

# Arithmetic Operations with Call Operations

## Abstract:

The main focus of this assignment is on the concepts of arithmetic operation implementation in pic18f452 by writing code in assembly language. It also focuses on how subroutines are written in assembly and how to invoke them using call operation. It also addresses the concept of different type of overflows in multiplication, carry flags in addition which occurs when a calculation exceeds the maximum storage capacity of a system's data type, which can ultimately lead to incorrect results. It also addresses the problem of division of any number by zero.

## Objective:

- Demonstrate basic arithmetic operations (addition, subtraction, multiplication, division) for unsigned numbers in Assembly programming.
- Understanding of call instruction for invoking subroutine.
- Efficient Code Writing and improvement in debugging skills.

## Question # 1

- Addition and Subtraction Using CALL

Write an Assembly program to perform addition and subtraction of two unsigned numbers by making separate subroutines.

- CODE:

### Explanation:

This code implements an assembly program for the PIC18F452 microcontroller that performs addition and subtraction of two 8-bit inputs provided via PORTB and PORTC. The results are displayed on PORTD. If a carry occurs during addition, the first bit of PORTE is set to 1 as an indicator. The program loops infinitely, displaying the results with a delay between operations.

```
;in this code there are two sub routines one for addition and one for subtraction  
;after taking 8 bit input from user, addition and subtraction are performed respectively  
;in addition if there is a carry generated, it is represented by setting porte of pic to 1
```

```
LIST P=18F452
```

```
#include <p18f452.inc>
```

```
result EQU 0x32 ;to store the end_result of addition and subtraction
```

ORG 0x00 ;sssigning starting memory location

GOTO START ; to jump onto the main part of the code

-----Addition-----

;subroutein to perform addition on input taken from user

ADD\_1:

MOVFB PORTB, W ;load 8-bit input 1 from port b to working register

ADDWFB PORTC, W ;add 8-bit input 2 from PORTC to Working register(having input 1)

MOVWFB result ;store the result,by moving value stored in working register after addition to file location named as result

;to check if there was a carry in the addition

;if bit in staus register for carry flag is set than it will skip next instruction of jumping onto label no\_carry

BTFSS STATUS, C ;to check if the carry flag is set, ifit is set it will skip next instruction and will go on instruction of setting porte to 1

GOTO NO\_CARRY ;if there is no carry, jump to NO\_CARRY

;setting porte first bit to 1 to indicate the carry flag

BSF PORTE, 0 ;bit set file here sets the porte first bit to 1, only first bit is set bcz i am only using first bit for output

;if there is no carry generated than it will simply return to the program insruction from where specificed subrouteinis called

NO\_CARRY:

RETURN

-----Subtraction-----

;subroutein to perform subtraction on input taken from user

SUB\_1:

MOVWF PORTC, W ;load 8-bit input 1 from port b to working register

SUBWF PORTB, W ;subtract 8-bit input 2 (from PORTC) from Working register(having input 1)

MOVWF result ;store the result,by moving value stored in working register after subtraction to file location named as result

RETURN

;-----Delay\_Function-----

;subroutine to give a delay after displaying one result on output portd

DELAY:

MOVLW 0xFF ;loading delay counter to working register

MOVWF 0x20 ;storing counter at memory location of 0x20

DelayLoop1:

MOVLW 0xFF ;loading another delay counter for inner loop into working register

MOVWF 0x21 ;storing inner loop counter at memory location of 0x21

DelayLoop2:

DECFSZ 0x21, F ;decrementing inner counter until it becomes equal to zero and storing back at its own location in memory

GOTO DelayLoop2 ;jumping back to inner loop until the inner loop counter becomes zero

DECFSZ 0x20, F ;decrementing outer counter until it becomes equal to zero and storing back at its own location in memory

GOTO DelayLoop1 ;jumping back to outer loop until the outer loop counter becomes zero

RETURN

;-----Main\_Program-----

START:

;configure portb as input for input 1

MOVLW 0xFF ;moving 1 to working register

```
MOVWF TRISB      ;moving value from working register to file location basically to set portb
as input port
```

```
;configure portc as input for input 2
```

```
MOVLW 0xFF      ;moving 1 to working register
```

```
MOVWF TRISC      ;moving value from working register to file location basically to set portc
as input port
```

```
;configure portd as output for resultant output
```

```
CLRF PORTD      ;clearing portd
```

```
MOVLW 0x00      ;moving 0 to working register
```

```
MOVWF TRISD      ;moving value from working register to file location basically to set portd
as output port
```

```
;configure porte as output for resultant output
```

```
CLRF PORTE      ;clearing porte
```

```
MOVLW 0x00      ;moving 0 to working register
```

```
MOVWF TRISE      ;moving value from working register to file location basically to set porte
as output port
```

```
;configure porta as output for resultant output
```

```
CLRF PORTA      ;clearing porta
```

```
MOVLW 0x00      ;moving 0 to working register
```

```
MOVWF TRISA      ;moving value from working register to file location basically to set porta
as output port
```

```
MAIN_LOOP:
```

```
;-----calling addition subroutine-----
```

```
CALL ADD_1      ;calling subroutine add_1 to perform addition
```

```
MOVF result, W   ;loading result of addition stored in file location result into a working
register
```

```

MOVWF PORTD    ;loading output of addition from working register to portd for output
display purpose

CALL DELAY      ;waiting for sometime to differ between different results by creating a delay
of our own choice by calling delay subroutein

;-----calling subtraction subroutein-----

CALL SUB_1      ;calling subrouteine sub_1 to perform subtraction

MOVF result, W  ;loading result of subtraction stored in file location result into a working
register

MOVWF PORTD     ;loading output of subtraction from working register to portd for output
display purpose

CALL DELAY      ;waiting for sometime to differ between different results by creating a delay
of our own choice by calling delay subroutein

GOTO MAIN_LOOP  ;to repeat process infinetely

END ; ending the program

```

- Output:

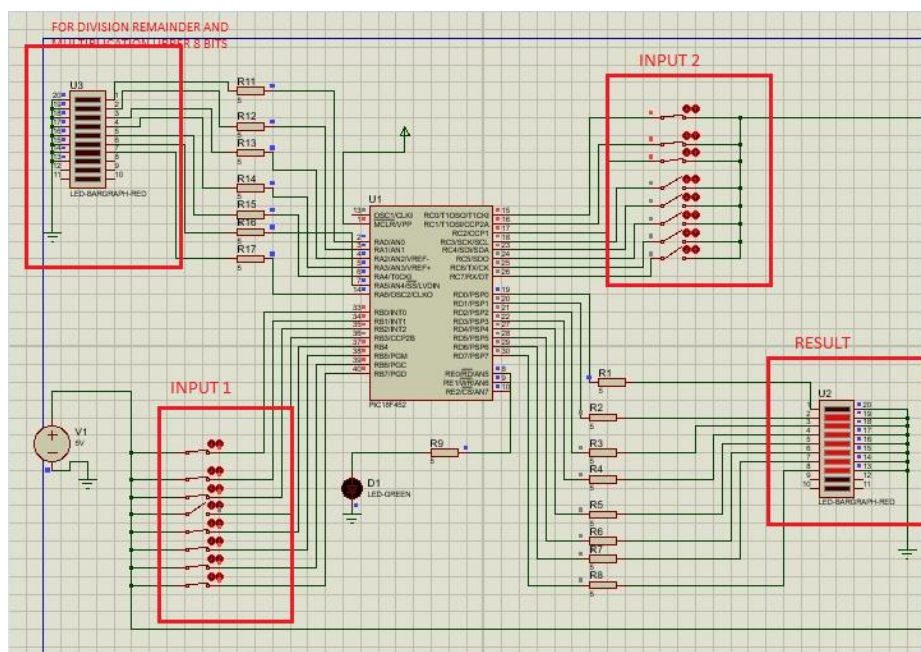


Figure 1: Proteus Circuit to show output of each arithmetic operation

Output after addition between two inputs generating no carry flag:

Input 1= 11110111 in binary and 247 in decimal

Input 2= 00000111 in binary and 7 in decimal

Addition in binary = 11110111 + 00000111 = 11111110 in binary and in decimal 254

Addition in decimal = 247+7 = 254

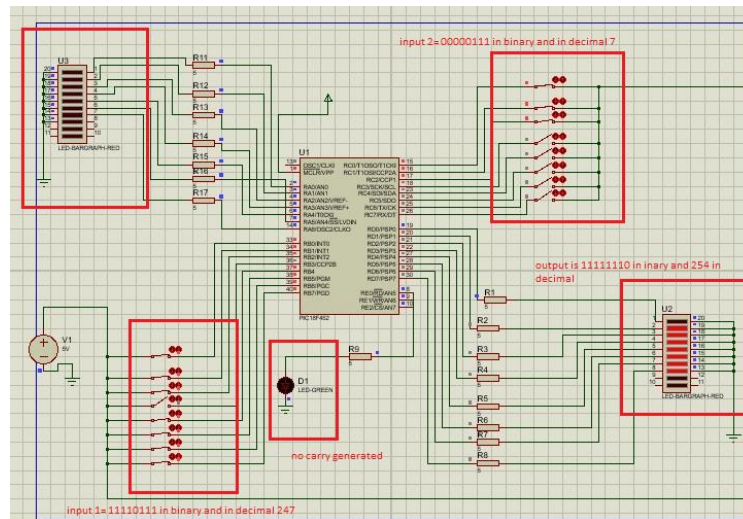


Figure 2: no carry flag is generated when input 1 is added with input 2 of 8-bit number because the resultant was in the range of 8 bit binary (details of inputs and output are highlighted in attached figure)

### Output after addition between two inputs generating with a carry flag:

Input 1= 11110101 in binary and 245 in decimal

Input 2= 10000111 in binary and 135 in decimal

Addition in binary = 11110101 + 10000111 = 11111100 in binary with 1 in carry

Addition in decimal = 135+245 = 380

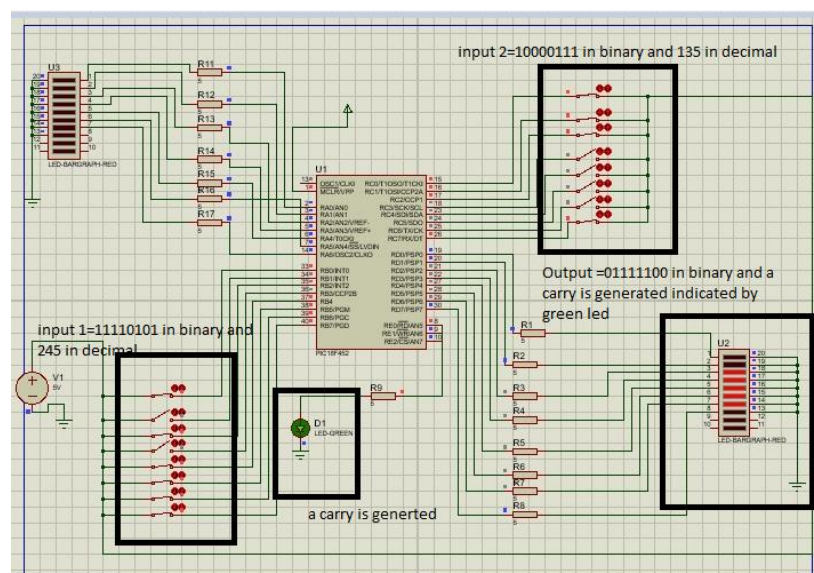


Figure 3: carry flag is generated (which is shown by green led) when input 1 is added with input 2 of 8-bit number because the resultant was out of the range of 8 bit binary (details of inputs and output are highlighted in attached figure)

### Output after subtraction between two inputs:

Input 1= 11110111 in binary and 247 in decimal

Input 2= 00000111 in binary and 7 in decimal

Subtraction in binary = 11110111 - 00000111 = 11110000 in binary and in decimal 240

Subtraction in decimal = 247-7 = 240

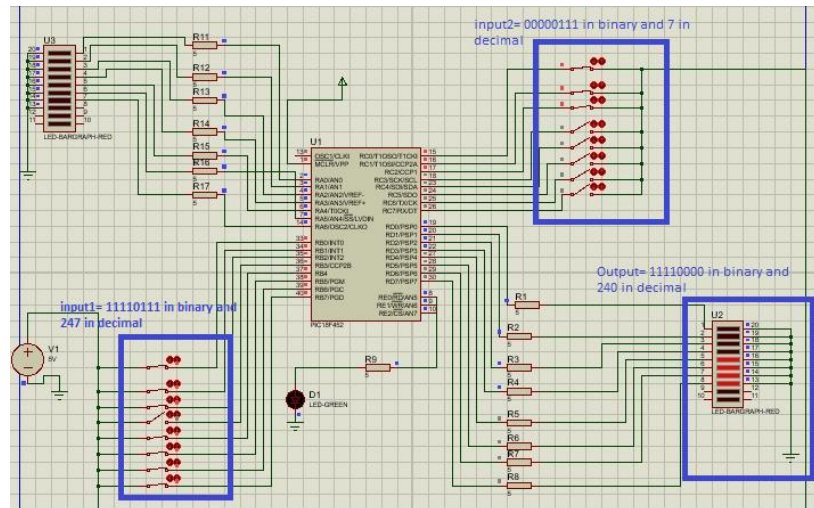


Figure 4: when input 1 is subtracted from input 2 of 8-bit number and result is shown with led bar-graph (details of inputs and output are highlighted in attached figure)

## Question # 2

- Multiplication and Division Using CALL

Write an Assembly program to perform Multiplication and Division of two unsigned numbers by making separate subroutines.

- CODE:

Explanation:

This code uses the PIC18F452 microcontroller to perform multiplication and division of two 8-bit inputs from PORTB and PORTC. For multiplication, lower 8 bits are displayed on PORTD and upper bits on PORTA, handling overflow. For division, the quotient is shown on PORTD, the remainder on PORTA, and PORTE is used to indicate division by zero. A delay routine separates result displays.

```
;in this code there are two sub routines one for multiplication and one for division
;after taking 8 bit input from user, multiplication and division are performed respectively
;in division if divisor is zero than led at porte is turned on, it is represented by setting porte of
pic to 1
;porte first bit is set to 1 to indicate that division by zero is not possible
;in division quotient and remainder are shown at different ports
;quotient is displayed on portd while remainder is displayed on porta
```

;in case of multiplication there is chances of number exceeding 8 bits

;exceeding of bits is possible because when two 8 bits number are multiplied their range increases

;to show correct result of multiplication lower 8 bits are displayed on portd

;the upper bits of multiplication is displayed over porta

LIST P=18F452

#include <p18f452.inc>

temp\_num1 EQU 0x30 ;memory location reserved for temporary storage of input 1 in multiplication

temp\_num2 EQU 0x31 ;memory location reserved for temporary storage of input 2 in multiplication

result EQU 0x32 ;to store lower 8 bits of result of multiplication and in case of division to store quotient

result2 EQU 0x33 ;to store upper 8 bits of result of multiplication and in case of division to store remainder but because of only 7 pins available we are omitting one bit

carry EQU 0x34 ;temporary carry in multiplication to help in code to check if resultant of multiplication has exceeded 8 bits

ORG 0x00 ;sssigning starting memory location

GOTO START ;to jump onto the main part of the code

;-----Division-----

;subroutin for division of two numbers

DIV\_1: ;division by repeated subtractions

CLRF result ;clearing result to avoid garbage values

MOVF PORTB, W ;loading dividend from portb to working register

MOVWF 0x31 ;storing dividend temporarily at memory location 0x31

MOVF PORTC, W ;loading divisor from portc into working register



BTFSS PORTC, 0 ;to check if bit in portc are zero, if it is not zero it will skip next instruction else it will jump to div\_zero

GOTO DIV\_ZERO ;on having divisor equals to zero jumping at label div\_zero

DIV\_Quotient: ;for calculation of division quotient

MOVF 0x31,W ;loading dividend into working register

MOVWF 0x32 ;storing dividend into memory location 0x32 for keeping track of remainder

MOVF PORTC, W ;loading portc value basically divisor into working register

SUBWF 0x31, F ;subtracting divisor from dividend and storing back into same location

BTFSS STATUS, C ;to check if on dividing the remainder is negative if it is negative jumping on the label div\_remainder else skipping the jump on specified label

GOTO DIV\_Remainder ;ending division if on subtraction dividend beocme negative

INCF result, F ;after each subtraction quotient is incremented to get correct disvison quotient

GOTO DIV\_Quotient ;jumping back to label untill division is completely done

DIV\_Remainder: ;for calculation of division remainder

MOVF 0x32, W ;loading remainder into working register

ANDLW 0x7F ;omitting 1 most significant bit because the port available at a are only 7

MOVWF result2 ;storing remainder into result2 to display on porte

RETURN ;returning to instruction from where call to subroutein is made

DIV\_ZERO:

BSF PORTE, 0 ;if divisor is zero led at porte is turned on because first bit of porte is set to 1

RETURN ;returning to instruction from where call to subroutein is made

;-----MULTIPLICATION-----

MUL\_1:

CLRF result ;clearing result to avoid garbage values

CLRF result2 ;clearing result2 to avoid garbage values

CLRF carry ;clearing carry to avoid garbage values

MOVF PORTB, W ;loading num1 from portb into working register

MOVWF temp\_num1 ;storing num1 in temporary memory location temp\_num1

MOVF PORTC, W ;loading num2 from portb into working register

MOVWF temp\_num2 ;storing num2 in temporary memory location temp\_num2

REPEAT\_ADD:

MOVF result, W ;loading current result basically zero to working register

ADDWF temp\_num1, W ;adding number 1 to working register and storing in working register

MOVWF result ;storing the new result after addition into same location for repeated addition

;to check for overflow (carry flag) and handle upper 8 bits

MOVF result, W ;loading lower 8 bits to working register

CPFSLT result2 ;value in working register is compared with result2 to check if it is smaller or not if smaller next instruction is skipped

BTFSS STATUS, C ;if value in working register is not smaller than it is checked if carry flag is set or not

MOVWF carry ;if there is carry store the carry in the memory location intialized with name of carry

MOVF carry, W ;moving the value at memory locaton carry into working register

ADDWF result2, F ;adding the value stored in memory location at carry with working register and storing at same location

DECFSZ temp\_num2, F ;decrementing number 2 to keep check on how many time we have to perform addition

GOTO REPEAT\_ADD ;repeat addition untill the number 2 is equal to zero

MUL\_DONE:

RETURN ;returning to instruction from where call to subroutin is made

;-----Delay\_Function-----

;subroutin to give a dealy after displaying one result on output portd

DELAY:

MOVLW 0xFF ;loading delay counter to working register

MOVWF 0x20 ;soring counter at memory location of 0x20

DelayLoop1:

MOVLW 0xFF ;loading another delay counter for inner loop into working register

MOVWF 0x21 ;storing inner loop counter at memory location of 0x21

DelayLoop2:

DECFSZ 0x21, F ;decrementing inner counter untill it becomes equal to zero and storing back at its own location in memory

GOTO DelayLoop2 ;jumping back to inner loop untill the inner loop counter becomes zero

DECFSZ 0x20, F ;decrementing outer counter untill it becomes equal to zero and storing back at its own location in memory

GOTO DelayLoop1 ;jumping back to outer loop untill the outer loop counter becomes zero

RETURN

;-----Main\_Program-----

START:

;configure portb as input for input 1

MOVLW 0xFF ;moving 1 to working register

MOVWF TRISB ;moving value from working register to file location basically to set portb as input port

;configure portc as input for input 2

```

    MOVLW 0xFF      ;moving 1 to working register

    MOVWF TRISC     ;moving value from working register to file location basically to set portc
as input port

    ;configure portd as output for resultant output

    CLRF PORTD     ;clearing portd

    MOVLW 0x00     ;moving 0 to working register

    MOVWF TRISD     ;moving value from working register to file location basically to set portd
as output port

    ;configure porte as output for resultant output

    CLRF PORTE     ;clearing porte

    MOVLW 0x00     ;moving 0 to working register

    MOVWF TRISE     ;moving value from working register to file location basically to set porte
as output port

    ;configure porta as output for resultant output

    CLRF PORTA     ;clearing porta

    MOVLW 0x00     ;moving 0 to working register

    MOVWF TRISA     ;moving value from working register to file location basically to set porta
as output port
MAIN_LOOP:
    ;-----calling multiplication subroutine-----

    CALL MUL_1     ;calling subroutine mul_1 to perform multiplication

    MOVF result, W  ;loading lower 8 bits of multiplication stored in file location result into a
working register

    MOVWF PORTD     ;loading lower 8 bits of multiplication from working register to portd for
output display purpose

    MOVF result2, W ;loading upper 8 bits of multiplication stored in file location result into a
working register

    MOVWF PORTA     ;loading upper 8 bits of multiplication from working register to porta for
output display purpose

    CALL DELAY     ;waiting for sometime to differ between different results by creating a delay
of our own choice by calling delay subroutine

    ;-----calling division subroutine-----

```

```

CALL DIV_1      ;calling subrouetine div_1 to perform division

MOVWF result, W ;loading quotient of divison stored in file location result into a working
register

MOVWF PORTD     ;loading quotient of divison from working register to portd for output
display purpose

MOVWF result2, W ;loading reaminder of divison stored in file location result into a working
register

MOVWF PORTA     ;loading reaminder of divison from working register to porta for output
display purpose

CALL DELAY      ;waiting for sometime to differ between different results by creating a delay
of our own choice by calling delay subrouetin

GOTO MAIN_LOOP  ;to repeat process infinetely

END ; ending the program

```

- Output:

### Output after multiplication between two inputs within 8-bit range:

Input 1= 00000011 in binary and 3 in decimal

Input 2= 00000011 in binary and 3 in decimal

Multiplication in binary = 00000011 \* 00000011 = 00001001 in binary and in decimal 9

Multiplication in decimal =  $3 \times 3 = 9$

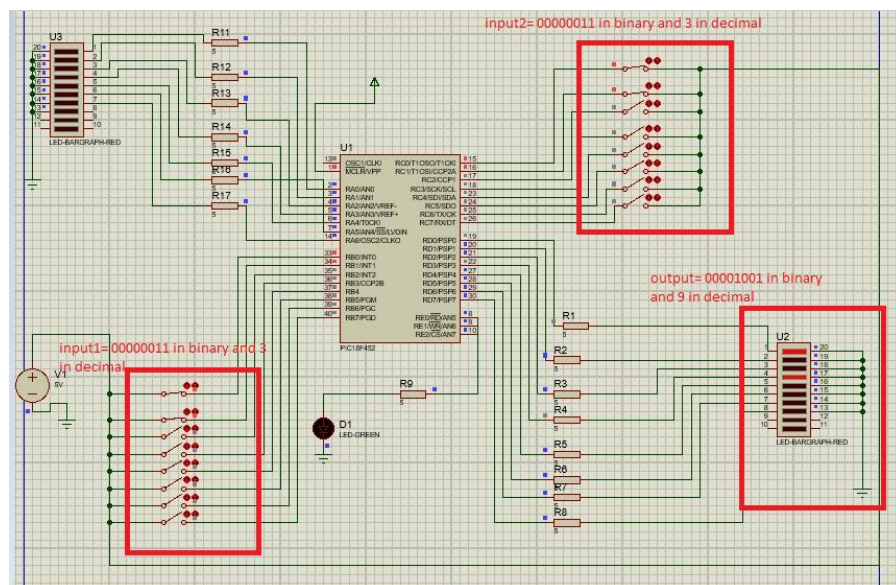


Figure 5: when input 1 is multiplied with input 2 of 8-bit number and the resultant was in the range of 8 bit binary (details of inputs and output are highlighted in attached figure)

### Output after multiplication between two inputs exceeding 8-bit range:

Input 1= 01110111 in binary and 119 in decimal

Input 2= 00000111 in binary and 7 in decimal

Multiplication in binary = 01110111 \* 00000111 = 0000011010000001 in binary and in decimal 883

Multiplication in decimal = 119\*7 = 883

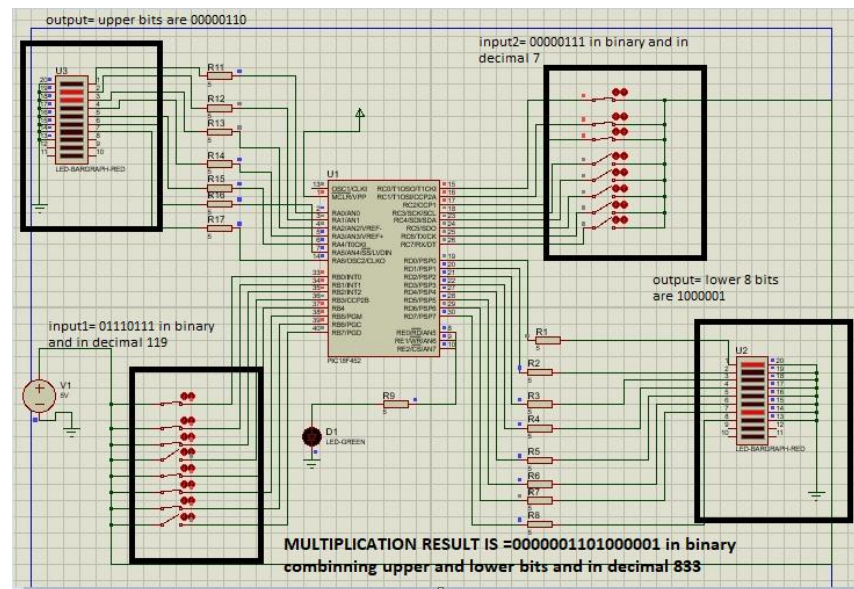


Figure 6: when input 1 is multiplied with input 2 of 8-bit number and the resultant was not in the range of 8 bit binary so lower bits are represented at portd and upper bits at porta (details of inputs and output are highlighted in attached figure)

## Output after division between two inputs but divisor is zero:

Input 1= 00000011 in binary and 3 in decimal

Input 2= 00000000 in binary and 0 in decimal

Division in binary = 00000011 / 00000000 = undefined represented by led turned on that no division is possible

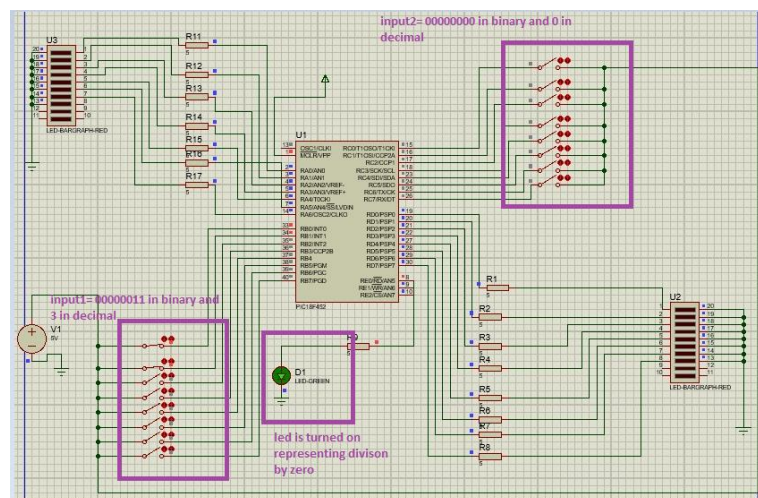


Figure 7: when input 1 is divided by input 2 of 8-bit number but input 2 is zero leading to no division possibility led is turned to show division is not possible (details of inputs and output are highlighted in attached figure)

## Output after division between two inputs but divisor is not zero and there is a remainder:

Input 1= 11110111 in binary and 247 in decimal

Input 2= 00000111 in binary and 7 in decimal

Division in binary =  $11110111 / 00000111 = \text{Quotient } 00100011$  in binary and in decimal 35 and  
Remainder is 00000010 in binary and 2 in decimal

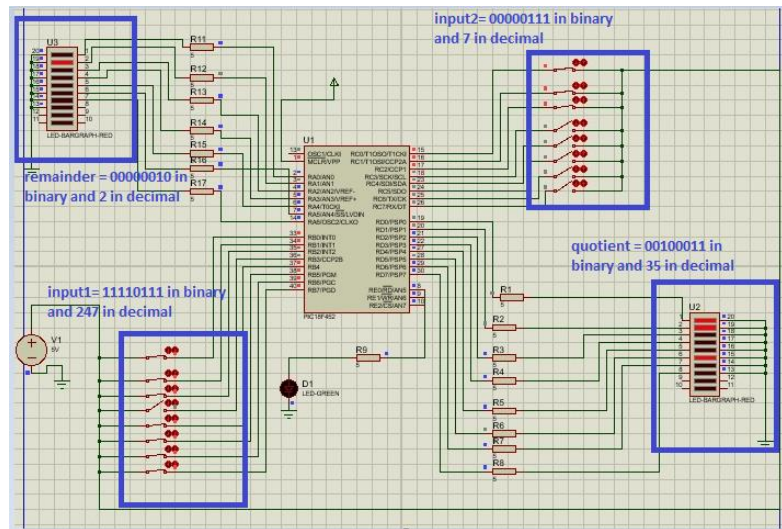


Figure 8: when input 1 is divided from input 2 of 8-bit number and quotient is shown with led bar-graph at portd and remainder is shown by led bar graph at porta (details of inputs and output are highlighted in attached figure)

## Output after division between two inputs but divisor is not zero and there is no remainder:

Input 1= 01110111 in binary and 119 in decimal

Input 2= 00000111 in binary and 7 in decimal

Division in binary =  $01110111 / 00000111 = \text{Quotient } 00010001$  in binary and in decimal 17 and  
Remainder is 00000000 in binary and 0 in decimal

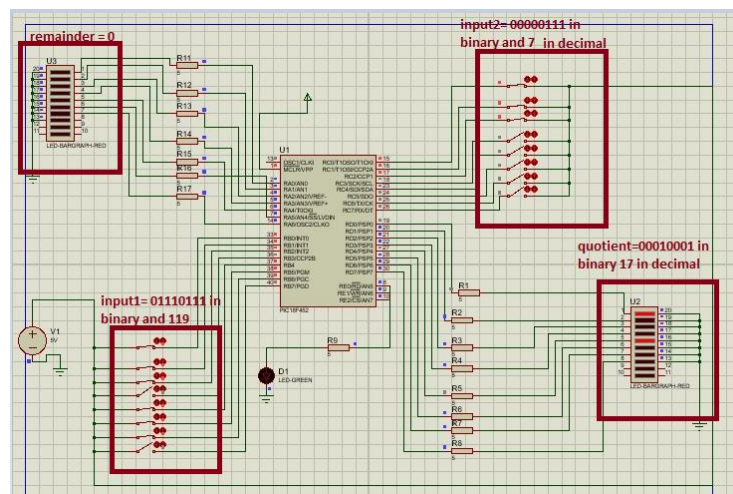


Figure 9: when input 1 is divided from input 2 of 8-bit number and quotient is shown with led bar-graph at portd and remainder is shown by led bar graph at porta which is zero in this case (details of inputs and output are highlighted in attached figure)