



Introduction to PSOC for Arduino and Motor Control

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AGENDA

01 Motor Control

02 What is PSOC?

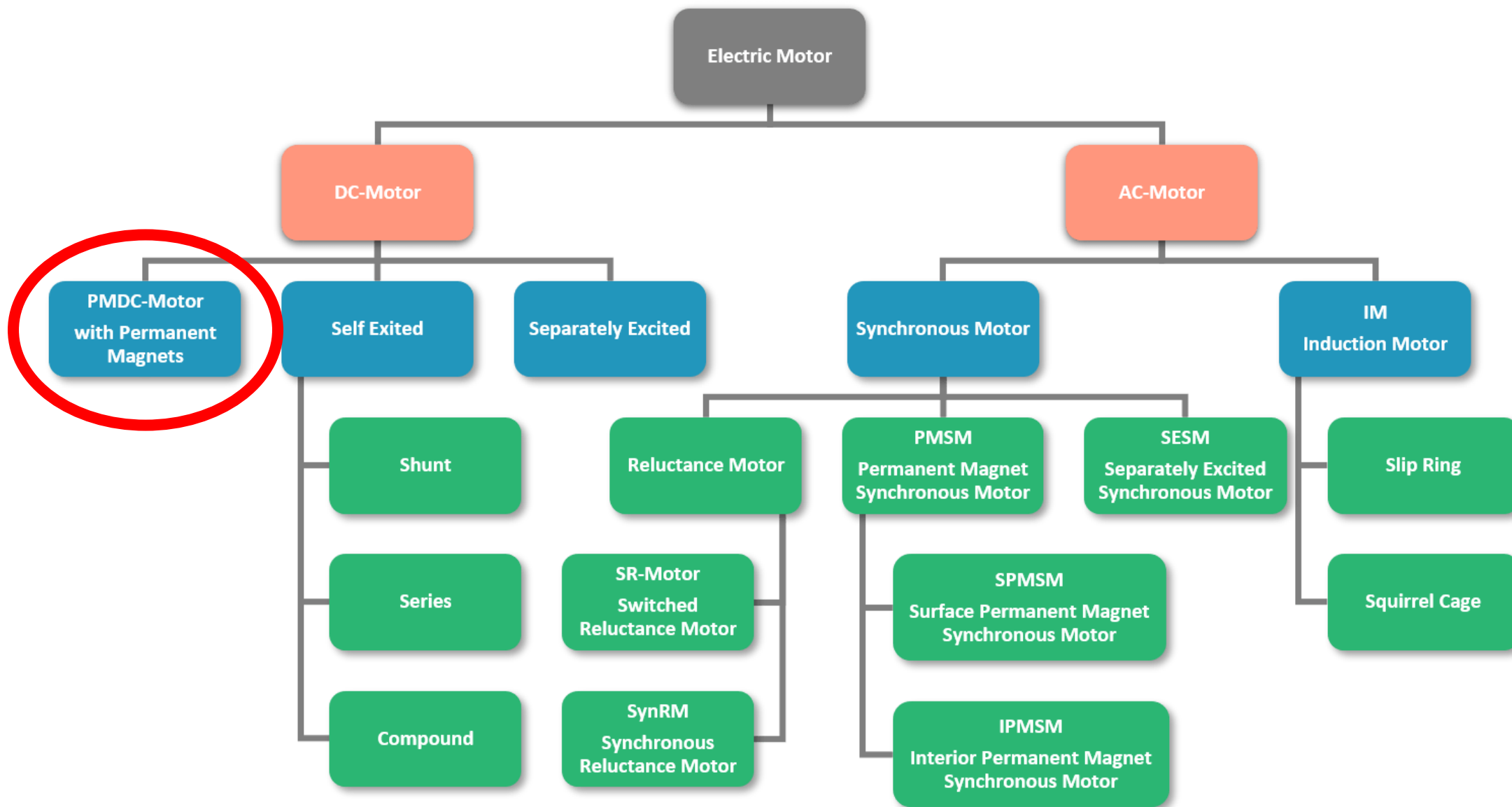


03 Why PSOC4 Arduino?

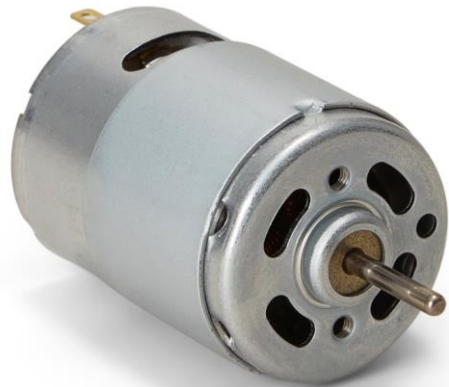
04 Installation



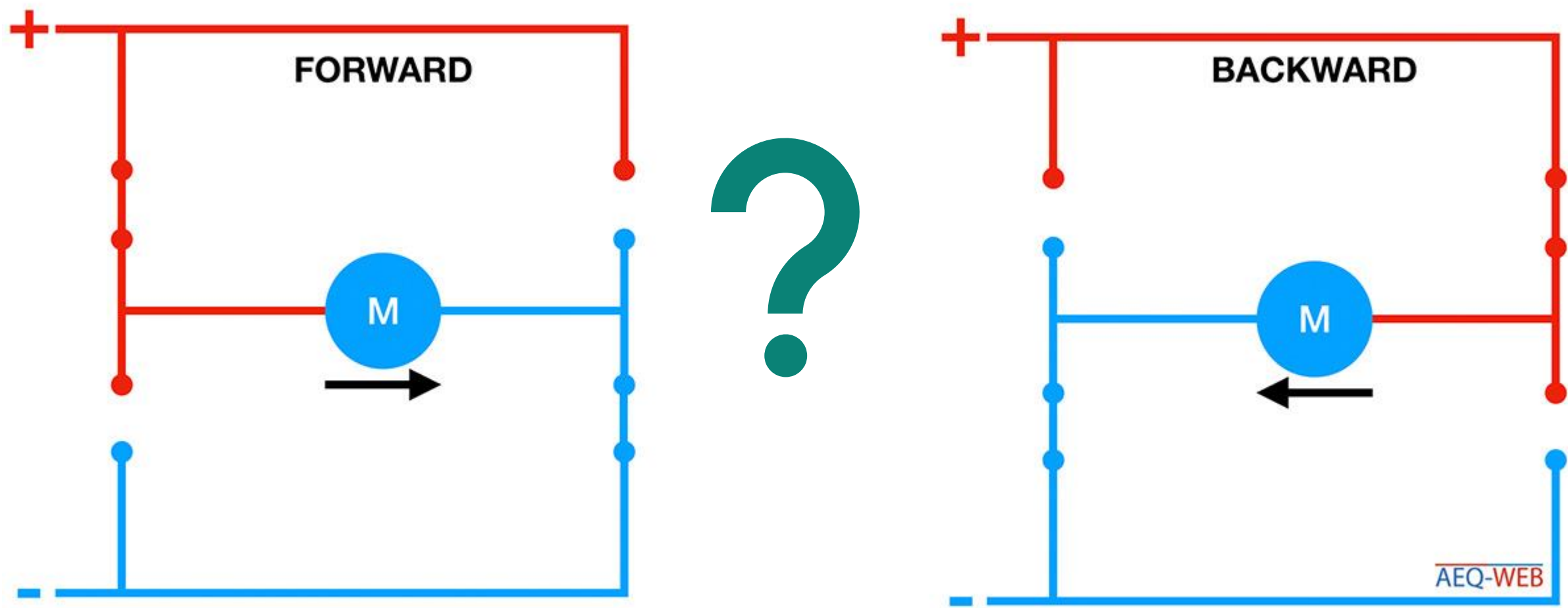
Motor Control



Motor Control



Motor Control



AEQ-WEB

Motor Control

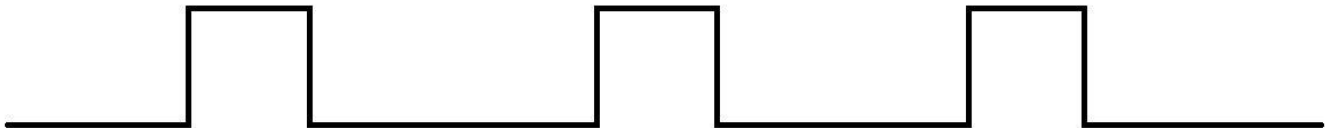
50% Duty Cycle



75% Duty Cycle



25% Duty Cycle



What is PSOC

- PSOC = Programmable System on Chip
- Microcontroller
- Functions:
- PWM
- ADC
- communication protocols (UART, CAN, SPI, I2C)



Why PSOC for Arduino?

Arduino ecosystem = simple, popular, numerous libraries

PSOC = powerful, flexible

Through integration, you can:

- Still develop easily in Arduino style

- Benefit from existing Arduino code

- Big community

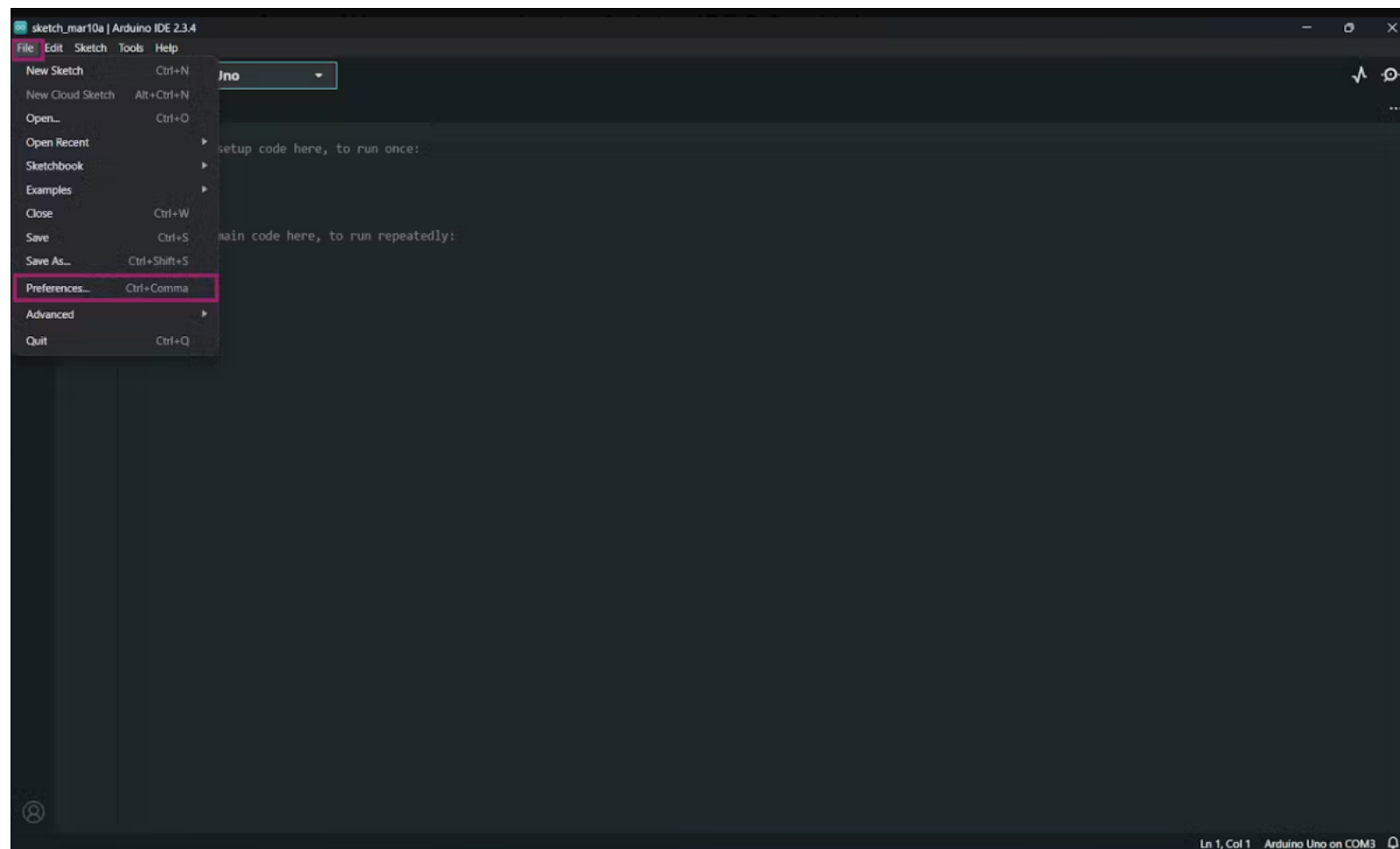


Installation

<https://github.com/infineon/hackathon>

Installation

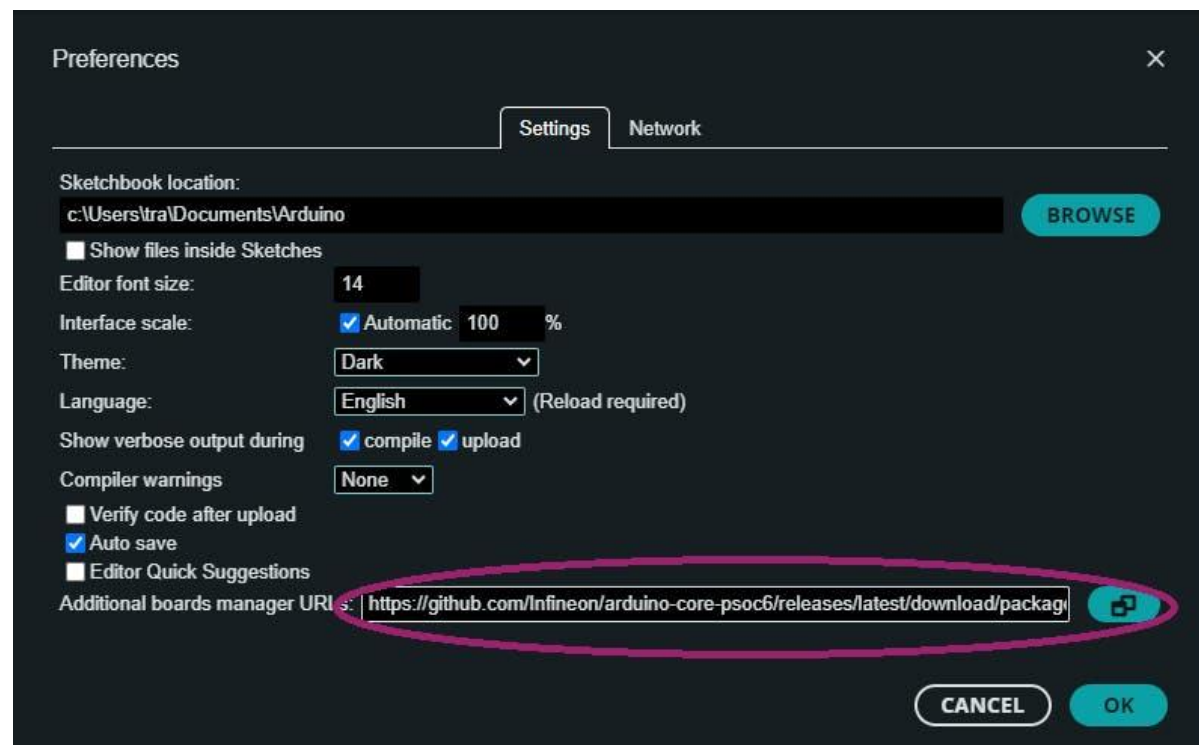
- 1. Download Arduino
- <https://www.arduino.cc/en/software/>
- Open Arduino
 - File → Preferences



Installation

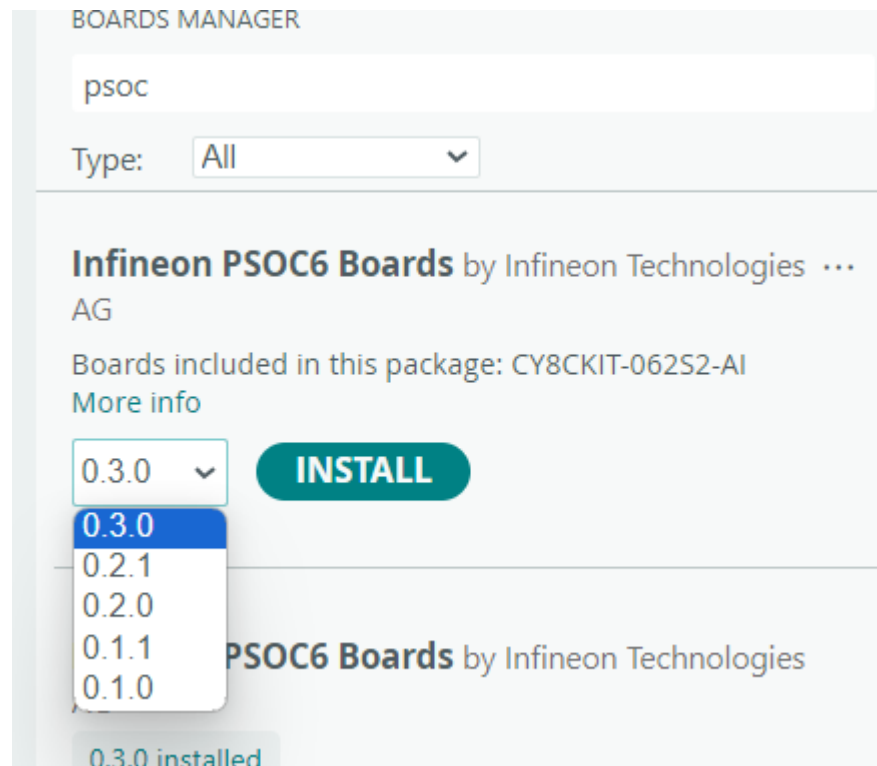
– Insert Link

https://github.com/Infineon/arduino-core-psoc6/releases/latest/download/package_psoc6_index.json



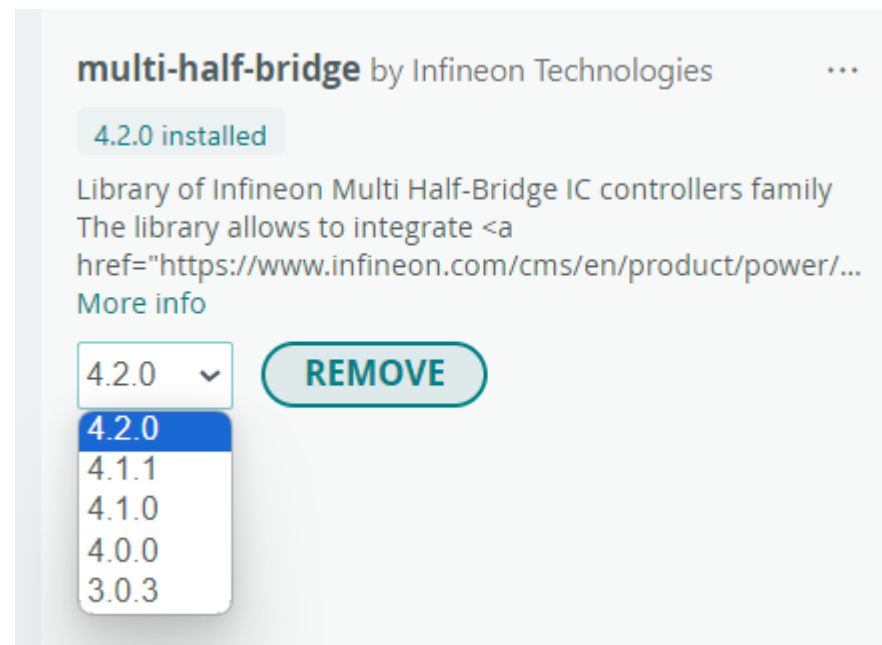
Installation

- Select the right version
- Version 0.3.0



Installation

- Libraries:
 - Multi-half-bridge (4.2.0)
- Arduino_BMI270_BMM150.h (1.2.1)
with [ZIP file](#)



Installation

Maybe you need it later



