

Chapter 1: Introduction

After completing this chapter, you will understand what this class is, what topics are covered, and the overall class objectives. You will also understand the programmer provided on the development kit and how to update its firmware.

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Document conventions

Convention	Usage	Example
Courier New	Displays code and text commands	CY_ISR_PROTO(MyISR) ; make build
<i>Italics</i>	Displays file names and paths	sourcefile.hex
[bracketed, bold]	Displays keyboard commands in procedures	[Enter] or [Ctrl] [C]
Menu > Selection	Represents menu paths	File > New Project > Clone
Bold	Displays GUI commands, menu paths and selections, and icon names in procedures	Click the Debugger icon, and then click Next .

1.1 What is this class?

This class is an in-depth look into the AIROC™ Bluetooth® SDK (BTSDK) MCU families. We introduce you to the basic operation of the MCU devices and familiarize you with their development flow within the ModusToolbox™ ecosystem. This enables you to create your own applications for devices in the AIROC™ Bluetooth® SDK (BTSDK) MCU families.

This is a "Level 2" class, meaning that it is intended as a detailed look into a specific product. This class is part of a series of classes that also include these other levels:

- Level 1 classes are an entry point into a particular topic and cover a broad range of topics at a shallow depth.
- Level 3 classes dig even deeper by looking at complete solutions such as Bluetooth®, Wi-Fi, Motor Control, or Machine Learning.

This class will cover application structure, using MCU peripherals, using an RTOS, and general low power operation. Bluetooth® operation is NOT covered in this class but once you understand the basics of using AIROC™ Bluetooth® SDK (BTSDK) MCUs, you will be able to follow along with a Level 3 class that covers Bluetooth® in detail.

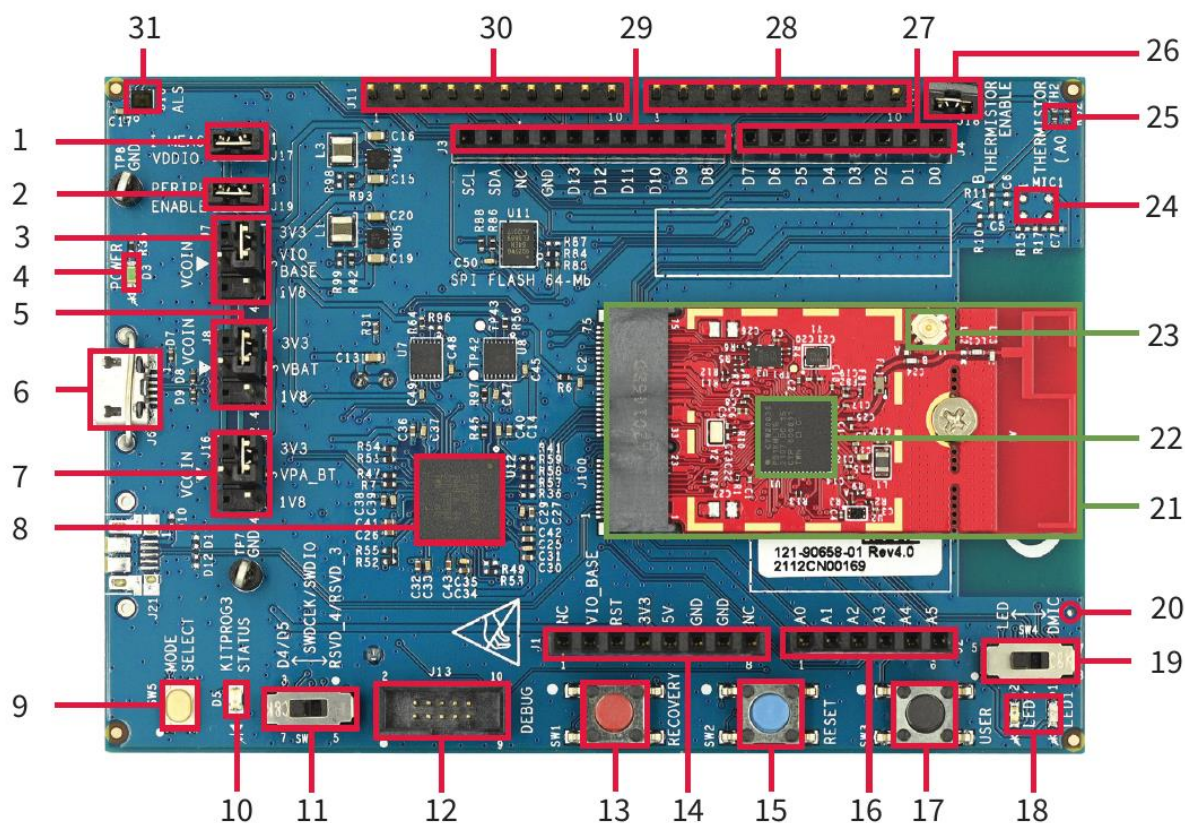
1.2 Prerequisites

- ModusToolbox™ Software Training Level 1 - Getting Started

This class will not cover what ModusToolbox™ software is, what tools it includes, or how to use any of its features. If you are unfamiliar with ModusToolbox™ software, you should take the "ModusToolbox™ Software Training Level 1 - Getting Started" class before embarking on this class.

1.3 Development kit

For this class we will use the CYW920835M2EVB-01 development kit.



- | | |
|------------------------------------------------|------------------------------------------------------------------------|
| 1. VDDIO current measurement jumper (J17) | 17. User button (SW3) |
| 2. Peripheral enable jumper (J19) | 18. User LEDs (D1, D2) |
| 3. VDDIO select jumper (J7) | 19. User LED/DMIC switch (SW4) |
| 4. Baseboard power status LED (D3) | 20. Digital mic sound port (J16) |
| 5. VBAT select jumper (J8) | 21. CYW920835M2IPA1 Bluetooth® M.2 radio card |
| 6. USB connector for programming/USB-UART (J6) | 22. AIROC™ CYW20835 Bluetooth® LE system-on-chip (CYW920835M2IPA1.U1A) |
| 7. VPA select jumper (J16) | 23. External antenna connector (CYW920835M2IPA1.J1) |
| 8. KitProg3 based on PSoC™ 5LP MCU (U12) | 24. Analog mic footprint (MIC1) |
| 9. KitProg3 mode select (SW5) | 25. Thermistor (TH2) |
| 10. KitProg3 status LED (D5) | 26. Thermistor enable jumper (J18) |
| 11. Debug interface select jumper (SW8) | 27. Header compatible with Arduino (J4) |
| 12. Debug header (J13) | 28. Bluetooth® I/O header (J12) |
| 13. Recovery button (SW1) | 29. Header compatible with Arduino (J3) |
| 14. Header compatible with Arduino (J1) | 30. Bluetooth® I/O header (J11) |
| 15. Reset button (SW2) | 31. Ambient light sensor (U10) |
| 16. Header compatible with Arduino (J2) | |

1.4 Introduction to AIROC™ Bluetooth® SDK (BTSDK) MCUs

AIROC™ Bluetooth® SDK (BTSDK) MCUs provide a single chip solution for all of your Bluetooth® application needs. These devices support Bluetooth® Low Energy, and in some cases Bluetooth® classic and Bluetooth® mesh.

The complete family of devices can be found at:

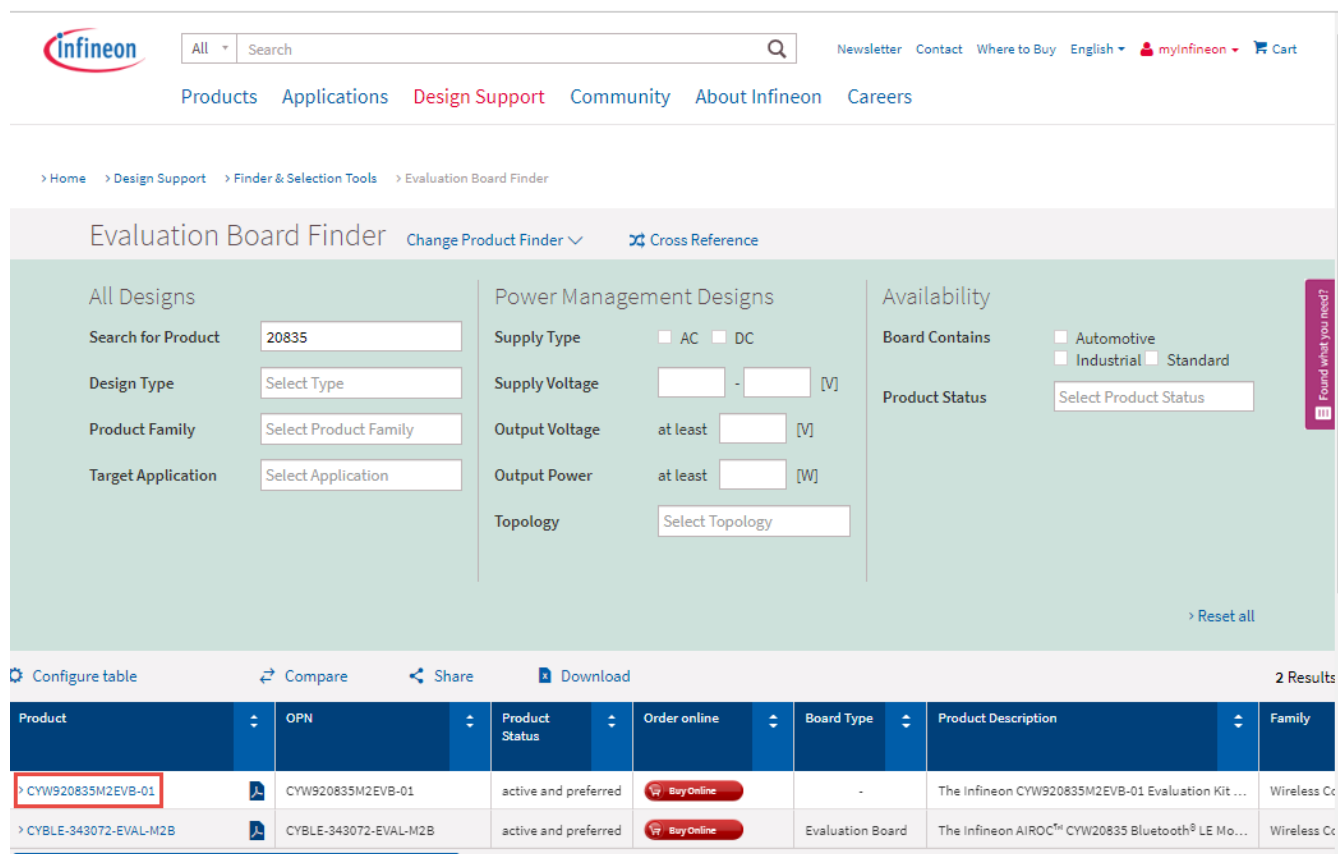
<https://www.infineon.com/cms/en/product/wireless-connectivity/airoc-bluetooth-le-bluetooth-multiprotocol/>

1.4.1 Development kits and Evaluation boards

Many development kits are available for these devices. To find the list of kits, visit:

<https://www.infineon.com/cms/en/design-support/finder-selection-tools/product-finder/evaluation-board/>

Enter the device part number (or a subset of it) in the "Search for Product" field to see a list of available kits. For example, you can enter "20835":



The screenshot shows the Infineon website's Evaluation Board Finder tool. The search results are as follows:

Product	OPN	Product Status	Order online	Board Type	Product Description	Family
CYW920835M2EVB-01	CYW920835M2EVB-01	active and preferred	Buy Online	-	The Infineon CYW920835M2EVB-01 Evaluation Kit ...	Wireless Cc
CYBLE-343072-EVAL-M2B	CYBLE-343072-EVAL-M2B	active and preferred	Buy Online	Evaluation Board	The Infineon AIROC™ CYW20835 Bluetooth® LE Mo...	Wireless Cc

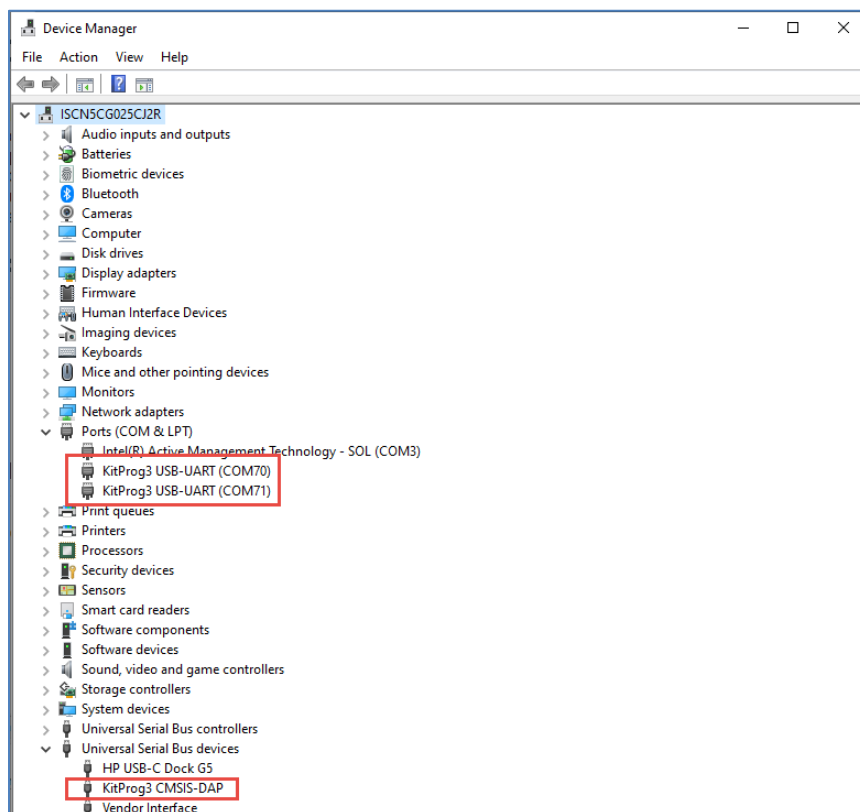
1.5 Infineon Kit Programmer/USB Bridge

The kit we are using has a PSoC™ 5LP chip on it that is used as a programmer and USB bridge. It provides the capability for your computer's USB to connect to the target device using multiple protocols such as Serial Wire Debug (SWD), UART, and I²C. The host application on your computer needs to talk to the programmer to download firmware into the flash and to debug the MCU.

There are a bunch of different protocols out there for debugging MCUs. However, a few years ago Arm developed a standard called CMSIS-DAP, which has two variants (Bulk and DAPLink).

The programmer will appear to your computer to be multiple USB endpoints that implement each of the functions described in the previous paragraphs. In the case of the kit we are using, the programmer will appear as three USB endpoints: one CMSIS-DAP Bulk endpoint, and two UART endpoints. One of the UART endpoints is used mainly for programming (called the HCI UART) while the other is used for printing messages to a serial terminal emulator window (called the Peripheral UART or PUART).

On a Windows PC, you can see these in the Device Manager:



1.5.1 Recovery Mode

Sometimes when attempting to program the device, the programmer will be unable to put the MCU into the correct mode to transfer the new target device firmware over the programming UART. In order to force the device into programming mode, use the following steps:

1. Press and hold the **RECOVERY** button on the board.
2. Press and then release the **RESET** button on the board.
3. Release the **RECOVERY** button.

1.6 Firmware Loader

Firmware loader (fw-loader) is a tool that we deliver as part of ModusToolbox™ software. It is a command-line tool that allows you to install new KitProg firmware onto a PSoC™ kit, and switch modes programmatically.

You can find it in the following directory:

```
<install_dir>/ModusToolbox/tools_<version>/fw-loader/bin
```

It is also available independently on GitHub at <http://github.com/infineon/firmware-loader>.

The following table shows some of the basic fw-loader commands:

Command	Description
fw-loader --help (or no argument)	Print out help information.
fw-loader --device-list	List all the KitProg devices attached to your computer.
fw-loader --update-kp3	Install the latest firmware onto your KitProg.
fw-loader --mode kp3-daplink	Put the KitProg into DAPLink CMSIS-DAP mode.
fw-loader --mode kp3-bulk	Put the KitProg into CMSIS-DAP Bulk mode.
fw-loader --mode kp3-hid	Put the KitProg into CMSIS-DAP HID mode (not typically used).
fw-loader --mode kp3-bootloader	Put the KitProg into bootloader mode (not typically used).

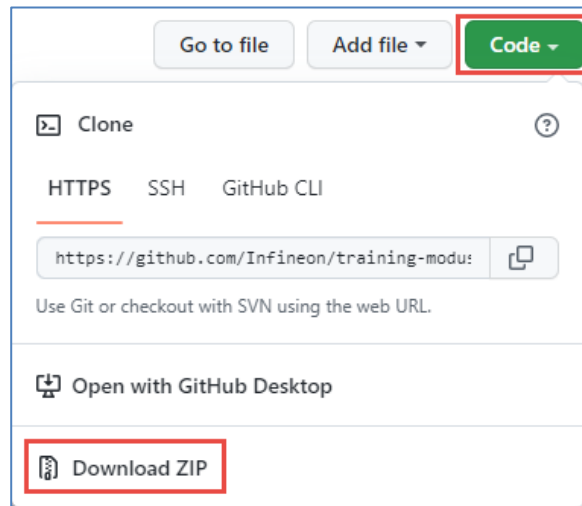
You will practice using this tool in exercise 2.

1.7 Exercises

Exercise 1: Download Class Material

In this exercise, you will download the class material from GitHub. This will give you local access to the manuals and projects.

- ☐ 1. Use a Web browser to go to the class GitHub site at: <https://github.com/Infineon/training-modustoolbox-level2-btsdk>
- ☐ 2. Click the Code button.



- ☐ 3. Click the Download ZIP button to download the repo to your local disk to a convenient location and then unzip it.

Note: If you are familiar with Git operations, you can clone the repository to your local disk using the URL instead of downloading a ZIP file if you prefer.

Exercise 2: Look at kit documentation



4. Visit the websites for the kit used in this class and familiarize yourself with the kit documentation.

Exercise 3: Update Programmer firmware

Your kit may have an older version of the programmer firmware. In this exercise we will determine what version your kit has and update it if necessary.



1. Connect your kit to your computer using the provided USB cable. If your kit has multiple USB connectors, be sure to connect to the one labeled KITPROG.



2. Run a command line terminal.

Windows: run `modus-shell` from the **Start** menu or enter `modus-shell` in the Windows search box.
MacOS or Linux: start a standard command terminal



3. Navigate to the directory `<install_dir>/ModusToolbox/tools_<version>/fw-loader/bin`

Note: On Windows, steps 2 and 3 can be done together by either running `fw-loader` from the Start menu list or by entering `fw-loader` in the Windows search box.



4. Check the firmware version on the kit:

```
./fw-loader --device-list
```



5. Does a device show up? Is it in KitProg3 CMSIS-DAP Bulk mode? What version of the firmware does it have installed?



6. If you see a message that the firmware is outdated, update it to the latest version of KitProg3:

```
./fw-loader --update-kp3
```


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