ZHEJIANG UNIVERSITY - UNIVERSITY OF ILLINOIS AT URBANA-CHAMPAIGN

ECE 310 DIGITAL SIGNAL PROCESSING

Homework 3

Prof. Zhi-Pei Liang Due: March 5, 2021

1. Show that an LSI system with unit pulse response h[n] is causal if and only if h[n] = 0 for n < 0.

- 2. Show that an LSI system with unit pulse response h[n] is BIBO-stable if and only if $\sum_{n=-\infty}^{\infty} |h[n]|$ is bounded (i.e., h[n] is absolutely summable).
- 3. Determine whether each of the following systems that map input signal $\{x[n]\}$ to output signal $\{y[n]\}$ is BIBO stable.
 - (a) $y[n] = x^5[n] + 3$
 - (b) y[n] = x[n] * u[n]
 - (c) y[n] = nx[n]
 - (d) $y[n] = \frac{x[n]}{x[1]}$

(e)
$$y[n] = x[n] * h[n]$$
, where $h[n] = \begin{cases} 0 & \text{for } n < 0 \\ 2^{(n+1)^2} & \text{for } 0 \le n < 100 \\ 0.5^n & \text{for } n \ge 100 \end{cases}$

- 4. Determine the z-transform and sketch the ROC for each of the following sequences:
 - (a) $x[n] = \delta[n+1] 2\delta[n-2]$
 - (b) $\{x[n]\} = \{-1, 0, 1, 2, 3\}$
 - (c) $x[n] = \left(\frac{1}{2}\right)^{n-1} u[n-2]$
 - (d) $x[n] = 2\left(\frac{1}{2}\right)^n u[n-2] + 3\left(\frac{1}{3}\right)^{n-3} u[n+3]$
- 5. Given the z-transform pair

$$x[n] \longleftrightarrow X(z) = \frac{1}{1 - (1/3)z^{-1}}, \text{ with ROC: } |z| > 1/3,$$

use the z-transform properties to determine the z-transform and ROC of the following sequences

- (a) y[n] = x[n-1]
- (b) $y[n] = n^2x[n]$
- (c) $y[n] = 2^n x[n]$
- (d) $y[n] = \cos(\pi n/4)x[n]$
- (e) y[n] = (x * u)[n]
- (f) y[n] = (x * h)[n] where h[n] = x[n-2]