ECE 310

Digital Signal Processing

Spring, 2021, ZJUI Campus

Lecture 4

Topics:

- ✓ Shift-invariance of discrete-time systems
- ✓ BIBO stability
- ✓ Convolution relationship of LSI systems

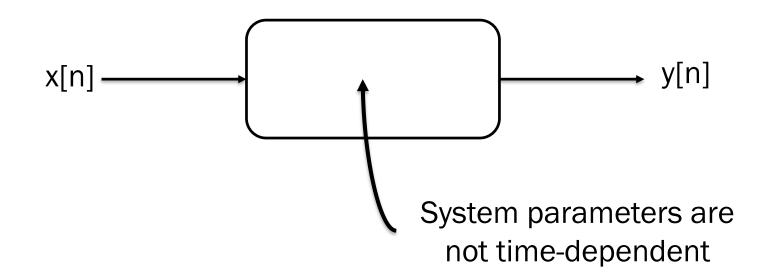
Educational Objectives:

- ✓ Understand shift-invariance and how to determine if a system is shift-invariant or shift-varying
- ✓ Understand BIBO stability and how to determine if a system is BIBO stable or not.
- ✓ Understand the convolution relationship of LSI systems
- ✓ Understand how to determine causality and BIBO stability of LSI systems

Shift Invariance

Definition

If
$$x[n] o y[n]$$
 then $x[n-n_0] o y[n-n_0]$



Shift-Invariance: Examples

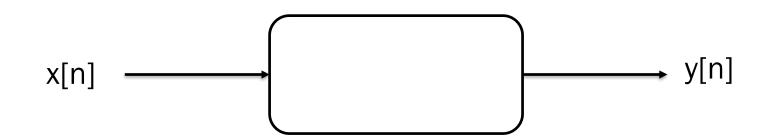
Example: show system (a) is time-varying

$$y[n] + \cos(n) y[n-1] = x[n]$$

Example: show system (b) is time-invariant

$$y[n] = \cos(x[n])$$

Bounded-Input Bounded Out (BIBO) Stability



Definition:

A system is BIBO (Bounded Input, Bounded Output) stable if **every bounded input bounded output**

- Bounded signal: $|x[n]| < B \implies$ finite

Examples

Example: Determine if the following functions are bounded:

- 1) $\delta[n]$
- 2) $e^{-3n} u[n]$
- 3) $e^{3n}u[n]$

Example: Determine if the following systems are BIBO stable:

1)
$$y[n] = 3x[n] + 2x[n-1]$$

$$2) \quad y[n] = nx[n]$$

3)
$$y[n] = \frac{1}{x[n]}$$

Convolution Relationship of LSI Systems

Input-output relationship of LSI system

$$x[n] \longrightarrow LSI \longrightarrow y[n]$$

Let $x[n] = \delta[n]$, unit pulse; y[n] = h[n], unit pulse response

Convolution Relationship of LSI Systems

Convolution Sum!

$$x[n] * h[n] \triangleq \sum_{l=-\infty}^{+\infty} x[l] \cdot h[n-l] = \sum_{l=-\infty}^{+\infty} x[n-l] \cdot h[l]$$

Causality and BIBO Stability of LSI Systems

• Causality $\iff h[n] = 0, n < 0$ right-sided signal

$$y[n] = \sum_{l=0}^{+\infty} x[n-l] \cdot h[l]$$
 current and past values!

Stability:

$$\sum_{n=-\infty}^{+\infty} |h[n]| < B$$

absolutely summable!

More Example on Linearity

Example:
$$y[n] = \frac{x[n]}{x[1]}$$

Let
$$x_1[n] \to y_1[n]$$
: $y_1[n] = \frac{x_1[n]}{x_1[1]} \dots$ (1)

$$x_2[n] \to y_2[n]$$
: $y_2[n] = \frac{x_2[n]}{x_2[1]} \dots$ (2)

Further assume
$$x_3[n] = ax_1[n] + bx_2[n] \rightarrow y_3[n]$$

we have
$$y_3[n] = \frac{x_3[n]}{x_2[1]} = \frac{ax_1[n] + bx_2[n]}{ax_1[1] + bx_2[1]} \dots$$
 (3)

Superposition rule requires

$$y_3[n] = ay_1[n] + by_2[n] = a\frac{x_1[n]}{x_1[1]} + b\frac{x_2[n]}{x_2[1]}$$

which is not consistent with the result in (3)