CS343 - Operating Systems

Module-3C Process Synchronization – Critical Sections



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Session Outline

- ❖ Background
- ❖ The Critical-Section Problem
- ❖ Peterson's Solution
- **❖** Synchronization Hardware
- **❖ Mutex Locks**

Objectives of Process Synchronization

- ❖ To introduce the concept of process synchronization.
- ❖ To introduce the critical-section problem, whose solutions can be used to ensure the consistency of shared data
- To present both software and hardware solutions of the critical-section problem
- To examine several classical process-synchronization problems
- To explore several tools that are used to solve process synchronization problems

Background

- Processes can execute concurrently
 - ❖ May be interrupted at any time, partially completing execution
- Concurrent access to shared data may result in data inconsistency
- Maintaining data consistency requires mechanisms to ensure the orderly execution of cooperating processes
- Illustration of the problem:

Suppose that we wanted to provide a solution to the consumer-producer problem that fills **all** the buffers. We can do so by having an integer **counter** that keeps track of the number of full buffers. Initially, **counter** is set to 0. It is incremented by the producer after it produces a new buffer and is decremented by the consumer after it consumes a buffer.

Bounded-Buffer – Producer & Consumer

```
item buffer[BUFFER_SIZE]; int in = 0; int out = 0;
```

Producer

```
while (true) {
    /* produce an item
   in next produced */
   while (counter == BUFFER SIZE)
           /* do nothing */
   buffer[in] = next produced;
   in = (in + 1) % BUFFER SIZE;
   counter++;
```

Consumer

```
while (true) {
   while (counter == 0)
        ; /* do nothing */
   next consumed = buffer[out];
   out = (out + 1) % BUFFER SIZE;
   counter--;
    /* consume the item in next
   consumed */
```

Race Condition

❖ counter++ could be implemented as ❖ counter-- could be implemented as

```
register1 = counter

register1 = register1 + 1

counter = register1

register2 = counter

register2 = register2 - 1

counter = register1
```

Consider this execution interleaving with count = 5 initially:

```
S0: producer execute register1 = counter
S1: producer execute register1 = register1 + 1 {register1 = 6}
S2: consumer execute register2 = counter
S3: consumer execute register2 = register2 - 1 {register2 = 4}
S4: producer execute counter = register1 {counter = 6}
S5: consumer execute counter = register2 {counter = 4}
```

Critical Section Problem

- \diamond Consider system of **n** processes $\{p_0, p_1, \dots p_{n-1}\}$
- Each process has critical section segment of code
 - Process may be changing common variables, updating table, writing file, etc
 - When one process in critical section, no other may be in its critical section
- Critical section problem is to design protocol to solve this

Critical Section

Each process must ask permission to enter critical section in entry section, may follow critical section with exit section, then remainder section

```
General structure of process P
```

```
do {
     entry section
          critical section
     exit section
          remainder section
} while (true);
```

```
do {
while (turn == j);
    critical section
turn = j;
    remainder section
   while (true);
```

Solution to Critical-Section Problem

- 1. Mutual Exclusion If process P_i is executing in its critical section, then no other processes can be executing in their critical sections
- Progress If no process is executing in its critical section and there exist some processes that wish to enter their critical section, then the selection of the processes that will enter the critical section next cannot be postponed indefinitely
- Bounded Waiting A bound must exist on the number of times that other
 processes are allowed to enter their critical sections after a process has
 made a request to enter its critical section and before that request is
 granted
 - Assume that each process executes at a nonzero speed
 - No assumption concerning relative speed of the *n* processes

Peterson's Solution

- Applicable for two process solution
- Assume that the load and store machine-language instructions are atomic; that is, cannot be interrupted
- The two processes share two variables:
 - int turn;
 - **❖ Boolean flag[2]**
- The variable turn indicates whose turn it is to enter the critical section
- ❖ The flag array is used to indicate if a process is ready to enter the critical section. flag[i] = true implies that process P_i is ready!

Peterson's Solution

```
Algorithm for Process P<sub>i</sub>
Algorithm for Process P<sub>i</sub>
                                 do ·
do
                                    flag[j] = true;
   flag[i] = true;
                                     turn = i;
   turn = j;
                                    while (flag[i]&&turn==i);
   while (flag[j]&&turn==j);
                                     critical section
   critical section
                                     flaq[j] = false;
   flag[i] = false;
                                     remainder section
   remainder section
                                      } while (true);
    } while (true);
```

Peterson's Solution

- ❖ All three CS requirement are met:
- Mutual exclusion is preserved
 P_i enters CS only if:
 either flag[j] = false or turn = i
- 2. Progress requirement is satisfied
- 3. Bounded-waiting requirement is met

Algorithm for Process Pi

```
do
   flag[i] = true;
   turn = j;
   while (flag[j]&&turn==j);
   critical section
   flag[i] = false;
   remainder section
     while (true);
```

Synchronization Hardware - Locks

- Many systems provide hardware support for implementing the critical section code.
- All solutions below based on idea of locking
 - Protecting critical regions via locks
- Uniprocessors could disable interrupts
- Modern machines provide special atomic hardware instructions
 - **❖ Atomic** = non-interruptible
 - Either test memory word and set value
 - Or swap contents of two memory words

```
do {
acquire lock
    critical section
release lock
    remainder section
 while (TRUE);
```

Synchronization Using test_and_set Instruction

```
boolean test_and_set (boolean *target)
{
    boolean rv = *target;
    *target = TRUE;
    return rv:
}
```

- 1. Executed atomically
- 2. Returns the original value of passed parameter
- 3. Set the new value of passed parameter to "TRUE".

Solution using test_and_set()

Shared Boolean variable lock, initialized to FALSE

```
do{
  while (test and set(&lock))
     ; /* do nothing */
     /* critical section */
     lock = false;
     /* remainder section */
}while (true);
```

```
boolean test and set
(boolean *lock)
 boolean rv = *lock;
 *lock = TRUE;
 return rv:
```

Synchronization Using compare_and_swap Instruction

```
int compare and swap(int *value, int expected, int new value)
    int temp = *value;
    if (*value == expected)
         *value = new value;
    return temp;
                              1. Executed atomically
                              2. Returns the original value of passed
                                 parameter "value"
                              Set the variable "value" to "new value"
                                 only if "value" =="expected". That is, the
                                 swap takes place only under this
                                 condition.
```

Solution using compare_and_swap ()

```
Shared integer lock initialized to 0;
   do {
         while (compare and swap(&lock, 0, 1) != 0)
          ; /* do nothing */
          /* critical section */
         lock = 0;
          /* remainder section */
      } while (true);
```

Mutex Locks

- Previous solutions are complicated and generally inaccessible to application programmers
- OS designers build software tools to solve critical section problem
- ❖ Simplest is mutex lock
- ❖ Protect a critical section by first acquire() a lock then release() the lock
 - Boolean variable indicating if lock is available or not
- Calls to acquire() and release() must be atomic
 - Usually implemented via hardware atomic instructions
- But this solution requires busy waiting
 - This lock therefore called a spinlock

Synchronization Using acquire() and release()

```
acquire()
    while (!available)
       ; /* busy wait */
    available = false;;
release()
    available = true;
```

```
do
    acquire lock
       critical section
    release lock
      remainder section
 } while (true);
```



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