Distributed Systems

ECE428

Lecture 12

Adopted from Spring 2021

While we wait...

Think:

- Which algorithms we have studied so far require a leader?
- How can such a leader be elected in a distributed system?
- What are the safety and liveness conditions for leader election?

Today's agenda

- Leader Election
 - Chapter 15.3

- Goal:
 - What is leader election in distributed systems?
 - How do we elect a leader?
 - To what extent can we handle failures when electing a leader?

Why Election?

- Example: Your Bank account details are replicated at a few servers, but one of these servers is responsible for receiving all reads and writes, i.e., it is the leader among the replicas
 - What if servers disagree about who the leader is?
 - What if there are two leaders per customer?
 - What if the leader crashes?
 Each of the above scenarios leads to inconsistency

More motivating examples

- The root server in a group of NTP servers.
- The master in Berkeley algorithm for clock synchronization.
- In the sequencer-based algorithm for total ordering of multicasts, the "sequencer" = leader.
- The central server in the "central server algorithm" for mutual exclusion.
- Other systems that need leader election: Apache Zookeeper, Google's Chubby.

Leader Election Problem

- Among processes, elect Leader to undertake special tasks
 - And let everyone know in the group about this Leader
- What happens when a leader fails (crashes)
 - Some process detects this (using a Failure Detector!)
 - Then what?
- Focus of this lecture: Election algorithm. Its goal:
 - 1. Elect one leader only among the non-faulty processes
 - 2. All non-faulty processes agree on who is the leader

Calling for an Election

- Any process can call for an election.
- A process can call for at most one election at a time.
- Multiple processes are allowed to call an election simultaneously.
 - All of them together must yield only a single leader
- The result of an election should not depend on which process calls for it.

Election Problem, Formally

- A run of the election algorithm must always guarantee:
 - Safety: For all non-faulty processes p:
 - p has elected:
 - q: a particular non-faulty process with the best or unique attribute value or Null (None)
 - Liveness: For all election runs:
 - election run terminates
 - & for all non-faulty processes p: p's elected is not Null
- At the end of the election protocol, the non-faulty process with the best (highest) election attribute value is elected.
 - Common attribute: the leader has the highest id
 - Other attribute examples: leader has the highest IP address, or fastest
 CPU, or most disk space, or most files, most battery etc.

System Model (Assumptions)

- N processes.
- Messages are eventually delivered.
- Failures may occur during the election protocol.
- Each process has a unique id.
 - Each process has a unique attribute (based on which Leader is elected).
 - If two processes have the same attribute, combine the attribute with the process id to break ties.

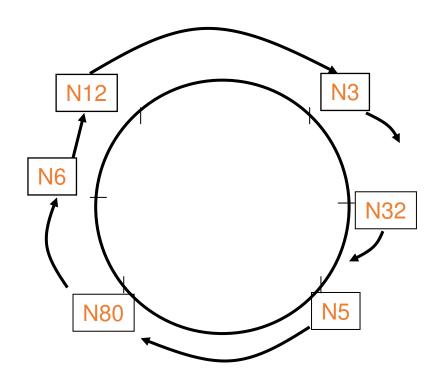
Classical Election Algorithms

Ring election algorithm

Bully algorithm

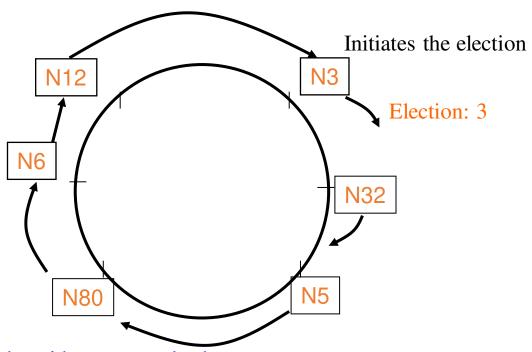
Ring Election Algorithm

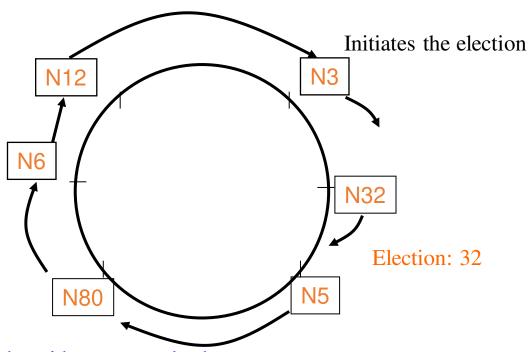
- N processes are organized in a logical ring
 - All messages are sent clockwise around the ring.

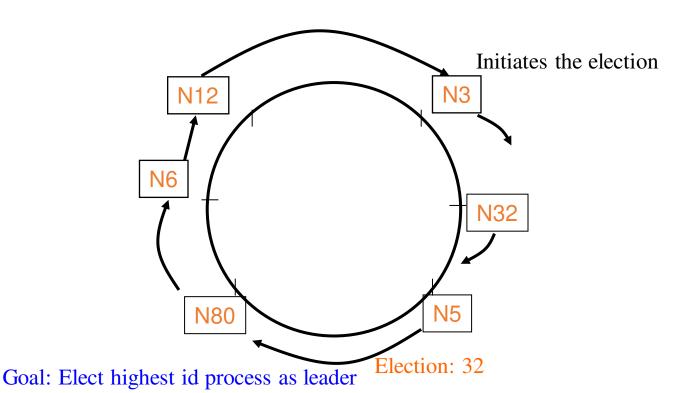


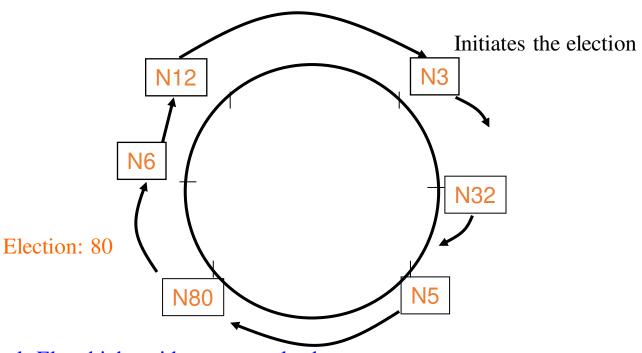
Ring Election Protocol (basic version)

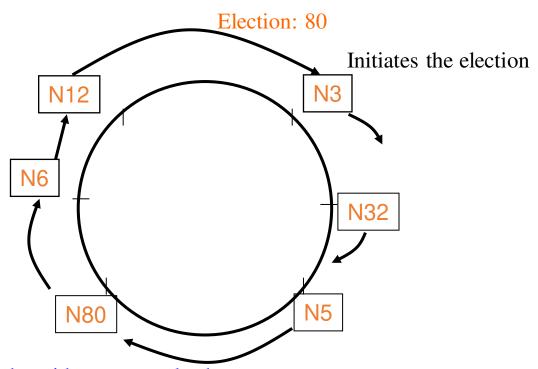
- When Pi start election
 - send <u>election</u> message with Pi's <attr_i, i> to ring successor.
- When Pj receives message (election, <attr_x, x>) from predecessor
 - If (attr_x, x) > (attr_i, j):
 - forward message (election, <attr_x, x>) to successor
 - If (attr_x, x) < (attr_i, j)
 - send (election, <attr_i, j>) to successor
 - If (attr_x, x) = (attr_j, j): Pj is the elected leader (why?)
 - send elected message containing Pj's id
- <u>elected</u> message forwarded along the ring until it reaches the leader

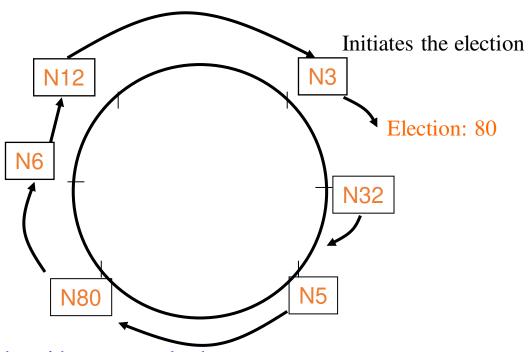


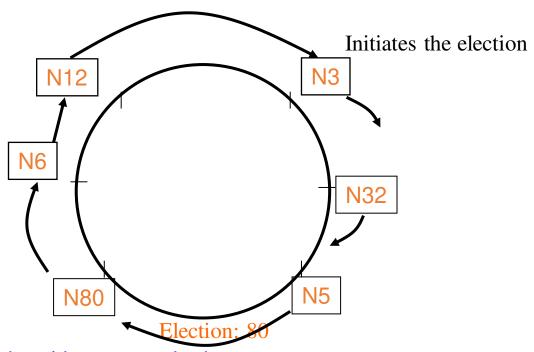


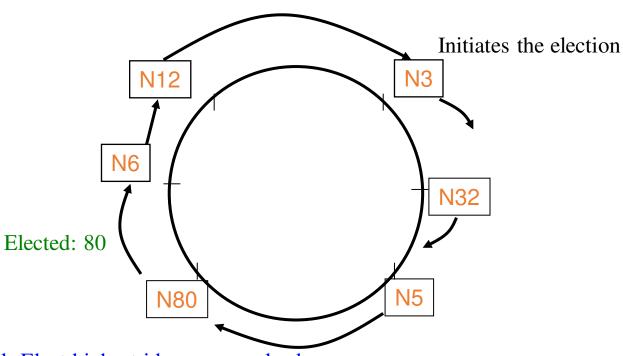


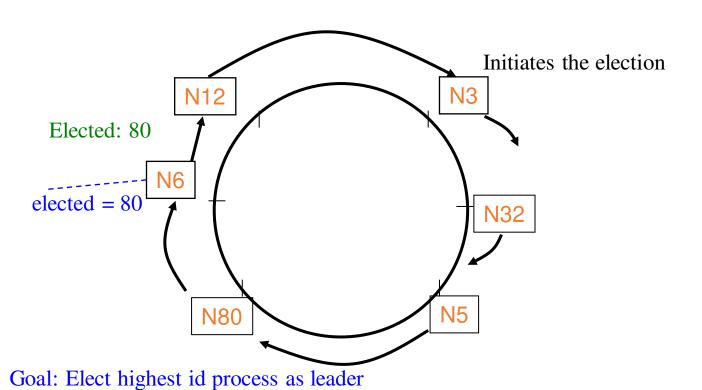


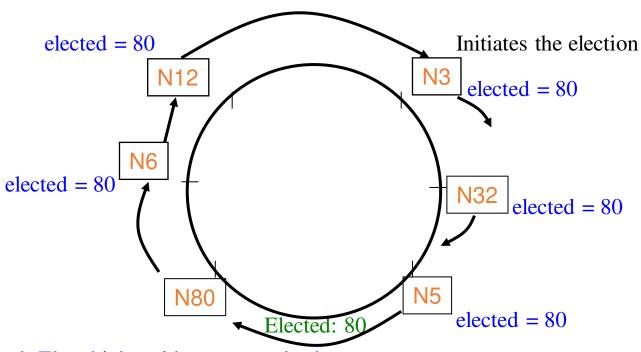


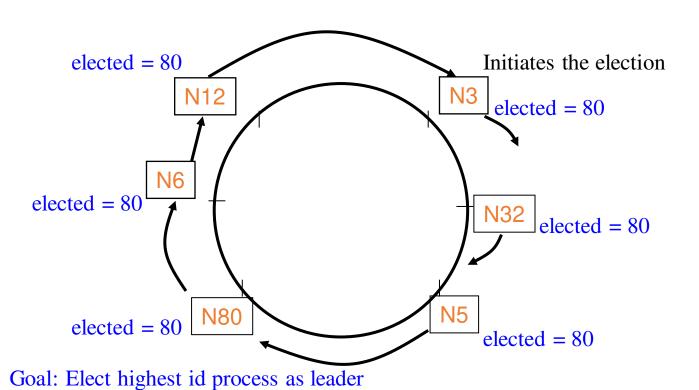








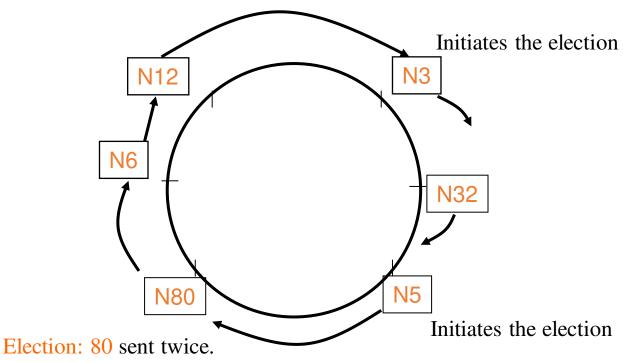




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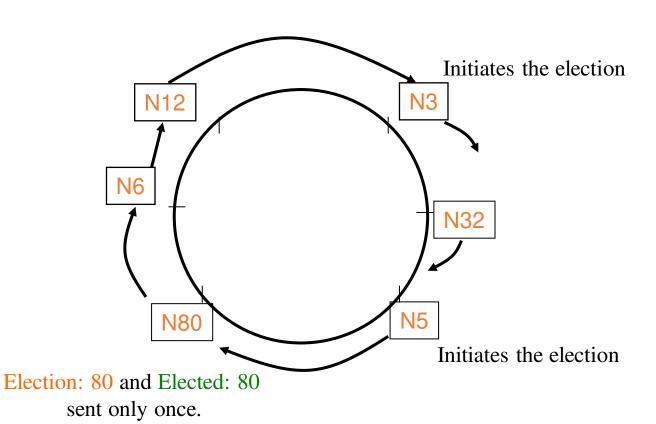
What happens when multiple processes call for an election?



Elected: 80 also sent twice.

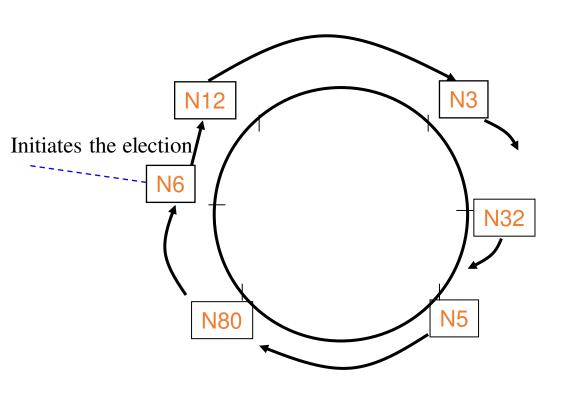
Ring Election Protocol [Chang & Roberts'79]

- When Pi start election
 - send <u>election</u> message with Pi's <attr_i, i> to ring successor.
 - set state to participating
- When Pj receives message (election, <attr_x, x>) from predecessor
 - If (attr_x, x) > (attr_i, j):
 - forward message (election, <attr_x, x>) to successor
 - set state to participating
 - If (attr_x, x) < (attr_j, j)
 - If (not participating):
 - send (election, <attr_i, j>) to successor
 - set state to participating
 - If (attr_x, x) = (attr_i, j): Pj is the elected leader (why?)
 - send <u>elected</u> message containing Pj's id
- <u>elected</u> message forwarded along the ring until it reaches the leader
 - Set state to not participating when an elected message is received.



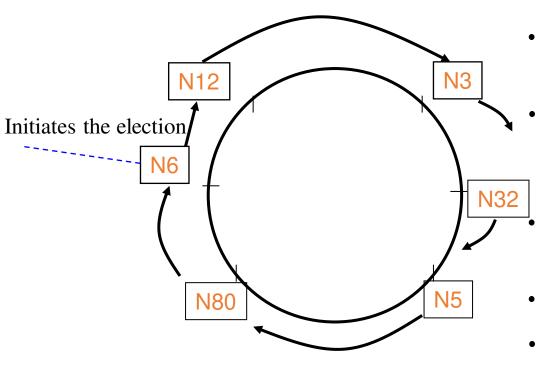
- Let's assume no failures occur during the election protocol itself, and there are N processes.
- Let's also assume that only one process initiates the algorithm
- Bandwidth usage: Total number of messages sent.
- Turnaround time: The number of serialized message transmission times between the initiation and termination of a single run of the algorithm.

Worst-case



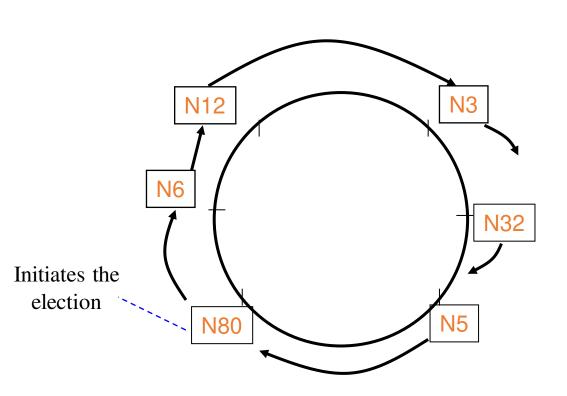
When the initiator is the ring successor of the would-be leader.

Worst-case



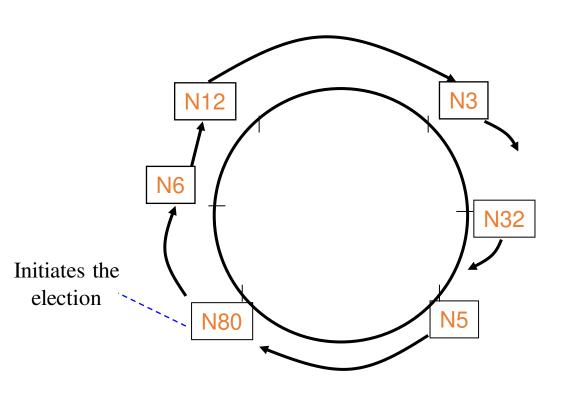
- (N-1) messages for Election message to get from N6 to N80.
- N messages for Election message to circulate around ring without message being changed.
 - N messages for Elected message to circulate around the ring
- No. of messages: (3N-1)
- Turnaround time: (3N-1) message transmission times

Best-case



When the initiator is the would-be leader.

Best-case



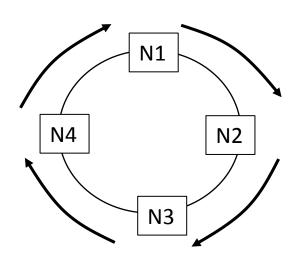
When the initiator is the would-be leader.

No. of messages: 2N

Turnaround time: 2N message transmission times

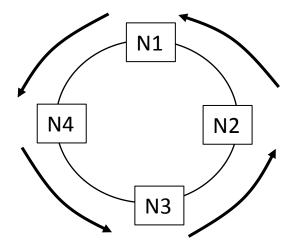
- Let's assume no failures occur during the election protocol itself, and there are N processes.
- Let's also assume that only one process initiates the algorithm
- Bandwidth usage (total number of messages)
 - O(N): Worst case = 3N 1; Best case = 2N.
- O(N) turnaround time.

- Let's assume no failures occur during the election protocol itself, and there are N processes.
- When each process initiates the algorithm?
 - O(N) messages in best-case.



- N election messages generated at the start of algorithm.
- Only one survives, and completes a full round.
 - N-1 messages.
- One round for the elected message
 - N messages.
- Total: 3N -1 messages

- Let's assume no failures occur during the election protocol itself, and there are N processes.
- When each process initiates the algorithm?
 - O(N) messages in best-case.
 - O(N²) in worst-case.



- N election messages generates at the starts of algorithm.
- N 1 survive the next time step.
- N − 2 survive the next time step.
- •

- Let's assume no failures occur during the election protocol itself, and there are N processes.
- When each process initiates the algorithm?
 - O(N) messages in best-case.
 - O(N²) messages in worst-case.
 - O(N) turnaround time.

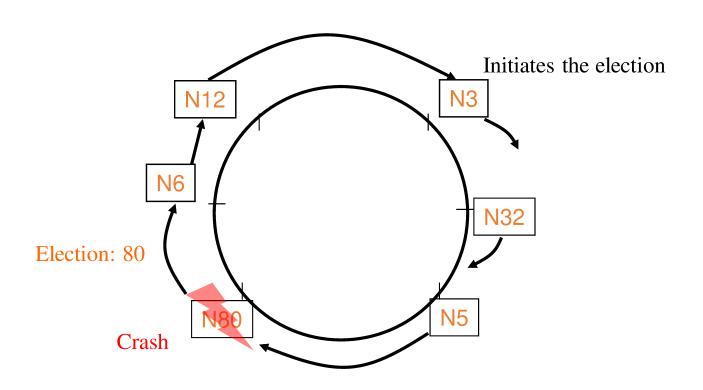
Correctness

Assuming no process fails.

- Safety:
 - Process with highest attribute elected by all nodes.

- Liveness:
 - Election completes within 3N 1 message transmission times.

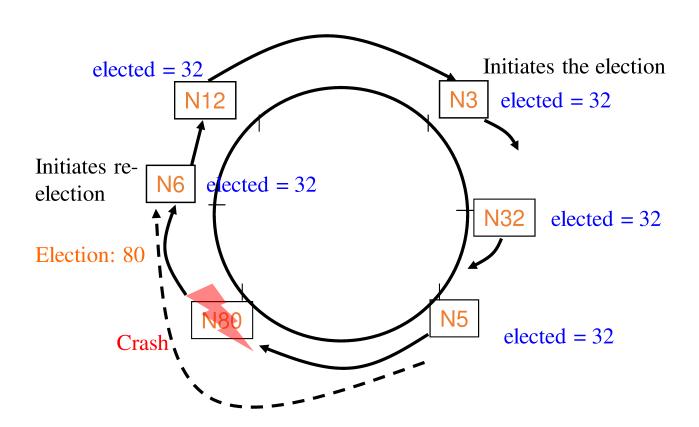
Handling Failures



Handling failures

- Use the failure detector.
- A process can detect failure of N80 via its own local failure detector:
 - Repair the ring.
 - Stop forwarding Election:80 message.
 - Start a new run of leader election.

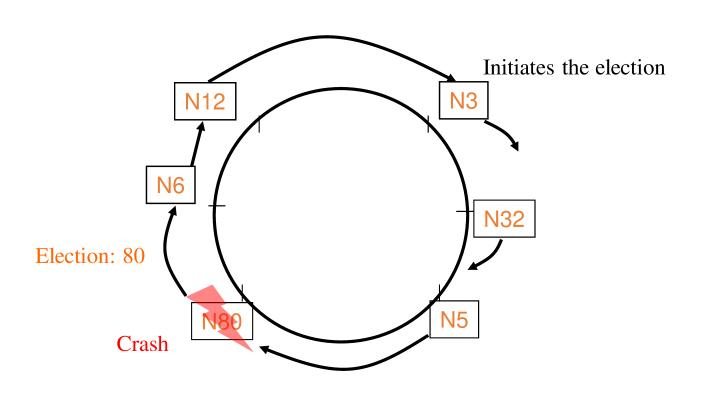
Handling Failures



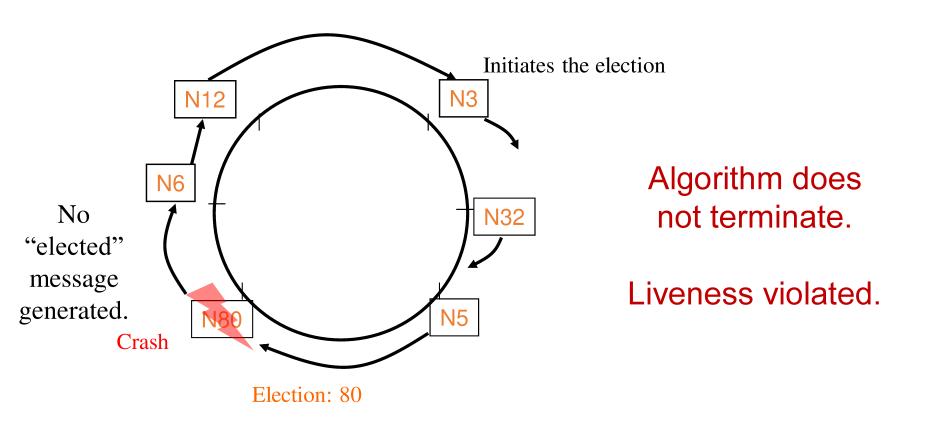
Handling failures

- Use the failure detector.
- A process that detects the failure of N80 via its own local failure detector:
 - Repair the ring.
 - Stop forwarding Election:80 message.
 - Start a new run of leader election.
- But failure detectors cannot be both complete and accurate.
 - Incomplete FD => N80's failure might be missed.

What happens if a process failure is undetected?

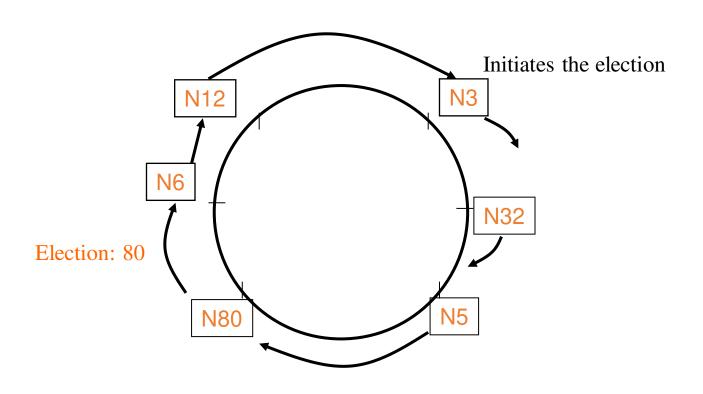


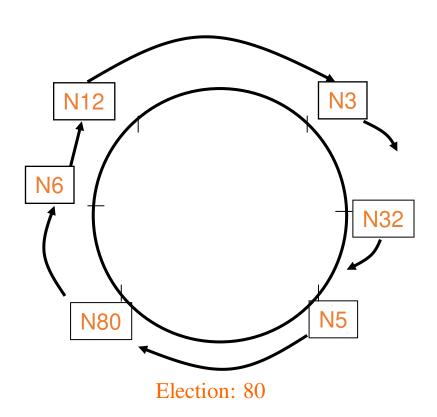
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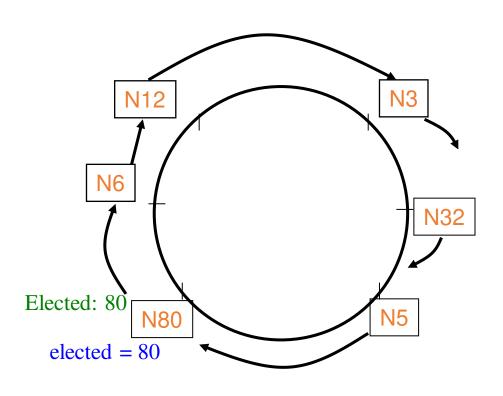


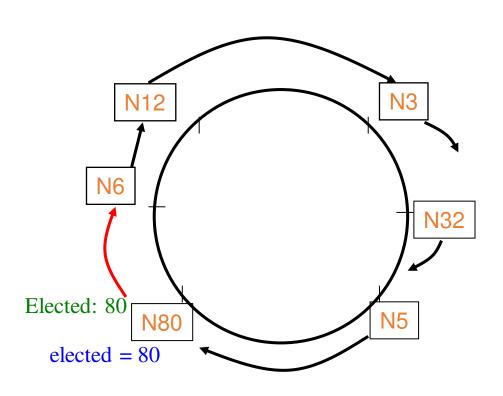
Handling failures

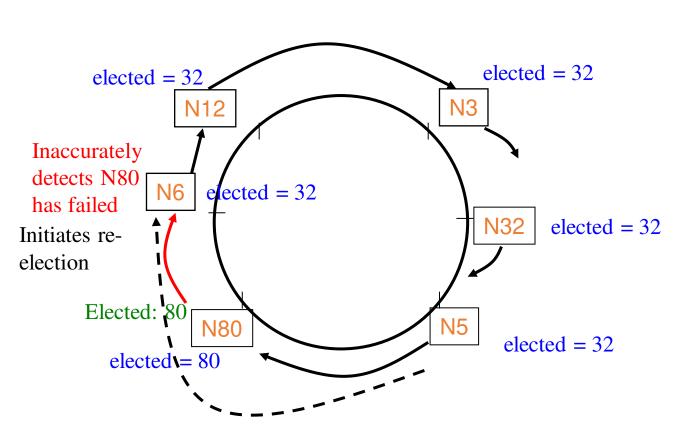
- Use the failure detector.
- A process can detect failure of N80 via its own local failure detector:
 - Repair the ring.
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- But failure detectors cannot be both complete and accurate.
 - Incomplete FD => N80's failure might be missed
 - violation of liveness
 - Inaccurate FD => N80 mistakenly detected as failed











Safety has been violated.

Fixing for failures

- Use the failure detector.
- A process can detect failure of N80 via its local failure detector:
 - Repair the ring.
 - Stop forwarding Election:80 message.
 - Start a new run of leader election.
- But failure detectors cannot be both complete and accurate.
 - Incomplete FD => N80's failure might be missed
 - violation of liveness
 - Inaccurate FD => N80 mistakenly detected as failed
 - new ring will be constructed without N80.
 - a process with lower attribute will be selected.
 - violation of safety

Classical Election Algorithms

Ring election algorithm

Bully algorithm

Bully algorithm

Faster turnaround time than ring election.

Explicitly build in notion of timeouts into the algorithm.

• Let's assume (for simplicity of exposition) that the attribute based on which leader is elected is the process id.

 Before discussing Bully algorithm, let's first discuss a simpler (related) algorithm.....

Multicast-based algorithm

- Start an election
 - Multicast <election, my ID> to all processes
 - If receive <agree> from all processes, then elected
 - Multicast <coordinator, my ID>
 - If receive <disagree> from any process
 - Give up election
- Receive <election, ID> from process p
 - If ID > my ID
 - Reply <agree> to p (unicast)
 - If ID < my ID
 - Reply <disagree> to p
 - Start election (if not already running)
- What about failures?

Multicast-based algorithm

- Start an election
 - Multicast <election, my ID> to all processes
 - If receive <agree> from all processes or timeout, then elected
 - Multicast <coordinator, my ID>
 - If receive <disagree> from any process
 - Give up election
- Receive <election, ID> from process p
 - If ID > my ID
 - Send <agree> to p (unicast)
 - If ID < my ID
 - Send <disagree> to p
 - Start election (if not already running)
- Can we improve on this?

Bully Algorithm

- All processes know other process' ids.
- Do not need to multicast election to all processes.
- Only to processes with higher id.

Bully Algorithm

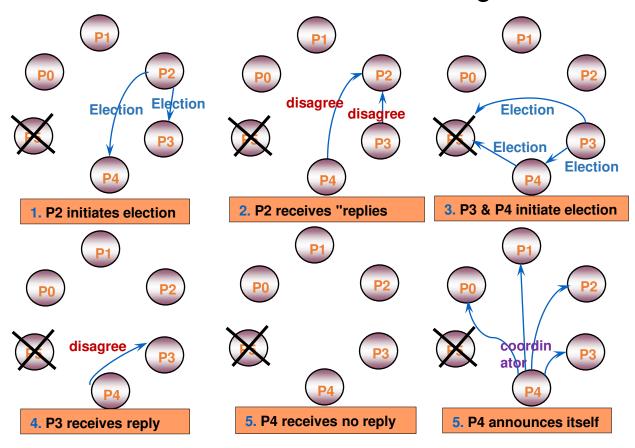
- When a process wants to initiate an election
 - if it knows its id is the highest
 - it elects itself as coordinator, and sends a Coordinator message to all processes with lower identifiers.
 Election is completed.
 - else
 - it initiates an election by sending an *Election* message (contd. on next page)

Bully Algorithm (2)

- else it initiates an election by sending an Election message
 - Sends it to only processes that have a higher id than itself.
 - **if** receives no answer within timeout, calls itself leader and sends *Coordinator* message to all lower id processes. Election completed.
 - if answer received, then there is some non-faulty higher process => so, wait for coordinator message. If none received after another timeout, start a new election run.
- A process that receives an *Election* message replies with disagree message, and starts its own leader election protocol (unless it has already done so).

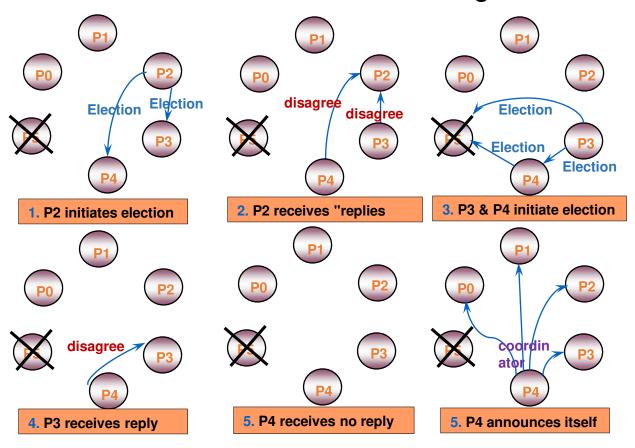
Bully Algorithm: Example

P2 initiates election after detecting P5's failure.



Bully Algorithm: Example

P2 initiates election after detecting P5's failure.



Bully Algorithm (2)

- else it initiates an election by sending an *Election* message
 - Sends it to only processes that have a higher id than itself.
 - if receives no answer within timeout, calls itself leader and sends *Coordinator* message to all lower id processes.
 Election completed.
 - **if** answer received however, then there is some non-faulty higher process => so, wait for coordinator message. If none received after another timeout, start a new election run.
- A process that receives an *Election* message replies with disagree message, and starts its own leader election protocol (unless it has already done so).

Timeout values

- Assume the one-way message transmission time (T) is known.
- First timeout value (when the process that has initiated election waits for the first response)
 - Must be set as accurately as possible.
 - If it is too small, a lower id process can declare itself to be the coordinator even when a higher id process is alive.
 - What should be the first timeout value be, given the above assumption?
 - 2T + (processing time) ≈ 2T
- When the second timeout happens (after 'disagree' message), election is re-started.
 - A very small value will lead to extra "Election" messages.
 - A suitable option is to use the worst-case turnaround time.

Next Class

Analysis of Bully Algorithm

Consensus