Concept Check

- 1. LSI System
 - a) Linearity

$$\mathcal{H}\{a_1x_1[n] + a_2x_2[n]\} = a_1\mathcal{H}\{x_1[n]\} + a_2\mathcal{H}\{x_2[n]\}$$

b) Time invariance / Shift invariance

$$y[n] = \mathcal{H}\{x[n]\} \Rightarrow y[n-n_0] = \mathcal{H}\{x[n-n_0]\}$$

- c) Causality: System output does not depend on future input.
- 2. Convolution

$$y[n] = h[n] * x[n]$$

Exercise:

• LSI system

	Linear	Shift-invariance	Causal
$y[n] = \cos(n+10) x[n]$			
$y[n] + \frac{1}{2}y[n-1] = x^2[n]$			
y[n] = x[n]x[n-1]			

Convolution

Example 2.6

Compute the output y[n] of a linear time-invariant system when the input x[n] and the impulse response h[n] are given by

$$x[n] = \begin{cases} 1, & 0 \le n \le N - 1 \\ 0, & \text{otherwise} \end{cases} \quad \text{and} \quad h[n] = \begin{cases} a^n, & 0 \le n \le M - 1 \\ 0, & \text{otherwise} \end{cases}$$
 (2.64)