



PSOC™ digital peripherals

Customer training workshop (CTW)

October 2025



Pre-requisites

- Install or update the following on your PC:
 - ModusToolbox™ Tools Package v3.5.0
 - ModusToolbox™ Eclipse IDE 3.5
 - ModusToolbox™ Programming Tools 1.4

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6	PSOC™ watchdog timer (WDT)	36

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PSOC™ project creation

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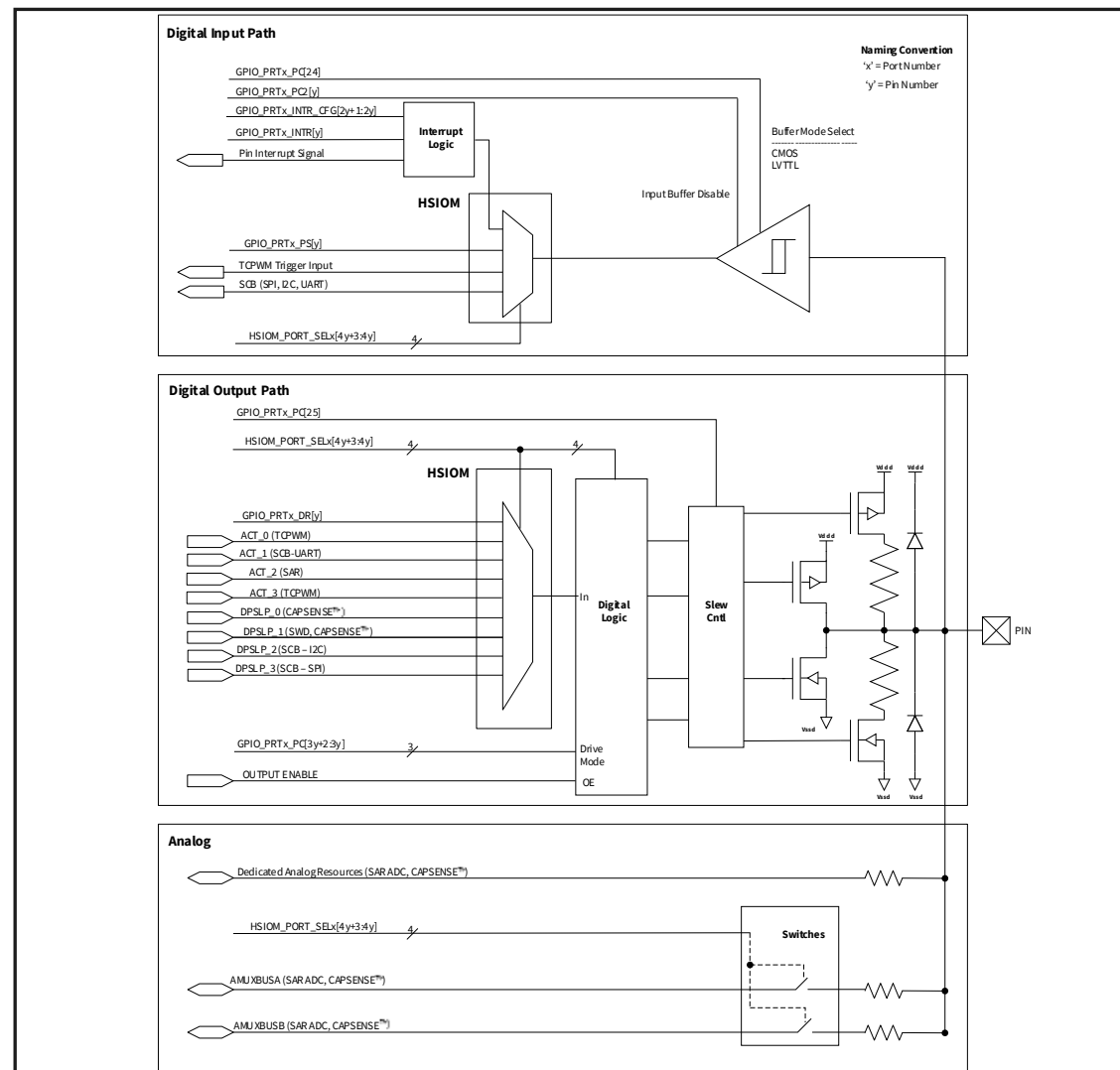
PSOC™ general-purpose I/O (GPIO) control

PSOC™ GPIO control lab agenda

- Configure a PSOC™ GPIO as a strong drive output for LED control using ModusToolbox™ and PDL APIs
- Configure a PSOC™ GPIO as a strong drive output for LED control using only PDL APIs
- Configure a PSOC™ GPIO as an input for reading the status of a user button using ModusToolbox™ and PDL APIs
- Configure a PSOC™ GPIO as an interrupt source using ModusToolbox™ and PDL APIs

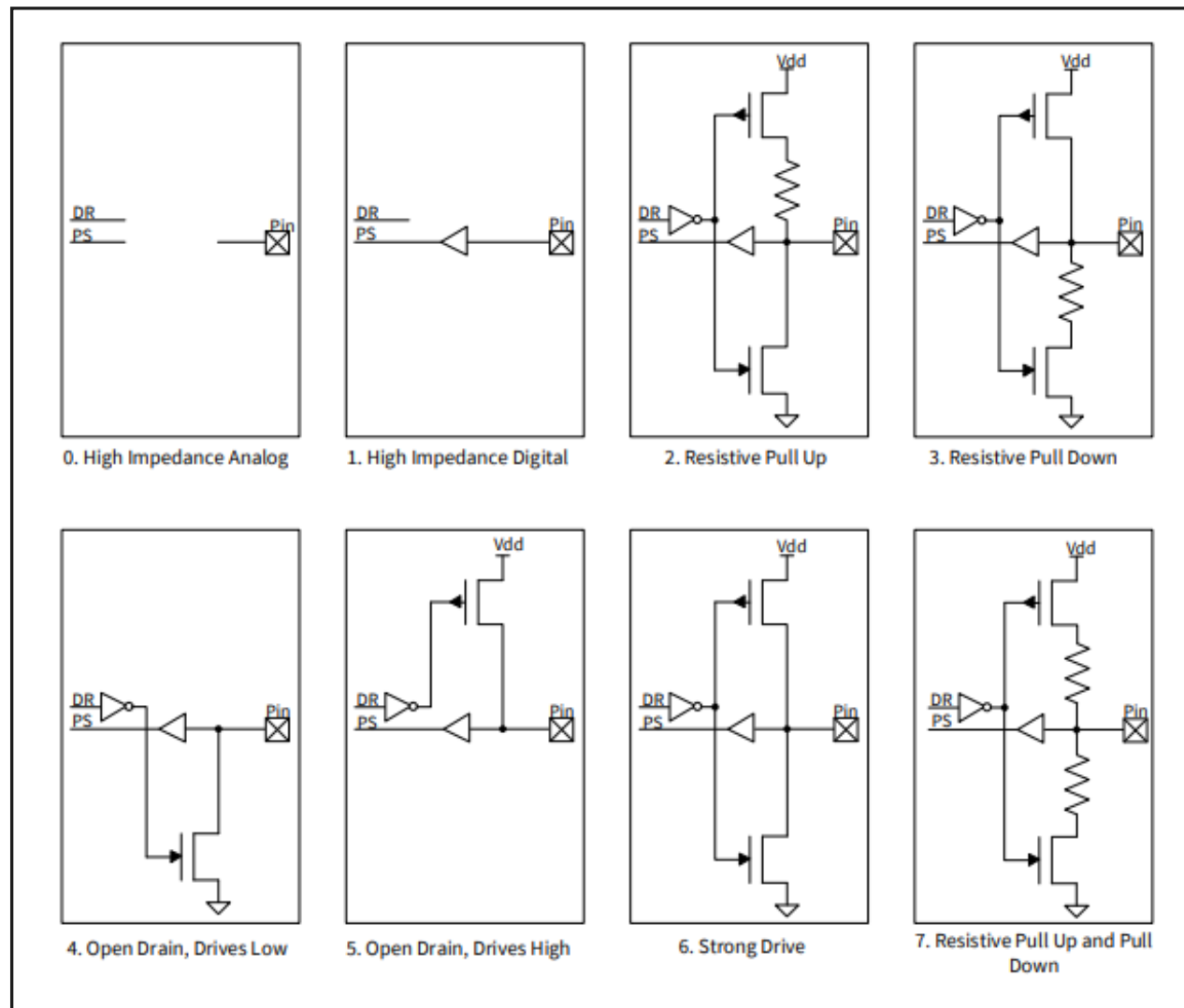
PSOC™ general purpose I/O (GPIO) block diagram

- Digital input path
 - Buffer mode select
 - Input buffer disable
 - High-speed IO matrix (HSIOM)
 - Interrupt logic
- Digital output path
 - Drive mode
 - Slew control
 - Output enable
 - HSIOM
- Analog path
 - Dedicated analog resources
 - HSIOM
 - Analog Mux (AMUX)



PSOC™ general purpose I/O (GPIO)

- Drive modes
 - High impedance (High-Z) analog
 - High impedance (High-Z) digital
 - Resistive pull-up, pull-down, pull-up, and pull-down
 - Open-drain, drives low or drives high
 - Strong drive
- Input buffer mode
 - CMOS
 - LVTTTL
- Slew rate



Considerations when using GPIOs as inputs and interrupts

- Driving circuit
 - **Strong drive**: configure input as a digital high-Z input
 - **Open-drain**: configure input as a resistive pull-up/down based on circuit polarity
 - **TTL compliance**: adjust input thresholds as needed
- Switch bounce
- Interrupt modes
 - Rising
 - Falling
 - Both
- Interrupt priority

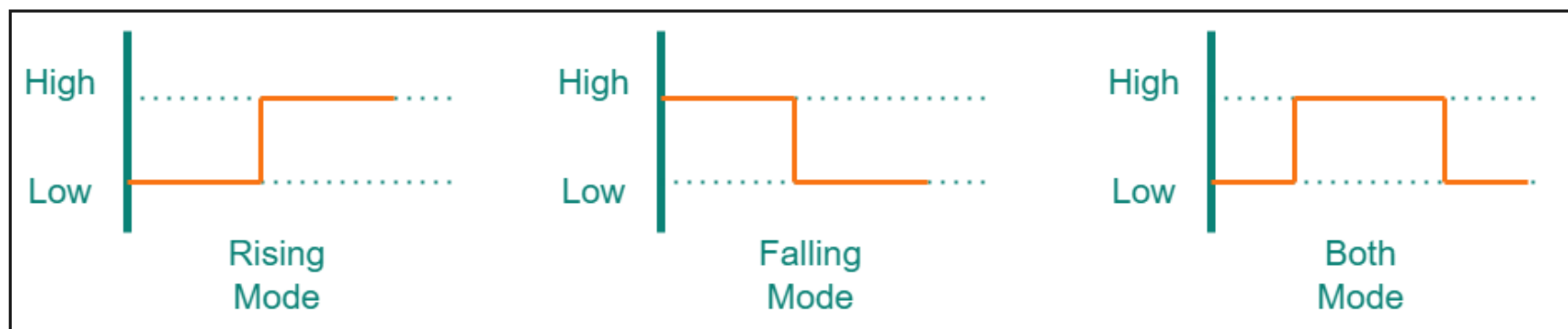
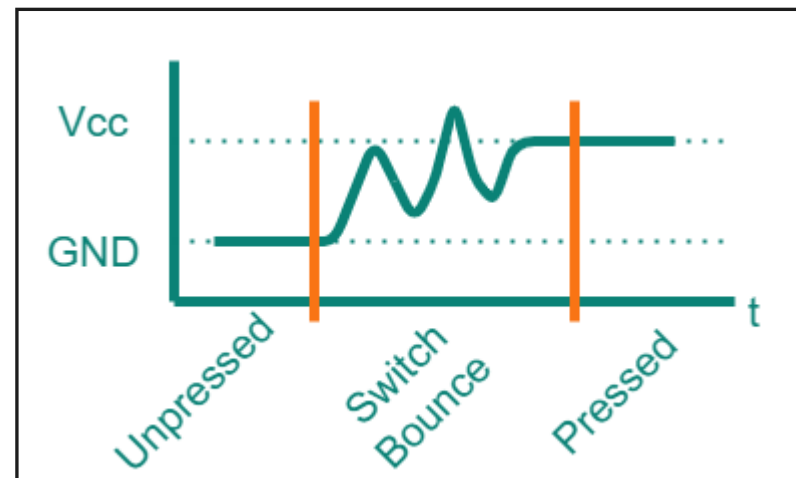


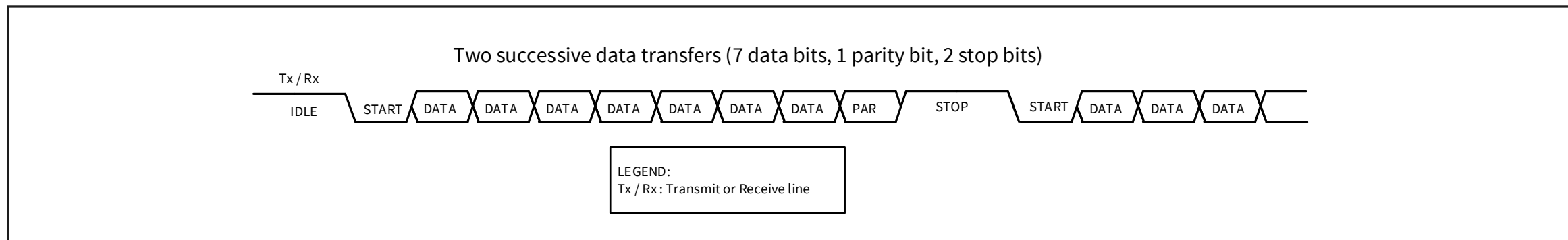
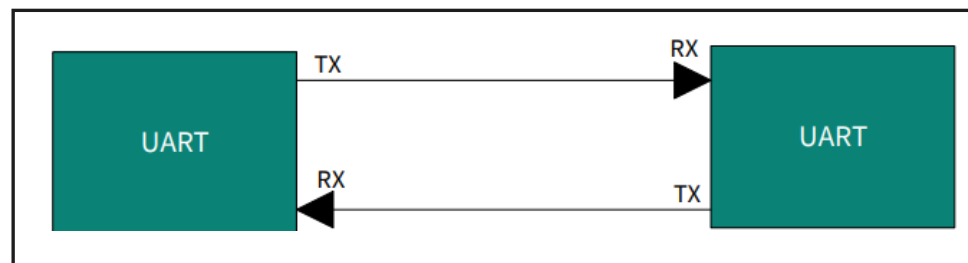
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PSOC™ serial communication blocks (SCB) with UART

PSOC™ serial communication block (SCB) with UART

- **Com mode:** Standard, Smartcard reader, IrDA, and LIN
- Configurable baud rate
- **Bit order:** MSB or LSB first
- **Parity:** Odd, even, none
- **Stop bits:** 1 to 3
- Advanced features like RS-485 support and flow control (RTS and CTS)



PSOC™ SCB UART lab agenda

- Configure a PSOC™ SCB for UART mode and send data using ModusToolbox™ and PDL APIs
- Use a PSOC™ SCB in UART mode to receive data with a polled method
- Use a PSOC™ SCB in UART mode to receive data with an interrupt method
- Enable standard C file printf using the retarget-IO library available in the ModusToolbox™ library manager

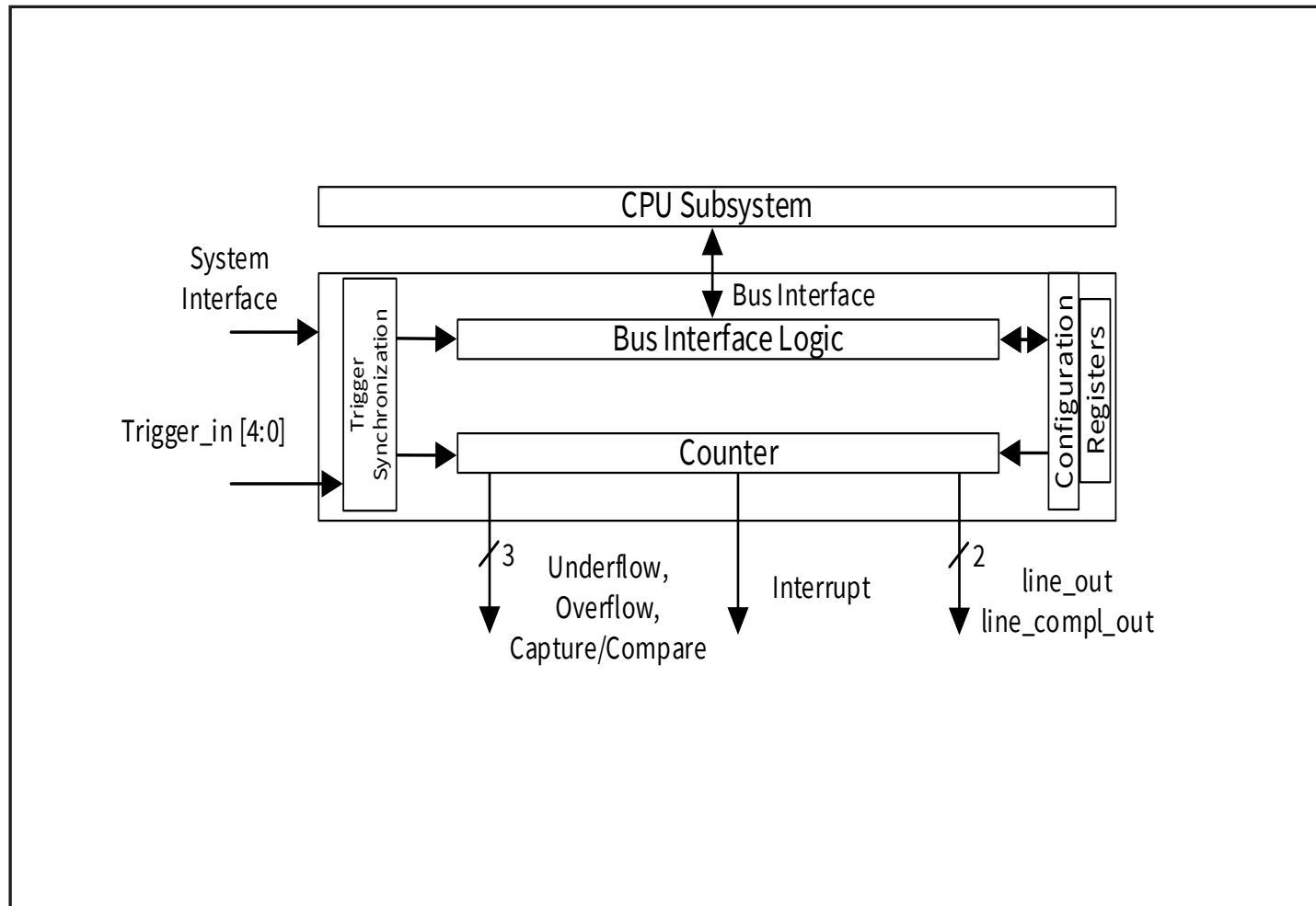
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PSOC™ Timer, Counter, PWM (TCPWM)

PSOC™ Timer, Counter, PWM (TCPWM)

- Operational modes
 - Timer-counter with compare
 - Timer-counter with capture
 - Quadrature decoding
 - Pulse width modulation
 - Pseudo-random PWM
 - PWM with dead time
- Up, down, and up/down counting modes
- Double buffering compare/capture and period values
- Underflow, overflow, and capture/compare output signals
- Interrupts on count and capture/compare

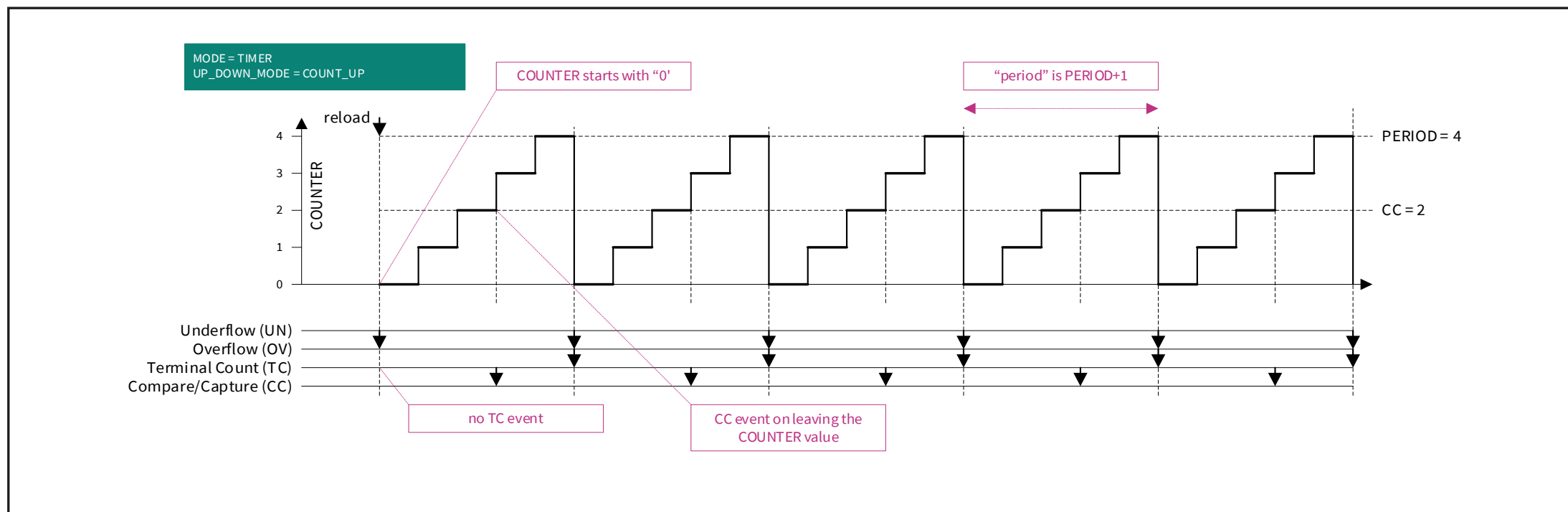


PSOC™ Timer, Counter, PWM (TCPWM) lab agenda

- Configure a PSOC™ TCPWM as a Timer using ModusToolbox™
- Configure a PSOC™ TCPWM for PWM output to control an LED using ModusToolbox™
- Configure a PSOC™ TCPWM as an event counter to keep track of the frequency of a signal using ModusToolbox™
- Configure a PSOC™ TCPWM as an input capture to keep track of the duty cycle of a signal using ModusToolbox™

PSOC™ timer counter

- Increments/decrements COUNTER from 0 to PERIOD
- COUNTER is compared with capture/compare (CC)



PSOC™ timer capture

- Increments/decrements COUNTER from 0 to PERIOD
- COUNT is copied to CC on PERIOD rollover; CC is copied to CC_BUFF on new Capture event

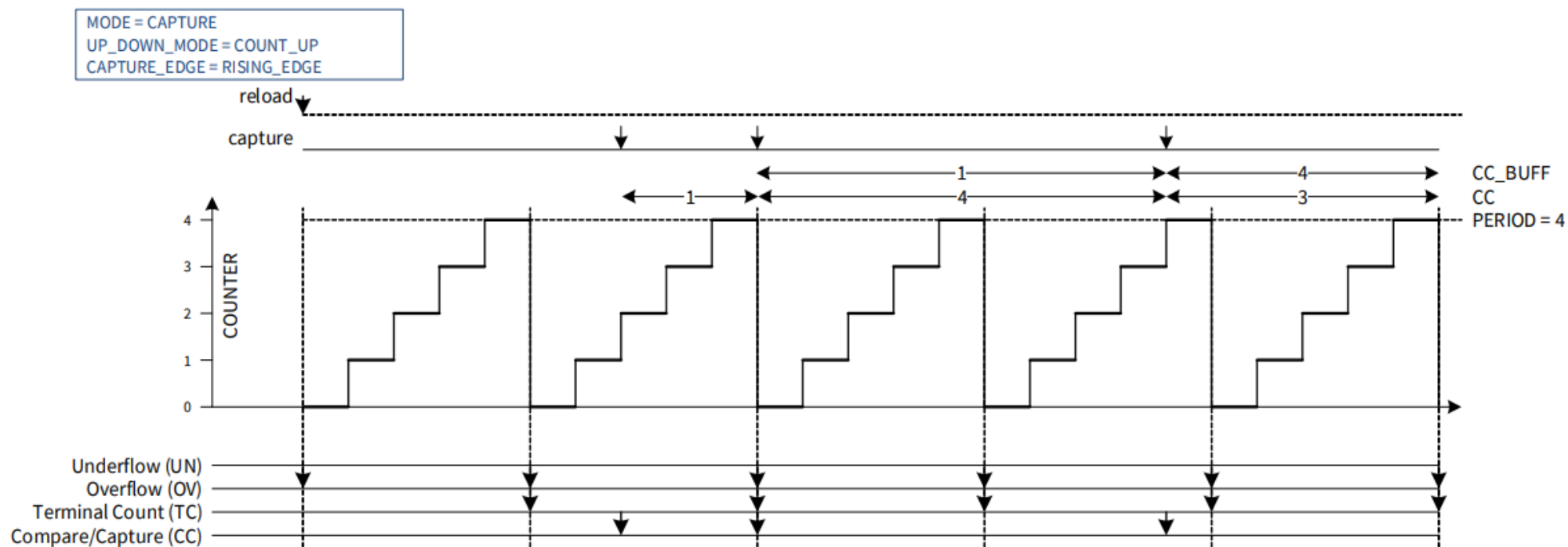


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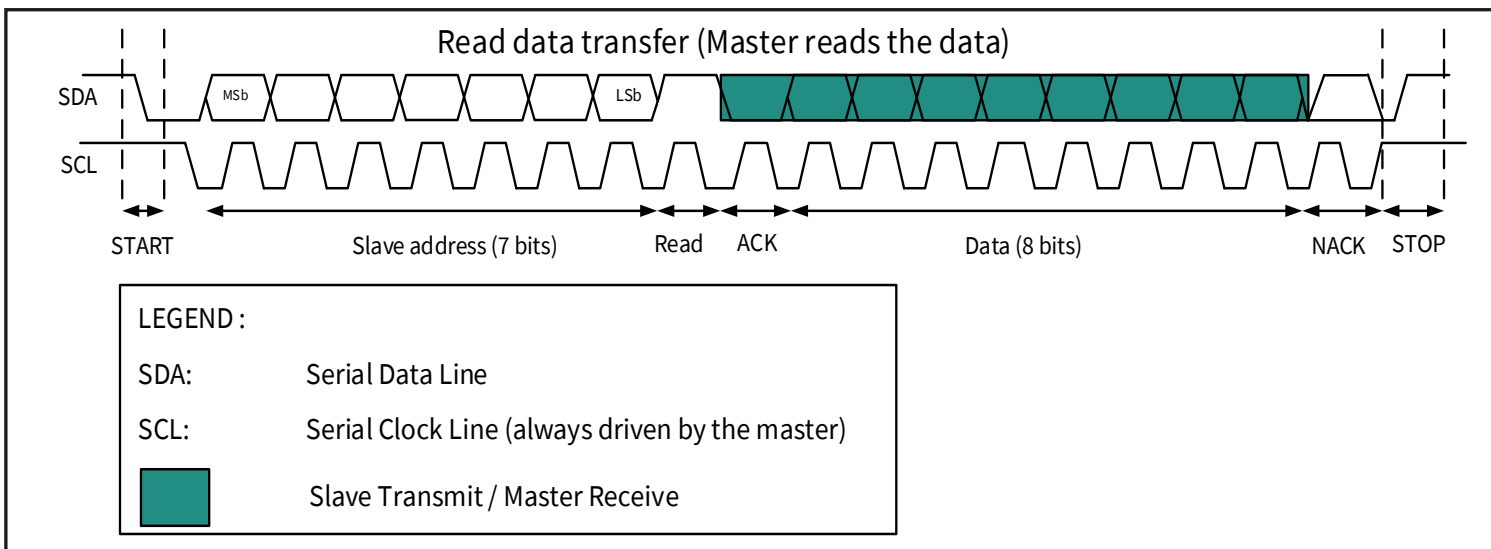
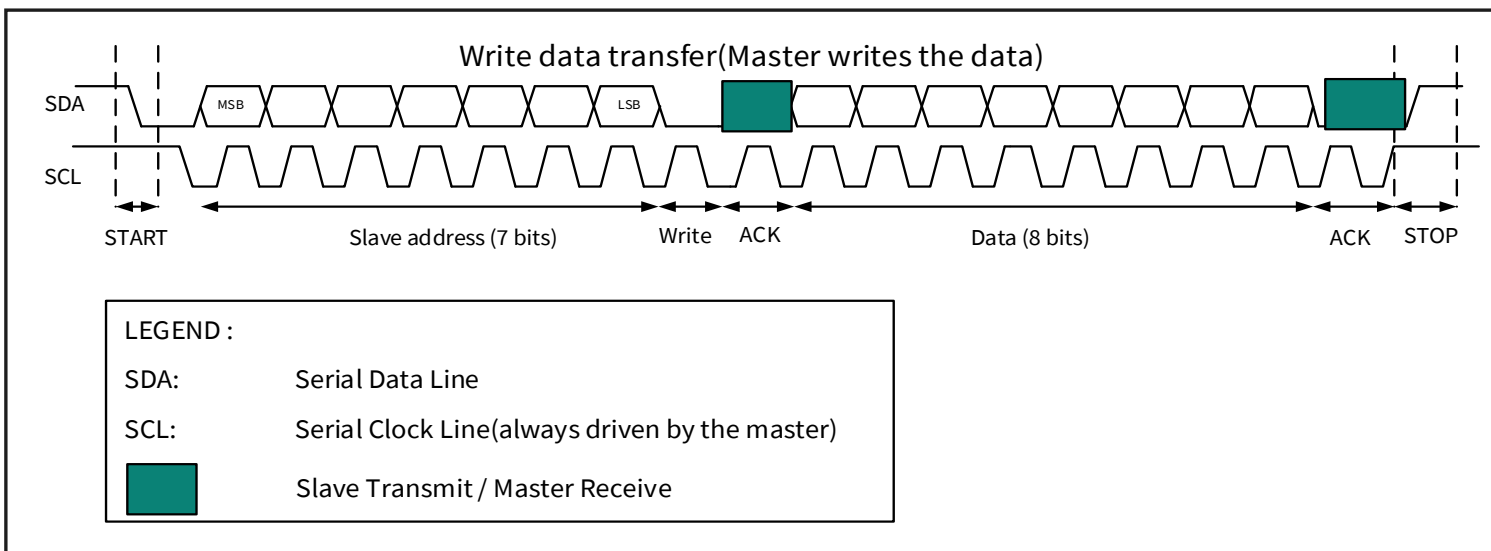
PSOC™ serial communication blocks (SCB) with EZI2C

PSOC™ SCB with EZI2C lab agenda

- Configure a PSOC™ SCB for I2C slave mode with the EZI2C driver using ModusToolbox™
 - Respond to an I2C master with static data
- Use a PSOC™ SCB for I2C slave mode to respond to an I2C master with up time data using the EZI2C driver
- Use a PSOC™ SCB for I2C slave mode to receive data from an I2C master to control an LED using the EZI2C driver

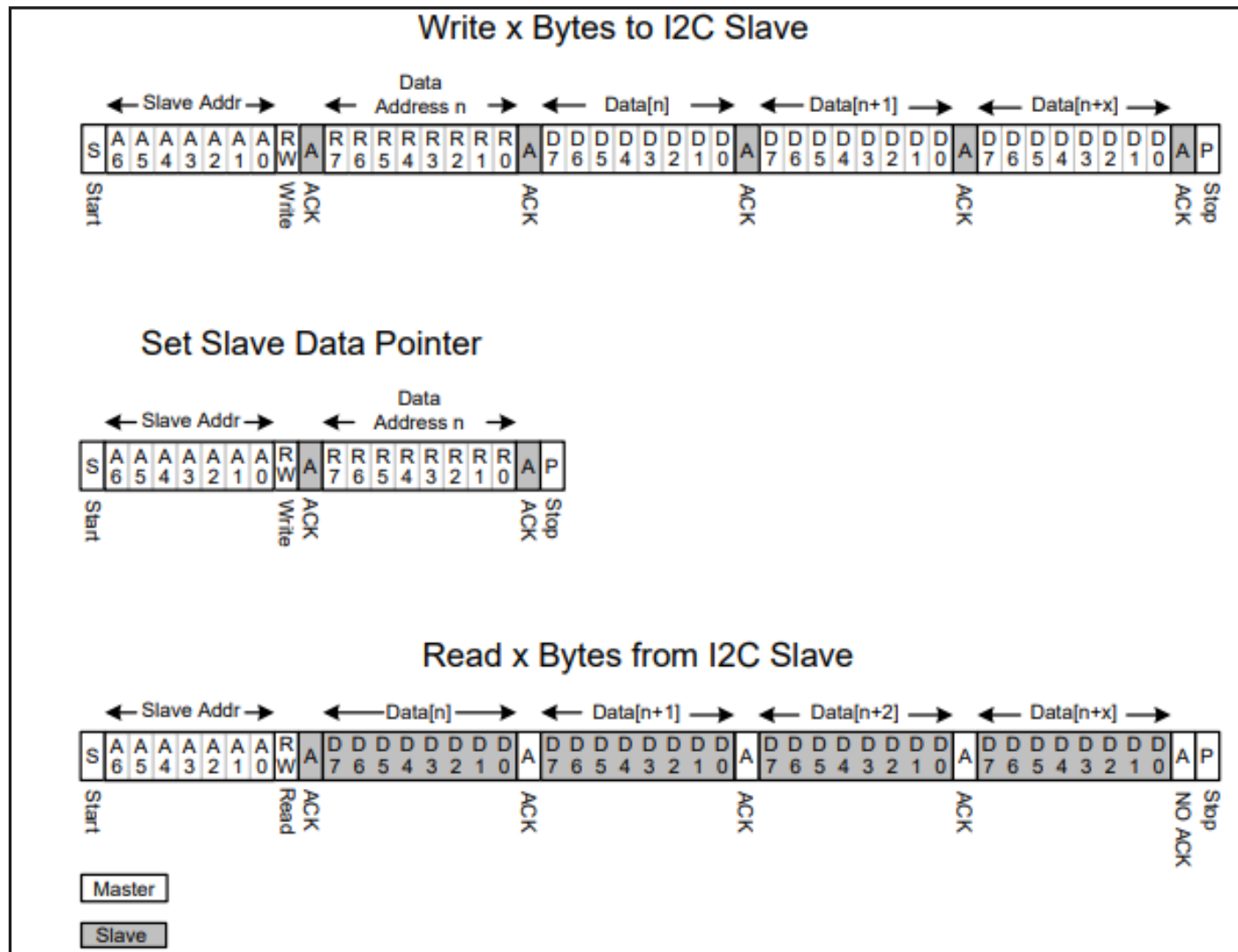
PSOC™ SCB with I2C

- Configurable I2C slave addresses
- Configurable baud rate
- Supports RX and TX interrupts
- Multi-Master bus arbitration is supported



PSOC™ with and the EZI2C software driver

- EZI2C enables a common EEPROM interface with 8- or 16-bit sub-address sizing
- Allows random access to a block of memory on the EZI2C slave



PSOC™ SCB configured for serial peripheral interface (SPI)

PSOC™ SCB with serial peripheral interface (SPI) lab agenda

- Configure a PSOC™ SCB for SPI master mode using ModusToolbox™
 - Using a second SCB for UART to print sent and received data
- Configure a PSOC™ SCB for SPI slave mode using ModusToolbox™
 - Using a second SCB for UART to print sent and received data

PSOC™ SCB with serial peripheral interface (SPI) and the high-level driver

- High configurability
 - Baud rate
 - Master or slave mode
 - Clock Polarity (CPOL) and Clock Phase (CPHA)
 - Multiple slave select lines (SS)
- Multiple SPI modes supported:
 - Motorola
 - Texas Instruments
 - National Semiconductor (half-duplex)

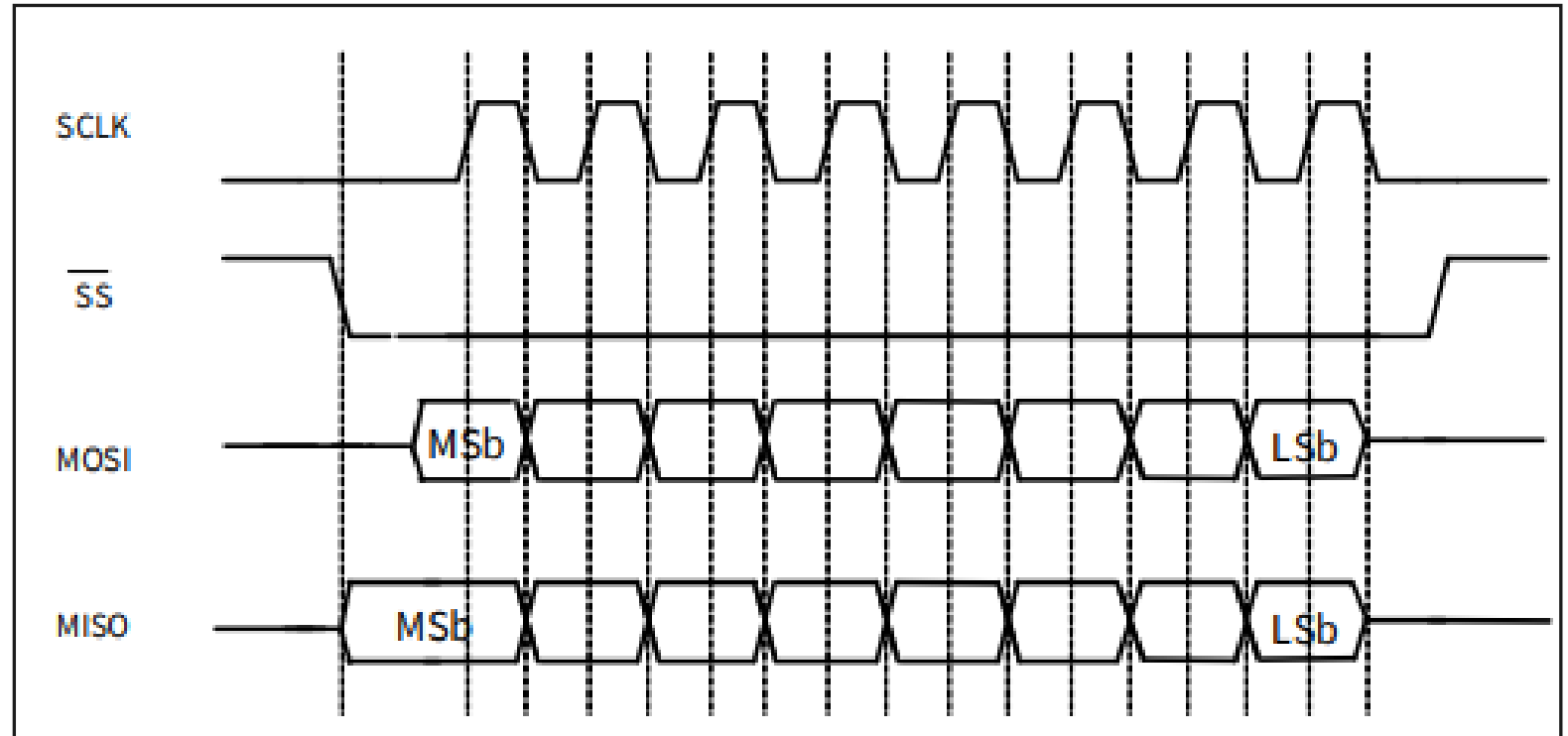


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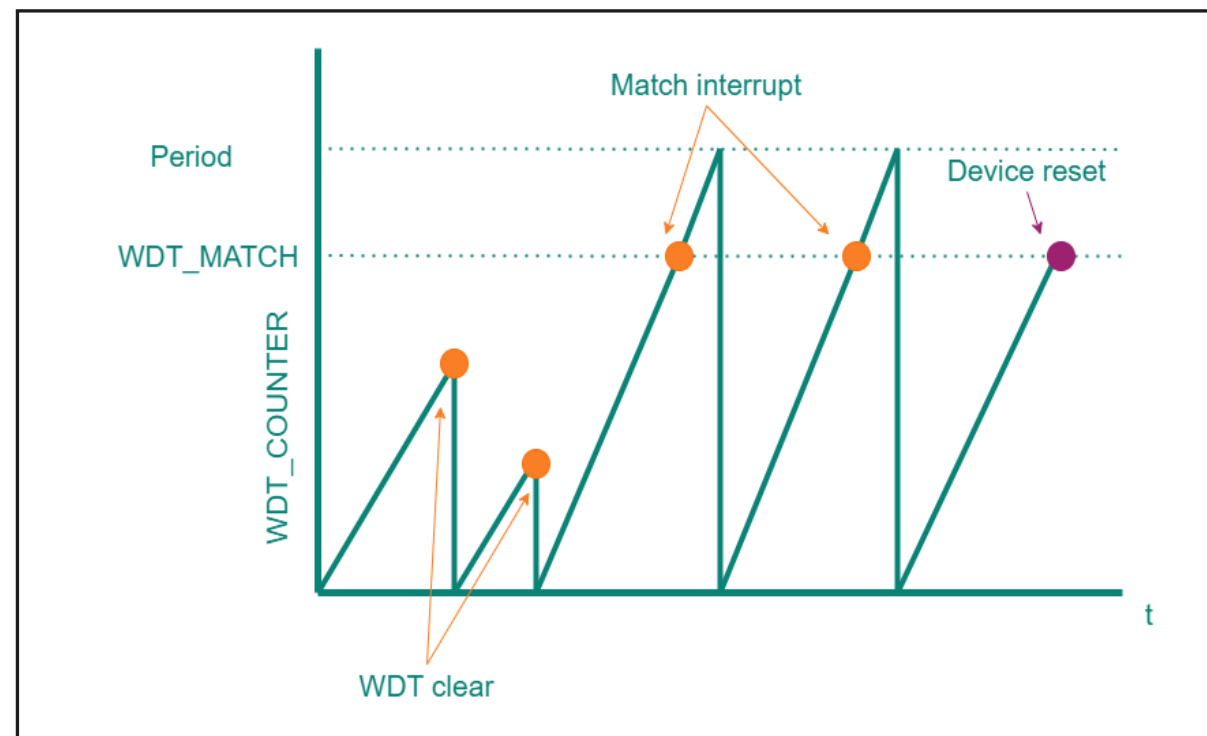
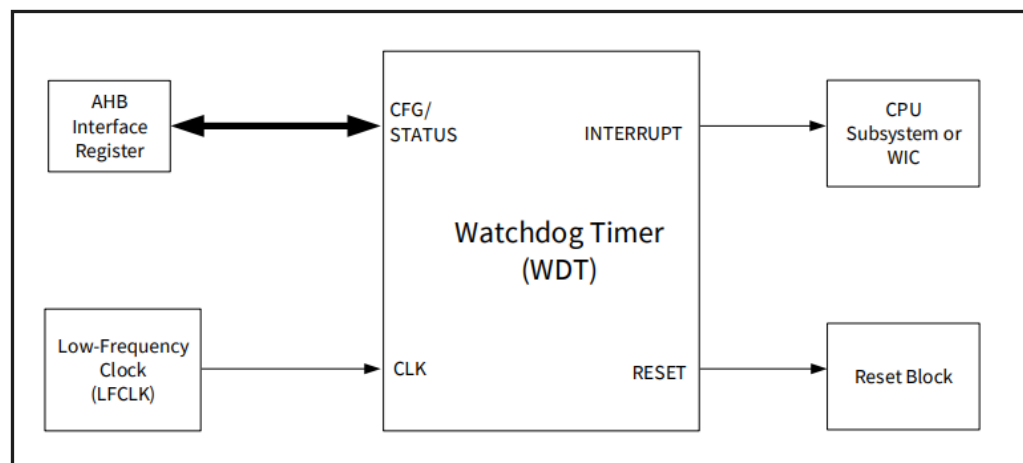
PSOC™ watchdog timer (WDT)

PSOC™ watchdog timer (WDT) lab agenda

- Configure a PSOC™ watchdog timer (WDT) to reset the MCU when the timer is not cleared
 - A button press will trigger an infinite while loop, mimicking a software fault

PSOC™ watchdog timer (WDT)

- Supports interrupt and system reset on timer expiration
- Sourced from LFCLK to support operation in hibernate mode
- The WDT asserts a system reset to the device on the third WDT match event, unless it is periodically serviced in firmware



Revision history

Document revision	Date	Description of change
**	2025-10-31	New spec.



Thank you! Stay tuned for more trainings...

Join with us on our mission to drive decarbonization and digitalization Together.



