**State-of-the-Art in Human Locomotion Action Recognition: A Review**

**Paras Jain1, Meenakshi Arora2 Rohini Sharma3**

P.G. Student, Department of CSE, Sat Kabir Institute of Technology and Management, Haryana, India1

Assistant Professor, of CSE, Sat Kabir Institute of Technology and Management, Haryana, India2

Assistant Professor, CS, GPGCW, Rohtak, Haryana, India3

**ABSTRACT:** Human action recognition is a vital area of research in computer vision and machine learning, with applications spanning surveillance, healthcare, sports analysis, and human-computer interaction. This review presents a comprehensive overview of various human action recognition methods, highlighting their distinctive approaches and contributions to the field. We categorize these methods into segmentation-based, handcraft feature extraction, shape-based, motion-based, local binary pattern, and fuzzy logic approaches. Segmentation techniques focus on dividing the video into meaningful segments to isolate actions. Handcraft feature extraction involves manually designing features that capture relevant aspects of human motion. Shape-based methods analyze the silhouette or contour of the human body to identify actions, while motion-based methods focus on the dynamics of movement over time. Local binary pattern techniques leverage texture information for action recognition. Lastly, fuzzy logic approaches incorporate uncertainty handling and approximate reasoning to improve recognition accuracy. This review aims to provide insights into the strengths and limitations of each method, guiding future research towards more robust and efficient human action recognition systems.

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**KEYWORDS:** Human action recognition, feature extraction, Shape-based methods

**INTRODUCTION:** There are several possible uses for Human Action Recognition (HAR). Its goal is to identify a person's movements based on visual information or sensors. HAR techniques can be divided into three groups: multi-modal, non-visual sensor-based, and visual sensor-based[1]. The form of the felt data is the primary distinction between the visual and other categories. Some sources record the visual data as 1D signals, whereas others record the data as 2D, 3D, or video pictures [2]. Wearable technology has advanced over the past few years, with the development of smartwatches, fitness bands, and smartphones. These are outfitted with tiny, non-visual sensors as well as communication and processing power. Additionally, their very inexpensive cost has helped to provide new opportunities due to their widespread usage. These consist of disease prevention, rehabilitation training, and health surveillance[2].

Simultaneously, among the most popular and hot topics in computer vision research are visual sensor-based approaches for human action identification. Applications include content-based video search, intelligent video surveillance, contextual assisted living, human-robot interaction, and human-computer interaction[3]. The recognition system is trained to discern between activities performed in a scene in each of those apps[4]. Based on that inference, it might also make some decisions or carry out additional processing. Based on the intricacy of human actions, action recognition systems can be divided into four groups. Primitive [5], solitary [6], interaction [7], and group [10] actions recognition are examples of this. Basic movements of human body parts, such as "lifting a hand" and "bending," are referred to as basic actions. Figure 1 shows basic classification of Hand-Crafted attributes Depiction for Action Recognition.

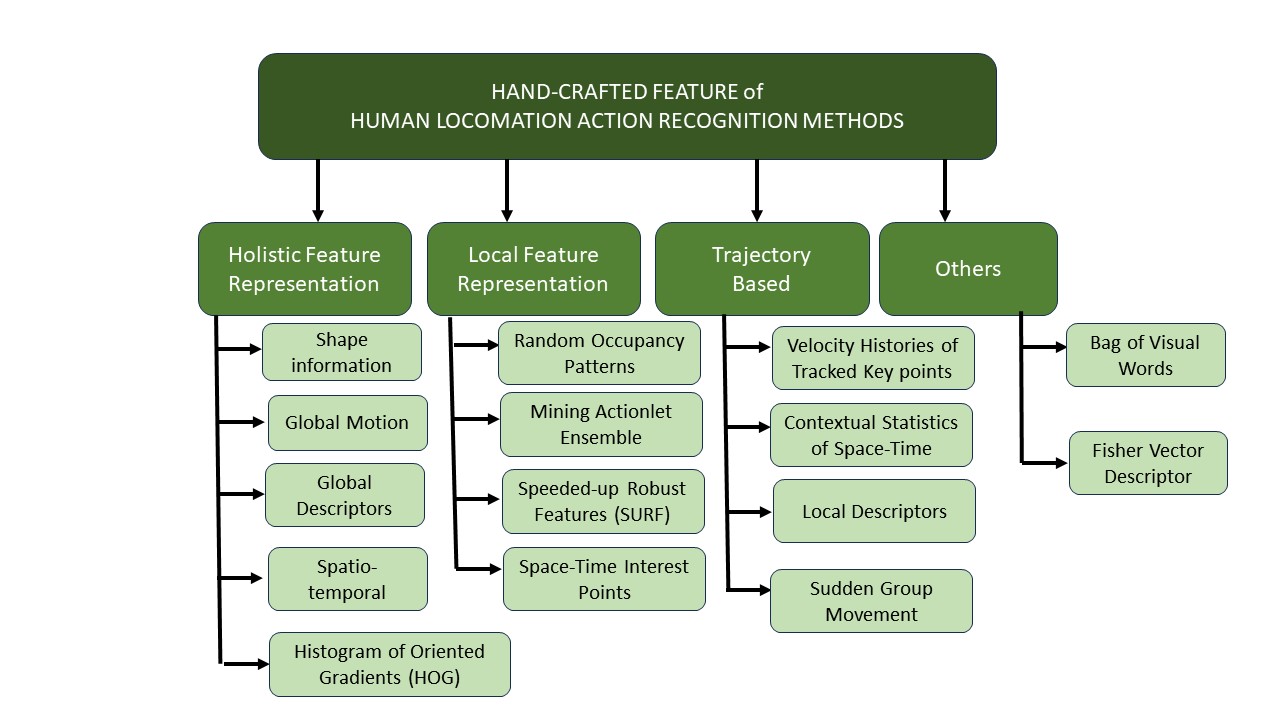


Figure 1: Classification of Hand-Crafted Depiction for Action Recognition

**RESEARCH BACKGROUND**

The field of human action recognition along with associated approaches has seen the publication of numerous significant survey and review publications. Nevertheless, published reviews typically become outdated. This is why, although being a difficult and demanding undertaking, producing an updated study on human action recognition is greatly needed. This review presents the latest techniques for vision-based human action identification, along with debates, analysis, and comparisons. Popular benchmark datasets, important applications, and methodologies based on deep learning and handcrafted techniques are presented. Additionally, this article examined various recognition model designs, such as hybrid, modalities-based, and view-invariant based systems**.**

The majority of approaches presume that tasks are carried out from a set point of view. But in a genuine scenario, the person's position and posture differ significantly depending on the angle at which the action is photographed. Additionally, different views appear with varying motion patterns, which further complicates the detection of an action. [8] approaches this problem by using numerous camera information to train a classifier. In order to obtain a view-invariant representation, a 3D body posture model for action recognition was also created, as shown in [9]. By employing cylindrical coordinate systems and the Fourier transform, researchers attempt to make use of view-invariant features space [10]. The majority of multi-view datasets, according to researchers [11], contain a homogeneous or unchanging background.

**HAND-CRAFTED FEATURE REPRESENTATION FOR ACTION RECOGNITION**

Human action recognition using hand-crafted features has been a prominent approach in the early stages of this research field. This method involves manually designing and extracting features that are expected to be relevant for distinguishing different actions. Here, we discuss two major categories: holistic feature representation-based methods and hybrid methods based on shape and global motion information.

**Holistic Feature Depiction Based Methods**

Approaches that rely on holistic representation of features handle Regions of Interest (ROIs) holistically, utilizing every pixel to generate descriptors. Person identification and descriptor computing are the two phases that holistic based approaches often involve in order to recognize an action. In holistic approaches, the entire human body is seen as a representation of an activity, with no need to localize specific bodily parts. According to the data utilized for the recognition issue, holistic approaches can be divided into two groups:

***Shape and Global Information Based Approaches***

Below is a comparison of different shape information-based methods for human action recognition, categorized into silhouette information, color and location information, RGB-D information, Histogram of Oriented Gradients, and space-time-based methods.

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| **Class** | **Technique** | **Approach** | **Strengths** | **Weaknesses** | **References** |
| **Silhouette Information** | Vision-based human motion analysis | Summary of vision-based approaches by means of silhouettes | Thorough review, finds crucial approaches | Absence of implementation specifics, general summary | [12] |
|  | Human shape-motion analysis in athletics videos | employs a transferable belief model to analyze shape and motion | Integrates form and action, making it effective for sports | Particular to sports, could not apply generally | [13] |
|  | Temporal templates | Motion Energy Images (MEI) and Motion History Images (MHI) are used. | Time-based data collection and straightforward application | little spatial information and susceptible to noise and obstructions | [14] |
| **Color and Location Information** | Event detection in crowded videos | uses location and color characteristics in congested settings to detect occurrences | Sturdy feature extraction that works well in cluttered environments | Expensive computing costs and lighting sensitivity | [15] |
| **RGB-D Information** | Color-Depth video database for daily activity recognition | Combines RGB and depth data for activity recognition | uses depth data and is resilient to changes in shape | depth sensors are needed, and data processing is expensive. | [16] |
|  | Action recognition based on a bag of 3D points | makes use of 3D point cloud data to identify actions | combines robust description and 3D spatial information. | heavy computing and the need for depth sensors | [17] |
|  | Action recognition using depth motion maps and local binary patterns (LBP) | integrate maps of depth motion with (LBP) | Reliable depth-based features that are resistant to occlusions | High processing cost and sensitivity to the quality of the depth map | [18] |
| **Histogram of Oriented Gradients (HOG)** | Human action recognition using depth motion map and KECA | employs KECA and a temporal cascading stack of depth motion map | Good motion depiction and a hierarchical framework | Exorbitant processing expenses and intricate feature extraction | [19] |
| **Space-Time Based** | Space-time occupancy patterns (STOP) | examines occupancy variations in space and time using depth map sequences | records 3D spatiotemporal data and is resistant to changing viewpoints. | high processing costs and the need for depth sensors | [20] |
|  | HON4D: Histogram of oriented 4D normals | Recognizes activity from depth sequences using 4D normals | Thick spatiotemporal characteristics and strong identification | Expensive computing costs and depth quality sensitivity | [21] |
| **Shape and Global Motion Information**  **(Hybrid Approach)** | DiscLDA: Discriminative Learning for Dimensionality Reduction and Classification | use discriminative latent dirichlet assignment to learn categorization and reduce dimensionality. | Efficient dimensionality reduction increases the precision of categorization | intricate model requiring a lot of computing power | [22] |
|  | Acknowledging Movement from a Distance | uses global motion characteristics to identify distant activities | robust to changes in perspective and scale, useful for remote actions | cognizant of background congestion and occlusions | [23] |
|  | Effective Visual Event Recognition Employing Volumetric Characteristics | makes use of volumetric properties to effectively detect visual events | Strong detection and high feature extraction efficiency | High processing costs and huge memory needs when dealing with volumetric data | [24] |

**Local Feature Depictions Based Approaches**

When it comes to RGB-based video, local feature-based techniques have a tendency to capture distinctive characteristics locally within a frame without requiring human identification or segmentation. Numerous recognition system applications, including action recognition, object identification, and scene recognition, have effectively used local feature-based approaches. Important shape and motion features for a particular region in a video can be captured by local capture-based techniques. Generally speaking, local feature-based techniques involve two stages: descriptor computing and point of interest (POI) detection. Interest spots in image processing are locations where there is a localized change in picture intensity.

**Table 2: Local Feature Depictions Based Approaches for Human Action Recognition**

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
| **Technique** | **Approach** | **Strengths** | **Weaknesses** | **References** |
| Random Occupancy Patterns | uses random occupancy patterns to identify actions based on depth information | Properly captures spatial occupancy knowledge, appropriate for depth data | sensitive to noise in detailed data and expensive to compute | [25] |
| Mining Actionlet Ensemble for Action Recognition with Depth Cameras | mines depth camera actionlet ensemble for reliable action identification | Efficient for handling occlusions in depth camera data | big training datasets and a high processing load are necessary | [26] |
| Speeded-up Robust Features (SURF) | extracts strong local characteristics for action recognition using SURF. | Rapid feature extraction, scalability, and rotation | Misses small details in the motions and is less effective when there is a lot of motion blur | [14] |
| Space-Time Interest Points | finds interest locations in space and time to record local characteristics for action recognition. | Capable of recording motion dynamics and resilient to changes in speed | significant computational cost and noise and occlusion sensitivity | [15] |

**Trajectories Based Approaches**

It has been asserted by numerous academics that the temporal and spatial domains in video have distinct properties. Therefore, it is not appropriate to detect points of interest in a 3D spatiotemporal domain. As a result, tracking identified locations of interest throughout the temporal domain has been a common practice in research. Next, the descriptors for video representation are frequently computed using the overall size of the trajectory points.

**Table 3: Trajectories Based Approaches for Human Action Recognition**

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
| **Technique** | **Approach** | **Strengths** | **Weaknesses** | **References** |
| Activity Recognition Using the Velocity Histories of Tracked Keypoints | Utilizes velocity histories of tracked key points for recognizing activities | Adaptable to changes in direction and speed, accurately represents motion dynamics | sensitive to noise in detailed data and expensive to compute | [27] |
| Contextual Statistics of Space-Time Ordered Features for Human Action Recognition | utilizes space-time ordered characteristics' situational statistics to identify actions. | gathers contextual data well, robust to modifications in actions | High processing costs and a need for sizable training datasets | [28] |
| Local Descriptors for Spatio-Temporal Recognition | uses spatial-temporal data captured by local descriptors for motion analysis | Capable of capturing the dynamics of local motion, resilient to changes in speed | cognizant of occlusions and noise, theoretically costly | [29] |
| Towards Unsupervised Sudden Group Movement Discovery for Video Surveillance | concentrates on the unsupervised detection of abrupt group movements for monitoring | Identifying group movements effectively makes it appropriate for surveillance purposes. | restricted to collective acts; may overlook individual acts | [30] |

**Other Feature Depictions Approaches**

**Table 4: Bag of Words (BOW) and Fisher Vector descriptors Approaches for Human Action Recognition**

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| **Class** | **Technique** | **Approach** | **Strengths** | **Weaknesses** | **References** |
| **Bag of Words (BOW)** | Visual Categorization with Bags of Keypoints | transforms local characteristics into a visual word histogram, allowing keypoint-based action identification. | Simple and effective, capable of handling a wide range of jobs, and simple to use. | depends on the quantity and caliber of the visual vocabulary; loses temporal and spatial information. | [31] |
| **Fisher Kernels on Visual Vocabularies for Image Categorization** | Fisher Kernels on Visual Vocabularies for Image Categorizatio | uses Gaussian Mixture Models to represent data and encodes higher-order statistics of the features to improve the BOW model. | gathers more precise data than BOW, performs better across a wide range of activities, and is resilient to change. | computationally demanding, more difficult to execute, and requires careful parameter adjustment. | [32] |

**CONCLUSION**

In this review, we compared several approaches for human action recognition (HAR), including holistic feature representation, local feature representation, trajectory-based methods, Bag of Words (BoW), and Fisher Vector descriptors. Each of these approaches offers unique strengths and weaknesses, making them suitable for different applications and scenarios.

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