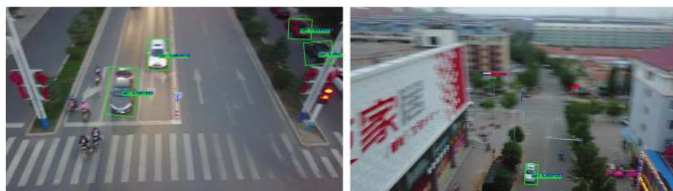Results on the VisDrone dataset. (a) Night condition; (b) overhead view; (c) image blur, as seen in "Multiclass Object Detection in UAV Images Based on Rotation Region Network," by J. Xiao, *et al.*, p. 188.