1 | **1)**

$$\vec{L} = \vec{p} \times m \vec{v}$$

Rotational velocity is measured in radians/second, so $\vec{v} = R\pi\vec{\omega}$.

$$\vec{L} = \vec{R} \times mR\pi\vec{\omega}$$

The vector is pointing into the page.
$$|\vec{L}| = mR\pi |\vec{R}| |\vec{\omega}| = mR^2\pi\omega$$

We know that $\sin\theta$ is 1 because the vectors are perpendicular.

2 | 2)

The angular momentum changes because although the momentum of the object does not change, its position changes.

3 | **3)**

$$\begin{split} \vec{L} &= \vec{p}\vec{v} \\ \frac{d\vec{L}}{dt} &= \frac{d\vec{p}}{dt} \times m\vec{v} + \frac{d\,m\vec{v}}{dt} \times \vec{p} \\ &= \vec{v} \times m\vec{v} + m\vec{a} \times \vec{p} \\ &= \vec{p} \times \vec{F} \\ &= \vec{\tau} \end{split}$$