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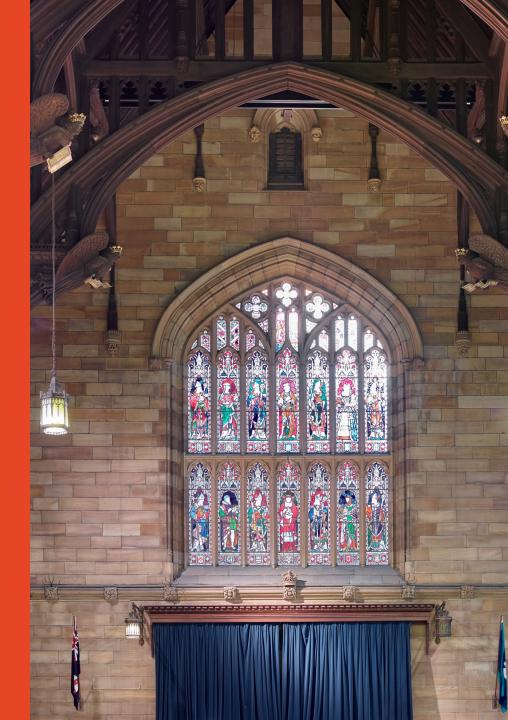
#### Data structures and Algorithms

Lecture 5: Priority Queues [GT 5]

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Some content is taken from material provided by the textbook publisher Wiley.





## **Priority Queue ADT**

Special type of ADT map to store a collection of key-value items where we can only remove smallest key:

- insert(k, v): insert item with key k and value v
- remove\_min(): remove and return the item with smallest key
- min(): return item with smallest key
- size(): return how many items are stored
- is\_empty(): test if queue is empty

We can also have a max version of this min version, but we cannot use both versions at once.

# **Example**

A sequence of priority queue methods:

Method	Return value	<b>Priority queue</b>
insert(5,A)		{(5,A)}
insert(9,C)		{(5,A),(9,C)}
insert(3,B)		{(3,B),(5,A),(9,C)}
min()	(3 <b>,</b> B)	{(3,B),(5,A),(9,C)}
remove_min()	(3 <b>,</b> B)	{(5,A),(9,C)}
insert(7,D)		{(5,A),(7,D),(9,C)}
remove_min()	(5,A)	{(7,D),(9,C)}
remove_min()	(7 <b>,</b> D)	{(9,C)}
remove_min()	(9,C)	{}
is_empty()	true	{}

## **Application: Stock Matching Engines**

At the heart of modern stock trading systems are highly reliable systems known as **matching engines**, which match the stock trades of buyers and sellers.

Buyers post bids to buy a number of shares of a given stock at or below a specified price

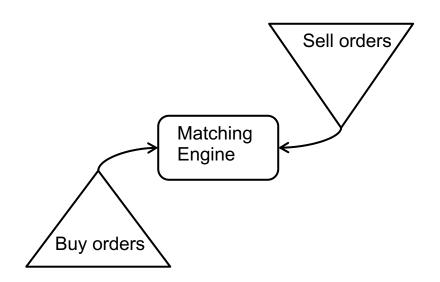
Sellers post offers (asks) to sell a number of shares of a given stock at or above a specified price. STOCK: EXAMPLE.COM
Buy Orders Sell Orders

Shares	Price	Time	Shares	Price	Time
1000	4.05	20 s	500	4.06	13 s
100	4.05	6 s	2000	4.07	46 s
2100	4.03	20 s	400	4.07	22 s
1000	4.02	3 s	3000	4.10	54 s
2500	4.01	81 s	500	4.12	2 s
			3000	4.20	58 s
			800	4.25	33 s
			100	4.50	92 s

## **Application: Stock Matching Engines**

Buy and sell orders are organized according to a price-time priority, where price has highest priority and time is used to break ties

When a new order is entered, the matching engine determines if a trade can be immediately executed and if so, then it performs the appropriate matches according to price-time priority.



STOCK: EXAMPLE.COM
Buy Orders Sell Orders

Shares	Price	Time	Shares	Price	Time
1000	4.05	20 s	500	4.06	13 s
100	4.05	6 s	2000	4.07	46 s
2100	4.03	20 s	400	4.07	22 s
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			100	4.50	92 s

## **Application: Stock Matching Engines**

A matching engine can be implemented with two **priority queues**, one for buy orders and one for sell orders.

This data structure performs element removals based on priorities assigned to elements when they are inserted.

# while True: bid ← buy\_orders.remove\_max() ask ← sell orders.remove\_min()

else

buy\_orders.insert(bid)
sell\_orders.insert(ask)

# STOCK: EXAMPLE.COM Buy Orders Sell Orders

Shares	Price	Time	Shares	Price	Time
1000	4.05	20 s	500	4.06	13 s
100	4.05	6 s	2000	4.07	46 s
2100	4.03	20 s	400	4.07	22 s
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2500	4.01	81 s	500	4.12	2 s
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			800	4.25	33 s
			100	4.50	92 s

## **Sequence-based Priority Queue**

#### **Unsorted** list implementation

# 4-5-2-3-1

- insert in O(1) time since we can insert the item at the beginning or end of the sequence
- remove\_min and min in O(n) time
   since we have to traverse the
   entire list to find the smallest key

#### Sorted list implementation



- insert in O(n) time since we have to find the place where to insert the item
- remove\_min and min in O(1) time since
   the smallest key is at the beginning

Method	Unsorted List	Sorted List
size, isEmpty	O(1)	O(1)
insert	O(1)	O(n)
min, removeMin	O(n)	O(1)

## **Priority Queue Sorting**

We can use a priority queue to sort a list of keys:

- 1. iteratively insert keys into an empty priority queue
- 2. iteratively remove\_min to get the keys in sorted order

#### Complexity analysis:

- n insert operations
- n remove\_min operations

Either sequence-based implementation take  $O(n^2)$ 

Method	Unsorted List	Sorted List
size, isEmpty	O(1)	O(1)
insert	O(1)	O(n)
min, removeMin	O(n)	O(1)

```
def priority_queue_sorting(A):
    pq ← new priority queue
    n ← size(A)
    for i in [0, n) do
        pq.insert(A[i])
    for i in [0, n) do
        A[i] = pq.remove_min()
```

#### **Selection-Sort**

Variant of pq-sort using unsorted sequence implementation:

- 1. inserting elements with n insert operations takes O(n) time
- 2. removing elements with n remove\_min operations takes  $O(n^2)$

```
Can be done in place (no need for extra space)
```

#### Top level loop invariant:

- A[0, i) is sorted
- A[i, n) is the priority queue
   and all ≥ A[i-1]

```
def selection_sort(A):
    n ← size(A)
    for i in [0, n) do
        # find s ≥ i minimizing A[s]
        s ← i
        for j in [i, n) do
            if A[j] < A[s] then
            s ← j
        # swap A[i] and A[s]
        A[i], A[s] ← A[s], A[i]</pre>
```

#### **Selection-Sort Example**

i	A	s
0	<u>7, 4, 8, 2, 5, 3, 9</u>	3
1	2, <u>4</u> , 8, 7, 5, <u>3</u> , 9	5
2	2, 3, <u>8</u> , 7, 5, <u>4</u> , 9	5
3	2, 3, 4, <u>7</u> , <u>5</u> , 8, 9	4
4	2, 3, 4, 5, <u>7</u> , 8, 9	4
5	2, 3, 4, 5, 7, <u>8</u> , 9	5
6	2, 3, 4, 5, 7, 8, <u>9</u>	6

```
def selection_sort(A):
    n ← size(A)
    for i in [0, n) do
        # find s ≥ i minimizing A[s]
        s ← i
        for j in [i, n) do
            if A[j] < A[s] then
            s ← j
        # swap A[i] and A[s]
        A[i], A[s] ← A[s], A[i]</pre>
```

#### **Insertion-Sort**

Variant of pq-sort using sorted sequence implementation:

- 1. inserting elements with n insert operations takes  $O(n^2)$  time
- 2. removing elements with n remove\_min operations takes O(n)

```
Can be done in place (no need for extra space)
```

Top level loop invariant:

- A[0, i) is the priority queue
   (and thus sorted)
- A[i, n) is yet-to-be-inserted

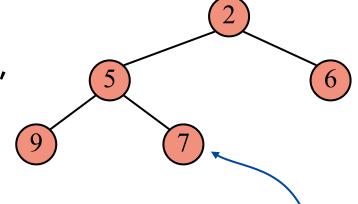
#### **Insertion-Sort Example**

i	Α	i
1	<u>7, 4,</u> 8, 2, 5, 3, 9	0
2	4, 7, <u>8</u> , 2, 5, 3, 9	2
3	<u>4, 7, 8, 2, 5, 3, 9</u>	0
4	2, 4, <u>7</u> , 8, <u>5</u> , 3, 9	2
5	2, <u>4</u> , 5, 7, 8, <u>3</u> , 9	1
6	2, 3, 4, 5, 7, 8, <u>9</u>	6

## Heap data structure (min-heap)

A heap is a binary tree storing (key, value) items at its nodes, satisfying the following properties:

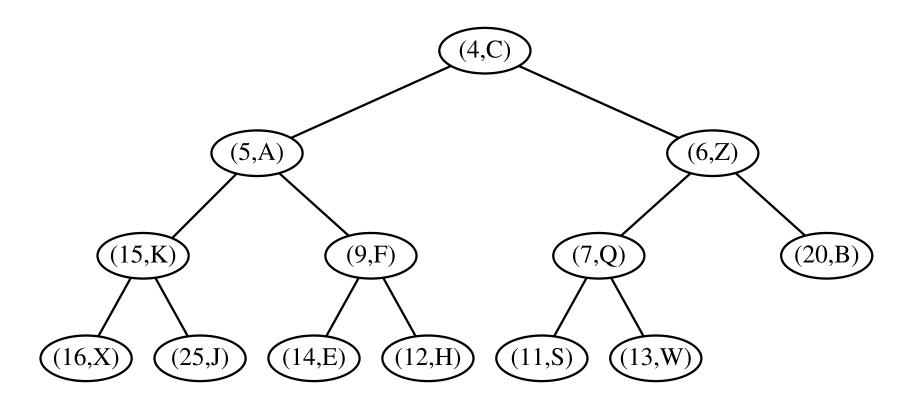
 Heap-Order: for every node m ≠ root, key(m) ≥ key(parent(m))



- 2. Complete Binary Tree: let h be the height
  - every level i < h is full (i.e., there are  $2^i$  nodes)
  - remaining nodes take leftmost positions of level h

The last node is the rightmost node of maximum depth

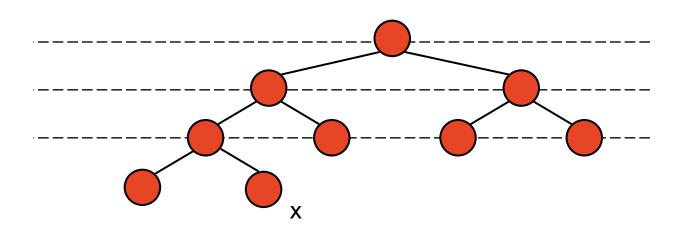
# **Example**



#### Minimum of a Heap

Fact: The root always holds the smallest key in the heap Proof:

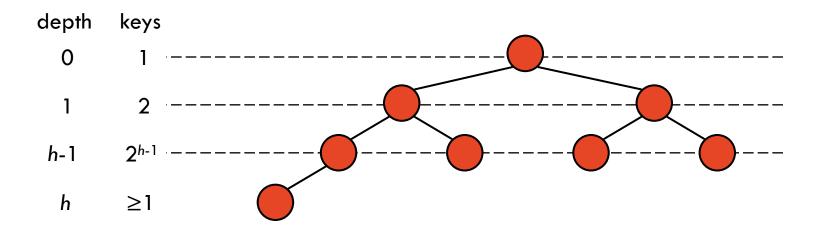
- Suppose the minimum key is at some internal node x
- Because of the heap property, as we move up the tree, the keys can only get smaller (assuming repeats, otherwise contradiction)
- If x is not the root, then its parent must also hold a smallest key
- Keep going until we reach the root



#### Height of a Heap

Fact: A heap storing *n* keys has height log *n* Proof:

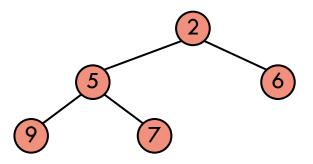
- Let h be the height of a heap storing n keys
- Since there are  $2^i$  keys at depth  $i=0,\ldots,h-1$  and at least one key at depth h, we have  $n\geq 1+2+4+\ldots+2^{h-1}+1$
- Thus,  $n \ge 2^h$ , applying  $\log_2$  on both sides,  $\log_2 n \ge h$

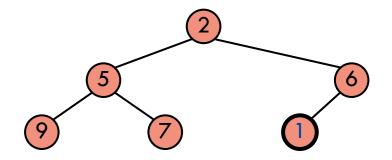


## Insertion into a Heap

- Create a new node with given key
- Find location for new node
- Restore the heap-order property

#### insert(1)





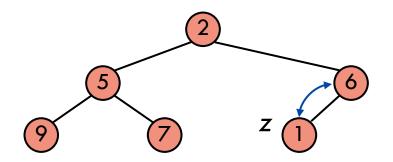
## Upheap

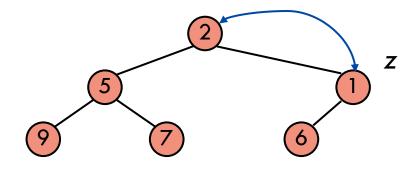
Restore heap-order property by swapping keys along upward path from insertion point

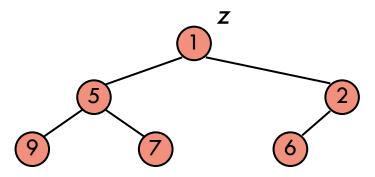
```
def up_heap(z):
    while z ≠ root and
        key(parent(z)) > key(z) do
        swap key of z and parent(z)
        z ← parent(z)
```

Correctness: after swapping the subtree rooted at z has the property

Complexity: O(log n) time because the height of the heap is log n



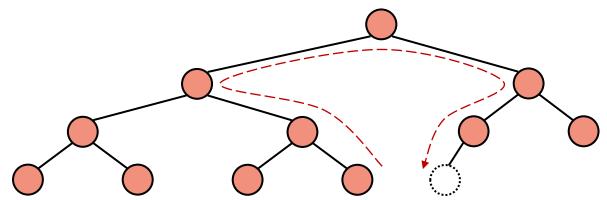




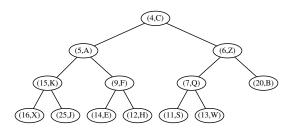
## Finding the position for insertion

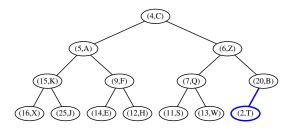
- start from the last node
- go up until a left child or the root is reached
- if we reach the root then need to open a new level
- otherwise, go to the sibling (right child of parent)
- go down left until a leaf is reached

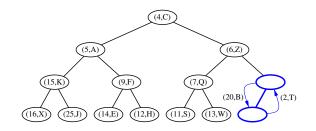
Complexity of this search is  $O(\log n)$  because the height is  $\log n$ . Thus, overall complexity of insertion is  $O(\log n)$  time

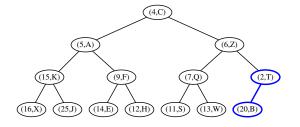


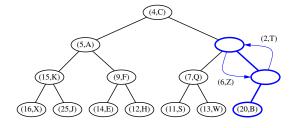
## **Example insertion**

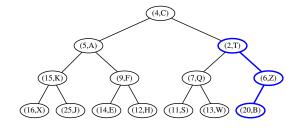


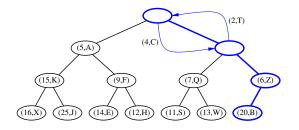


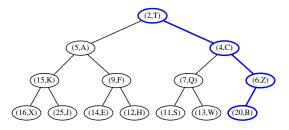








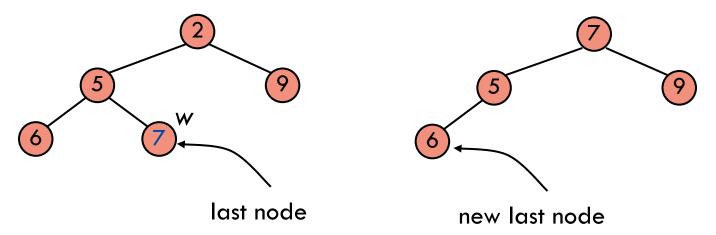




#### Removal from a Heap

- Replace the root key with the key of the last node w
- Delete w
- Restore the heap-order property

remove\_min()

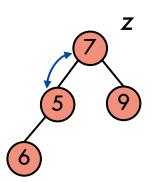


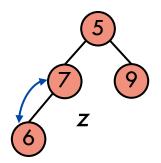
#### Downheap

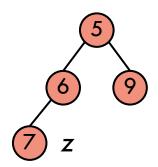
Restore heap-order property by swapping keys along downward path from the root

Correctness: after swap z heaporder property is restored up to level of z

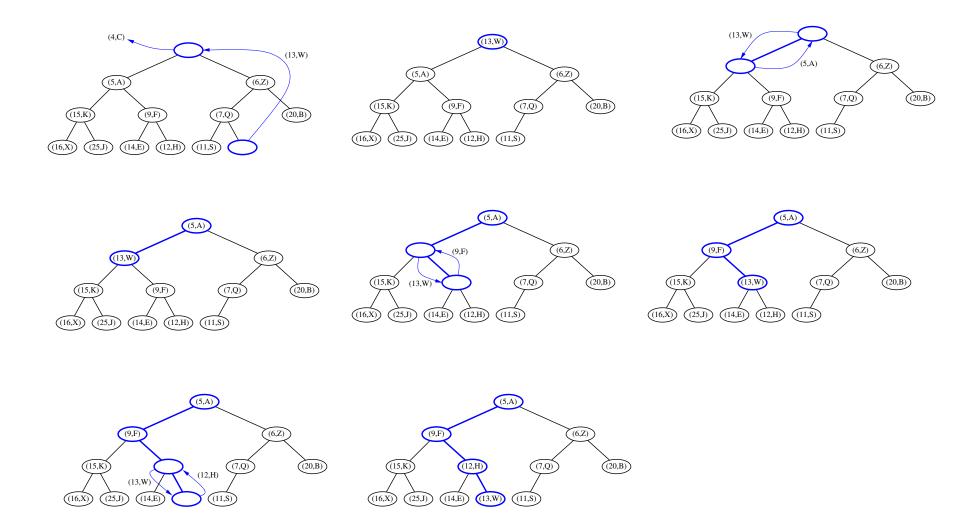
Complexity: O(log n) time because the height of the heap is log n







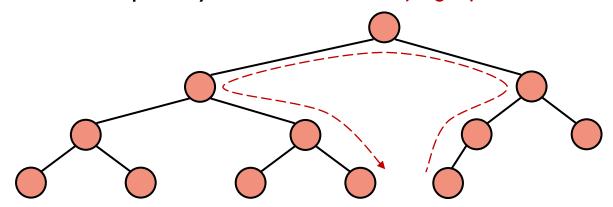
#### **Example removal**



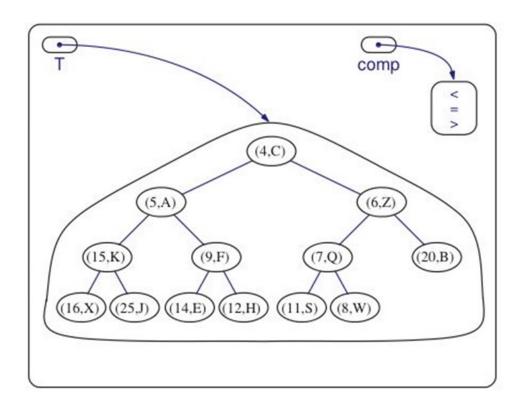
## Finding next last node after deletion

- start from the (old) last node
- go up until a right child or the root is reached
- if we reach the root then need to close a level
- otherwise, go to the sibling (left child of parent)
- go down right until a leaf is reached

Complexity of this search is  $O(\log n)$  because the height is  $\log n$ . Thus, overall complexity of deletion is  $O(\log n)$  time



## Heap-based implementation of a priority queue



Operation	Time
size, isEmpty	O(1)
min,	O(1)
insert	$O(\log n)$
removeMin	$O(\log n)$

## **Heap-Sort**

Consider a priority queue with *n* items implemented with a heap:

- the space used is O(n)
- methods insert and remove\_min take O(log n)

Recall that priority-queue sorting uses:

- n insert ops
- n remove\_min ops

Heap-sort is the version of priority-queue sorting that implements the priority queue with a heap. It runs in O(n log n) time.

## Heap-in-array implementation

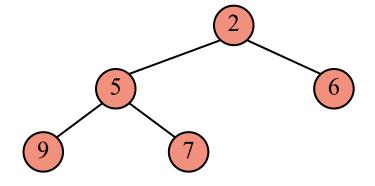
We can represent a heap with n keys by means of an array of length n

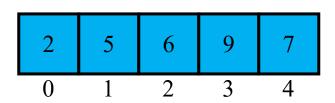
#### Special nodes:

- root is at 0
- last node is at n-1

#### For the node at index i:

- the left child is at index 2i+1
- the right child is at index 2i+2
- Parent is at index (i-1)/2





#### Refinements and Generalization

Heap-sort can be arranged to work in place using part of the array for the output and part for the priority queue

A heap on n keys can be constructed in O(n) time. But the n remove\_min still take  $O(n \log n)$  time

Sometimes it is useful to support a few more operations (all all given a pointer to e):

- remove(e): Remove item e from the priority queue
- replace\_key(e, k): update key of item e with k
- replace\_value(e, v): update value of item e with v

# **Summary: Priority queue implementations**

Method	Unsorted List	Sorted List	Heap
size, isEmpty	O(1)	O(1)	O(1)
insert	O(1)	O(n)	$O(\log n)$
min	O(n)	O(1)	O(1)
removeMin	O(n)	O(1)	$O(\log n)$
remove	O(1)	O(1)	$O(\log n)$
replaceKey	O(1)	O(n)	$O(\log n)$
replaceValue	O(1)	O(1)	O(1)

# Implementing a Priority Queue

Entries: An object that keeps track of the associations between keys and values

Comparators: A function or an interface to compare entry objects

compare(a, b): returns an integer i such that

- i < 0 if a < b,
- i = 0 if a = b
- i > 0 if a > b

Warning: do not assume that compare(a,b) is always -1, 0, 1

#### **Stock Application Revisited**



Online trading system where orders are stored in two priority queues (one for sell orders and one for buy orders) as (p, t, s) entries:

- The key is (p, t), the price of the order p and the time t
   such that we first sort by p and break ties with t
- The value is s, the number of shares the order is for

How do we implement the following:

- What should we do when a new order is placed?
- What if someone wishes to cancel their order before it executes?
- What if someone wishes to update the price or number of shares for their order?