Intersection of Convex Sets

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Andreas Haupt

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1 The Intersection Problem

Conventions

- **bold** lowercase letters are column vectors in \mathbb{R}^n
- uppercase **bold** letters are in $\mathbb{R}^{n \times n}$
- $K, K_1, K_2 \subseteq \mathbb{R}^n$ convex.
- $\|\cdot\|$ is the ℓ^2 -norm.

Definition 1.1 (Oracles). EO_f: Input x, Output f(x)

 $OO_{\varepsilon}(\mathbf{K})$: Input c, Output $\max_{\mathbf{x}} \mathbf{c}^T \mathbf{x}$

 $SO_{\varepsilon,\delta}(f)$: Input **x**, Output: Assertion $f(\mathbf{x}) \leq \min_{\mathbf{y}} f(\mathbf{y}) + \eta$ or $\mathbf{c} \neq 0$, b with $b \leq \delta \|\mathbf{c}\|$ and $\{\mathbf{z} | f(\mathbf{z}) \leq f(\mathbf{x})\} \subseteq$ $\{\mathbf{z} | \mathbf{c}^T \mathbf{z} \le \mathbf{c}^T \mathbf{x} + b\}$

SGO_{δ}: Input **x**, Output: **y** $\in \{g \in \Omega | f(\mathbf{y}) + \delta \geq f(\mathbf{x}) + \delta \}$ $\mathbf{g}^T(y-x), \forall \mathbf{v} \in \Omega$.

Definition 1.2 (Strong Concavity). $f: K \to \mathbb{R}$ is α -strongly concave iff $f(\mathbf{x}) + \alpha ||\mathbf{x}||$ is concave.

Lemma 1.3. If f is α -strongly concave with minimizer \mathbf{x}^* , $f(\mathbf{y}) \leq f(\mathbf{x}^*) + \varepsilon$, then $\frac{1}{2}\alpha \|\mathbf{x}^* - \mathbf{y}^*\|^2 \leq \varepsilon$, $\forall \varepsilon > 0$. Strongly concave functions have unique maximizers.

Theorem 1.4 (Our Cutting-Plane Method). Let $f: \mathbb{R}^n \to \mathbb{R}$, $\alpha \in (0,1), \ \Omega \subseteq B_{\infty}(\mathbf{0},R)$ convex containing a minimizer of f. Then we can compute $\mathbf{x} \in \mathbb{R}^n$ with

$$f(\mathbf{x}) - \min_{\mathbf{y} \in \Omega} f(\mathbf{y}) \le \eta + \alpha (\max_{\mathbf{y} \in \Omega} f(\mathbf{y}) - \min_{\mathbf{y} \in \Omega} f(\mathbf{y}))$$

$$\begin{split} & in \quad O(n\operatorname{SO}_{\eta,\delta}(f)\log(\frac{n\kappa}{\alpha}) \ + \ n^3\log^{O(1)}(\frac{n\kappa}{\alpha})), \\ & \Theta(\frac{\alpha\operatorname{MinWidth}(\Omega)}{n^{\frac{3}{2}}\ln(\kappa)}), \ \kappa = \frac{R}{\operatorname{MinWidth}(\Omega)}. \end{split}$$

MATROID INTERSECTION PROBLEM

Matroids (E, \mathcal{I}_1) , (E, \mathcal{I}_2) given via independence (or rank) oracles of complexity \mathcal{T}_{ind} (or $\mathcal{T}_{\text{rank}}$), $\boldsymbol{w} \in \mathbb{R}^E$, $\|\boldsymbol{w}\|_{\infty} \leq M$.

Find $S \in \operatorname{arg\,min}_{S \in \mathcal{I}_1 \cap \mathcal{I}_2} w(S)$. Task:

2 Solving the Intersection Problem

Assumptions

$$K_1, K_2 \subseteq B_2(0, M), M \ge 1, \quad \|\mathbf{c}\|_2 \le M, \quad K_1 \cap K_2 \ne \emptyset$$
(A)

Regularize the Problem

$$f_{\lambda}(\mathbf{x}, \mathbf{y}) \coloneqq \frac{1}{2} \mathbf{c}^T \mathbf{x} + \frac{1}{2} \mathbf{c}^T \mathbf{y} - \frac{\lambda}{2} \|\mathbf{x} - \mathbf{y}\|^2 - \frac{1}{2\lambda} \|\mathbf{x}\|^2 - \frac{1}{2\lambda} \|\mathbf{y}\|^2 x$$

Lemma 2.1. Assuming (A), f_{λ} has a unique maximizer $(\mathbf{x}_{\lambda}, \mathbf{y}_{\lambda})$ on $K_1 \times K_2$ such that $\|\mathbf{x}_{\lambda} - \mathbf{y}_{\lambda}\|^2 \leq \frac{6M^2}{\lambda}$ and

$$\max_{\mathbf{x} \in K_1 \cap K_2} \mathbf{c}^T \mathbf{x} \le f_{\lambda}(\mathbf{x}_{\lambda}, \mathbf{y}_{\lambda}) + \frac{M^2}{\lambda}.$$

Lemma 2.2 (Sion 1958, Corollary of 3.3). Let $f: X \times Y \rightarrow X$ $\mathbb{R}, (x,y) \mapsto f(x,y)$ continuous, convex in x, concave in y, X or Y compact. Then

$$\sup_{x \in X} \inf_{y \in Y} f(\mathbf{x}, \mathbf{y}) = \inf_{y \in Y} \sup_{x \in X} f(\mathbf{x}, \mathbf{y}).$$

Max-Min Problem

$$\Omega \coloneqq \{(\boldsymbol{\theta}_1, \boldsymbol{\theta}_2, \boldsymbol{\theta}_3) | \|\boldsymbol{\theta}_1\| \le 2M, \|\boldsymbol{\theta}_2\|, \|\boldsymbol{\theta}_3\| \le M\}$$

$$g_{\lambda}(\mathbf{x}, \mathbf{y}, \boldsymbol{\theta}) \coloneqq \left(\frac{\boldsymbol{c}}{2} + \lambda \boldsymbol{\theta}_1 + \frac{1}{\lambda} \boldsymbol{\theta}_2\right)^T \boldsymbol{x}$$

$$+ \left(\frac{\boldsymbol{c}}{2} - \lambda \boldsymbol{\theta}_1 + \frac{1}{\lambda} \boldsymbol{\theta}_3\right)^T \boldsymbol{y}$$

$$+ \frac{\lambda}{2} \|\boldsymbol{\theta}_1\|^2 + \frac{1}{2\lambda} (\|\boldsymbol{\theta}_2\|^2 + \|\boldsymbol{\theta}_3\|^2)$$

$$h_{\lambda}(\boldsymbol{\theta}) \coloneqq \max_{(\boldsymbol{x}, \boldsymbol{y}) \in K_1 \times K_2} g_{\lambda}(\mathbf{x}, \mathbf{y}, \boldsymbol{\theta}), \boldsymbol{\theta} = (\theta_1, \theta_2, \theta_3)$$

Getting an Approximately Optimal Solution

Lemma 2.3. Assuming (A), $\lambda \geq 2$,

$$f_{\lambda}(\mathbf{x}, \mathbf{y}) = \min_{\boldsymbol{\theta} \in \Omega} g_{\lambda}(\mathbf{x}, \mathbf{y}, \boldsymbol{\theta}).$$

$$h_{\lambda}(\boldsymbol{\theta}') \leq \min_{\boldsymbol{\theta} \in \Omega} h_{\lambda}(\boldsymbol{\theta}) + \varepsilon,$$

then $z = -\frac{1}{2}(\theta_2' + \theta_3')$ satisfies

$$\max_{\boldsymbol{x} \in K_1 \cap K_2} \boldsymbol{c}^T \boldsymbol{x} \leq \boldsymbol{c}^T \boldsymbol{z} + \frac{20M^2}{\lambda} + 20\lambda^3 \varepsilon$$

and $\|\boldsymbol{z} - \boldsymbol{x}_{\lambda}\| + \|\boldsymbol{z} - \boldsymbol{y}_{\lambda}\| \le 4\sqrt{2\lambda\varepsilon} + \sqrt{\frac{6M^2}{\lambda}}, \ (\boldsymbol{x}_{\lambda}, \boldsymbol{y}_{\lambda}) \in$ $\arg\max_{(\boldsymbol{x},\boldsymbol{y})\in K_1\times K_2} f_{\lambda}(\boldsymbol{x},\boldsymbol{y}).$

Getting a Separation Oracle for h_{λ}

Lemma 2.4. $SO_{O(\sqrt{\varepsilon\lambda D}),O(\sqrt{\varepsilon\lambda D})}(h_{\lambda})$ on $\{\boldsymbol{\theta}|\|\boldsymbol{\theta}\|\leq D\}$ has Consider set P_{ε} of solution of value at most $OPT+\varepsilon$. complexity $O(OO_{\varepsilon}(K_1) + OO_{\varepsilon}(K_2))$

Solving the Intersection Problem

Theorem 2.5 (Main Theorem). Assuming (A). Then for any $0 < \delta < 1$, we can find z, $d(z, K_1) + d(z, K_2) \leq \delta$ such that

$$\max_{\boldsymbol{x} \in K_1 \cap K_2} \boldsymbol{c}^T \boldsymbol{x} \le \boldsymbol{c}^T \boldsymbol{z} + \delta$$

in time

$$O(n(OO_{\eta}(K_1) + OO_{\eta}(K_2))\log(\frac{nM}{\delta}) + n^3\log^{O(1)}(\frac{nM}{\delta})),$$
$$\eta \in \Omega((\frac{\delta}{nM})^{O(1)}).$$

Lemma 2.6 (Klivans and Spielman 2001, Lemma 4). Let C be a set of linear forms in variables z_1, \ldots, z_ℓ with coefficients in [K]. For $z_1, \ldots, z_\ell \sim \text{Unif}_{\lceil \lceil \frac{K\ell}{2} \rceil \rceil}$, with probability greater than $1-\varepsilon$, there is a unique form of minimal value at

- Note $\min_{x \in P} \mathbf{z}^T \mathbf{x} = \min_{x \in P} \mathbf{x}^T \mathbf{z} = \min_{x \in P} x(\mathbf{z})$, where $x \in \mathcal{L}(\mathbb{R}^n), \mathbf{z} \mapsto \mathbf{x}^T \mathbf{z}.$
- This is the reason why algorithms in the applications give guarantees only with a certain probability.

Unique Solutions and an Error Estimate

Lemma 2.7 (Uniqueness Lemma). Let $P := \{\mathbf{x} | Ax \geq b\} \subseteq$ $B_M^{\infty}(\mathbf{0})$ be integral, $\mathbf{A} \in \mathbb{Z}^{m \times n}$, $\mathbf{b} \in \mathbb{Z}^n$, $\mathbf{c} \in \mathbb{Z}^n$.

- Then we can find $\mathbf{z} \in \mathbb{Z}^n, \|\mathbf{z}\|_{\infty} \leq 100n^2M^2\|c\|_{\infty} + 10nM$ such that with probability at least $\frac{9}{10}$, $\min_{\mathbf{z} \in \mathcal{Z}} \mathbf{z}^T \mathbf{z}$ has a unique minimizer x^* and $x^* \in \arg\min_{x \in P} c^T x$.
- If $\mathbf{y} \in P$, $\mathbf{z}^T \mathbf{y} \leq \min_{\mathbf{x} \in P} \mathbf{z}^T \mathbf{x} + \delta$, then $\|\mathbf{y} \mathbf{x}^*\| \leq 2nM\delta$.

Applications 3

Weighted Matroid Intersection

Theorem 3.1. Weighted Matroid Intersection with $\mathbf{w} \in \mathbb{Z}^n$, $\|\mathbf{w}\|_{\infty} \leq M$ can be solved in

$$O(n\operatorname{GO}\log(nM) + n^3\log^{O(1)}(nM))$$

with probability at least $\frac{9}{10}$, where GO is the complexity of optimizing $\min_{S \in \mathcal{I}_i} w(S)$.

For expensive GO and/or large r speedup.

Submodular Flow

Submodular Flow Problem

(G,c) weighted digraph, $l,u:V(G)\to\mathbb{R}$, $f: 2^{V(G)} \to \mathbb{R}, \ f(\emptyset) = f(V) = 0$

Find a flow $\varphi \colon E(G) \to \mathbb{R}, \ l(e) \leq \varphi(e) \leq$ Task: $u(e), \forall e \in E(G), \sum_{v \in S} \exp(v) \le f(S).$

LP formulation (A incidence matric of G)

$$\max_{\mathbf{x} \in P} \mathbf{c}^T \mathbf{x}, P \coloneqq \{ \boldsymbol{\varphi} | \mathbf{1} \le \boldsymbol{\varphi} \le \mathbf{u}, \ \mathbf{x} = \mathbf{A} \boldsymbol{\varphi}, \mathbf{x}(S) \le f(S), \forall S \subseteq V \}$$

$$P_{\varepsilon} = \{ \mathbf{x} | \exists \varphi \colon \mathbf{l} \le \varphi \le \mathbf{u}, \ \mathbf{x} = \mathbf{A}\varphi \}$$
$$\cap \{ \mathbf{x} | \mathbf{x}(S) \le f(S), \forall S \subseteq V, \mathbf{x}(V) = f(V) \}$$

Submodular Flow

Theorem 3.2. The Submodular Flow Problem can be solved in

$$O(n^2 \operatorname{EO}_f \log(mCU) \log(n) + n^3 \log^{O(1)}(mCU))$$

with probability at least $\frac{9}{10}$.

Previously best: $\tilde{O}(n^6 \, \mathrm{EO}_f + n^7)$ Fleischer, Iwata, and Mc-Cormick 2002 and $O(mn^5 \log(nU) EO)$ Fleischer and Iwata 2000

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