Memory & Cache

Computer Organization

Wednesday, 25 September 2024

Many slides adapted from: Computer Organization and Design, Patterson & Hennessy 5th Edition, © 2014, MK and from Prof. Mary Jane Irwin, PSU



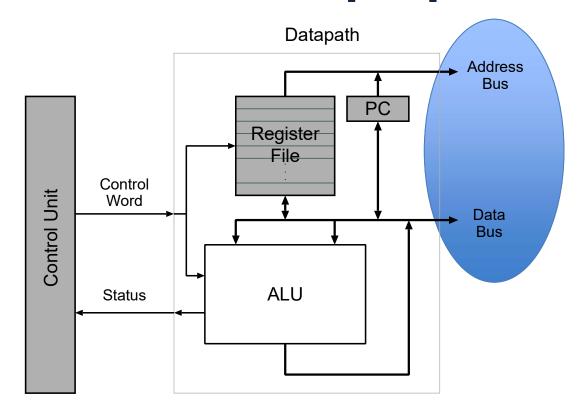
Summary

- Previous Class
 - Role of the Compiler
- Today:
 - Memory hierarchy
 - Caches



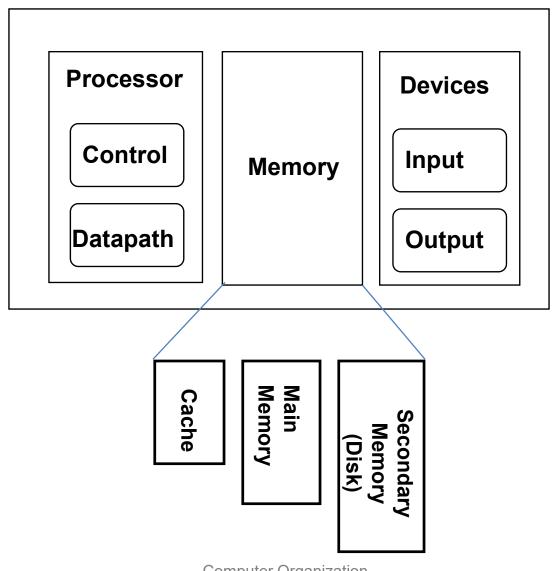
Inside the Processor (CPU)

- Datapath: performs operations on data
- Control: sequences datapath, memory, ...
- Trace < command, address, [data] >





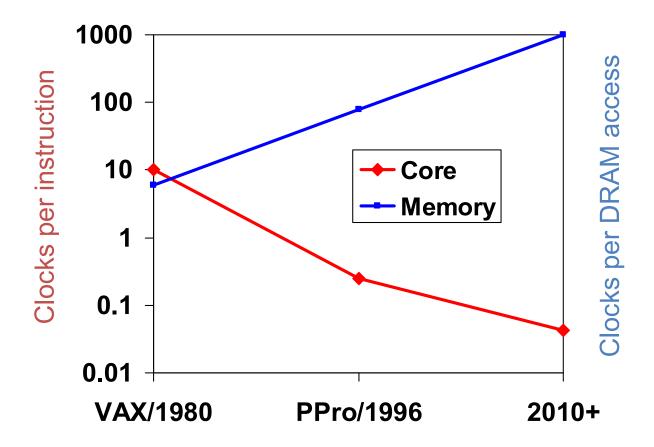
Review: Major Components of a Computer





The "Memory Wall"

Processor vs DRAM speed disparity continues to grow



Good memory hierarchy (cache) design is increasingly important to overall performance



Memory Technology

Static RAM (SRAM)

$$0.5 \text{ns} - 2.5 \text{ns}$$

Dynamic RAM (DRAM)

Flash memory

$$5 \mu s - 50 \mu s$$

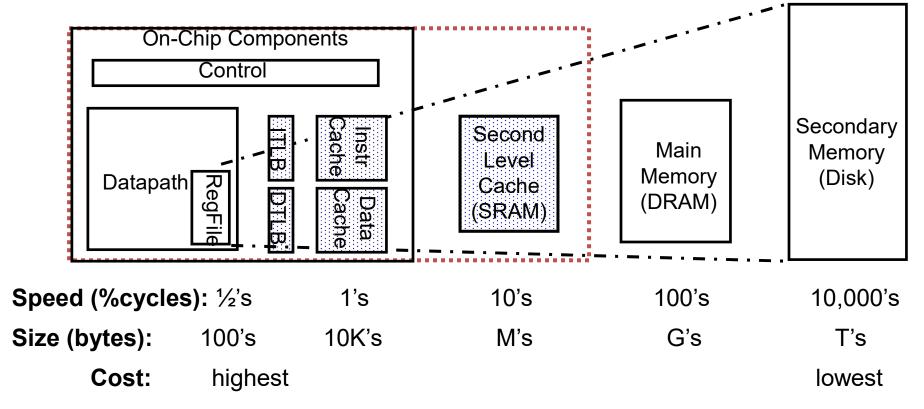
Magnetic disk

$$5ms - 20ms$$

- Ideal memory
 - Access time of SRAM
 - Capacity and cost/GB of disk

A Typical Memory Hierarchy

 Take advantage of the principle of locality to present the user with as much memory as is available in the cheapest technology at the speed offered by the fastest technology





Memory Hierarchy Technologies

- Caches use SRAM for speed and technology compatibility
 - Fast (typical access times of 0.5 to 2.5 nsec)
 - Low density (6 transistor cells), higher power, expensive
 - Static: content will last "forever" (as long as power is left on)
- Main memory uses DRAM for size (density)
 - Slower (typical access times of 50 to 70 nsec)
 - High density (1 transistor cells), lower power, cheaper
 - Dynamic: needs to be "refreshed" regularly (~ every 8 ms)
 - consumes 1% to 2% of the active cycles of the DRAM
 - Addresses divided into 2 halves (row and column)
 - RAS or Row Access Strobe triggering the row decoder
 - CAS or Column Access Strobe triggering the column selector



The Memory Hierarchy: Why Does it Work?

- Temporal Locality (locality in time)
 If a memory location is referenced then it will tend to be referenced again soon
 - → Keep most recently accessed data items closer to the processor
 - e.g., instructions in a loop, induction variables
- Spatial Locality (locality in space)
 If a memory location is referenced, the locations with nearby addresses will tend to be referenced soon
 - Move blocks consisting of contiguous words closer to the processor
 - e.g., sequential instruction access, array data

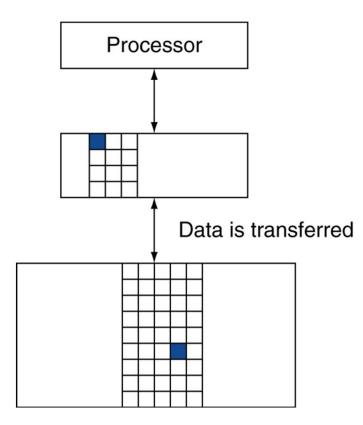


Taking Advantage of Locality

- Memory hierarchy
- Store everything on disk
- Copy recently accessed (and nearby) items from disk to smaller DRAM memory
 - Main memory
- Copy more recently accessed (and nearby) items from DRAM to smaller SRAM memory
 - Cache memory attached to CPU



Memory Hierarchy Levels



- Block (aka line): unit of copying
 - May be multiple words
- If accessed data is present in upper level
 - Hit: access satisfied by upper level
 - Hit ratio: hits/accesses
- If accessed data is absent
 - Miss: block copied from lower level
 - Time taken: miss penalty
 - Miss ratio: misses/accesses
 - = 1 hit ratio
 - Then accessed data supplied from upper level



The Memory Hierarchy: Terminology

- Block (or line): the minimum unit of information that is present (or not) in a cache
- Hit Rate: the fraction of memory accesses found in a level of the memory hierarchy
 - Hit Time: Time to access that level which consists of
 Time to access the block + Time to determine hit/miss
- Miss Rate: the fraction of memory accesses not found in a level of the memory hierarchy ⇒ 1 - (Hit Rate)
 - Miss Penalty: Time to replace a block in that level with the corresponding block from a lower

Hit Time << Miss Penalty



How is the Hierarchy Managed?

- registers ↔ memory
 - by compiler (programmer?)
- cache ↔ main memory
 - by the cache controller hardware
- main memory ↔ disks
 - by the operating system (virtual memory)
 - virtual to physical address mapping assisted by the hardware (TLB)
 - by the programmer (files)



Cache Memory

- Cache memory
 - The level of the memory hierarchy closest to the CPU
- Given accesses X₁, ..., X_{n-1}, X_n

X ₄
X ₁
X _{n-2}
X _{n-1}
X ₂
X ₃

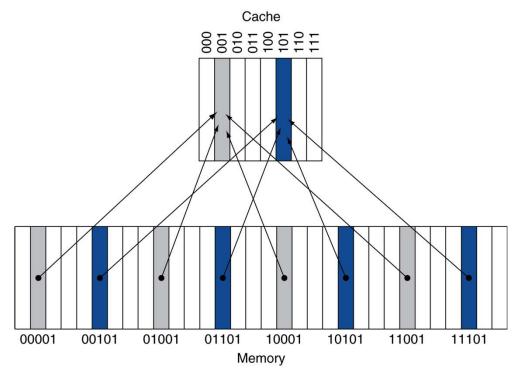
X ₄ X ₁
X ₁
X _{n-2}
X _{n-1}
X ₂
X _n
X ₃

- How do we know if the data is present?
- Where do we look?

a. Before the reference to X_n b. After the reference to X_n

Direct Mapped Cache

- Location determined by address
- Direct mapped: only one choice (Block address) modulo (#Blocks in cache)



- -#Blocks are a power of 2
- Use low-order address bits



Tags and Valid Bits

- How do we know which particular block is stored in a cache location?
 - Store block address as well as the data
 - Actually, only need the high-order bits
 - Called the tag
- What if there is no data in a location?
 - Valid bit: 1 = present, 0 = not present
 - Initially 0



- 8-blocks, 1 word/block, direct mapped
- Initial state

Index	V	Tag	Data
000	N		
001	N		
010	N		
011	N		
100	N		
101	N		
110	N		
111	N		



Word addr	Binary addr	Hit/miss	Cache block
22	10 110		

Index	V	Tag	Data
000	N		
001	N		
010	N		
011	N		
100	N		
101	N		
110	N		
111	N		



Word addr	Binary addr	Hit/miss	Cache block
22	10 110	Miss	110

Index	V	Tag	Data
000	N		
001	N		
010	N		
011	N		
100	N		
101	N		
110	Y	10	Mem[10110]
111	N		



Word addr	Binary addr	Hit/miss	Cache block
26	11 010		

Index	V	Tag	Data
000	N		
001	N		
010	N		
011	N		
100	N		
101	N		
110	Υ	10	Mem[10110]
111	N		



Word addr	Binary addr	Hit/miss	Cache block
26	11 010	Miss	010

Index	V	Tag	Data
000	N		
001	N		
010	Y	11	Mem[11010]
011	N		
100	N		
101	N		
110	Υ	10	Mem[10110]
111	N		



Word addr	Binary addr	Hit/miss	Cache block
22	10 110		

Index	V	Tag	Data
000	N		
001	N		
010	Υ	11	Mem[11010]
011	N		
100	N		
101	N		
110	Υ	10	Mem[10110]
111	N		



Word addr	Binary addr	Hit/miss	Cache block
22	10 110	Hit	110

Index	V	Tag	Data
000	N		
001	N		
010	Υ	11	Mem[11010]
011	N		
100	N		
101	N		
110	Υ	10	Mem[10110]
111	N		



Word addr	Binary addr	Hit/miss	Cache block
22	10 110	Hit	110
26	11 010	Hit	010

Index	V	Tag	Data
000	N		
001	N		
010	Υ	11	Mem[11010]
011	N		
100	N		
101	N		
110	Υ	10	Mem[10110]
111	N		



Word addr	Binary addr	Hit/miss	Cache block
16	10 000	Miss	000
3	00 011	Miss	011
16	10 000	Hit	000

Index	V	Tag	Data
000	Y	10	Mem[10000]
001	N		
010	Υ	11	Mem[11010]
011	Y	00	Mem[00011]
100	N		
101	N		
110	Υ	10	Mem[10110]
111	N		



Word addr	Binary addr	Hit/miss	Cache block
18	10 010		

Index	V	Tag	Data
000	Υ	10	Mem[10000]
001	N		
010	Υ	11	Mem[11010]
011	Υ	00	Mem[00011]
100	N		
101	N		
110	Υ	10	Mem[10110]
111	N		

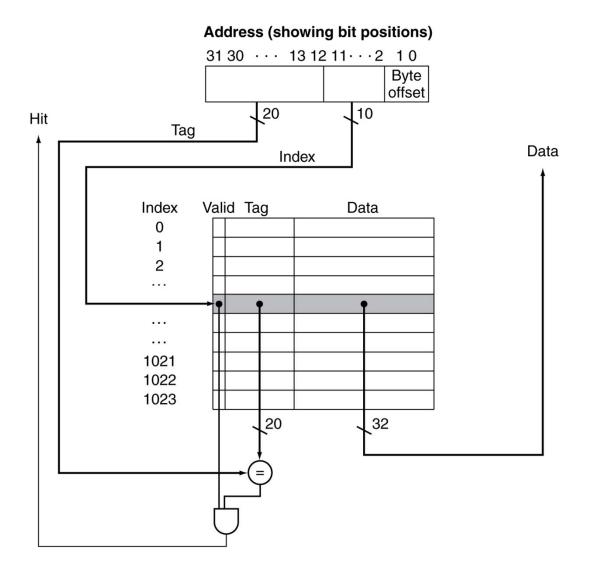


Word addr	Binary addr	Hit/miss	Cache block
18	10 010	Miss	010

Index	V	Tag	Data
000	Υ	10	Mem[10000]
001	N		
010	Y	10	Mem[10010]
011	Υ	00	Mem[00011]
100	N		
101	N		
110	Υ	10	Mem[10110]
111	N		



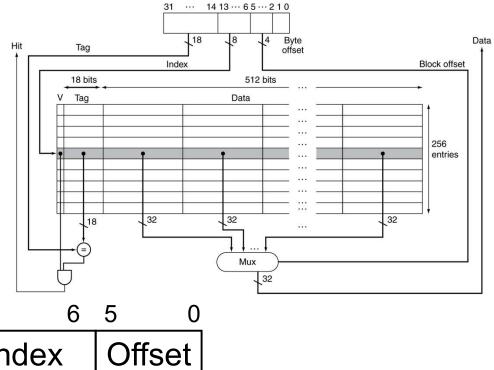
MIPS Direct Mapped Cache Example



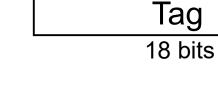


- 256 blocks, 16 words/block
 - To what block number does address 19200 map?

Block number ?



Address (showing bit positions)

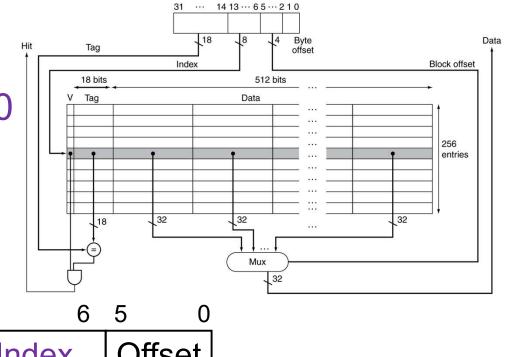


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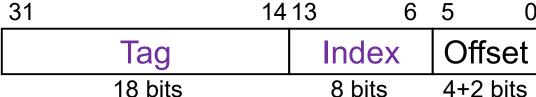
Index 4+2 bits 8 bits

14 13

- 256 blocks, 16 words/block
 - To what block number does address 19200 map?
- Block address
 - = [19200/(16x4)] = 300
 - -- Removing the Offset

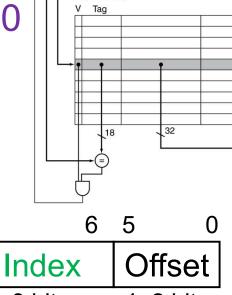


Address (showing bit positions)





- 256 blocks, 16 words/block
 - To what block number does address 19200 map?
- Block address
 - = [19200/(16x4)] = 300
 - -- Removing the Offset
- Block number
 - $= 300 \mod 256 = 44$



Tag

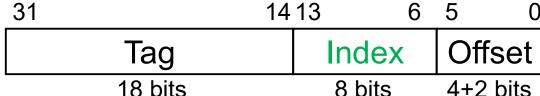
18 bits

Address (showing bit positions)

512 bits

Data

Index





Data

Block offset

256 entries

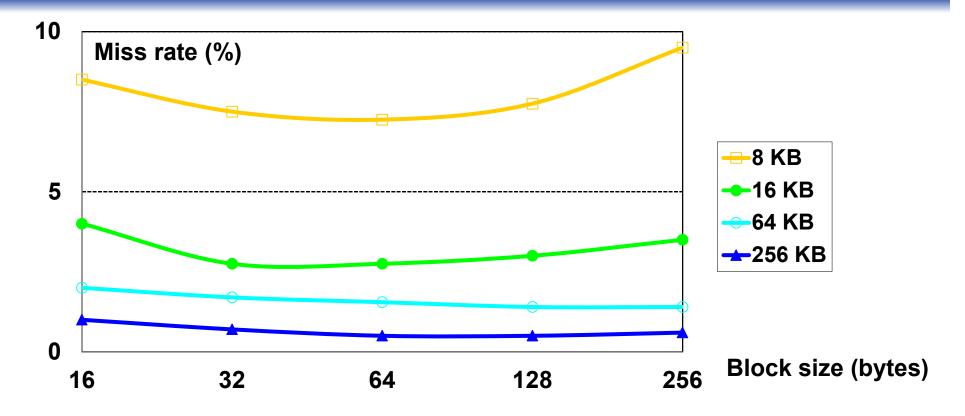
32

Block Size Considerations

- Larger blocks should reduce miss rate
 - Due to spatial locality
- But in a fixed-sized cache
 - Larger blocks ⇒ fewer blocks
 - More competition ⇒ increased miss rate
 - Larger blocks ⇒ pollution
- Larger miss penalty
 - » since we have more bytes to transfer
 - Can override benefit of reduced miss rate
 - Early restart and critical-word-first can help



Miss Rate vs Block Size vs Cache Size

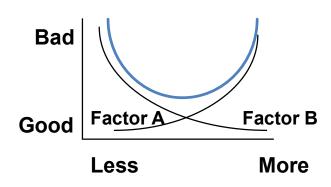


 Miss rate goes up if the block size becomes a significant fraction of the cache size because the number of blocks that can be held in the same size cache is smaller (increasing capacity misses)



Concluding Remarks

- Fast memories are small, large memories are slow
 - We really want fast, large memories
 - Caching gives this illusion
- Principle of locality
 - Programs use a small part of their memory space frequently
- The optimal choice is a compromise
 - depends on access characteristics
 - workload
 - use (I-cache, D-cache, TLB)
 - depends on technology / cost





Next Class

Improving Cache Performance



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- 64 blocks, 16 bytes/block
 - To what block number does address 1200 map?
- Block address

- Block number
 - $= 75 \mod 64 = 11$

