

Remark: For surfaces described by functions of x and z (or y and z), we can make the following adjustments to the definition above: if S is the graph of $y = g(x, z)$ and R is its projection onto the xz -plane, then

$$\iint_S f(x, y, z) dS := \iint_R f(x, g(x, z), z) \sqrt{1 + \frac{\partial g^2}{\partial x^2} + \frac{\partial g^2}{\partial z^2}} dx dz.$$

If S is the graph of $x = g(y, z)$ and R is its projection onto the yz -plane, then $\iint_S f(g(y, z), y, z) \sqrt{1 + \frac{\partial g^2}{\partial y^2} + \frac{\partial g^2}{\partial z^2}} dy dz$. If $f = 1$ ($\iint_S dS = \text{ct}(S)$)

Example: Evaluate the surface integral

$$\iint_S (y^2 + 2xz) dS, \text{ where } S \text{ is the first-octant portion of the plane}$$

$$2x + y + 2z = 0$$

② A cone-shaped surface lamina S is given by: $z = 4 - 2\sqrt{x^2 + y^2}$, $0 \leq z \leq 4$. At each point on S , the density is proportional to the distance between the point and the z -axis. Let us compute the mass of S

$$\rho(x, y) \mapsto k\sqrt{x^2 + y^2}; R = \{(x, y) \in \mathbb{R}^2 : x^2 + y^2 \leq 1\}, m = \frac{16\pi k\sqrt{5}}{3}$$

Surface integral over a parametric surface

$$\text{Let } S: r(u, v) = x(u, v)\vec{i} + y(u, v)\vec{j} + z(u, v)\vec{k}, (u, v) \in D,$$

$$\iint_S f(x, y, z) dS = \iint_D f(x(u, v), y(u, v), z(u, v)) \|r_u(u, v) \wedge r_v(u, v)\| du dv.$$

Example: $S = \{(x, y, z) \in \mathbb{R}^3 : x > 0, y > 0, z > 0, y^2 + z^2 \leq g^2\}$

Def.: Unit normal vector field on surface and orientation can be defined when a unit normal vector is defined and S is orientable. We will find a continuous unit normal vector field of a surface on S .

$$S = G^{-1}(\{0\}) \text{ where } G(x, y, z) = z - g(x, y).$$

The unit normal vector field of S is $N = \frac{\nabla G}{\|\nabla G\|}$

$$\text{that is: } N = \frac{1}{\sqrt{1 + \frac{\partial g^2}{\partial x^2} + \frac{\partial g^2}{\partial y^2}}} \left(-\frac{\partial g}{\partial x} \vec{i} - \frac{\partial g}{\partial y} \vec{j} + \vec{k} \right)$$

$$N = \frac{(v_n, n)}{\|v_n, n\|} \text{ for } N = \frac{v_n \wedge n}{\|v_n \wedge n\|}.$$

On each nonboundary point