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bnr…label of object, p_md…processing mode, part…partition, ro_rg…ro-range, ref_l…reference line, cas…case of object, n_pix…minimal length of line, c_ld…correct line detection, sek…type of line sequence, c_pos…correct position, c_sek…correct line sequence, c_adj_l…correct adjustment of lines,*manually derived line orientation, x,y…additional lines of other orientation than main, es…extract single building, ld…line detection, sl…sequence of lines, al…adj of line, ic…intersect corners, ac…adj of corner coordinates.

bnr	p_md	part	ro_rg	ref_l	cas	n_pix	c_ld	sek	c_pos	c_sek	c_adj_l	lines	spObj
3	demo	0_p	3	1	4_long	35	Y	Mpts	Y	-	-	2,49,1,12	-
41	obj_wise	1	3	1	extr_wd	11	Y	Mpts	Y	-	Y	219,31,1,255	-
42	obj_wise	2	3	1	100_all	11	Y	Mpts	Y	-	Y	40,29,46,100,3,1	-
61	obj_wise	1_p1	3	1	100_all	15		bdr-f	N	Y	Y	415,1,42,2,75,162, 155,2,60,19	ld,sl
62	obj_wise	2_p2	3	4	100_all	3	N	bdr-f	N	Y	Y	27,4,118,34,16,4, 126,145	ld,sl

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