

Lecture 16
Numerical Approximations for IVP
MA 322: Scientific Computing



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1 Convergence of Euler Method

Our IVP

$$y' = f(x, y), \quad y(x_0) = y_0. \quad (1)$$

1.1 Example

Like earlier, let us discuss Euler method for a numerical example.

Example: Consider the IVP

$$y' = \frac{1}{1+x^2} - 2y^2, \quad y(0) = 0. \quad (2)$$

The true solution is given by

$$y(x) = \frac{x}{1+x^2} \quad (3)$$

and the numerical solutions at different points for different h are presented in the following table (Source: An Introduction to Numerical Analysis, by Atkinson) using the Euler scheme

$$y_{n+1} = y_n + hf(x_n, y_n), \quad y_0 = 0 \quad \& \quad x_{n+1} = x_n + h, \quad x_0 = 0. \quad (4)$$

Euler's method				
	x	$y_h(x)$	$y(x)$	$y(x) - y_h(x)$
$h = .2$	0.00	0.0	0.0	0.0
	.40	.37631	.34483	-.03148
	.80	.54228	.48780	-.05448
	1.20	.52709	.49180	-.03529
	1.60	.46632	.44944	-.01689
	2.00	.40682	.40000	-.00682
$h = .1$.40	.36085	.34483	-.01603
	.80	.51371	.48780	-.02590
	1.20	.50961	.49180	-.01781
	1.60	.45872	.44944	-.00928
	2.00	.40419	.40000	-.00419
$h = .05$.40	.35287	.34483	-.00804
	.80	.50049	.48780	-.01268
	1.20	.50073	.49180	-.00892
	1.60	.45425	.44944	-.00481
	2.00	.40227	.40000	-.00227

In order to assess the accuracy of the numerical method (4), we define the error, e_n , by

$$e_n = y(x_n) - y_n. \quad (5)$$

Now, we wish to show that, for Euler method, the error at each grid point decreases to zero as h decreases to 0. The associated theory is called convergence theory. In developing convergence theory, we will require some preliminary results.

Lemma 1.1 *If the numbers $|E_i|$, $i = 0, 1, 2, 3, \dots, n$, satisfy*

$$|E_{i+1}| \leq A|E_i| + B, \quad i = 0, 1, 2, 3, \dots, n-1 \quad (6)$$

where A and B are nonnegative constants and $A \neq 1$, then

$$|E_i| \leq A^i |E_0| + \frac{A^i - 1}{A - 1} B, \quad i = 1, 2, 3, \dots, n. \quad (7)$$

Proof. For $i = 0$, (6) yields

$$|E_1| \leq A|E_0| + B = A|E_0| + \frac{A-1}{A-1}B,$$

so that (7) is valid for $i = 1$. The proof is now completed by induction. Assume that for fixed i , (7) is valid, that is

$$|E_i| \leq A^i|E_0| + \frac{A^i-1}{A-1}B. \quad (8)$$

Then we must prove that

$$|E_{i+1}| \leq A^{i+1}|E_0| + \frac{A^{i+1}-1}{A-1}B. \quad (9)$$

Using (8) in (6), we obtain

$$|E_{i+1}| \leq A \left[A^i|E_0| + \frac{A^i-1}{A-1}B \right] + B = A^{i+1}|E_0| + \frac{A^{i+1}-1}{A-1}B$$

and the proof is completed.

Remark: The value of Lemma 1.1 is as follows:

- If each term of a sequence $\{|E_i| : i = 0, 1, 2, \dots\}$ is related to the previous term by (6), then Lemma 1.1 enables one to relate each term directly to $|E_0|$ only, that is, to the very first term of the sequence.

Now, we are in a position to discuss the main result of this lecture.

Theorem 1.1 Suppose y is an unique solution for the IVP

$$y' = f(x, y), \quad y(0) = \alpha \quad (10)$$

in $I = [0, L]$, $L > 0$. Assume that y' and y'' are continuous and that there exist positive constants M , N such that

$$|y''(x)| \leq N \quad \& \quad \left| \frac{\partial f}{\partial y} \right| \leq M, \quad 0 \leq x \leq L, \quad -\infty < y < \infty. \quad (11)$$

Next, let I be subdivided into n equal parts by the grid points $x_0 < x_1 < x_2 < \dots < x_n$, where $x_0 = 0$ and $x_n = L$. The grid size is given by $h = \frac{L}{n}$. Let y_k be the numerical solution of (10) by Euler's method on the grid point x_k , so that

$$y_{k+1} = y_k + hf(x_k, y_k), \quad y_0 = \alpha, \quad k = 0, 1, 2, \dots, n-1. \quad (12)$$

Finally, define the error e_k at each grid point x_k by

$$e_k = y(x_k) - y_k \quad k = 0, 1, 2, \dots, n. \quad (13)$$

Then

$$|e_k| \leq \frac{[(1 + Mh)^k - 1]Nh}{2M}, \quad k = 0, 1, 2, \dots, n. \quad (14)$$

Proof. First observe that

$$|e_{k+1}| = |y(x_{k+1}) - y_{k+1}| = |y(x_k + h) - y_{k+1}|.$$

Introducing Taylor expansion for $y(x_k + h)$ implies

$$\begin{aligned}
|e_{k+1}| &= |y(x_k + h) - y_{k+1}| = |y(x_k) + hy'(x_k) + \frac{h^2}{2}y''(\xi_k) - (y_k + hf(x_k, y_k))| \\
&= |(y(x_k) - y_k) + h(y'(x_k) - f(x_k, y_k)) + \frac{h^2}{2}y''(\xi_k)| \\
&= |e_k + h(f(x_k, y(x_k)) - f(x_k, y_k)) + \frac{h^2}{2}y''(\xi_k)| \\
&= |e_k + h(f(x_k, Y_k) - f(x_k, y_k)) + \frac{h^2}{2}y''(\xi_k)|, \quad Y_k = y(x_k).
\end{aligned} \tag{15}$$

Now, by the MVT for a function of two variables, we obtain

$$f(x_k, Y_k) - f(x_k, y_k) = (Y_k - y_k) \frac{\partial f}{\partial y}(x_k, \eta_k) = e_k \frac{\partial f}{\partial y}(x_k, \eta_k), \tag{16}$$

where η_k is areal number between $Y_k = y(x_k)$ and y_k . Using above identity in (15), we arrive at

$$\begin{aligned}
|e_{k+1}| &= \left| e_k + he_k \frac{\partial f}{\partial y}(x_k, \eta_k) + \frac{h^2}{2}y''(\xi_k) \right| \\
&\leq |e_k| + h|e_k|M + \frac{h^2}{2}N.
\end{aligned} \tag{17}$$

Here, we have used (11). Therefore, we arrive at

$$|e_{k+1}| \leq |e_k|(1 + Mh) + \frac{h^2}{2}N \tag{18}$$

which together with Lemma 1.1, for $A = (1 + Mh)$ and $B = \frac{h^2}{2}N$, we obtain

$$|e_k| \leq (1 + Mh)^k |e_0| + \frac{(1 + Mh)^k - 1}{(1 + Mh) - 1} \left(\frac{h^2}{2}N \right). \tag{19}$$

However, since $e_0 = y(x_0) - y_0 = \alpha - \alpha = 0$, estimate (20) simplifies to

$$\begin{aligned}
|e_k| &\leq \frac{(1 + Mh)^k - 1}{Mh} \left(\frac{h^2}{2}N \right) \\
&= \frac{[(1 + Mh)^k - 1]Nh}{2M}.
\end{aligned} \tag{20}$$

This completes the rest of the proof.

Corollary 1.1 *Now, for $x \geq -1$, use the fact that*

$$0 \leq (1 + x)^m \leq e^{mx}$$

to have

$$\begin{aligned}
|e_k| &\leq \frac{(e^{Mhk} - 1)Nh}{2M} = \frac{(e^{Mx_k} - 1)Nh}{2M}, \quad x_k = x_0 + kh = kh \\
&\leq \frac{(e^{Mx_n} - 1)Nh}{2M} = \frac{(e^{ML} - 1)Nh}{2M}, \quad L = x_n.
\end{aligned} \tag{21}$$

Thus, there exists a positive constant C independent of the mesh parameter h such that

$$|e_k| \leq Ch, \quad C = \frac{(e^{ML} - 1)N}{2M}, \quad k = 0, 1, 2, \dots, n. \tag{22}$$

In particular, we obtain

$$|e_n| \leq Ch \rightarrow 0 \quad \text{as } h \rightarrow 0. \tag{23}$$

Remark 1.2 At each grid point, roughly, we obtain

$$|\text{error}| \approx Ch, \quad \text{where } C \text{ is independent of } h.$$

Therefore, when h is halved, we obtain

$$|\text{new error}| \approx C \frac{h}{2},$$

so that

$$\frac{|\text{new error}|}{|\text{error}|} \approx \frac{1}{2}.$$

Hence, the error at each point grid point decreases by about half when h is halved.