

theorem: line integral of for area

If D is a plane region ~~simply connected~~ bounded by a piecewise simple closed curve C , the
 $A(D) = \frac{1}{2} \oint_C x dy - y dx$. → oriented
and counterclockwise

Example: $D = \{ \frac{x^2}{a^2} + \frac{y^2}{b^2} \leq 1 \}$; $C = \begin{cases} x = a \cos t \\ y = b \sin t \end{cases} \quad 0 \leq t \leq 2\pi$.

II-3- Surface integrals

II-3-1- Parametric surfaces

Definition:

Let x, y, z be functions of u and v that are continuous on a domain $D \subset \mathbb{R}^2$. the set of points (x, y, z) given by:

$$S: \mathbf{r}(u, v) = x(u, v) \vec{i} + y(u, v) \vec{j} + z(u, v) \vec{k} \quad (\text{parametric surface})$$

is called parametric surface. The following equations:

$$\begin{cases} x = x(u, v) \\ y = y(u, v) \\ z = z(u, v) \end{cases} \quad (u, v) \in D$$
 are the parametric equations for the surface S .

Examples: (1) $S = S^2 = \{ (x, y, z) \in \mathbb{R}^3 : x^2 + y^2 + z^2 \leq 1 \}$

$$\mathbf{r}(\phi, \theta) = \cos \theta \sin \phi \vec{i} + \sin \theta \sin \phi \vec{j} + \cos \phi \vec{k}; \quad D = [0, \pi] \times [0, 2\pi]$$

$$(2) S: x = 3 \cos u \vec{i} + 3 \sin u \vec{j} + v \vec{k}; \quad D = [0, 2\pi] \times [0, 4]$$

$$(3) \text{ If } S = \{ (x, y, z) \in \mathbb{R}^3 : (x, y) \in D \text{ and } z = f(x, y) \}$$

then $\mathbf{r}(x, y) = x \vec{i} + y \vec{j} + f(x, y) \vec{k}$; $(x, y) \in D$, for example:

$$S = \{ (x, y, z) \in \mathbb{R}^3 : z^2 = x^2 + y^2 \text{ and } 0 \leq z \leq R \}; \quad f: (x, y) \mapsto \sqrt{x^2 + y^2}; \quad D = \overline{C(0,0;R)}$$

Definition: Normal vector of a smooth parametric surface

Let $S: \mathbf{r}(u, v) = x(u, v) \vec{i} + y(u, v) \vec{j} + z(u, v) \vec{k}$; $(u, v) \in D$

be a smooth parametric surface over an open subset $D \subset \mathbb{R}^2$.

A normal vector field at the point $(x_0, y_0, z_0) = (x(u_0, v_0), y(u_0, v_0), z(u_0, v_0)) \in S$, $(u_0, v_0) \in D$ is given by $N(x_0, y_0, z_0) = \mathbf{r}_u(u_0, v_0) \times \mathbf{r}_v(u_0, v_0)$

with $\mathbf{r}_u = \frac{\partial \mathbf{r}}{\partial u}$ and $\mathbf{r}_v = \frac{\partial \mathbf{r}}{\partial v}$.

Remark: $-N(x_0, y_0, z_0) = \mathbf{r}_v(u_0, v_0) \times \mathbf{r}_u(u_0, v_0)$ is also a normal vector of S at (x_0, y_0, z_0) .