We first set up the same set of basic assumptions and variables.

```
GRAV <- 9.8 # gravity (m/s^2) MASS <- 1 # mass (kg)  
I_ROT <- 1 \text{ # roational inertia (kg m^2)} 
L1 <- 0.5 \text{ # distance from rotation point to CoM (m)} 
L2 <- 1 \text{ # distance from rotation ponit to tension (m)} 
PHI <- 0.1 \text{ # angle of Ft relative to floor (rad)} 
FT <- 11 \text{ # tension force (N)} 
OMEGA <- 0.1 \text{ # angle of floor relative to gravity (rad) (because shifted axis)}
```

Additionally, we set the time interval and seed values for time and theta (distance from flat):

```
dt <- 0.05
t_max <- 5
theta <- 0
time <- 0</pre>
```