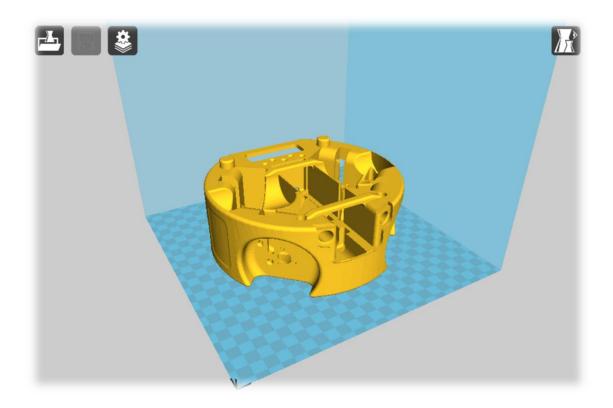
# IMMORTALS

# PRINTED PARTS

#### MAIN BODY

Base part of the 3D-printed robot which all the other parts e.g. shafts, encoders, etc. will be mounted on this part. Printing settings for main body is as below:

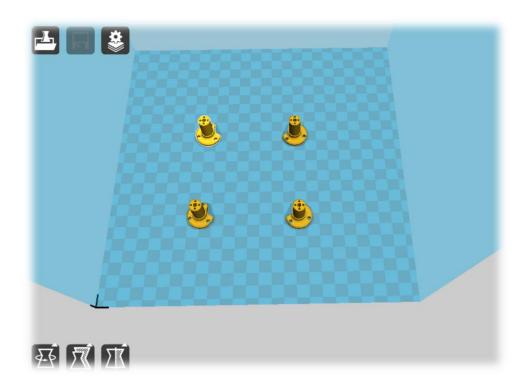
- Material: PLA 1.75mm diameter, for 3D-printer nozzle 0.4mm diameter
- **Infill density:** 20 to 30 percent.
- Shell thickness: 0.8mm (for 0.4mm nozzle means two layers of PLA for shell)
- Layer height: 0.2mm
- Amount for one robot : 1
- **Support:** Supports will touch the build plate.
- Heated bed temperature: 50 C



#### **SHAFT**

Wheels rotates around the axis of the shafts.

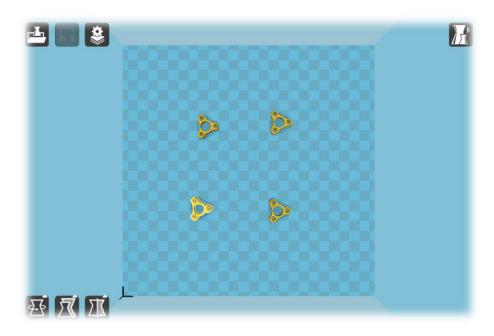
- Material: Carbon-Fiber 1.75mm diameter, for 3D-printer nozzle 0.4mm diameter
- Infill density: 100 percent.
- Shell thickness: 0.8mm (for 0.4mm nozzle means two layers of PLA for shell)
- Layer height: 0.1mm
- Amount for one robot : 4 (two by two mirror about X axis)
- **Support**: Supports will touch the build plate.
- Heated bed temperature: 70 CNozzle temperature: 250 C



### **RING**

Rings are used to strengthen the shafts.

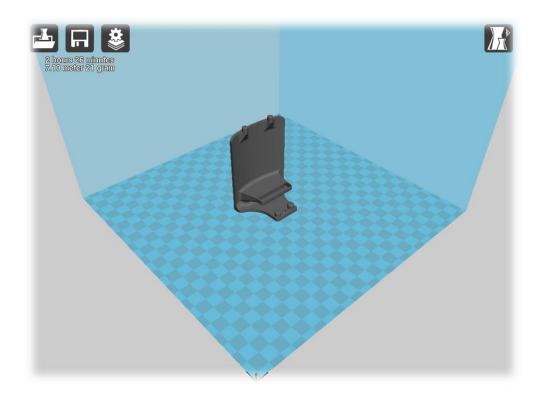
- Material: Carbon-Fiber 1.75mm diameter, for 3D-printer nozzle 0.4mm diameter
- Infill density: 100 percent.
- Shell thickness: 0.8mm (for 0.4mm nozzle means two layers of PLA for shell)
- Layer height: 0.1mm
- Amount for one robot : 4 (two by two mirror about X axis)
- **Support:** Supports will touch the build plate.
- Heated bed temperature: 70 C
- Nozzle temperature: 250 C



### Window

This is a part which can easily remove for changing the battery and access to the main PCB buttons.

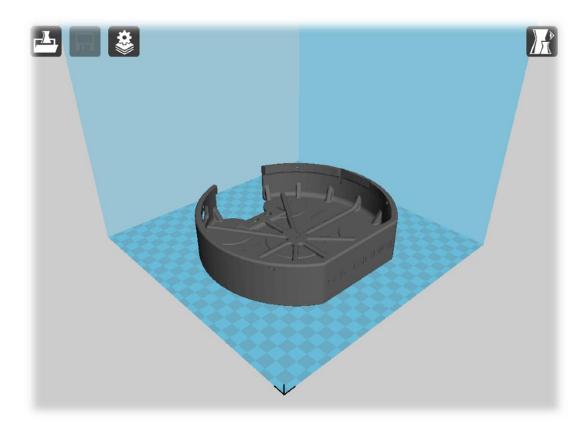
- Material: PLA 1.75mm diameter, for 3D-printer nozzle 0.4mm diameter
- Infill density: 25 to 30 percent.
- Shell thickness: 1.2mm
- Layer height: 0.2mm
- Amount for one robot : 1
- Support: Everywhere
- Heated bed temperature: 50 C
- Nozzle temperature: 220 C



### Second Floor

Second floor is robot top cover

- Material: PLA 1.75mm diameter, for 3D-printer nozzle 0.4mm diameter
- Infill density: 15 to 20 percent.
- Shell thickness: 0.8mm (for 0.4mm nozzle means two layers of PLA for shell)
- Layer height: 0.2mm
- Amount for one robot : 1
- **Support:** Supports will touch the build plate.
- Heated bed temperature: 50 C
- Nozzle temperature : 220 C



## Main PCB Spacer:

Main PCB will mount on this part.

• Material: PLA 1.75mm diameter, for 3D-printer nozzle 0.4mm diameter

• Infill density: 20 to 25 percent.

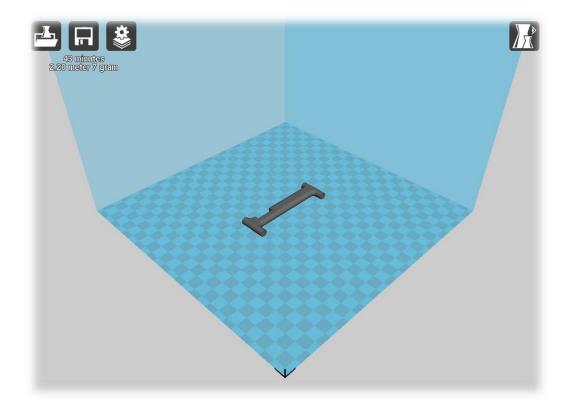
• Shell thickness: 0.8mm (for 0.4mm nozzle means two layers of PLA for shell)

• Layer height: 0.2mm

• Amount for one robot : 1

• Support: no need.

Heated bed temperature: 50 CNozzle temperature: 220 C



## Chip Door:

This part allow us to access chip kicker core from bottom of robot.

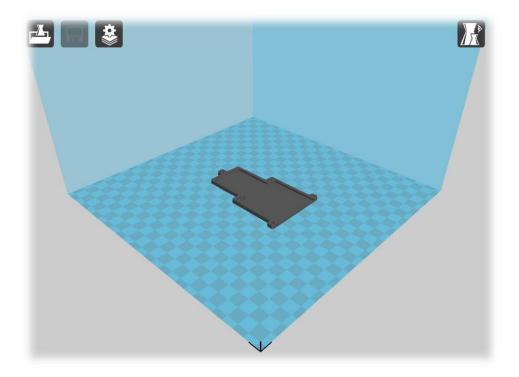
• Material: PLA 1.75mm diameter, for 3D-printer nozzle 0.4mm diameter

• Infill density: 20 to 25 percent.

Shell thickness: 1.2mm
Layer height: 0.2mm
Amount for one robot: 1

• Support: no need.

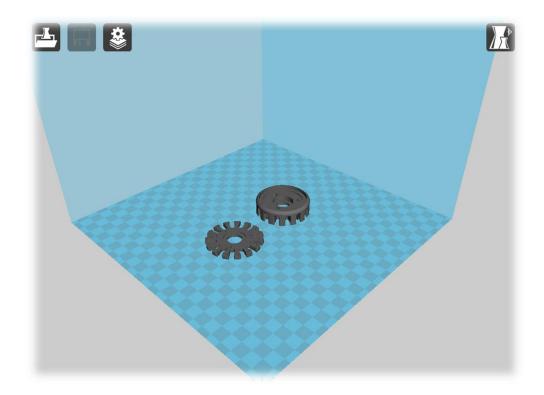
Heated bed temperature: 50 CNozzle temperature: 220 C



### Wheel:

Each wheel has two printing parts which we advise print them together.

- Material: PLA 1.75mm diameter, for 3D-printer nozzle 0.4mm diameter
- **Infill density:** 25 to 35 percent.
- Shell thickness: 1.2mm
- Layer height: 0.2mm (for better results 0.1mm)
- Amount for one robot : 4
- **Support:** Supports will touch the build plate.
- Heated bed temperature: 50 C
- Nozzle temperature: 220 C



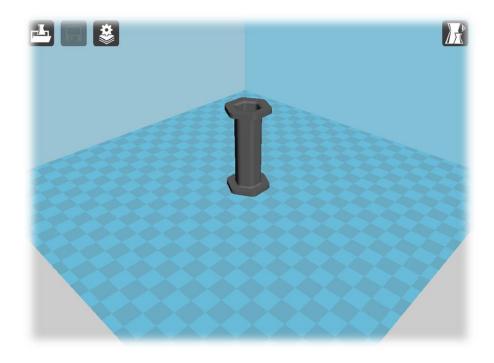
## Hex Coil:

• Material: PLA 1.75mm diameter, for 3D-printer nozzle 0.4mm diameter

• Infill density: 35 to 50 percent.

Shell thickness: 1.2mm
 Layer height: 0.2mm
 Amount for one robot: 1
 Support: Everywhere

Heated bed temperature: 50 CNozzle temperature: 220 C



## Hex Plunger:

• Material: Carbon-fiber 1.75mm diameter, for 3D-printer nozzle 0.4mm diameter

• **Infill density:** 35 to 50 percent.

Shell thickness: 1.2mmLayer height: 0.1mm

• Amount for one robot : 1

• Support: no need.

Heated bed temperature: 70 CNozzle temperature: 250 C

