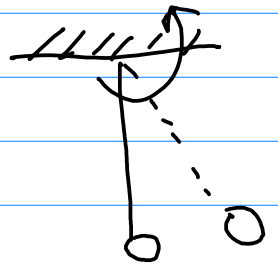


Session 3: Non-Linear ODEs

$$\frac{d^2 x}{dt^2} = -\omega^2 x \quad \left\} \quad x(t) = A \sin(\omega t + \phi)$$

$$\frac{d^2 \theta}{dt^2} = -\frac{g}{L} \sin(\theta)$$

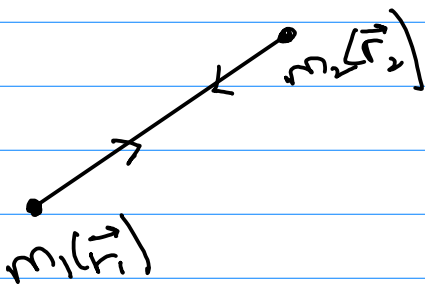
$$\sin \theta \approx \theta \quad \theta \ll 1$$



$$\sin \theta = \theta - \frac{\theta^3}{3!} + \frac{\theta^5}{5!} - \dots$$

$$\theta = 0 \rightarrow \text{singularity}$$

Gravitation (Newtonian)



$$\vec{F}_{12} = -\frac{G m_1 m_2}{|\vec{r}_1 - \vec{r}_2|^3} (\vec{r}_1 - \vec{r}_2) = m_1 \frac{d^2 \vec{r}_1}{dt^2} \quad (1)$$

$$\vec{F}_{21} = -\frac{G m_1 m_2}{|\vec{r}_2 - \vec{r}_1|^3} (\vec{r}_2 - \vec{r}_1) = m_2 \frac{d^2 \vec{r}_2}{dt^2} \quad (2)$$

$$\vec{F} = \frac{G m_1 m_2}{r^2} \left(\frac{\vec{r}}{r} \right) \rightarrow \vec{r}$$

$$(2) - (1)$$

$$\frac{d^2 (\vec{r}_2 - \vec{r}_1)}{dt^2} = -\frac{G}{|\vec{r}_2 - \vec{r}_1|^3} [m_1 (\vec{r}_2 - \vec{r}_1) - m_2 (\vec{r}_1 - \vec{r}_2)]$$

$$\vec{r}_2 - \vec{r}_1 = \vec{r} \rightarrow \text{separation vector}$$

$$\frac{d^2 \vec{r}}{dt^2} = - \frac{G}{|\vec{r}_2 - \vec{r}_1|^3} (m_1 + m_2) \vec{r} = - \frac{GM}{|\vec{r}|^3} \vec{r}$$

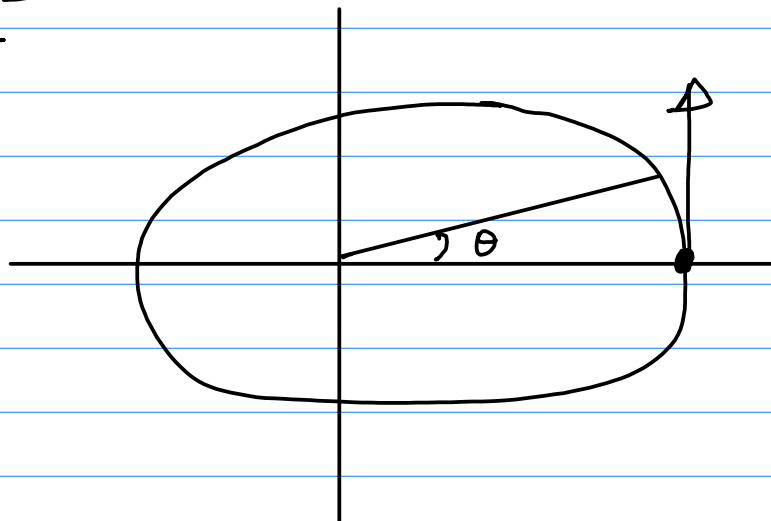
$$\frac{d^2 \vec{r}}{dt^2} = - \frac{GM}{r^2} \hat{r} \quad \vec{r} = x\hat{i} + y\hat{j}$$

$$\vec{r} = \begin{bmatrix} x \\ y \end{bmatrix}$$

$$\begin{bmatrix} \frac{d\vec{r}}{dt} = \dot{\vec{r}} \\ \frac{d\dot{\vec{r}}}{dt} = - \frac{GM}{r^2} \hat{r} = - \frac{GM}{r^3} \vec{r} \end{bmatrix} \quad \rightarrow K$$

$$\frac{d}{dt} \begin{bmatrix} \vec{r} \\ \dot{\vec{r}} \end{bmatrix} = \begin{bmatrix} \dot{\vec{r}} \\ - \frac{GM}{r^3} \vec{r} \end{bmatrix} \quad A(r)$$

$$|\vec{r}| = \sqrt{r[0]^2 + r[1]^2} = \sqrt{x^2 + y^2}$$



$$r(\theta) = \frac{p}{1 + e \cos(\theta)}$$