

# 1 | Definitions

## 1.1 | Algebraic Structures

### 1.1.1 | Group

A set of items and an operation that satisfy closure, identity, inverse, associativity

### 1.1.2 | Field

A group and another "secondary" operation that the set is almost a group under (except the additive identity will have no multiplicative inverse).

### 1.1.3 | Vector Space

A field and a set of vectors that can be added together or multiplied by scalars from the field, **with the following five properties:**

- commutativity
- associativity
- additive identity
- additive inverse
- distributive property

### 1.1.4 | Subspace

A subset of a vector space that is itself a vector space. Only need to show that it:

1. Includes the additive identity (0)
2. Is closed under addition
3. Is closed under scalar multiplication

**The subspace must use the same addition and scalar multiplication of its "superspace"**

### 1.1.5 | Sum

A sum of **(multiple) subsets** is all vectors that can be written as the sum of one vector from each sub **set** (or zero).

### 1.1.6 | Direct Sum

If each element in a sum of **(multiple)** subspaces can be written in only one way (with one summand from each subspace).

## 1. Results

- (a) Condition for a direct sum **The only way to write zero as sum of one element from each summand space is all zeros iff the sum is a direct sum.**
- (b) Condition for a direct sum of two subspaces The intersection of the two subspaces is zero iff the sum is a direct sum.

1.1.7 | **Linear Combination**

A linear combination is the sum of some list of vectors with each one multiplied by a coefficient from  $\mathbb{F}$

1.1.8 | **Linear (In)Dependence**

**A list of vectors is linearly independent if the only coefficients in a linear combination equal to zero are all zeros. (The only  $a_1, \dots, a_n$  s.t.  $a_1v_1 + \dots + a_nv_n = 0$  is  $0, \dots, 0$ )** Equivalent: A vector is linearly dependent in a list (and that list is linearly dependent) if it can be written as a linear combination of other vectors in the list. Any list that is not linearly dependent is linearly independent.

1.1.9 | **Span**

The span of a list is all linear combinations of that list

1.1.10 | **Basis**

The basis of a vector space is a linearly independent list of the elements in that vector space that spans the vector space (whose span is the vector space). A list of vectors is a basis if there is exactly one way to write every vector as a linear combination of the basis.

## 1. Results

- (a) All bases of a vector space are the same length
- (b) A linearly independent or spanning list of the right length is a basis (buy one get one free)

1.1.11 | **Dimension**

The dimension of a subspace is the length of its basis. If the basis does not exist (infinitely long), then the space is infinite dimensional.

1.1.12 | **Elementary Matrix**

A matrix that applies exactly one valid "row operation": multiply a row, add one row to another, swap row orders.

1.1.13 | **Nonsingular / invertible matrix**

A non-singular matrix is a matrix that has an inverse, and whose determinant is not zero.

## 1.2 | Linear Transformations

### 1.2.1 | Linearity

A transformation is linear if it satisfies additivity (adding inside/outside same) and homogeneity (scalar multiplying inside/outside same).

### 1.2.2 | Injective

When the outputs being the same implies the inputs were the same. (Mapping is one to one; each element is mapped to at most once).

### 1.2.3 | Surjective

When every element in the codomain is in the range (Mapping is onto the codomain; each element mapped to at least once).

### 1.2.4 | Linear Map

A map from one vector space to another that is linear (satisfies additivity and homogeneity)

#### 1. Properties

(a) Linear maps from one space to another is a subspace

(b) Algebraic Properties

i. Associative:  $T_1(T_2T_3) = (T_1T_2)T_3$

ii. Identity:  $IT = TI = T$

iii. Distributive:  $(S_1 + S_2)T = TS_1 + TS_2$  And the same for the other side, but you have to be careful about whether maps can be multiplied (composed).

2. Product of Linear Map The product  $ST$  of two linear maps  $T \in \mathcal{L}(U, V)$  and  $S \in \mathcal{L}(V, W)$  is the linear map  $S(T(u))$  for  $u \in U$ .

### 1.2.5 | Image (range, column space)

Every vector that can be a result of a linear map.

#### 1. Properties

(a) CHANGES AFTER RREF!

(b) Surjectivity is the same as the column space being the domain (input space?)

### 1.2.6 | Kernel (null space)

Every vector that the linear map sends to zero.

#### 1. Properties

(a) Always includes zero

(b) Doesn't change after RREF

(c) Injectivity is the same as the null space being zero