

#flo #hw

1 | Eigen things!

instead of maps from vec space to another vec space, this is about a vec space to itself

the study of this is the most important part of linalg, according to axler

a subspace which gets mapped into itself is an **invariant subspace**

ie, a subspace can be invariant under T if $T|_U$ is an operator on U

pausing, pg 133

simplest possible nontrivial invariant subspace is an invariant subspace with $\dim 1$

we can take any non-zero vector in V and make the set of all scalar multiples of it $\text{span}(v) = U = \{\lambda v : \lambda \in F\}$
thus, U must have $\dim 1$, cus we only need the orig vec to define the basis

if U is invariant under an operator, then that means that $Tv \in U$ which means that there exists some scalar in F which does the same thing as the map

$$Tv = \lambda v$$

pausing, again, pg. 134

we get the formal definition of an eigenvalue, which is essentially the scalar from F that does the same thing as the transformation

we also get relations to surjectivity and injectivity and invertibility and ect. KBrefSurjectiveFunction KBrefInjective KBrefInvertibleLinearMaps

an eigenvector is the corresponding vector that you pass through the linear map / λ ie, a vector that only gets scaled when you pass it through a linear map, as opposed to getting rotated or translated

we also know that eigenvectors are LID when they have distinct eigenvalues and also, the number of distinct eigen values has to be $\leq \dim v$

restriction operators and quotient operators restricted to U means you can only map into U ? ie, instead of $U \rightarrow V$, it becomes $U \rightarrow U$?

1.1 | 5.B!

the reason why we care more about operators than normal linear maps is because operators can be raised to powers we can do T^2 , because we know it will be in $\mathcal{L}(V)$! they follow all the normal exponentiation rules, except that T^0 is the identity

and we get polynomial $p(T)$ which is where instead of $z \dots z^m$ we have T 's

and also, **operators on complex vector spaces have an eigenvalue**

define diagonal of a matrix to be the diagonal of a square matrix upper triangular is when all entries below the diag are 0. the upper-triangular matrix is usually represented in the form:

$$\begin{pmatrix} \lambda_1 & & * \\ & \ddots & \\ 0 & & \lambda_n \end{pmatrix};$$

which is very pretty!

every operator over C has an upper triangular matrix we can also use these to determine where the operator is invertible. if the diag contains any 0's then it's non invertible!

relation to eigen values,

if the operator has an upper-triangular matrix w.r.t. some basis of V , then the eigenvalues of that operator are the entries on the diag.

and with that, we get to ## 5.C! diagonals and eigenspaces *oh boy, here comes the real stuff!*

diag matrix is a matrix with only non-zero numbers on the diag

the eigenvalues of an operator are the entries along the diag of a diag matrix

and we also get to define, **eigenspace** denoted $E(\lambda, T)$ which is the set of all eigenvectors corresponding to $\lambda + 0 \text{ vec}$ (which is also a subspace)

and, ofc, the sum of the eigenspaces is a direct sum, as a single vec cannot be scaled by multiple λ 's

import def, **diagonalizable** operators on V can be diagonalizable if the op has a diag matrix w.r.t. some basis of V

also a bunch of things that are equivalent to being diagonalizable, shown in 5.41

1.2 | 5.C, inclass

#extract?

- linear algebra can be seen as an equivalence class between multiple different forms
 - algebra is about manipulating these different representations
- diagonal form is one of these forms. its one of the *standard* forms

1.2.1 | so, what is diagonalization anyways?

KBrefDiagonalMatrix

how we actually compute the eigenvalues is not how axler computes the eigen values how we actually do it, is set $(A - \lambda I)v = 0$ this is also equivalent to the inverse of the first term not existing and the determinant being 0

the determinant of a matrix is the product of its eigenvalues! whaaaat?

the characteristic equation of a matrix A becomes a polynomial of degree N

title: characteristic polynomial

the characteristic polynomial of a square matrix is a polynomial which is invariant under matrix similarity

the **trace** is the sum of the diag