

## 1 | Precessional Velocity

Taking the setup, we can figure the sum of the angular momentums and leverage it to figure the spin angular momentum.

Let's first define a system:  $\hat{i}$  is "right" on the figure,  $\hat{j}$  "in" the page,  $\hat{k}$  "up" the figure.

We note that the normal spin of the flywheel gives us:

$$\vec{L}_s = I\vec{\omega}_s \hat{i} \quad (1)$$

As the flywheel is rotating at a constant speed, we have actually no torque that this contributes to the net system — that is  $\frac{d\vec{L}_s}{dt} = 0$ .

Furthermore, we can figure torque—and subsequent angular momentum contribution—of gravity as follows:

$$\vec{\tau}_g = lmg\hat{j} \quad (2)$$

The total net torque on the system, then:

$$\vec{\tau}_{net} = \vec{\tau}_g + 0 \quad (3)$$

$$= \vec{\tau}_g \quad (4)$$

We also have that:

$$\vec{\tau}_{net} = \frac{d\vec{L}_{net}}{dt} \quad (5)$$