



Sumbu X

- $x_1 = l_1 \sin \theta_1$
- $x_2 = l_1 \sin \theta_1 + l_2 \sin \theta_2$

sumbu Y

- $y_1 = -l_1 \cos \theta_1$
- $y_2 = -l_1 \cos \theta_1 - l_2 \cos \theta_2$

Anggota Kelompok

- Dinda Cahya Macharani
- Indri Oktaviani
- Muhammad Fauzi Badru