## 自由相对论性粒子的运动方程

从自由粒子的作用量 (2.21) 出发,导出其三维和四维形式的运动方程,即 (2.24) 和 (2.25) 式,并验证它们都给出同样的运动模式,即匀速直线运动.

自由粒子的作用量 (2.21) 式为

$$S = -mc \int ds = -mc \int d\tau \left( \frac{dx^{\mu}}{d\tau} \frac{dx_{\mu}}{d\tau} \right)^{1/2}, \tag{1}$$

其中  $\mathrm{d}s = (\sum_{\mu} \mathrm{d}x_{\mu} \mathrm{d}x^{\mu})^{1/2}$ , 按照书中将其简写为  $\mathrm{d}s = (\mathrm{d}x_{\mu} \mathrm{d}x^{\mu})^{1/2}$ 

导出其三维形式的运动方程:

首先写出三维形式的拉格朗日量, 注意到  $ds = \sqrt{c^2 dt^2 - dx^2} = c dt \sqrt{1 - \mathbf{v}^2/c^2}$ ,

即

$$S = -mc^2 \int \mathrm{d}t \sqrt{1 - \frac{\mathbf{v}^2}{c^2}},\tag{2}$$

因此我们得到一个相对论性自由粒子的拉格朗日量为

$$L(\mathbf{v}) = -mc^2 \sqrt{1 - \frac{\mathbf{v}^2}{c^2}}.$$
(3)

粒子的广义动量为

$$\mathbf{p} = \frac{\partial L}{\partial \mathbf{v}},\tag{4}$$

由 (2.17) 式——

$$\frac{\partial L}{\partial q_i} - \frac{\mathrm{d}}{\mathrm{d}t} \frac{\partial L}{\partial \dot{q}} = 0, \tag{5}$$

此处相应有

$$\frac{\partial L}{\partial \mathbf{x}} - \frac{\mathrm{d}}{\mathrm{d}t} \frac{\partial L}{\partial \mathbf{v}} = 0, 
0 - \frac{\mathrm{d}\mathbf{p}}{\mathrm{d}t} = 0.$$
(6)

粒子的运动方程为

$$\frac{\mathrm{d}\mathbf{p}}{\mathrm{d}t} = 0. \tag{7}$$

导出其四维形式的运动方程:

由 (2.21) 即本文中式 (1) 有

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$$S = -mc \int ds$$

$$= -mc \int \sqrt{dx_{\mu}dx^{\mu}},$$
(8)

对  $x_{\mu}$  做变分,

$$\delta S = -mc \int \delta \sqrt{\mathrm{d}x_{\mu} \mathrm{d}x^{\mu}} 
= -mc \int \delta \sqrt{\eta^{\mu\nu} \mathrm{d}x_{\mu} \mathrm{d}x_{\mu}} 
= -mc \int \frac{\eta^{\mu\nu} \mathrm{d}\delta x_{\mu} \mathrm{d}x_{\mu} + \eta^{\mu\nu} \mathrm{d}x_{\mu} \mathrm{d}\delta x_{\mu}}{2\mathrm{d}s} 
= -mc \int \frac{\eta^{\mu\nu} \mathrm{d}\delta x_{\mu} \mathrm{d}x_{\mu}}{\mathrm{d}s} 
= -mc \int \frac{\mathrm{d}\delta x_{\mu} \mathrm{d}x^{\mu}}{\mathrm{d}s} 
= -mc \int \frac{\mathrm{d}\delta x_{\mu} \mathrm{d}x^{\mu}}{\mathrm{d}s} 
= -mc \int \left(\frac{\mathrm{d}x^{\mu}}{\mathrm{d}s}\right) \mathrm{d}(\delta x_{\mu}).$$
(9)

取边界 a,b 进行分部积分,

$$\delta S = -mcrac{\mathrm{d}x^{\mu}}{\mathrm{d}s}\delta x_{\mu}igg|_a^b + mc\int_a^b (\delta x_{\mu})\mathrm{d}igg(rac{\mathrm{d}x^{\mu}}{\mathrm{d}s}igg).$$
 (10)

参考书中第 24 页式 (2.16) 下面对 式 (2.16) 的处理, 在端点处要求  $\delta x_{\mu}(a) = \delta x_{\mu}(b) = 0$ , 因此上式第一式的 贡献是 0.

$$\delta S = mc \int_a^b \frac{\mathrm{d}^2 x^{\mu}}{\mathrm{d}s^2} \delta x_{\mu} \mathrm{d}s, \tag{11}$$

由于  $\delta x_{\mu}$  是任意的变分, 因此要使  $\delta S=0$  需有

$$\frac{\mathrm{d}^2 x^{\mu}}{\mathrm{d}s^2} = 0, \text{for } \mu = 0, 1, 2, 3 \tag{12}$$

验证它们(式(7),式(12))都给出同样的运动模式:

式 (7) 意味着

$$\frac{\mathrm{d}\mathbf{v}}{\mathrm{d}t} = 0. \tag{13}$$

式 (12) 意味着

$$\frac{\mathrm{d}x^{\mu}}{\mathrm{d}s} = \text{Constant, for } \mu = 0, 1, 2, 3 \tag{14}$$

也即

$$\frac{\mathrm{d}s}{\mathrm{d}x^{\mu}} = \frac{\sqrt{\sum_{\mu} \mathrm{d}x_{\mu} \mathrm{d}x^{\mu}}}{\mathrm{d}x^{\mu}} = \text{Constant, for } \mu = 0, 1, 2, 3$$
(15)

考虑  $\mu = 0$ ,  $x^0 = ct$ , 此时

$$x_0 = \eta_{00} x^0 = x^0 = ct, (16)$$

考虑  $\mu = i$ , i = 1, 2, 3, 此时

$$x_i = \eta_{ii} x^i = -x^i, \text{ for } i = 1, 2, 3,$$
 (17)

式 (15) 展开为

$$\frac{\mathrm{d}s}{\mathrm{d}x^{\mu}} = \frac{\sqrt{\mathrm{d}x^{0}\mathrm{d}x^{0} - \mathrm{d}x^{1}\mathrm{d}x^{1} - \mathrm{d}x^{2}\mathrm{d}x^{2} - \mathrm{d}x^{3}\mathrm{d}x^{3}}}{\mathrm{d}x^{\mu}}$$

$$= \frac{\sqrt{(\mathrm{d}ct)^{2} - (\mathrm{d}x)^{2} - (\mathrm{d}y)^{2} - (\mathrm{d}z)^{2}}}{\mathrm{d}x^{\mu}}$$
(18)

考虑  $\mu = 0$ ,

$$\frac{\mathrm{d}s}{\mathrm{d}ct} = \frac{\sqrt{(\mathrm{d}ct)^2 - (\mathrm{d}x)^2 - (\mathrm{d}y)^2 - (\mathrm{d}z)^2}}{\mathrm{d}ct}$$

$$= \frac{1}{c}\sqrt{c^2 - \left(\frac{\mathrm{d}x}{\mathrm{d}t}\right)^2 - \left(\frac{\mathrm{d}y}{\mathrm{d}t}\right)^2 - \left(\frac{\mathrm{d}z}{\mathrm{d}t}\right)^2}} \tag{19}$$

因此公式 (15) 意味着

$$\begin{cases} \frac{\mathrm{d}x}{\mathrm{d}t} = \mathrm{Contsant}, \\ \frac{\mathrm{d}y}{\mathrm{d}t} = \mathrm{Contsant}, \\ \frac{\mathrm{d}z}{\mathrm{d}t} = \mathrm{Contsant}, \end{cases}$$
(20)

也即

$$\frac{d\mathbf{x}}{dt} = \text{Constant}, 
\frac{d\mathbf{v}}{dt} = 0.$$
(21)

因此两式给出相同的运动模式,

另: 引入固有时  $\tau$ ,

$$ds = cd\tau. (22)$$

(即高显《经典力学》中的 |ds|). 式 (12)

$$egin{aligned} rac{\mathrm{d}^2 x^{\mu}}{\mathrm{d}s^2} &= 0, \\ rac{1}{c^2} rac{\mathrm{d}^2 x^{\mu}}{\mathrm{d}\tau^2} &= 0, \\ rac{\mathrm{d}^2 x^{\mu}}{\mathrm{d}\tau^2} &= 0. \end{aligned}$$

也表示匀速直线运动.

## 自由相对论性粒子的四动量

验证一个自由的相对论性粒子的四动量形式,即(2.26)和(2.27)式.

验证 (2.26) 式和 (2.27) 式, (2.26) 式如下,

$$p^{\mu} = mc \frac{\mathrm{d}x^{\mu}}{\mathrm{d}s} = \left(\frac{E}{c}, \mathbf{p}\right). \tag{24}$$

(2.27) 式如下

$$E = \frac{mc^2}{\sqrt{1 - \frac{\mathbf{v}^2}{c^2}}}. (25)$$

(2.26) 式从对式 (10) 中的边界项的系数得到  $p^\mu=mcrac{\mathrm{d}x^\mu}{\mathrm{d}s}$ , 空间分量即需验证如此得到的动量与

$$\mathbf{p} = \frac{\partial L}{\partial \mathbf{v}} = \frac{m\mathbf{v}}{\sqrt{1 - \frac{\mathbf{v}^2}{c^2}}}$$
(26)

相同. 空间分量即  $\mu = 1, 2, 3$  时

$$p^{\mu} = mc \frac{\mathrm{d}x^{\mu}}{\mathrm{d}s}$$

$$= mc \frac{\mathrm{d}x^{\mu}}{\sqrt{(\mathrm{d}ct)^{2} - (\mathrm{d}x)^{2} - (\mathrm{d}y)^{2} - (\mathrm{d}z)^{2}}}$$

$$= mc \frac{\mathrm{d}x^{\mu}/\mathrm{d}t}{\sqrt{c^{2} - \left(\frac{\mathrm{d}x}{\mathrm{d}t}\right)^{2} - \left(\frac{\mathrm{d}y}{\mathrm{d}t}\right)^{2} - \left(\frac{\mathrm{d}z}{\mathrm{d}t}\right)^{2}}}$$

$$= m \frac{v^{\mu}}{\sqrt{1 - \frac{\mathbf{v}^{2}}{c^{2}}}}.$$
(27)

时间分量即  $\mu = 0$  时,

$$p^{0} = mc \frac{\mathrm{d}x^{0}}{\mathrm{d}s}$$

$$= mc \frac{\mathrm{d}x^{0}}{\sqrt{(\mathrm{d}ct)^{2} - (\mathrm{d}x)^{2} - (\mathrm{d}y)^{2} - (\mathrm{d}z)^{2}}}$$

$$= mc \frac{\mathrm{d}ct/\mathrm{d}t}{\sqrt{c^{2} - \left(\frac{\mathrm{d}x}{\mathrm{d}t}\right)^{2} - \left(\frac{\mathrm{d}y}{\mathrm{d}t}\right)^{2} - \left(\frac{\mathrm{d}z}{\mathrm{d}t}\right)^{2}}}$$

$$= \frac{mc}{\sqrt{1 - \frac{\mathbf{v}^{2}}{c^{2}}}}.$$
(28)

由于  $\frac{E}{c}=p^0$ , 因此

$$E = \frac{mc^2}{\sqrt{1 - \frac{\mathbf{v}^2}{c^2}}}. (29)$$

即 (2.27) 式得证. 至此 (2.26) 式时间分量空间分量也得证.

## 相对论性粒子与标量场的相互作用

仿照相对论性自由粒子运动方程的推导,给出一个相对论性粒子与标量外场相互作用的运动方程 (2.31),并根据拉格朗日量 (2.32) 推导等价的三维形式的粒子运动方程.

仿照相对论性自由粒子运动方程的推导,给出一个相对论性粒子与标量外场相互作用的运动方程 (2.31).

因此

$$\frac{\mathrm{d}^2 x^{\mu}}{\mathrm{d}s^2} + \frac{\mathrm{d}x^{\mu}}{\mathrm{d}s} \frac{\partial \Phi}{\partial x^{\nu}} \frac{\mathrm{d}x^{\nu}}{\mathrm{d}s} = \frac{\partial \Phi(x)}{\partial x_{\mu}}$$
(31)

根据拉格朗日量 (2.32) 推导等价的三维形式的粒子运动方程:

系统的拉格朗日量 (2.32) 为

$$L = -mc^2 \sqrt{1 - \frac{\mathbf{v}^2}{c^2}} e^{\Phi(\mathbf{x},t)},\tag{32}$$

广义动量为

$$\mathbf{p} = \frac{\partial L}{\partial \mathbf{v}} = \frac{m\mathbf{v}}{\sqrt{1 - \frac{\mathbf{v}^2}{c^2}}} e^{\Phi(\mathbf{x}, t)}, \tag{33}$$

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拉格朗日方程有

$$\frac{\partial L}{\partial \mathbf{x}} - \frac{\mathrm{d}}{\mathrm{d}t} \frac{\partial L}{\partial \mathbf{v}} = 0, 
\frac{\partial L}{\partial \mathbf{x}} - \frac{\mathrm{d}\mathbf{p}}{\mathrm{d}t} = 0.$$
(34)

运动方程为

$$\frac{\mathrm{d}}{\mathrm{d}t} \left( \frac{m\mathbf{v}}{\sqrt{1 - \frac{\mathbf{v}^2}{c^2}}} e^{\Phi(\mathbf{x}, t)} \right) = \frac{\partial L}{\partial \mathbf{x}}$$

$$\frac{\mathrm{d}}{\mathrm{d}t} \left( \frac{m\mathbf{v}}{\sqrt{1 - \frac{\mathbf{v}^2}{c^2}}} \right) e^{\Phi(\mathbf{x}, t)} + \frac{m\mathbf{v}}{\sqrt{1 - \frac{\mathbf{v}^2}{c^2}}} \frac{\mathrm{d}}{\mathrm{d}t} e^{\Phi(\mathbf{x}, t)} = -mc^2 \sqrt{1 - \frac{\mathbf{v}^2}{c^2}} \frac{\partial e^{\Phi(\mathbf{x}, t)}}{\partial \mathbf{x}}$$

$$\frac{\mathrm{d}}{\mathrm{d}t} \left( \frac{m\mathbf{v}}{\sqrt{1 - \frac{\mathbf{v}^2}{c^2}}} \right) e^{\Phi(\mathbf{x}, t)} + \frac{m\mathbf{v}}{\sqrt{1 - \frac{\mathbf{v}^2}{c^2}}} e^{\Phi(\mathbf{x}, t)} \frac{\mathrm{d}}{\mathrm{d}t} \Phi(\mathbf{x}, t) = -mc^2 \sqrt{1 - \frac{\mathbf{v}^2}{c^2}} e^{\Phi(\mathbf{x}, t)} \frac{\partial \Phi(\mathbf{x}, t)}{\partial \mathbf{x}}$$

$$\frac{\mathrm{d}}{\mathrm{d}t} \left( \frac{m\mathbf{v}}{\sqrt{1 - \frac{\mathbf{v}^2}{c^2}}} \right) + \frac{m\mathbf{v}}{\sqrt{1 - \frac{\mathbf{v}^2}{c^2}}} \frac{\mathrm{d}}{\mathrm{d}t} \Phi(\mathbf{x}, t) = -mc^2 \sqrt{1 - \frac{\mathbf{v}^2}{c^2}} \frac{\partial \Phi(\mathbf{x}, t)}{\partial \mathbf{x}}$$

$$\frac{\mathrm{d}}{\mathrm{d}t} \left( \frac{m\mathbf{v}}{\sqrt{1 - \frac{\mathbf{v}^2}{c^2}}} \right) + \frac{m\mathbf{v}}{\sqrt{1 - \frac{\mathbf{v}^2}{c^2}}} \frac{\mathrm{d}}{\mathrm{d}t} \Phi(\mathbf{x}, t) + mc^2 \sqrt{1 - \frac{\mathbf{v}^2}{c^2}} \frac{\partial \Phi(\mathbf{x}, t)}{\partial \mathbf{x}} = 0$$

为参考高显《经典力学》(4.41) 以核对上式结果是否正确. 记  $p_i = \frac{mv_i}{\sqrt{1-\frac{\mathbf{v}^2}{c^2}}}$ , 上式写成分量形式为

$$\dot{p}_i + p_i \dot{\Phi} + mc^2 \sqrt{1 - \frac{\mathbf{v}^2}{c^2}} \frac{\partial \Phi}{\partial x_i} = 0, \tag{36}$$

与高显《经典力学》(4.41) 一致.

6. 相对论性粒子与矢量场的相互作用之四维协变形式

仿照相对论性自由粒子运动方程的推导,给出一个相对论性粒子与矢量外场 A(x) 相互作用的四维协变形式的运动方程 (2.37) 并验证四维场强张量的表达式 (2.38).

根据题意即从 (2.33) 式得到 (2.37) 式. 作用量为 (2.33) 式如下

$$S = -mc \int ds - \frac{e}{c} \int A_{\mu}(x) dx^{\mu}. \tag{37}$$

将上式第一项记为  $S_{\text{free}}$ , 第二项记为  $S_{\text{int}}$ .

$$\delta S_{\text{int}} = -\frac{e}{c} \int \delta \left( A_{\mu} dx^{\mu} \right) 
= -\frac{e}{c} \int \left[ (\delta A_{\mu}) dx^{\mu} + A_{\mu} \delta \left( dx^{\mu} \right) \right] 
= -\frac{e}{c} \int \left[ \frac{\partial A_{\mu}}{\partial x^{\nu}} \delta x^{\nu} \frac{dx^{\mu}}{ds} + \underbrace{A_{\mu}} \frac{d \left( \delta x^{\mu} \right)}{ds} \right] ds 
= -\frac{e}{c} \int \left[ \frac{\partial A_{\mu}}{\partial x^{\nu}} \delta x^{\nu} \frac{dx^{\mu}}{ds} - \frac{dA_{\mu}}{ds} \delta x^{\mu} \right] ds 
= -\frac{e}{c} \int \left[ \frac{\partial A_{\mu}}{\partial x^{\nu}} \frac{dx^{\mu}}{ds} \delta x^{\nu} - \frac{\partial A_{\mu}}{\partial x^{\nu}} \frac{dx^{\nu}}{ds} \delta x^{\mu} \right] ds 
= -\frac{e}{c} \int \underbrace{\left( \frac{\partial A_{\nu}}{\partial x^{\mu}} - \frac{\partial A_{\mu}}{\partial x^{\nu}} \right)}_{F_{\mu\nu}} \frac{dx^{\nu}}{ds} \delta x^{\mu} ds$$
(38)

$$\delta S_{\text{free}} = mc \int_{a}^{b} \frac{\mathrm{d}^{2} x^{\mu}}{\mathrm{d}s^{2}} \delta x^{\mu} \mathrm{d}s$$

$$\delta S_{\text{int}} = -\frac{e}{c} \int F_{\mu\nu} \frac{\mathrm{d}x^{\nu}}{\mathrm{d}s} \delta x^{\mu} \mathrm{d}s$$

$$\delta S = 0 \iff mc \frac{\mathrm{d}^{2} x^{\mu}}{\mathrm{d}s^{2}} - \frac{e}{c} F_{\mu\nu} \frac{\mathrm{d}x^{\nu}}{\mathrm{d}s} = 0$$
(39)

## 相对论性粒子与矢量场的相互作用之三维形式

给出一个相对论性粒子与矢量外场 A(x) 相互作用的三维形式的运动方程 (2.39) 并验证其中的电场强度 E 和磁感应强度 B 的确由 (2.40) 式给出.

由作用量相应地有

$$L_{\text{free}} = -mc^2 \sqrt{1 - \mathbf{v}^2/c^2},$$

$$L_{\text{int}} = -e\Phi + \frac{e}{c} \mathbf{v} \cdot \mathbf{A},$$
(40)

广义动量为

$$\mathbf{P} = \frac{\partial L}{\partial \mathbf{v}} = \gamma m \mathbf{v} + \frac{e}{c} \mathbf{P}.$$
 (41)

欧拉-拉格朗日方程为

$$\frac{\mathrm{d}\boldsymbol{P}}{\mathrm{d}t} = \frac{\partial L}{\partial x}.\tag{42}$$

$$\frac{\mathrm{d}\boldsymbol{P}}{\mathrm{d}t} = \frac{\mathrm{d}\boldsymbol{p}}{\mathrm{d}t} + \frac{e}{c}\frac{\mathrm{d}\boldsymbol{A}}{\mathrm{d}t} = \frac{\mathrm{d}\boldsymbol{p}}{\mathrm{d}t} + \frac{e}{c}\left(\frac{\partial\boldsymbol{A}}{\partial t} + (\boldsymbol{v}\cdot\boldsymbol{\nabla})\boldsymbol{A}\right)$$

$$\frac{\partial L}{\partial \boldsymbol{x}} = \boldsymbol{\nabla}\left(-e\boldsymbol{\Phi} + \frac{e}{c}\boldsymbol{v}\cdot\boldsymbol{A}\right) = -e\boldsymbol{\nabla}\boldsymbol{\Phi} + \frac{e}{c}\boldsymbol{\nabla}(\boldsymbol{v}\cdot\boldsymbol{A})$$
(43)

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$$\frac{\mathrm{d}\boldsymbol{p}}{\mathrm{d}t} = -e\boldsymbol{\nabla}\Phi + \frac{e}{c}\boldsymbol{\nabla}(\boldsymbol{v}\cdot\boldsymbol{A}) - \frac{e}{c}\left(\frac{\partial\boldsymbol{A}}{\partial t} + (\boldsymbol{v}\cdot\boldsymbol{\nabla})\boldsymbol{A}\right) 
= \left(-e\boldsymbol{\nabla}\Phi - \frac{e}{c}\frac{\partial\boldsymbol{A}}{\partial t}\right) + \frac{e}{c}(\boldsymbol{\nabla}(\boldsymbol{v}\cdot\boldsymbol{A}) - (\boldsymbol{v}\cdot\boldsymbol{\nabla})\boldsymbol{A}) 
= \left(-e\boldsymbol{\nabla}\Phi - \frac{e}{c}\frac{\partial\boldsymbol{A}}{\partial t}\right) + \frac{e}{c}(\boldsymbol{v}\times(\boldsymbol{\nabla}\times\boldsymbol{A})) 
= e\boldsymbol{E} + \frac{e}{c}\boldsymbol{v}\times\boldsymbol{B}$$
(44)

其中

$$\boldsymbol{E} = -\boldsymbol{\nabla}\Phi - \frac{1}{c}\frac{\partial \boldsymbol{A}}{\partial t}, \, \boldsymbol{B} = \boldsymbol{\nabla} \times \boldsymbol{A}.$$
 (45)

前面用到

$$\mathbf{v} \times (\mathbf{\nabla} \times \mathbf{A}) = \mathbf{\nabla}(\mathbf{v} \cdot \mathbf{A}) - (\mathbf{v} \cdot \mathbf{\nabla})\mathbf{A}$$
(46)

下面证明上式.

首先证明三重矢积

$$\mathbf{A} \times (\mathbf{B} \times \mathbf{C}) = (\mathbf{A} \cdot \mathbf{C})\mathbf{B} - (\mathbf{A} \cdot \mathbf{B})\mathbf{C}$$
(47)

借助 Levi-Civita 符号,任意两向量叉乘为 $\mathbf{a} \times \mathbf{b} = \varepsilon_{ijk} \mathbf{a}_i \mathbf{b}_j \mathbf{e}_k$ ,

$$\mathbf{A} \times (\mathbf{B} \times \mathbf{C}) = \varepsilon_{ijk} A_i (\varepsilon_{lmn} B_l C_m \mathbf{e}_n)_j \mathbf{e}_k$$

$$= \varepsilon_{ijk} \varepsilon_{lmj} A_i B_l C_m \mathbf{e}_k$$

$$= (\delta_{kl} \delta_{im} - \delta_{km} \delta_{il}) A_i B_l C_m \mathbf{e}_k$$

$$= \delta_{kl} \delta_{im} A_i B_l C_m \mathbf{e}_k - \delta_{km} \delta_{il} A_i B_l C_m \mathbf{e}_k$$

$$= A_i B_k C_i \mathbf{e}_k - A_i B_i C_k \mathbf{e}_k$$

$$= (\mathbf{A} \cdot \mathbf{C}) \mathbf{B} - (\mathbf{A} \cdot \mathbf{B}) \mathbf{C}$$

$$(48)$$

下面借助三重矢积证明式 (46).

以下标 c 标记  $\nabla$  算符不作用在  $\mathbf{v}$  上面.

LHS = 
$$\mathbf{v} \times (\nabla \times \mathbf{A})$$
  
=  $\mathbf{v}_c \times (\nabla \times \mathbf{A})$   
=  $\nabla (\mathbf{v}_c \cdot \mathbf{A}) - (\mathbf{v}_c \cdot \nabla) \mathbf{A}$  (49)

v 是独立变量, ▼ 算符不作用在 v 上.

$$RHS = \nabla (\boldsymbol{v}_c \cdot \boldsymbol{A}) - (\boldsymbol{v}_c \cdot \nabla) \boldsymbol{A}$$

$$= LHS$$
(50)