



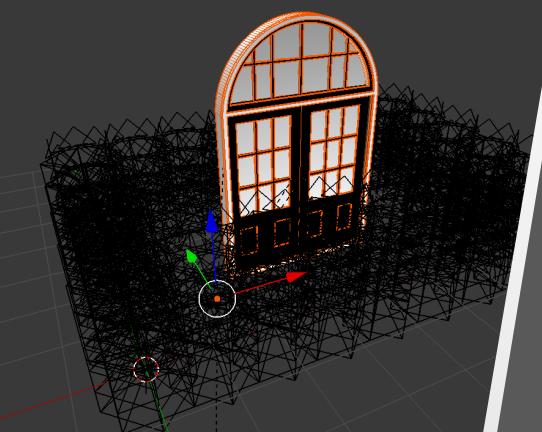
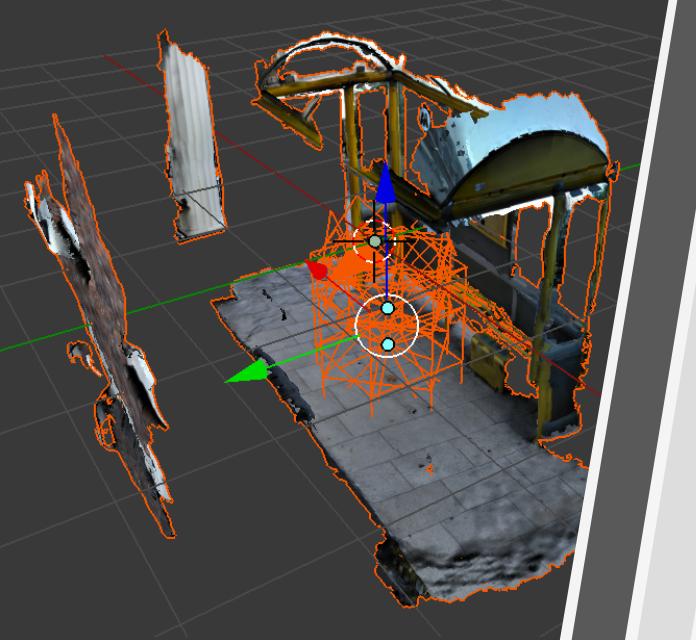
Creating a Geospatial Macro Level Feature Database

Final Presentation

Jason Brewer

Recap

- The Siloam system aims to provide a data collection and analysis platform to assist BoVI users in their exploration of new outdoor areas
- Comprised of three parts:
 - Google Project Tango powered raw data collection app (SiloamSee)
 - Offline machine learning component (SiloamLearn)
 - Couchbase server powered online database (SiloamSilo)



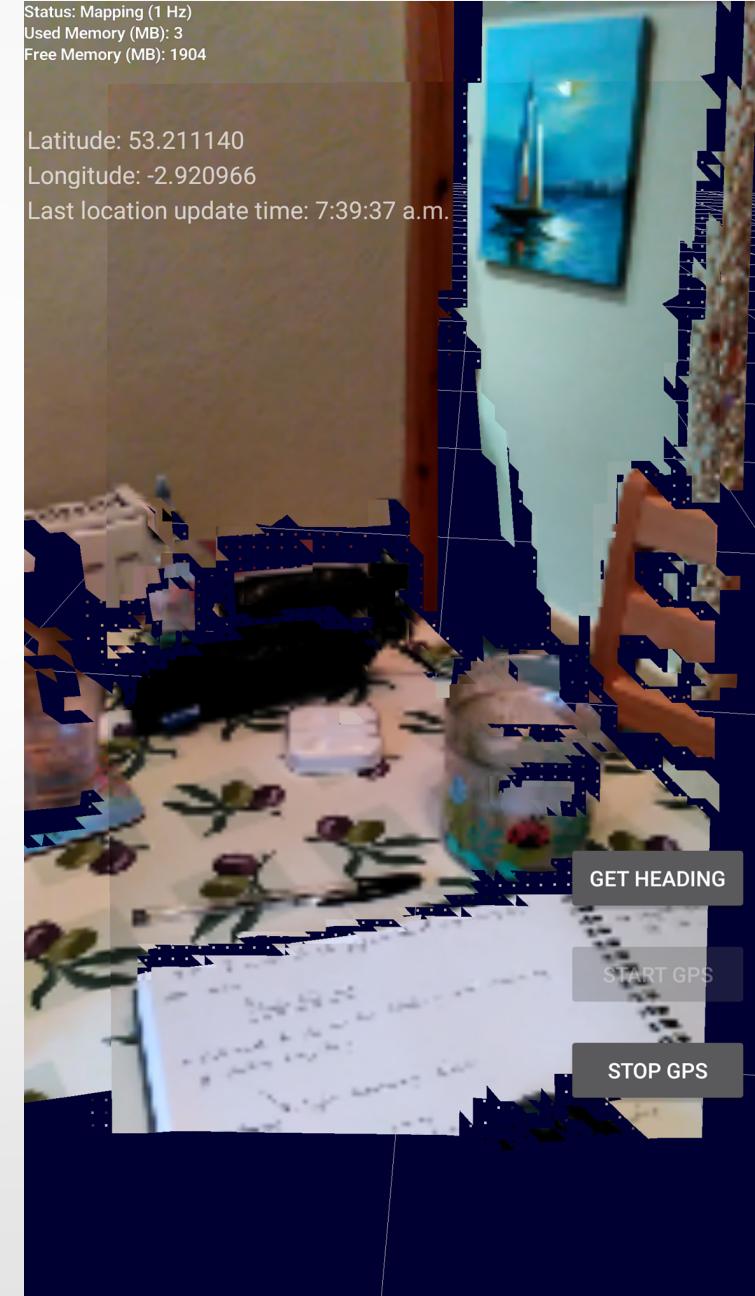
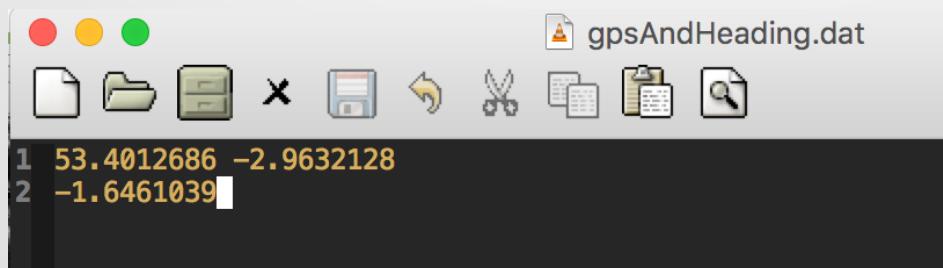
```
// Finds clusters in the initial D_st
// could be artifacts of the background

void find_clusters(int normal_noise_thres
{
    png_bytep row = NULL;
    png_bytep px = NULL;
    dataset cluster_dataset;
    cluster_analysis::dbscan cluster_finder(1.0f,
    cluster_analysis::dbscan_data clustering_result,
    cluster_analysis::cluster_sequence_ptr clusters_
```

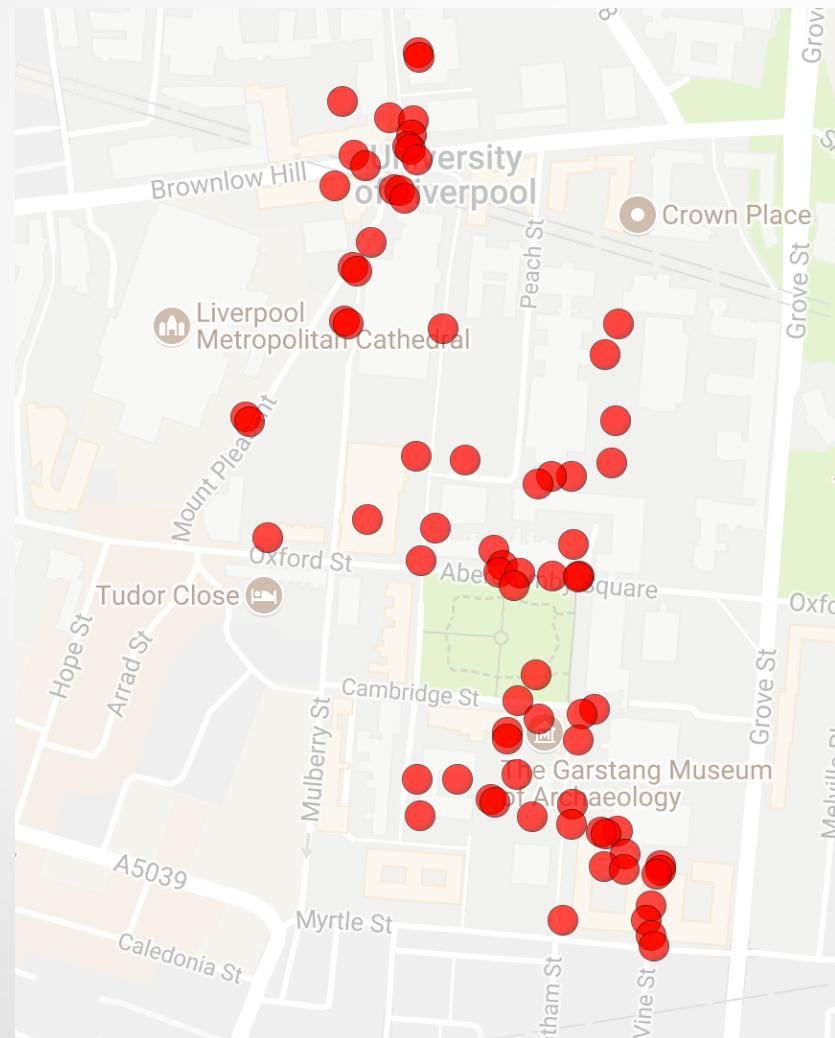
Outputs

- SiloamSee

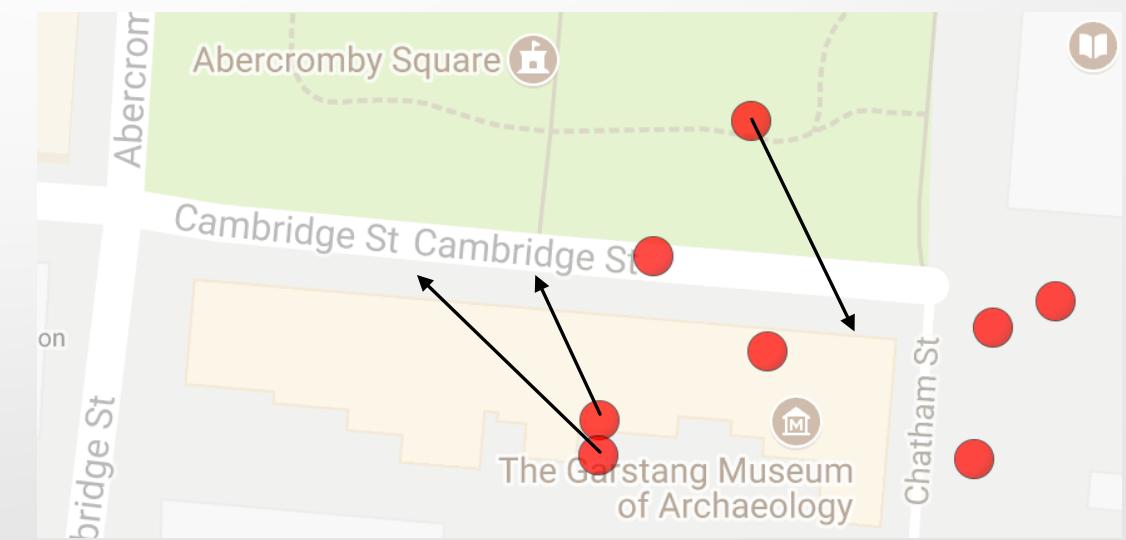
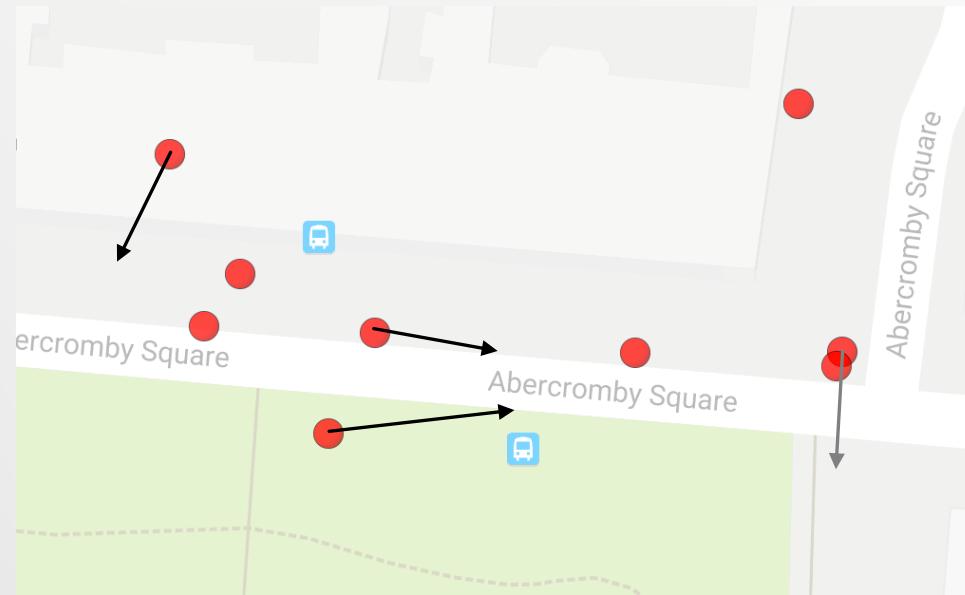
- An extension of the RTAB-Map Android app by introlab (Interdisciplinary Robot Lab @ Université de Sherbrooke)
- Adds GPS and magnetometer data logging
- Each model captured in the wild is exported as an OBJ along with an associated .dat file with the GPS point of the capturer and angle from magnetic north in the range $-\pi < \theta < \pi$
- This information is used by SiloamLearn to geocode each macro level feature



Data collection points

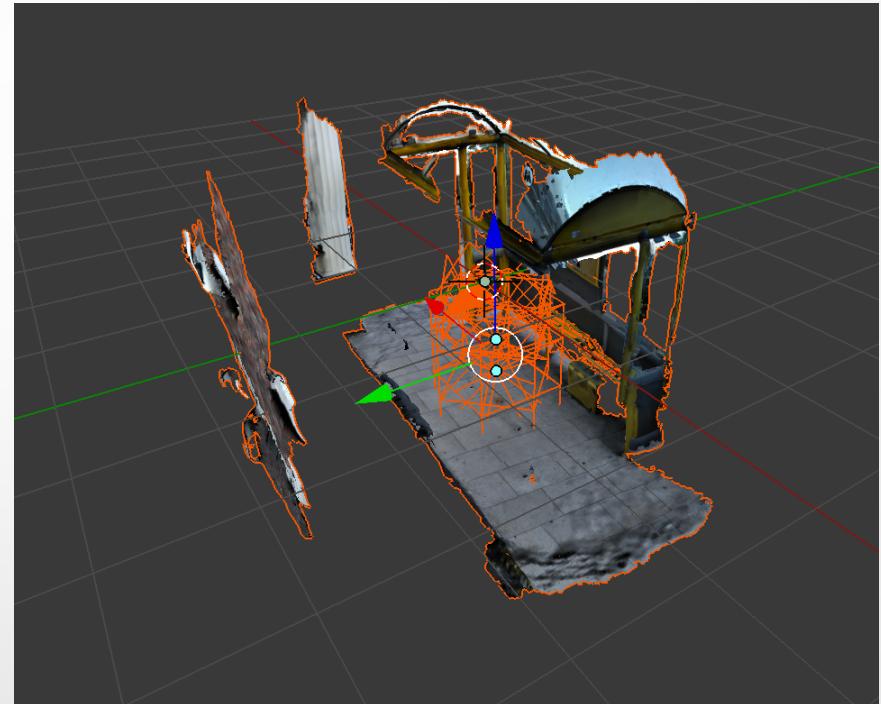


GPS inaccuracy



Data preparation: OBJ to RGB-D

- The transition is completed via Python scripting in Blender, an open source 3D modelling application
- Generates RGB-D from SiloamSee models automatically
- Generating RGB-D data from Trimble Warehouse DAE models is a more interactive process



Outputs

SiloamLearn

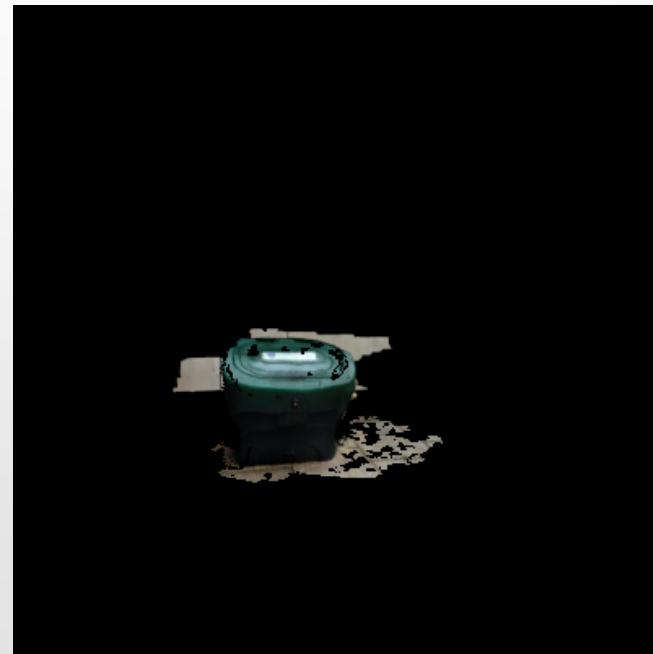
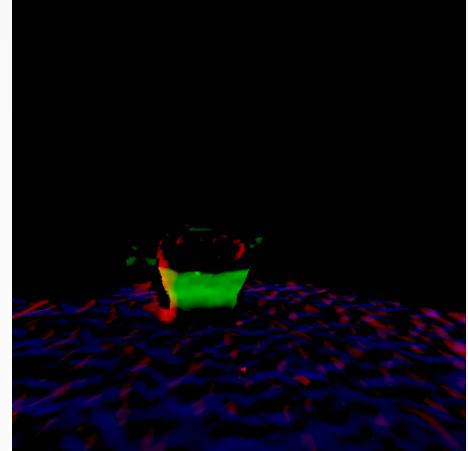
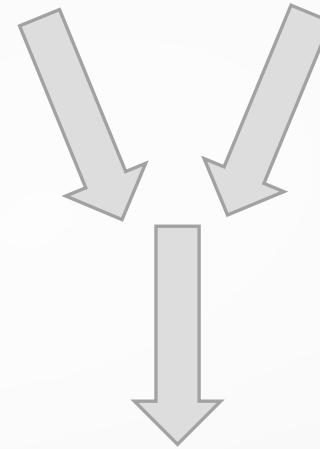
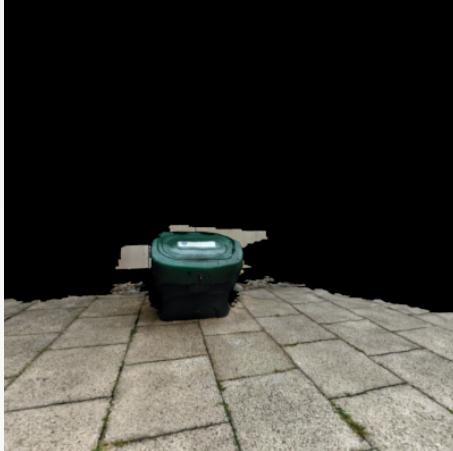
- Prepares the data for the SVM using:
 - libpng
 - OpenCV
 - pyclustering (despite the name it is also a C++ library)
- The idea is that the SVM will be trained to detect four categories of feature from the RGB-D dataset:
 - Bus stop
 - Crossing
 - Doorway
 - Steps

```
renders/SiloamSee/SiloamSee-170811-153218-train/forwards8
This round of segmentation done!
Removing floors from: "/Users/LordNelson/Documents/Work/LiverpoolUni/DissertationStore/2-learn/
renders/SiloamSee/SiloamSee-170811-153218-train/forwards8"
This round of segmentation done!
Removing floors from: "/Users/LordNelson/Documents/Work/LiverpoolUni/DissertationStore/2-learn/
renders/SiloamSee/SiloamSee-170811-153218-train/forwards9"
This round of segmentation done!
Removing floors from: "/Users/LordNelson/Documents/Work/LiverpoolUni/DissertationStore/2-learn/
renders/SiloamSee/SiloamSee-170811-153628-train/forwards0"
This round of segmentation done!
Removing floors from: "/Users/LordNelson/Documents/Work/LiverpoolUni/DissertationStore/2-learn/
renders/SiloamSee/SiloamSee-170811-153628-train/forwards1"
This round of segmentation done!
Removing floors from: "/Users/LordNelson/Documents/Work/LiverpoolUni/DissertationStore/2-learn/
renders/SiloamSee/SiloamSee-170811-153628-train/forwards10"
This round of segmentation done!
Removing floors from: "/Users/LordNelson/Documents/Work/LiverpoolUni/DissertationStore/2-learn/
renders/SiloamSee/SiloamSee-170811-153628-train/forwards11"
```

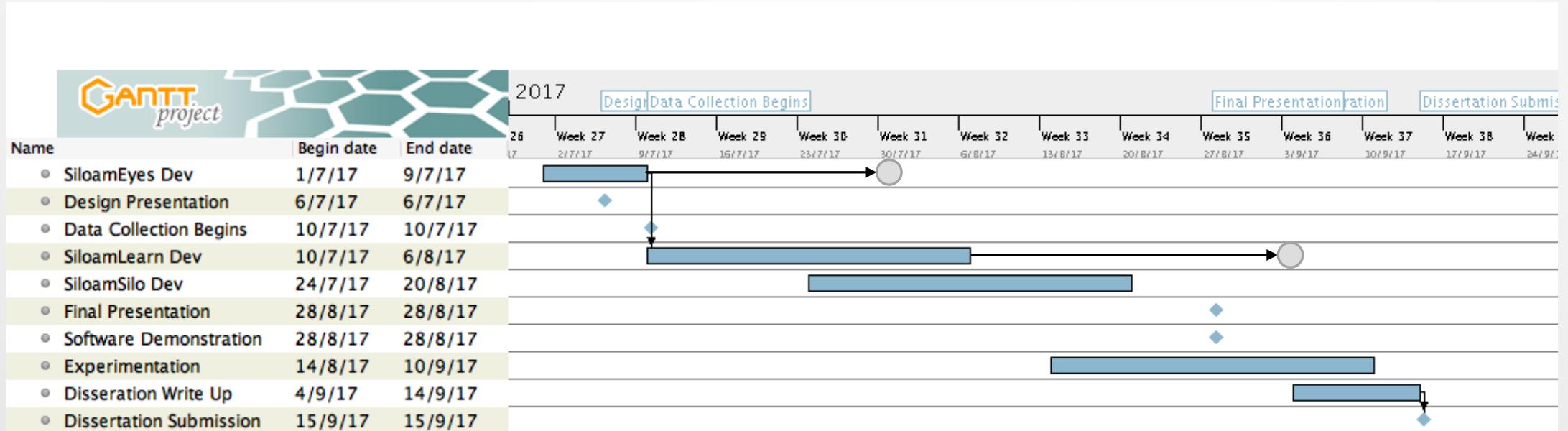
The screenshot shows a terminal window with the following details:

- File Explorer:** Shows files in the 'Products' and 'SiloamLearn' directories, including 'png_utilities.hpp', 'png_utilities.cpp', and 'png_utilities.h'.
- Code Editor:** Displays a portion of the 'png_utilities.cpp' file with code related to cluster processing and ground truth matching.
- Terminal Output:** Shows the execution of the 'SiloamLearn' application, displaying log messages about segmentation rounds and floor removal for various datasets ('forwards8', 'forwards9', 'forwards0', 'forwards1', 'forwards10', 'forwards11').

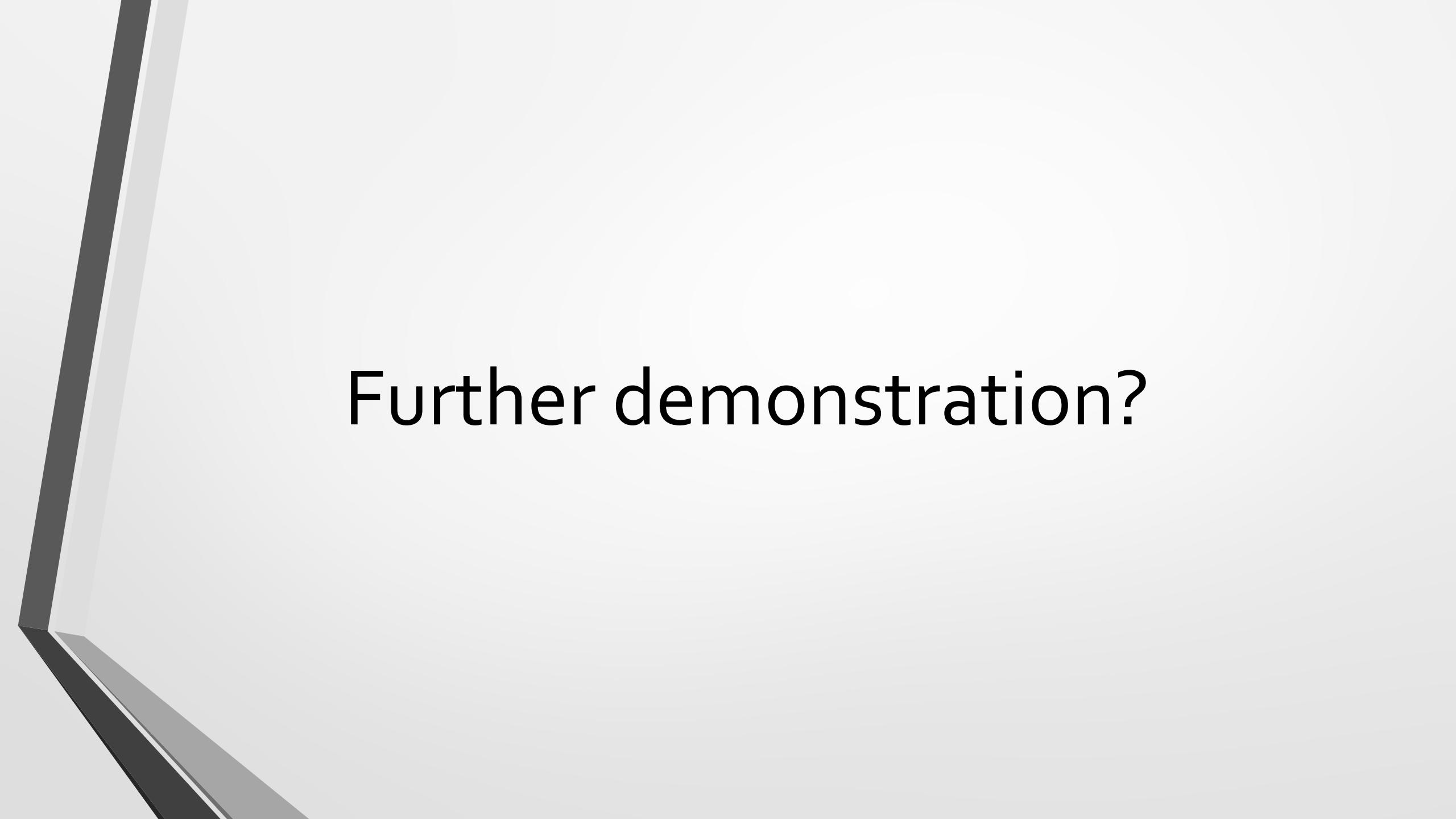
Floor Removal



Evaluation



- MoSCoW
 - Data collection and preparation
 - Machine learning – very close to completion but experimentation with image segmentation required



Further demonstration?