

Assembler

5 laboratory work

Lecturers: dr. Pavel Stefanovič, Rokas Štrimaitis, dr. Tomas Petkus



The main aim of laboratory work

- To remember the IA-32 assembler commands learned in the first course.
- To learn how to use SSE instructions.
- Improving programming skills.



5 laboratory work (I part)

(until 2019.12.20)



- Knowing the length of a number string (in which all ASCII characters are numbers, maximum number 10 characters), you have to create a program using IA-32 commands, that converts a number string to its numeric decimal equivalent.
- For simplicity, the calculation of the string length and the output of the result can be done in C language.

STRING "5245345" -> INT 5245345



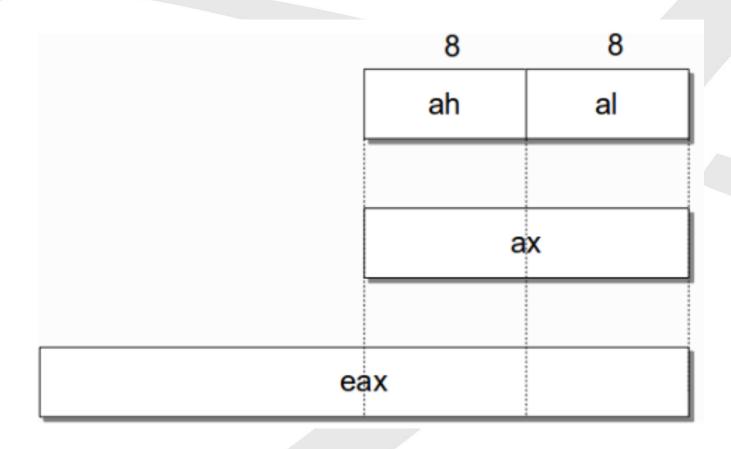
IA-32 registers (1)

- In the *IA-32* processor there are 32 bits registers, which can be used for:
 - four 32 bits registers (EAX, EBX, ECX, EDX);
 - four 16 bits registers(AX, BX, CX, DX);
 - eight 8 bits registers(AL, AH, BL, BH, CL, CH, DL, DH).

Data type	Saved in:
char (8 bits)	AL
short (16 bits)	AX
int (32 bits)	EAX



IA-32 registers (2)





Main instructions

Command	Example	Value		
Addition	add eax, ebx	eax = eax + ebx		
Subtraction	sub eax, ebx	eax = eax - ebx		
Multiplication	mul ebx	$edx:eax = eax \times ebx$		
Multiplication	imul eax, ebx	$eax = eax \times ebx$		
Division	div ebx	edx:eax = eax / ebx		
Logical AND	and eax, ebx	eax & ebx		
Logical OR	or eax, ebx	eax ebx		
Logical XOR	xor eax, ebx	eax ^ ebx		
Assign	mov eax, ebx	eax = ebx		
Compare	cmp eax, ebx	Compare values between registers		
Increase by one	inc eax	eax = eax + 1		
Decrease by on	dec eax	eax = eax - 1		



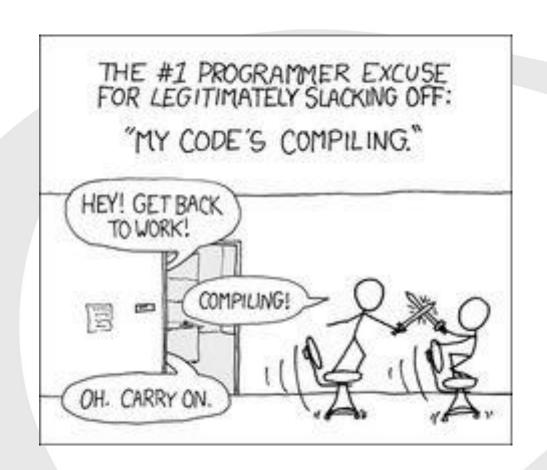
Program frames which can be used

```
#include <stdio.h>
int main(int argc, char** argv ) {
      int iOut = 0:
      char* pcInp;
      if(argc < 2) {
            printf("Missing parameter: number\n");
            return(0);
      pcInp = argv[1];
        asm {
            push eax
            push ebx
            push ecx
            push edx
            /* put code here */
            pop edx
            pop ecx
            pop ebx
            pop eax
      printf("The number was processed as %d\n", iOut );
```

```
#include <stdio.h>
int main(int argc, char** argv ) {
      int iOut = 0;
      char* pcInp = argv[1];
      if( argc < 2 ) {
            printf("Missing parameter: number\n");
            return(0);
      // use %0 for iOut and %1 for pcInp
       asm (
            /* put code here */
             : "=m" (iOut)
                            // gcc inline asm input specification
             : "m" (pcInp)
                              // "m" is memory (pointer)
             : "eax", "ebx", "ecx", "edx" // clobbered registers
                                            //(that are changed inside asm()
        );
      printf("The number was processed as %d\n", iOut );
```



Example



```
#include <iostream>
using namespace std;
int main()
   int result; // final result
 asm {
   push eax // creating register
   mov eax, 0 // assign eax = 0
   for loop:
               // loop name
       cmp eax, 10 // if eax = 10
       je exit_loop // if true, exit the loop
   inc eax  // eax++
jmp for_loop  // back to loop
   exit_loop: // exit loop
       mov result, eax // result = eax
                   // cleaning register
   pop eax
 printf("Result=%d\n", result); //showing the result
```

More examples are in the "MOODLE"

5 laboratory work (II part)

• Numbers x, y and z are Pythagoreans numbers, if the condition is met:

$$x^2 + y^2 = z^2$$

• Your task is to find all integer Pythagorean numbers where:

$$x, y \in \{1, ..., 1000\}.$$

- You must use SSE instructions to perform checking are the x, y integer Pythagorean numbers.
- Looping, output may be done in C.



SSE komandos

• The advantage of SSE instruction is that its is possible to make calculation parallel.

SSE																
R_4 R_3					R_2				R_1							
	8 _{bits}															

• All instruction are given in the link below.

https://en.wikipedia.org/wiki/X86_instruction_listings



SSE realization

1	2	3	4	xmm0	First 4 values
2	3	4	5	xmm1	Second 4 values
1	4	9	16	xmm2	Squares of first
4	9	16	25	xmm3	Squares of second
5	13	25	41	xmm4	Sum of squares
2,23607	3,60555	5	6,40312	xmm5	Square root of previous sum
2	3	5	6	xmm5	integer of previous square
4	9	25	36	xmm5	square of previous integer
-1	-4	0	-5	xmm5	difference or comparison of xmm5 and xmm4
		Found!			



Example of the roots calculation

```
int main ( int argc, char** argv) {
        __declspec(align(16))float fmas[16]={0,1,2,3,4,5,6,7,8,9,10,11,12,13,14,15};
        __declspec(align(16))float fgmas[16];
       int imsize = sizeof(fmas)/sizeof(float);
       float* fptr;
       float* fgptr;
       for ( int i = 0; i < imsize; i+=4){
               fptr = fmas + i;
                fgptr = fgmas + i;
                asm{
                        mov eax, fptr
                        movaps xmm0,[eax]
                        sqrtps xmm0,xmm0
                        mov eax,fgptr
                        movaps [eax],xmm0
       for ( int i = 0; i < 16; i++) {
                printf("Squere from %.0f is equal to %.20f\n", fmas[i], fgmas[i]);
       system("pause");
```



Evaluation



General requirements (1 point)

I part (4 points)

II part (4 points)

- 2. Program code is optimized (0.5).
- 1. One program for both parts (0.5). 1. Input data took from command line (1).
 - 2. Restrictions on the data have to be programmed (1). 2. Filter: output only primary numbers (1)
 - 3. The program works correctly (2).

- 1. The program works correctly (2).
- 3. The results are presented in a separate file (1).