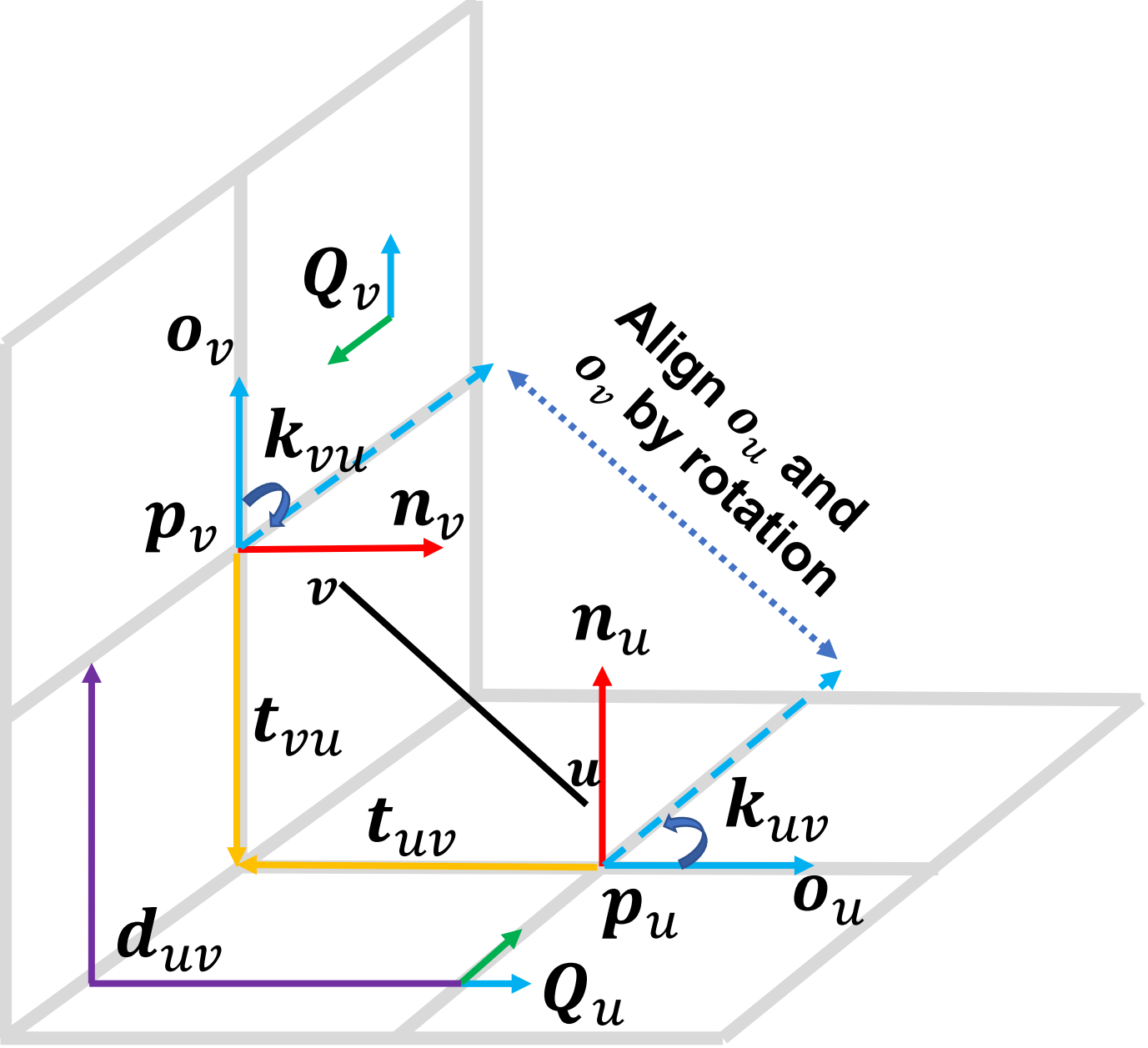
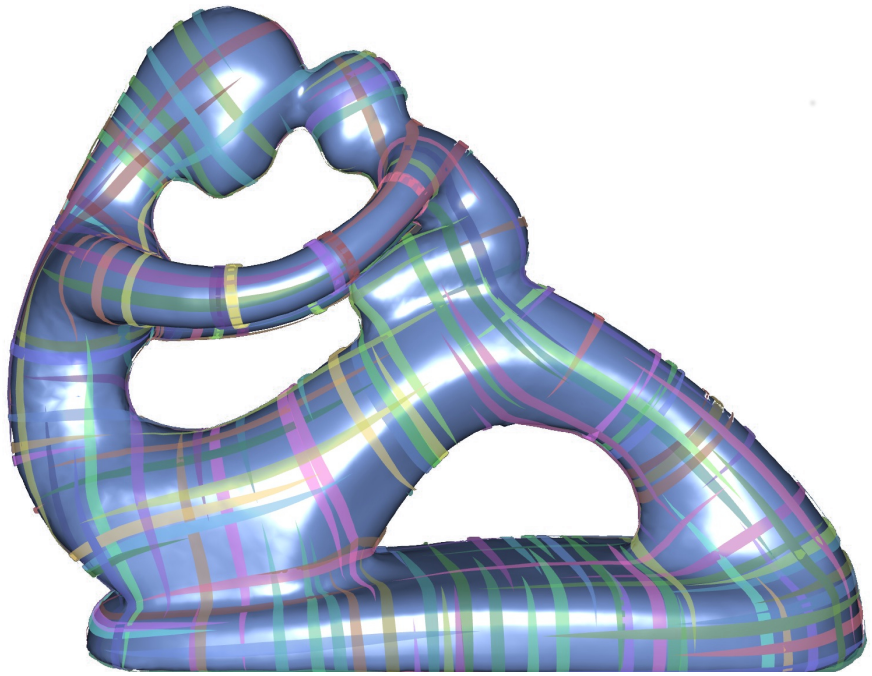
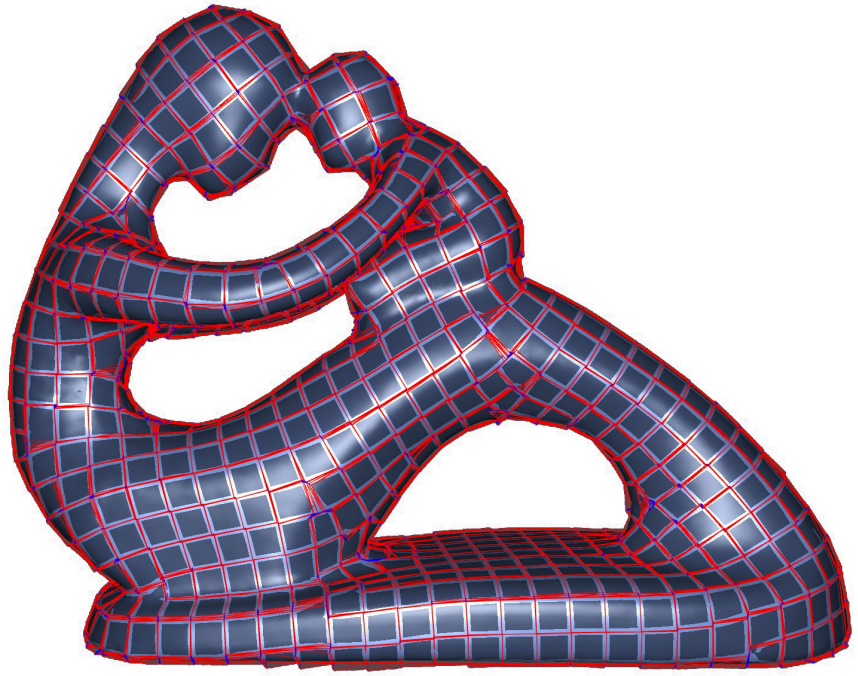

$Q_v$
$o_v$
$k_{vu}$
$p_v$
$n_v$
Align $o_u$ and $o_v$ by rotation
$v$
$n_u$
$t_{vu}$
$u$
$k_{uv}$
$t_{uv}$
$o_u$
$p_u$
$d_{uv}$
$Q_u$

(a)

(b)



(c)