

Infor. Cons

7. XII. 2020

- breakpoint en mode debug.

RUN / Start Debugging



passe l'affichage en mode debug

```
19
20     printf("argc=%d\n", argc);
21     for (k = 0; k < argc; k++)
22     {
23         printf("argv[%d]=%s\n", k, argv[k]);
24     }
```

A screenshot of a debugger interface showing a code editor and a status bar. The code editor contains a C program with a for loop that prints argv values. The status bar shows 'Expression' followed by a dropdown menu with 'k==3'. A yellow oval highlights the value 'k==3' in the dropdown, and a yellow arrow points from it to the handwritten note 'point d'arrêt conditionné'.

point d'arrêt
conditionné

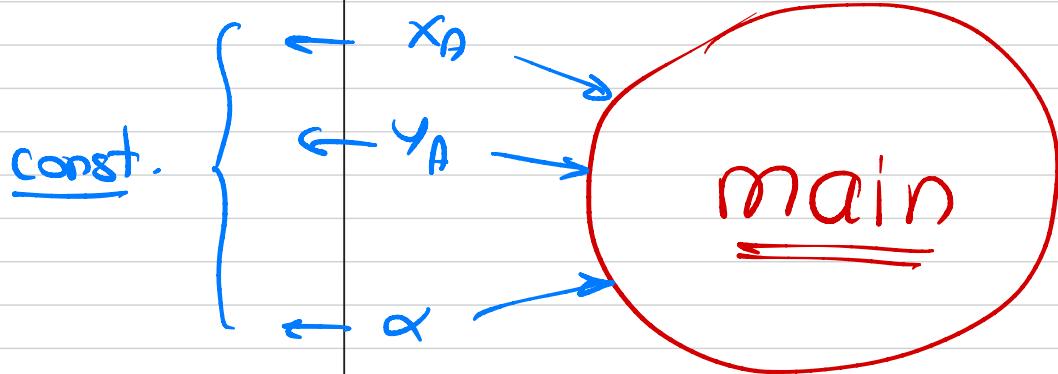
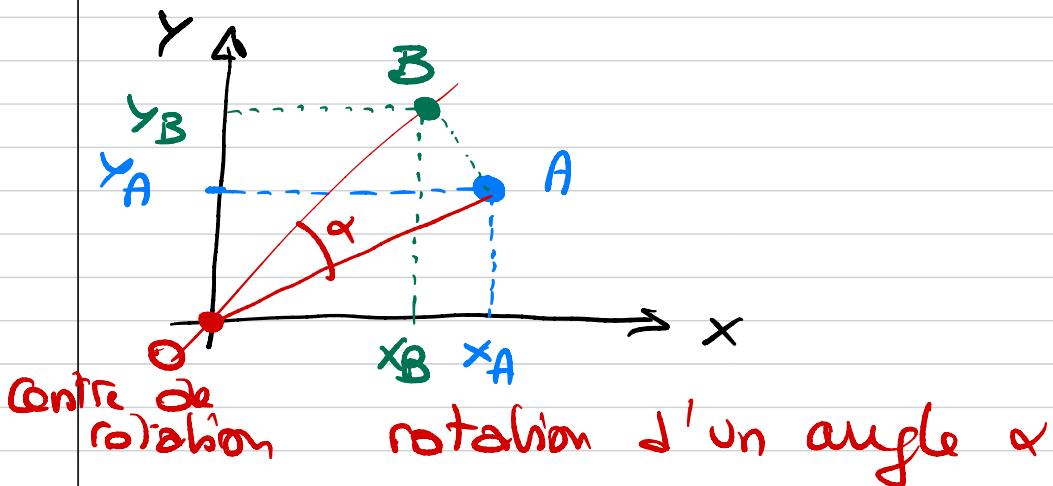
sur $k == 3$

Call Stack

TD 2020/2021

Rotation

Utilisation d'une matrice 2D pour calculer les coordonnées d'un point après rotation.



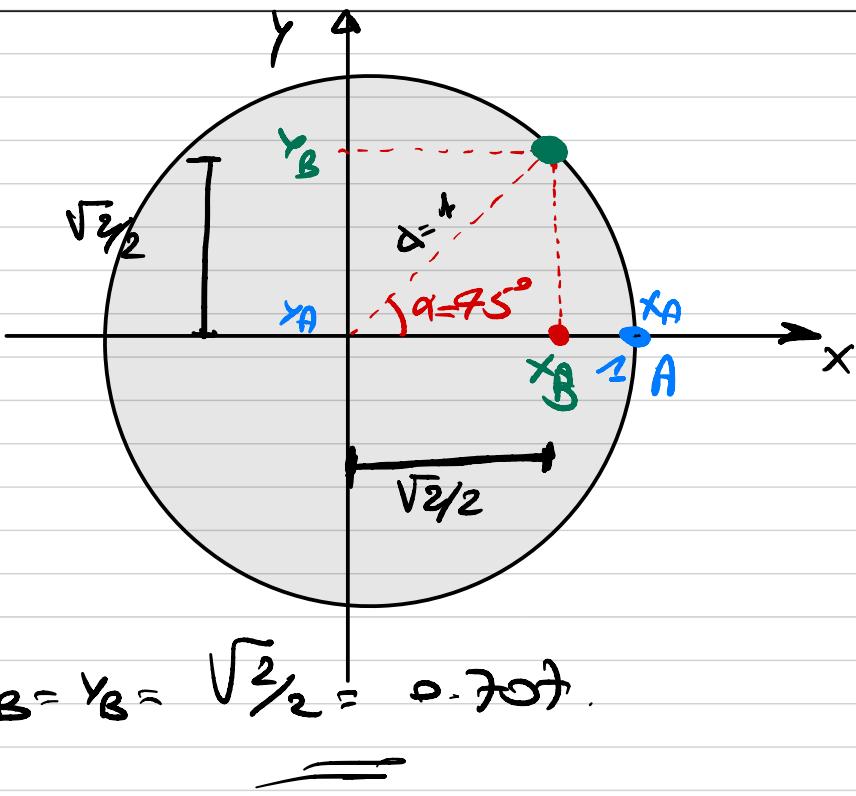
Calculer et afficher
 x_B et y_B
{ % + .3 pp.

$$x_B = x_A \cos \alpha + y_A (-\sin \alpha)$$

$$y_B = x_B \sin \alpha + y_B \cos \alpha$$

AN: $x_A = 2$. $y_A = 0$. $\alpha = 45^\circ$

15%



$$\begin{pmatrix} X_B \\ Y_B \end{pmatrix} = \begin{bmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{bmatrix} \cdot \begin{pmatrix} X_A \\ Y_A \end{pmatrix}$$

$$B = M \cdot A$$

$$B = \begin{bmatrix} X_B \\ Y_B \end{bmatrix}$$

$$A = \begin{bmatrix} X_A \\ Y_A \end{bmatrix}$$

$$M = \begin{bmatrix} \square & \square \\ \square & \square \end{bmatrix}$$

2 lignes
1 colonne

→ dimension : 2 lignes
1 colonne

2 lignes
2 colonnes

Ajoutons

cos 3

variables

28

① créer A sous la forme d'un tableau
de 2 lignes et 1 colonne

② — B —
— 2 lignes et 1 colonne

③ — C —
— 2 lignes et 2 colonnes

initialisation à \emptyset .

double A[2][1] = {

{ Ø, Ø,
{ Ø, Ø,

f;

double A[2]={

{ Ø, Ø,
{ Ø

double $A[2][1] = \{$

{ \emptyset, \emptyset
{ \emptyset, \emptyset

f;

double $A[2] = \{$

{ \emptyset, \emptyset
{ \emptyset

double $B[2] = \{ \emptyset, \emptyset \}$

double $M[2][2] = \{$

#lignes

#colonnes

1^{er} Ugn

{ $\emptyset, \emptyset \}$

{ $\emptyset, \emptyset \}$

2nd Ugn

Remplir les éléments A et M

(x_A y_A $\cos(\alpha)$ $\sin(\alpha)$...)

#define M 2
#define N 2

```
double a[M] = {0,0};  
double b[M] = {0,0};  
double m[M][N] = {  
    {0,0},  
    {0,0}  
};
```

```
a[0] = xa;  
a[1] = ya;  
m[0][0] = cos(alpha_rad); // ligne 1, col 1  
m[0][1] = -sin(alpha_rad); // ligne 1, col 2  
m[1][0] = sin(alpha_rad); // ligne 2, col 1  
m[1][1] = cos(alpha_rad); // ligne 2, col 2
```

3f

2x2

If A is an $m \times n$ matrix and B is an $n \times p$ matrix,

$$A = \begin{pmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{pmatrix}, \quad B = \begin{pmatrix} b_{11} & b_{12} & \cdots & b_{1p} \\ b_{21} & b_{22} & \cdots & b_{2p} \\ \vdots & \vdots & \ddots & \vdots \\ b_{n1} & b_{n2} & \cdots & b_{np} \end{pmatrix} \quad 2 \times 2$$

the matrix product $C = AB$ (denoted without multiplication signs or dots) is defined to be the $m \times p$ matrix [6][7][8][9]

$$C = \begin{pmatrix} c_{11} & c_{12} & \cdots & c_{1p} \\ c_{21} & c_{22} & \cdots & c_{2p} \\ \vdots & \vdots & \ddots & \vdots \\ c_{m1} & c_{m2} & \cdots & c_{mp} \end{pmatrix}$$

(C) = [A][B]

2x1

such that

$$c_{ij} = a_{i1}b_{1j} + a_{i2}b_{2j} + \cdots + a_{in}b_{nj} = \sum_{k=1}^n a_{ik}b_{kj},$$

for $i = 1, \dots, m$ and $j = 1, \dots, p$.

ligne i , colonne j

$$c_{ij} = \sum_{k=1}^n a_{ik} \cdot b_{kj}$$

for ($k = \phi$; $k < N$; $k++$)

If \mathbf{A} is an $m \times n$ matrix and \mathbf{B} is an $n \times p$ matrix,

$$\mathbf{A} = \begin{pmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{pmatrix}, \quad \mathbf{B} = \begin{pmatrix} b_{11} & b_{12} & \cdots & b_{1p} \\ b_{21} & b_{22} & \cdots & b_{2p} \\ \vdots & \vdots & \ddots & \vdots \\ b_{n1} & b_{n2} & \cdots & b_{np} \end{pmatrix}$$

the matrix product $\mathbf{C} = \mathbf{AB}$ (denoted without multiplication signs or dots) is defined to be the $m \times p$ matrix [6][7][8][9]

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such that

$$c_{ij} = a_{i1}b_{1j} + a_{i2}b_{2j} + \cdots + a_{in}b_{nj} = \sum_{k=1}^n a_{ik}b_{kj},$$

for $i = 1, \dots, m$ and $j = 1, \dots, p$.

$$\mathbf{B} = M \cdot \mathbf{A}$$

$$\begin{bmatrix} x_B \\ y_B \end{bmatrix} = \begin{bmatrix} \vdots & \vdots & \vdots \end{bmatrix} \begin{bmatrix} x_A \\ y_A \end{bmatrix}$$

$$\begin{bmatrix} B[0] \\ B[1] \end{bmatrix} = \begin{bmatrix} M[0][0] & M[0][1] \\ M[1][0] & M[1][1] \end{bmatrix} \begin{bmatrix} A[0] \\ A[1] \end{bmatrix}$$

$$B[0] = M[0][0] \cdot A[0] + M[0][1] \cdot A[1]$$

$$B[1] = M[1][0] \cdot A[0] + M[1][1] \cdot A[1]$$

boucle sur les lignes
"i"

$$j = [0 \dots M[$$

#boucles

$$k: [\emptyset \dots N[$$

2 boucles imbriquées

for (i=0 ... , i)

for (k=0 ... , k)
 \equiv calcul de $B[i]$

f.