TECHNICAL SKILLS

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Image Processing & Visualization (MATLAB, Digitalizing Tool - DLTdv, Pixel-based Locomotion Analysis, Photoshop)

Computational Fluid Dynamics & Simulation Tools (ANSYS-Fluent, OpenFOAM, C++)

Geometric Design & CAD Tools (SolidWorks, AutoCAD)

Fabrication & Tools (CNC, 3D Printer, Silicone Molding)

Web Development (HTML, CSS)

## JOURNAL PUBLICATIONS

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1. Le, T.H.H., **Nguyen, K.**, Vuong, T.H.N., **2024**, [Numerical analysis for aerodynamic characteristics of the unmanned aerial vehicle \(UAV\) in forward flight](#). *Journal of Aeronautics, Astronautics and Aviation*, 56. 6s, 1081-1097, 2024. (The second author is the main contributor)
2. **Nguyen, K.**, Ha, G.H., Kang, T.S., Park, H.C., **2024**, [Dynamic flight stability characteristics of a hovering insect-like flapping-wing robot on Mars](#). *Aerospace Science and Technology*, 152, 109371.
3. **Nguyen, K.**, Park, H.C., **2023**, [Feasibility study on mimicking the tail-beating supported gliding flight of flying fish](#). *Ocean Engineering*, 287, 115745.
4. Pham, T.H., **Nguyen, K.**, Park, H.C., **2023**, [A robotic fish capable of fast underwater swimming and water leaping with high Froude number](#). *Ocean Engineering*, 268, 113512.
5. **Nguyen, K.**, Au, L.T.K., Phan, H.V., Park, H.C., **2021**, [Comparative dynamic flight stability of insect-inspired flapping-wing micro air vehicles in hover: Longitudinal and lateral motions](#). *Aerospace Science and Technology*, 119, 107085
6. **Nguyen, K.**, Au, L.T.K., Phan, H.V., Park, S.H., Park, H.C., **2021**, [Effects of wing kinematics, corrugation, and clap-and-fling on aerodynamic efficiency of a hovering insect-inspired flapping-wing micro air vehicle](#). *Aerospace Science and Technology*, 118, 106990
7. Tran, D.K.K., **Nguyen, K.**, Le, T.H.H., Nguyen, N.H., **2020**, [Numerical simulation for the forward flight of the tri-copter using virtual blade model](#). *Journal of Advanced Research in Fluid Mechanics and Thermal Sciences*, 67, 1, 1-32

## CONFERENCE PAPERS

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1. **Nguyen, K.**, Ha, G.H., Park, H.C., [Design and fabrication of high-thrust tail-beating mechanism for fish-inspired swimming robot](#), Int'l Conf. of Intelligent Unmanned System (ICIUS), Bandung, *Indonesia*, Aug. 20-24, 2024. **(Presenter)**
2. **Nguyen, K.**, Park, H.C., [Analytical and experimental performance verifications of a fast-swimming robotic fish](#), Int'l Conf. of Intelligent Unmanned System (ICIUS), Bandung, *Indonesia*, Aug. 20-24, 2024. **(Presenter)**
3. **Nguyen, K.**, Kang, T.S., Park, H.C., [Hovering characteristics of an insect-like flapping-wing robot on Mars](#), Proceedings of Korean Society for Aeronautical and Space Sciences (KSAS), *Korea*, Nov. 16, 2023. **(Presenter)**
4. **Nguyen, K.**, Ha, G.H., Park, H.C., [Preliminary design of a fish-like fast robot by scaling of the KUFish](#), Int'l Conf. of Intelligent Unmanned System (ICIUS), Adelaide, *Australia*, July 5-7, 2023.
5. **Nguyen, K.**, Park, H.C., [Roles of hydrodynamic forces generated by tail-beating motion in gliding flight of flying-fish-mimicking robot](#), Int'l Conf. of Intelligent Unmanned System (ICIUS), Adelaide, *Australia*, July 5-7, 2023. **(Presenter)**
6. Ha, G.H., **Nguyen, K.**, Park, H.C., [Thrust generation by flapping-wings under the low-air density condition](#), Int'l Conf. of Intelligent Unmanned System (ICIUS), Adelaide, *Australia*, July 5-7, 2023.
7. Le, T.H.H., **Nguyen, K.**, Tran, M.H., [Numerical analysis for aerodynamic characteristics of the unmanned aerial vehicle \(UAV\) in forward flight](#), Southeast Asia Workshop on Aerospace Engineering (SAWAE), *Thailand*, 2023.
8. **Nguyen, K.**, Pham, T.H., Park, H.C., [Numerical investigation of hydrodynamics for a fish-like robot under undulatory forward swimming](#), Proceedings of the Korean Society of Mechanical Engineers Annual Meeting, Jeju, *Korea*, 2022. **(Presenter)**
9. Ha, G.H., **Nguyen, K.**, Park, H.C., [Prediction of flapping wing characteristics in ultra-low air-density condition using a dynamic model](#), Int'l Conf. of Intelligent Unmanned System (ICIUS), Tokushima, *Japan*, Aug. 9-12, 2022.
10. Pham, T.H., **Nguyen, K.**, Park, H.C., [Leaping out of water of the KUFish: Prediction and demonstration](#), ICIUS, Tokushima, *Japan*, Aug. 9-12, 2022. (Selected best paper award)
11. **Nguyen, K.**, Pham, T.H., Park, H.C., [Numerical estimation of hydrodynamic thrust using the measured tail-beating kinematics of a fish-like robot](#), ICIUS, Tokushima, *Japan*, Aug. 9-12, 2022. **(Presenter)**
12. **Nguyen, K.**, Au, L.T.K., Phan, Hoang Vu and Park, H.C., [Wing kinematics modulation in an insect-like tailless flapping wing micro air vehicle \(FW-MAV\) for higher aerodynamic efficiency](#), ICIUS, *Vietnam*, Aug. 25-27, 2021. **(Presenter)**
13. Dao, T.T., **Nguyen, K.**, and Park, H.C., [CFD and FSI-based parametric study on tail fin for high-speed underwater locomotion](#), ICIUS, *Vietnam*, Aug. 25-27, 2021.
14. **Nguyen, K.**, Au, L.T.K., and Park, H.C., [Three-dimensional wing kinematics for improved aerodynamic performance of insect-like flapping-wing micro air vehicle](#), KSAS, *Korea*, 2020. **(Presenter)**
15. Au, L.T.K., **Nguyen, K.**, Park, H.C., [Effect of wing corrugation on aerodynamic performance in 3D flapping wings](#), Proceedings of Korean Society for Aeronautical and Space Sciences (KSAS), *Korea*, 2019. **(Presenter)**
16. Tran, D.K.K., **Nguyen, K.**, Le, T.H.H., [Numerical simulation for the forward flight of the tri-copter using Virtual Blade Model](#), Southeast Asia workshop on Aerospace Engineering (SAWAE), *Malaysia*, 2019.
17. **Nguyen, K.**, Nguyen, N.H., Le, T.H.H., [Numerical approach for the vertical take-off and landing UAVs using the virtual blade model](#), Southeast Asia workshop on Aerospace Engineering (SAWAE), *Thailand*, 2018. **(Presenter)**