Honors in Machine Learning and Artificial Intelligence Mini Project Evaluating the performance of Deep Reinforcement Learning for solving the Cartpole Problem

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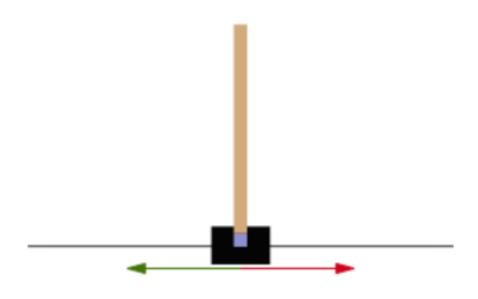
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Introduction

Reinforcement learning is an area of machine learning concerned with how intelligent agents ought to take actions in an environment in order to maximize the notion of cumulative reward.

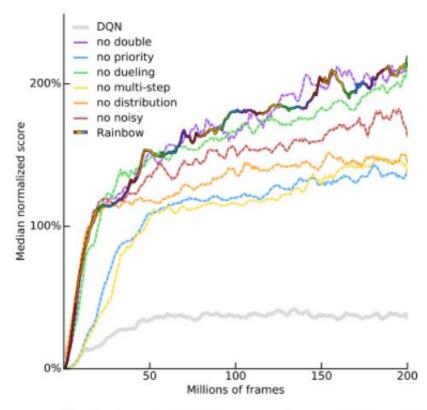
Cartpole problem

Cartpole - known also as an Inverted Pendulum is a pendulum with a center of gravity above its pivot point. It's unstable but can be controlled by moving the pivot point under the center of mass. The goal is to keep the cartpole balanced by applying appropriate forces to a pivot point.



Cartpole schematic drawing

Rainbow



Performance of Rainbow on Atari Benchmark

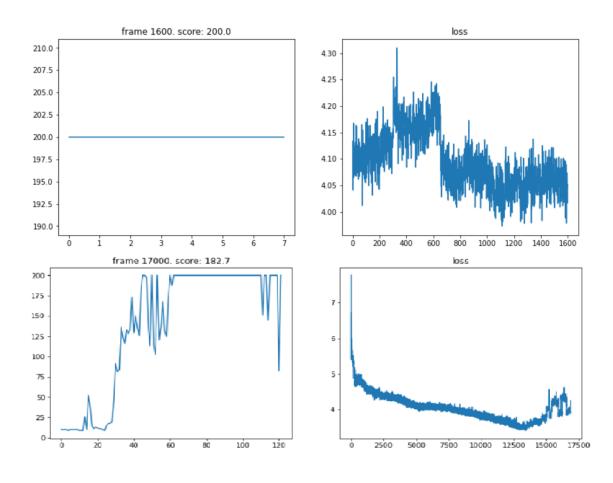
A selection of the below six extensions that each have addressed a limitation and improved overall performance were integrated into a single integrated agent, Rainbow for improved performance on RL tasks [8]:

- 1. Double Q-learning
- 2. Prioritized replay
- 3. Dueling networks
- 4. Multi-step learning
- 5. Distributional RL
- 6. Noisy Nets

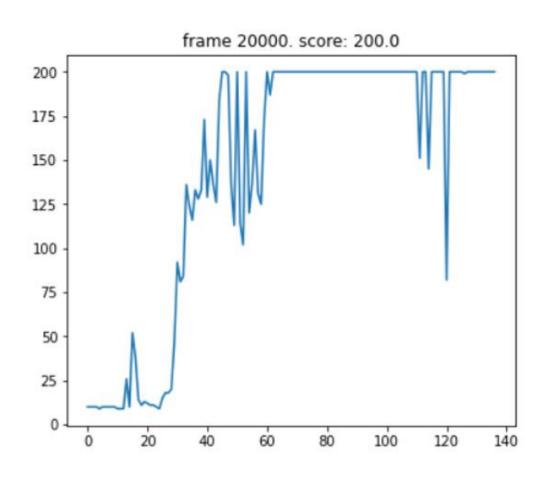
Rainbow Agent

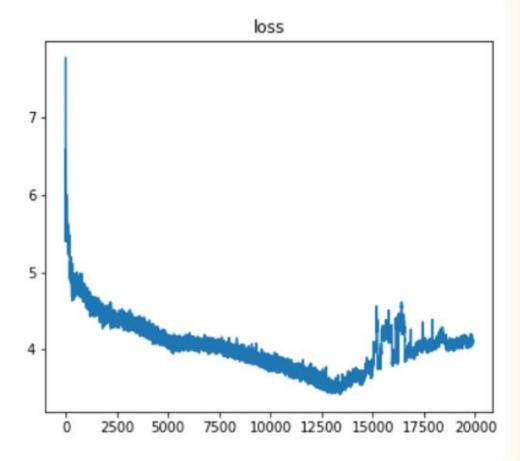
Method	Note
select_action	select an action from the input state.
step	take an action and return the response of the env.
compute_dqn_loss	return dqn loss.
update_model	update the model by gradient descent.
target_hard_update	hard update from the local model to the target model.
train	train the agent during num_frames.
test	test the agent (1 episode).
plot	plot the training progresses.

Training



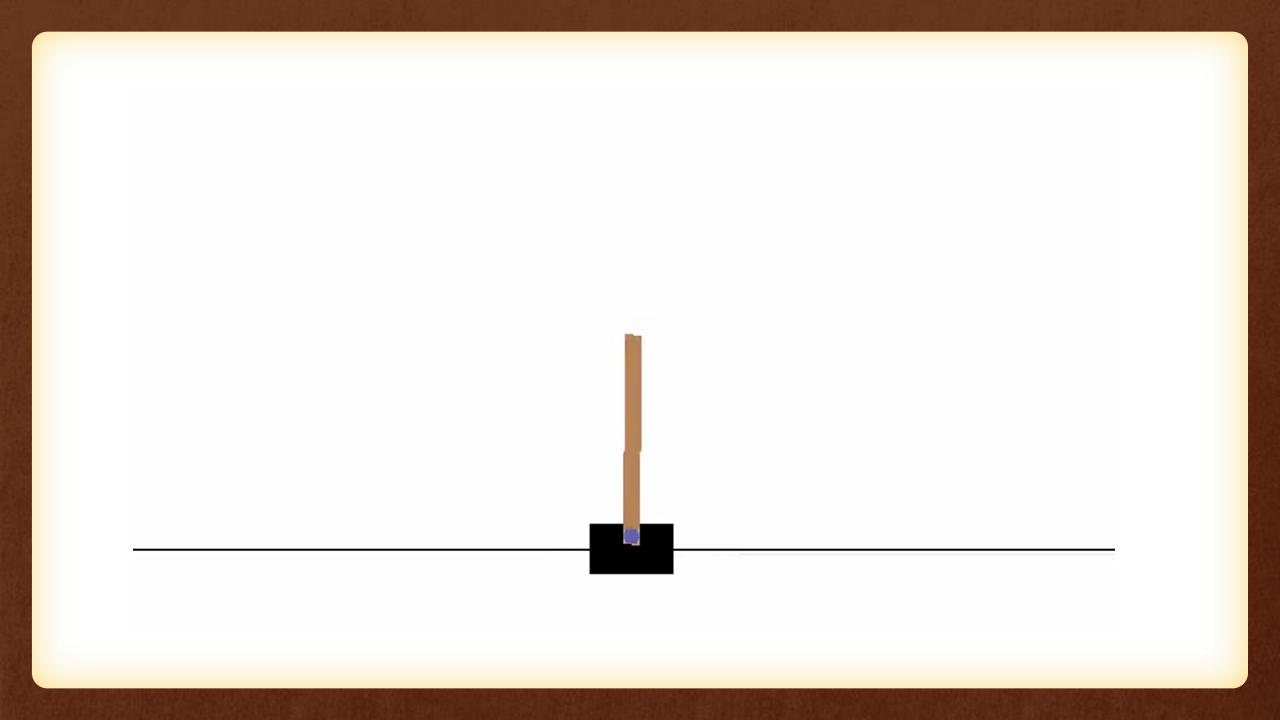
Results





Conclusion

- The model is able to reach a score of 200 with a minimal training time of 5 minutes. We selected a small sample of training to demonstrate in the project and showed the model after training during this period.
- Thus in this project we have applied and demonstrated the efficiency of the Rainbow method of Reinforcement Learning and used it for solving the cartpole problem.
- The final video and performance of model can be seen in next slide and is attached as a part of the submission.



References

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