

# Chapter 7: Problems with Predictors

## Problems with Predictors

- Errors in predictors
- Change of scale
- Collinearity

## Errors in Predictors

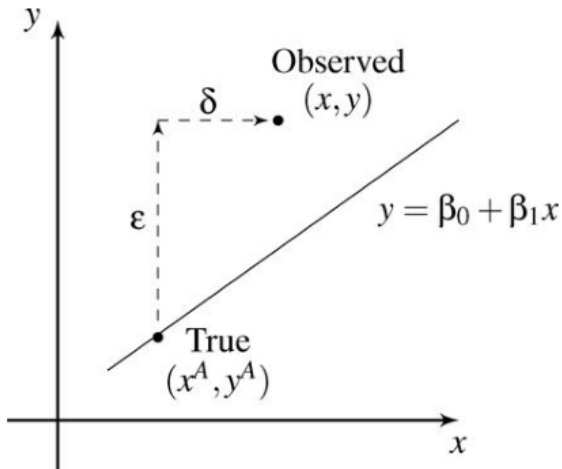


Figure: Measurement error: true vs. observed data

## Errors in Predictors

Consider **simple regression** as example.

The  $X$  we observe is not the  $X$  that generates the  $y$ .

$$y_i^O = y_i^A + \epsilon_i$$

$$x_i^O = x_i^A + \delta_i$$

The true relationship is:

$$y_i^A = \beta_0 + \beta_1 x_i^A$$

We get:

$$y_i^O = \beta_0 + \beta_1 x_i^O + (\epsilon_i - \beta_1 \delta_i)$$

## Notations and Assumptions

Assume  $E(\epsilon_i) = E(\delta_i) = 0$

Let

$$\text{var}(\epsilon_i) = \sigma_\epsilon^2$$

$$\text{var}(\delta_i) = \sigma_\delta^2$$

$$\sigma_x^2 = \sum (x_i^A - \bar{x}^A)^2 / n$$

$$\sigma_{x\delta} = \text{cov}(x^A, \delta)$$

## Effect on the fit

We use least squares to estimate  $\beta_1$ . It turns out

$$E(\hat{\beta}_1) = \beta_1 \times \left[ \frac{\sigma_x^2 + \sigma_{x\delta}}{\sigma_x^2 + \sigma_\delta^2 + 2\sigma_{x\delta}} \right]$$

**Scenario 1.**  $x^A$  and  $\delta$  are unrelated, i.e.,  $\sigma_{x\delta} = 0$ . Then

$$E(\hat{\beta}_1) = \beta_1 \times \left[ \frac{1}{1 + \sigma_\delta^2 / \sigma_x^2} \right] \leq \beta_1$$

- Shrinks toward 0
- If  $\sigma_x^2 \gg \sigma_\delta^2$ , the error can be ignored.

## Simulation Example

**Model:**  $\beta_1 = 1$

$$y^O = x^A + \epsilon$$

```
## No error in X
```

```
> xA <- 10*runif(50)
```

```
> yA <- xA
```

```
> yO <- yA + rnorm(50)
```

```
> summary(lm(yO ~ xA))
```

Coefficients:

	Estimate	Std.Error	t value	Pr(> t )
(Intercept)	-0.23841	0.28125	-0.848	0.401
xA	1.06733	0.05414	19.715	<2e-16

## Model:

$$y^O = x^O + \delta + \epsilon$$

```
> x0 <- xA + rnorm(50)
```

```
> summary(lm(y0 ~ x0))
```

Coefficients:

	Estimate	Std.Error	t value	Pr(> t )
(Intercept)	0.56790	0.33005	1.721	0.0918
x0	0.89873	0.06198	14.501	<2e-16

## Larger errors

```
> x0_2 <- xA + 5*rnorm(50)
```

```
> summary(lm(y0 ~ x0_2))
```

Coefficients:

	Estimate	Std.Error	t value	Pr(> t )
(Intercept)	4.34652	0.49175	8.839	1.23e-11
x0_2	0.07710	0.07035	1.096	0.279



## Effect on the fit

**Scenario 2.** Consider two possibilities:

- $x^A$  is fixed, but measured as  $x^O$ . If measurement is repeated,  $x^A$  is the same, but  $x^O$  will change.
- $x^O$  is fixed, while  $x^A$  changes at every repetition. In this case,

$$\sigma_{x\delta} = \text{cov}(X^O - \delta, \delta) = -\sigma_\delta^2$$

Hence  $E(\hat{\beta}_1) = \beta_1$ .

```
## Observed X are fixed
> x0 <- seq(0, 10, length=50)
> xA <- x0 + 5*rnorm(50)
> y0 <- xA + rnorm(50)
> summary(lm(y0 ~ x0))
```

Coefficients:

	Estimate	Std.Error	t value	Pr(> t )
(Intercept)	1.0942	1.3962	0.784	0.437060
x0	0.8581	0.2406	3.567	0.000832

## Change of Scale

$$x_j \rightarrow \frac{x_j + a}{b}$$

- Predictors of similar magnitude are easier to compare.
- Numerical stability
- Easy interpretation

## Consequences

- Rescaling  $x_j$  leaves the  $t$  and  $F$  tests and  $\hat{\sigma}^2$  and  $R^2$  unchanged.

$$\hat{\beta}_j \rightarrow b\hat{\beta}_j$$

- Rescaling  $y$  leaves the  $t$  and  $F$  tests and  $R^2$  unchanged but both  $\hat{\sigma}$  and  $\hat{\beta}$  rescaled by  $b$ ;  $\hat{\beta}_0$  is both shifted by  $a$  and rescaled by  $b$ .

## Savings Example

```
> data(savings)
> result <- lm(sr ~ ., data=savings)
> summary(result)
```

Coefficients:

	Estimate	Std.Error	t value	Pr(> t )
Intercept	28.5666100	7.3544986	3.884	0.000334
pop15	-0.4612050	0.1446425	-3.189	0.002602
pop75	-1.6915757	1.0835862	-1.561	0.125508
dpi	-0.0003368	0.0009311	-0.362	0.719296
ddpi	0.4096998	0.1961961	2.088	0.042468

Residual standard error: 3.803 on 45 degrees of freedom

Multiple R-Squared: 0.3385    Adjusted R-squared: 0.2797

F-statistic: 5.756 on 4 and 45 DF    p-value: 0.0007902

## Savings Example

```
## Scale one predictor variable  
> summary(lm(sr ~ pop15 + pop75 + I(dpi/1000)  
  + ddpi, data=savings))
```

Coefficients:

	Estimate	Std.Error	t value	Pr(> t )
(Intercept)	28.5666	7.3545	3.884	0.000334
pop15	-0.4612	0.1446	-3.189	0.002602
pop75	-1.6916	1.0836	-1.561	0.125508
I(dpi/1000)	-0.3368	0.9311	-0.362	0.719296
ddpi	0.4097	0.1962	2.088	0.042468

Residual standard error: 3.803 on 45 degrees of freedom

Multiple R-Squared: 0.3385      Adjusted R-squared: 0.2797

F-statistic: 5.756 on 4 and 45 DF      p-value: 0.0007902

## Standardizing variables

- Convert all variables to standard units (mean 0, variance 1)
- Can compare coefficients directly
- Helps numerical stability
- Interpretation may be easier or harder

```
## Standardize all variables
```

```
> sctemp <- data.frame(scale(savings))
```

```
> summary(lm(sr ~ ., data=sctemp))
```

Coefficients:

	Estimate	Std.Error	t value	Pr(> t )
Intercept	-2.453e-16	1.200e-01	-2.04e-15	1.0000
pop15	-9.420e-01	2.954e-01	-3.189	0.0026
pop75	-4.873e-01	3.122e-01	-1.561	0.1255
dpi	-7.448e-02	2.059e-01	-0.362	0.7193
ddpi	2.624e-01	1.257e-01	2.088	0.0425

Residual standard error: 0.8487 on 45 degrees of freedom

Multiple R-Squared: 0.3385      Adjusted R-squared: 0.2797

F-statistic: 5.756 on 4 and 45 DF      p-value: 0.0007902



# Collinearity

- Collinearity:  $X^T X$  close to singular
- Cause: some predictors are (almost) linear combinations of others.
- Detection:
  - **Correlation matrix**: large pairwise correlation
  - Regress  $x_j$  on other predictors – get  $R_j^2$ .  
 $R_j^2$  close to 1 indicates a problem
  - **Condition number** of  $X^T X$ :  $\kappa = \sqrt{\frac{\lambda_1}{\lambda_{p+1}}}$   
where  $\lambda_1$  is the largest eigenvalue and  $\lambda_{p+1}$  is the minimum eigenvalue of  $X^T X$ .
  - Rule of Thumb:  $\kappa > 30$  are signs of collinearity.

## Consequences of Collinearity

- Imprecise estimate of  $\beta$
- Inflated standard error
- $t$ -test fails to reveal significant predictors
- Sensitivity to measurement errors
- Numerical instability

## Collinearity Continued

Why? Let  $S_{x_j} = \sum_i (x_{ij} - \bar{x}_j)^2$ , then

$$\text{var}(\hat{\beta}_j) = \sigma^2 \left( \frac{1}{1 - R_j^2} \right) \frac{1}{S_{x_j}}$$

- Variance inflation factor (VIF):  $\frac{1}{1 - R_j^2}$
- Spread of  $x_j$ 
  - Rule of Thumb:  $\text{VIF} > 10$  are signs of collinearity.

## Car Example

- Car drivers adjust the seat position for comfort
- Response: seat position
- Predictors: age, weight, height with and without shoes, seated height, arm length, thigh length, lower leg length

```
> data(seatpos)
> result <- lm(hipcenter ~ ., data=seatpos)
> summary(result)
```

Coefficients:

	Estimate	Std.Error	t value	Pr(> t )
(Intercept)	436.43213	166.57162	2.620	0.0138
Age	0.77572	0.57033	1.360	0.1843
Weight	0.02631	0.33097	0.080	0.9372
HtShoes	-2.69241	9.75304	-0.276	0.7845
Ht	0.60134	10.12987	0.059	0.9531
Seated	0.53375	3.76189	0.142	0.8882
Arm	-1.32807	3.90020	-0.341	0.7359
Thigh	-1.14312	2.66002	-0.430	0.6706
Leg	-6.43905	4.71386	-1.366	0.1824

Residual standard error: 37.72 on 29 degrees of freedom

Multiple R-Squared: 0.6866      Adjusted R-squared: 0.6001

F-statistic: 7.94 on 8 and 29 DF      p-value: 1.306e-05

## Collinearity: 1

```
## Correlation matrix
```

```
> round(cor(seatpos)[2:7, 2:7], 2)
```

	Weight	HtShoes	Ht	Seated	Arm	Thigh
Weight	1.00	0.83	0.83	0.78	0.70	0.57
HtShoes	0.83	1.00	1.00	0.93	0.75	0.72
Ht	0.83	1.00	1.00	0.93	0.75	0.73
Seated	0.78	0.93	0.93	1.00	0.63	0.61
Arm	0.70	0.75	0.75	0.63	1.00	0.67
Thigh	0.57	0.72	0.73	0.61	0.67	1.00

## Collinearity: 3

```
## Condition number
> X <- model.matrix(result)[, -1]
> e <- eigen(t(X) %*% X)
> e$val
[1] 3.653671e+06 2.147948e+04 9.043225e+03
[4] 2.989526e+02 1.483948e+02 8.117397e+01
[7] 5.336194e+01 7.298209e+00
> round(sqrt(e$val[1]/e$val), 3)
[1] 1.000 13.042 20.100 110.551 156.912
[6] 212.156 261.667 707.549
```

## Collinearity: 2

```
## Variance inflation factor
```

```
> library(faraway)
```

```
> round(vif(X), 3)
```

Age	Weight	HtShoes	Ht	Seated
1.998	3.647	307.429	333.138	8.951
Arm	Thigh	Leg		
4.496	2.763	6.694		



## Consequence of Collinearity

## Sensitivity to measurement errors

```
> junk <- lm(hipcenter + 10*rnorm(38) ~ ., data=seatpos)
> summary(junk)
```

Coefficients:

	Estimate	Std.Error	t value	Pr(> t )
(Intercept)	431.13413	176.13709	2.448	0.0207
Age	0.60041	0.60308	0.996	0.3277
Weight	-0.10886	0.34998	-0.311	0.7580
HtShoes	-3.86967	10.31311	-0.375	0.7102
Ht	1.33472	10.71159	0.125	0.9017
Seated	0.79736	3.97792	0.200	0.8425
Arm	-0.01702	4.12417	-0.004	0.9967
Thigh	-1.54993	2.81278	-0.551	0.5858
Leg	-4.73289	4.98456	-0.950	0.3502

```
## Correlation of variables measuring length
```

```
> round(cor(X[, 3:8]), 2)
```

	HtShoes	Ht	Seated	Arm	Thigh	Leg
HtShoes	1.00	1.00	0.93	0.75	0.72	0.91
Ht	1.00	1.00	0.93	0.75	0.73	0.91
Seated	0.93	0.93	1.00	0.63	0.61	0.81
Arm	0.75	0.75	0.63	1.00	0.67	0.75
Thigh	0.72	0.73	0.61	0.67	1.00	0.65
Leg	0.91	0.91	0.81	0.75	0.65	1.00

```
## Using a subset of predictor variables
> result2 <- lm(hipcenter ~ Age + Weight + Ht,
  data=seatpos)
> summary(result2)
Coefficients:
```

	Estimate	Std.Error	t value	Pr(> t )
Intercept	528.297729	135.31295	3.904	0.000426
Age	0.519504	0.408039	1.273	0.211593
Weight	0.004271	0.311720	0.014	0.989149
Ht	-4.211905	0.999056	-4.216	0.000174

Residual standard error: 36.49 on 34 degrees of freedom  
Multiple R-Squared: 0.6562    Adjusted R-squared: 0.6258  
F-statistic: 21.63 on 3 and 34 DF    p-value: 5.125e-08

## What to do about collinearity

- If you mostly care about prediction, drop highly correlated predictors
- Variable selection may be used (Ch 8)
- If interpretation is important and you must keep all predictors, do not use least squares. Use some other estimation method, e.g., ridge regression (Ch 9)