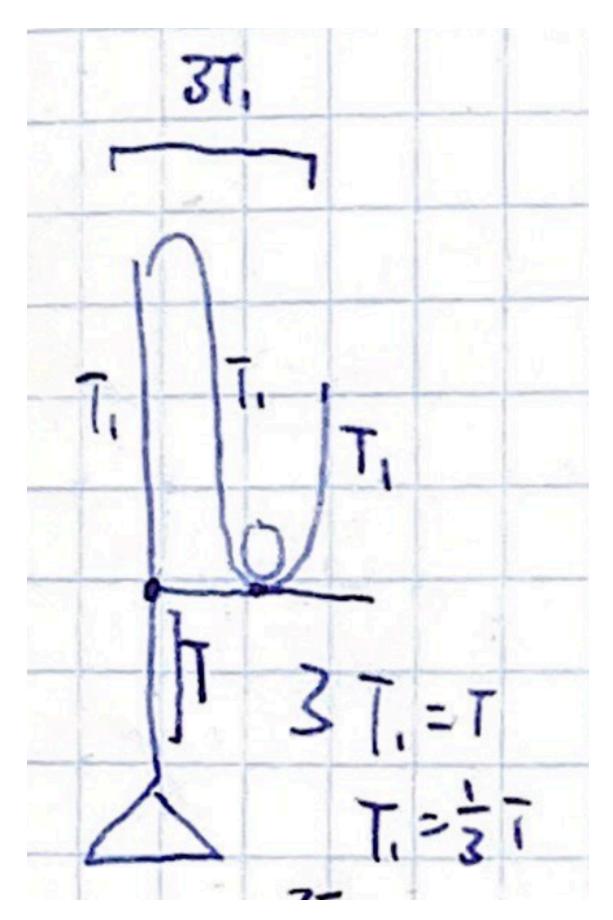
# 1 | Pulley Problem

## 1.1 | Number 1

Three tie points, tied onto one point.

$$3T_1 = T (1)$$

$$\Rightarrow T_1 = \frac{1}{3}T\tag{2}$$

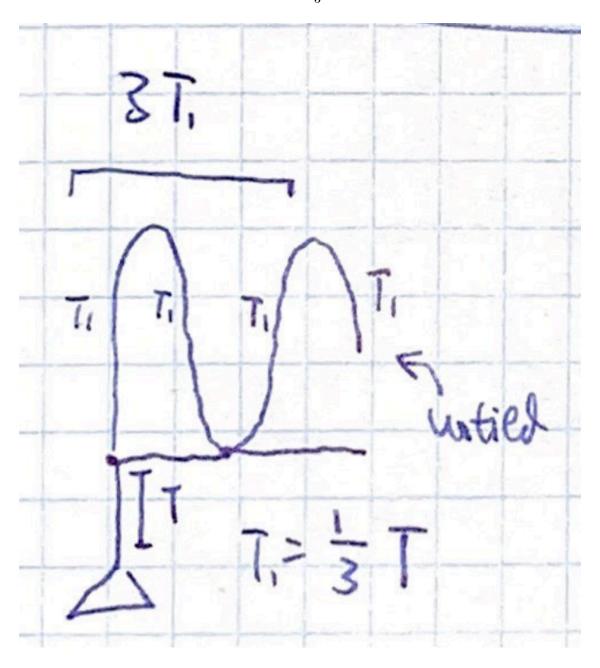


## 1.2 | Number 2

Three tie points, tied onto one point. The extra additional pull, given its not tied, simply transfers tension.

$$3T_1 = T (3)$$

$$\Rightarrow T_1 = \frac{1}{3}T\tag{4}$$



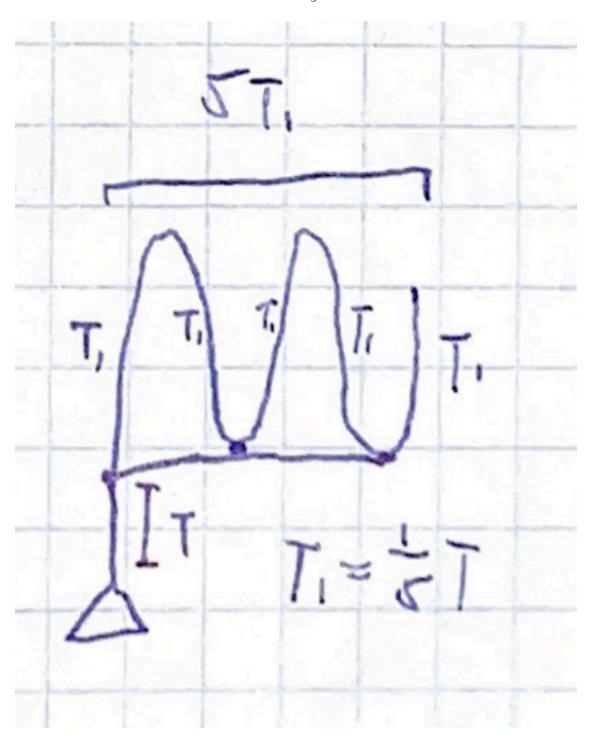
## 1.3 | Number 3

Five points, tied onto one point.

$$5T_1 = T ag{5}$$

$$5T_1 = T$$

$$\Rightarrow T_1 = \frac{1}{5}T$$
(5)
(6)



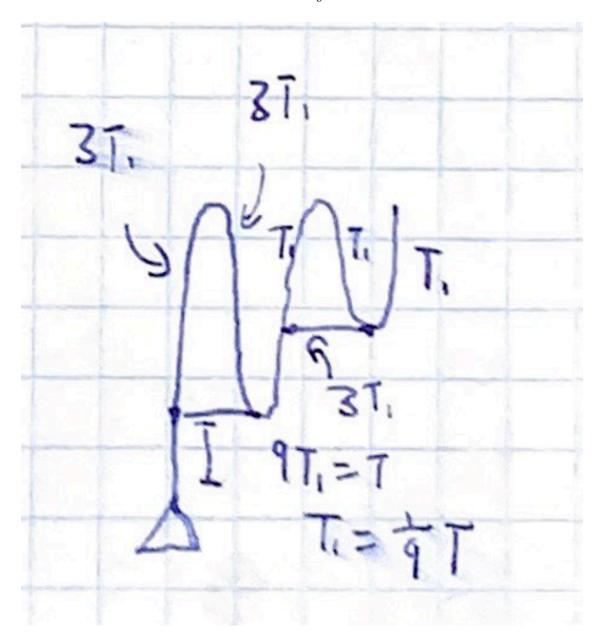
#### 1.4 | Number 4

Two tie points on one, which is added to another set of tie points. The higher (smaller) set has a total tension of  $3T_1$ , which is tied again onto the bottom tie point.

$$9T_1 = T \tag{7}$$

$$9T_1 = T$$

$$\Rightarrow T_1 = \frac{1}{9}T$$
(8)



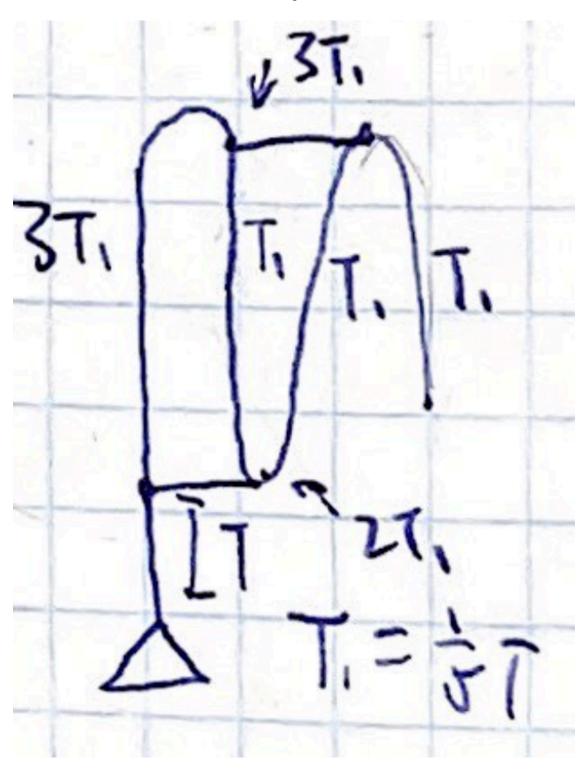
## 1.5 | Number 5

The top tie point has  $3T_1$  of tension. The bottom has  $2T_1$ , and they are finally all added together.

$$3T_1 + 2T_1 = T (9)$$

$$3T_1 + 2T_1 = T$$

$$\Rightarrow T_1 = \frac{1}{5}T$$
(10)

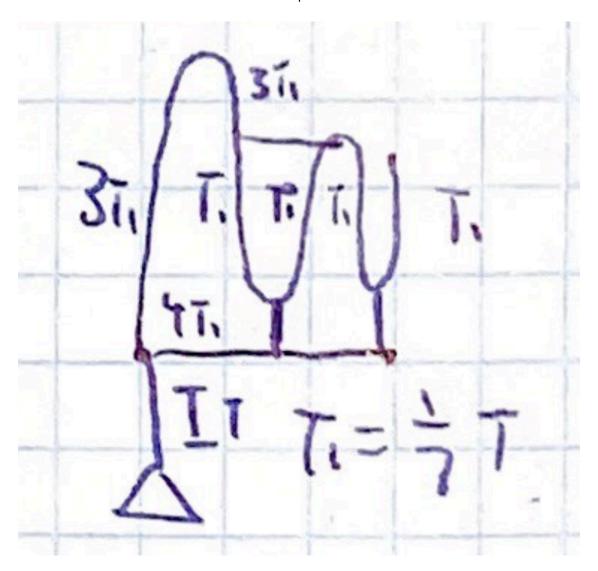


#### 1.6 | Number 6

The top tie point has  $3T_1$  of tensions, and the bottom has four tie points and tied together towards the bottom.

$$3T_1 + 4T_1 = T (11)$$

$$\Rightarrow T_1 = \frac{1}{7}T\tag{12}$$

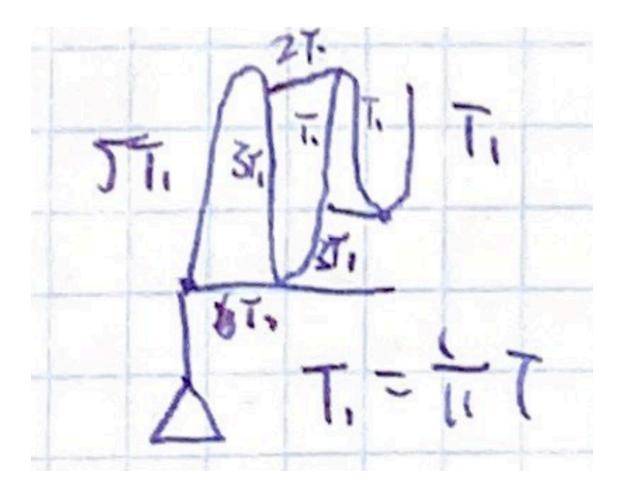


#### 1.7 | Number 7

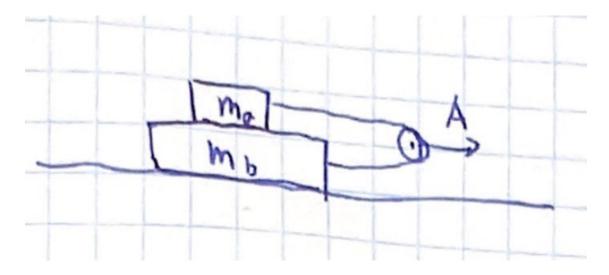
The top tie point has  $2T_1$  of ties, the bottom has  $3T_1$ , which is finally tied to another propagated to another  $6T_1$  tie point. In total, therefore:

$$2T_1 + 3T_1 + 6T_1 = T (13)$$

$$\Rightarrow T_1 = \frac{1}{11}T\tag{14}$$

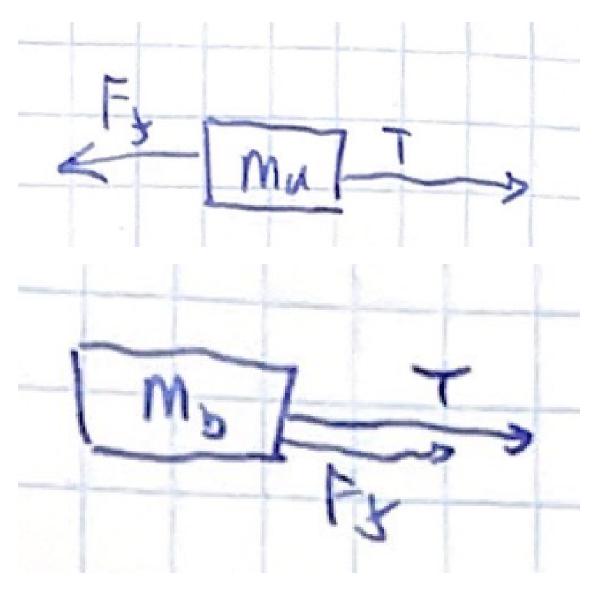


## 2 | Sliding Blocks



Given the masses  $M_a$ ,  $M_b$ ,  $F_f$  between them, and A the acceleration of the pully pulling them, we are to figure the tension T on the rope.

We will first draw free-body diagrams of each of the objects, like so:



We will note that, given  $M_b > M_a$ ,  $M_a$  will slide to the "right" (+x) direction. As such, in the reference frame of  $M_a$ , the force of friction is in the opposite direction as T, whereas this is the opposite case for  $M_b$ .

According to these free-body diagrams, then, we can conclude that:

$$\begin{cases} M_a a_a = T - F_f \\ M_b a_b = T + F_f \end{cases}$$
 (15)

As we have three unknowns and two expressions, we have one remaining degree of freedom to address. This can be analysed by looking at the rope connecting  $M_a$  and  $M_b$ .

We will define the position of  $M_a$  as  $x_a$ ,  $M_b$  as  $x_b$ , and finally the position of the pulley as  $x_p$ . We will further introduce a temporary constant value L representing the length of the perfect rope connecting the two blocks.

We can, therefore, claim that:

$$(x_p - x_a) + (x_p - x_b) = L (16)$$

That the two distances from block to pulley added up is the length of the rope.

Performing slight algebraic simplifications:

$$(x_p - x_a) + (x_p - x_b) = L (17)$$

$$\Rightarrow 2x_p - (x_a + x_b) = L \tag{18}$$

$$\Rightarrow 2x_p = L + (x_a + x_b) \tag{19}$$

$$\Rightarrow x_p = \frac{L + (x_a + x_b)}{2} \tag{20}$$

We can now take two derivatives w.r.t. time:

$$\frac{d^2x_p}{dt^2} = \frac{\ddot{x_a} + \ddot{x_b}}{2} \tag{21}$$

And, therefore:

$$A = \frac{a_a + a_b}{2} \tag{22}$$

We now have three unknowns and three equations, which therefore allows for solving:

$$\begin{cases}
M_a a_a = T - F_f \\
M_b a_b = T + F_f \\
A = \frac{a_a + a_b}{2}
\end{cases}$$
(23)

Solving for the equations above symbolically, we arrive at the following expressions:

$$\[a_a = \frac{2(AM_b - F_f)}{M_a + M_b}, a_b = \frac{2(AM_a + F_f)}{M_a + M_b}, T = \frac{(2AM_b - F_f)M_a + F_fM_b}{M_a + M_b}\]$$
(24)

The value for tension, therefore, is the last expression highlighted above.