

# Group Roles

## **Project Leader**

**Besma Belakhal**

(responsible for organisational part and communication with us (e.g. submitting weekly reports) and should keep track of progress and deadlines)

## **Robotics Group Leader**

**Omar Draidrya** (David)

## **Vision Group Leader**

**Selva Nachimuthu** (Andrei, Besma)

## **ROS interface coordinator**

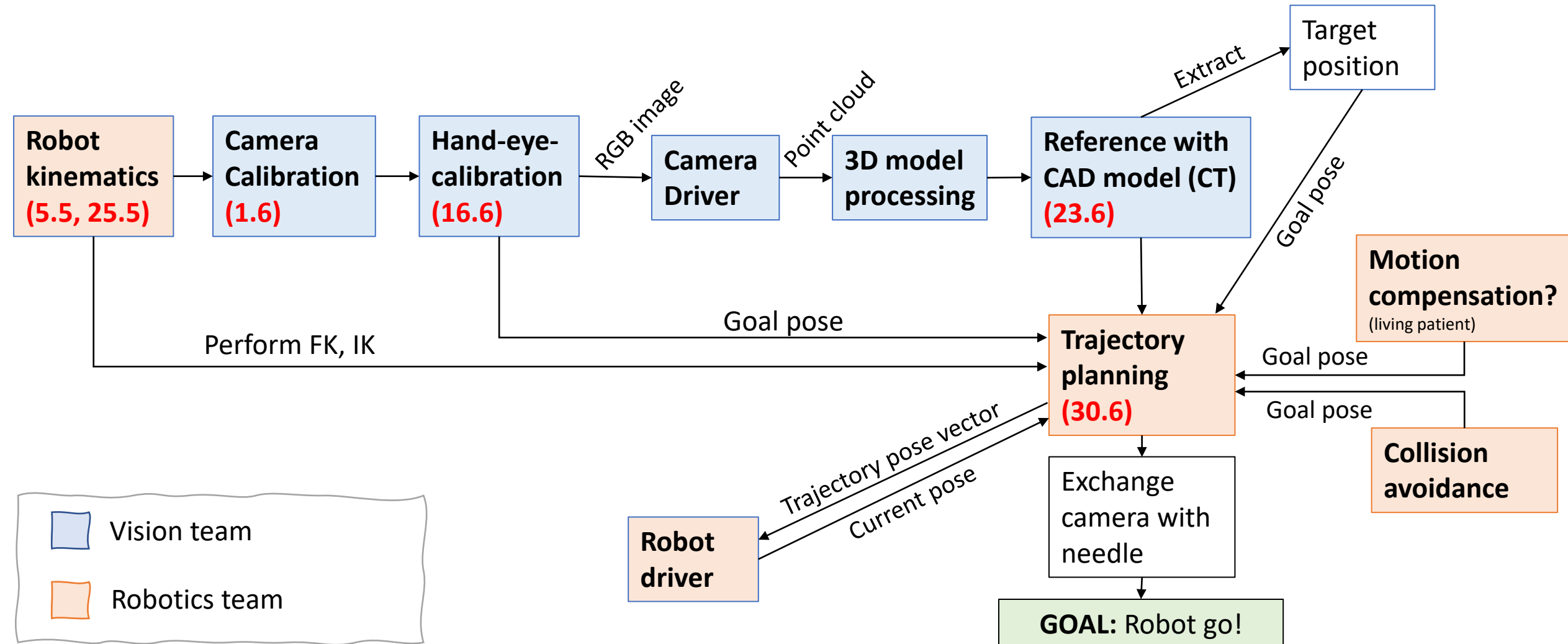
**Manav Thakkar**

(to ensure that all parts of the group can and will be brought together at the end of the project)

Participants in brackets are part of the work group for that topic.

# Project Plan

## Interface Sketch + Deadlines



# Deadlines + Subgoals

Deadlines	Date
Project plan	27 <sup>th</sup> of April
Inverse kinematics	25 <sup>th</sup> of May
Project presentation	10.07-13.07
Project report	15 <sup>th</sup> of August

Subgoals	Date
Working forward kinematics of the Panda	5 <sup>th</sup> of May
Working inverse kinematics of the Panda	25 <sup>th</sup> of May
Working camera calibration	1 <sup>st</sup> of June
Working hand-eye calibration	16 <sup>th</sup> of June
Model recording and registration	23 <sup>rd</sup> of June
Planning of feasible needle path	30 <sup>th</sup> of June