Chapter 7: Problems with the Error

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Lecture Note

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What can go wrong with the errors?

Recall we assumed $\epsilon \sim \textit{N}(0, \sigma^2\textit{I})$

- Unequal variance
- Correlated
- Heavy-tailed

Weighted Least Squares

Errors uncorrelated, but unequal variance, i.e.,

$$\epsilon \sim N(0, \sigma^2 W^{-1})$$

where

$$W^{-1} = diag(1/w_1, \dots, 1/w_n)$$

Examples:

- Error variance proportional to the response: $w_i = y_i^{-1}$
- y_i is the average of n_i observations: $w_i = n_i$
- y_i is the sum of n_i observations: $w_i = n_i^{-1}$

Estimates

Transformation:

$$y_i \rightarrow \sqrt{w_i}y_i$$

 $x_i \rightarrow \sqrt{w_i}x_i$

Regress $\sqrt{w_i}y_i$ on $\sqrt{w_i}x_i$. Then

$$\hat{\beta} = (X^T W X)^{-1} X^T W y$$
$$var(\hat{\beta}) = (X^T W X)^{-1} \sigma^2$$

French Election Example

- French presidential election in 1981
- 10 candidates in the first round, top 2 in the second round
- Who do the votes go to in the second round?

French Election Model Selection

Model:

$$A2 = \beta_A A + \beta_B B + \beta_C C + \beta_D D + \beta_E E + \beta_F F + \beta_G G + \beta_H H + \beta_J J + \beta_K K + \beta_N N + \epsilon$$

where β_i represents the proportion of votes transferred from candidate i to A_2 .

- Constraint
 - $0 < \beta_i < 1$ for all i.

French Election Model Selection

French Election Model Selection

There exists a package 'mgcv' which automatically enforce all coefficients falling into [0, 1].

- See an example in page 118.

Issue of Finding Weights

In most cases, finding weights is not easy.

- $\omega_i \propto n_i$
- $\omega_i \propto \frac{1}{n_i}$
- $\omega_i \propto x_i$
- $\omega_i \propto \gamma_0 + x_i^{\gamma_1}$

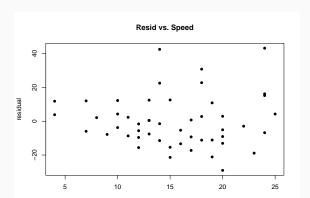
Cars Example

Speed and Stopping Distances of Cars

The data gives the speed of cars and the distances taken to stop.

A data frame with 50 observations on 2 variables.

- speed Speed (mph)
- dist Stopping distance (ft)



Cars Example

```
> require(nlme)
> wlmod = gls(dist~ speed, data = cars,
weight = varConstPower(1, form = ~speed))
> summary(wlmod)
Variance function:
Structure: Constant plus power of variance covariate
Formula: ~speed
Parameter estimates:
const power
3.160444 1.022368
Coefficients:
Value Std.Error t-value p-value
(Intercept) -11.085378 4.052378 -2.735524 0.0087
speed 3.484162 0.320237 10.879947 0.0000
Correlation:
(Intr)
speed -0.9
```

Generalized Least Squares (GLS)

In general

$$\epsilon \sim N(0, \sigma^2 \Sigma)$$

Write

$$\Sigma = SS^T$$

where S is a lower triangular matrix (the Cholesky decomposition).

Transformation:

$$y \rightarrow S^{-1}y$$
$$x \rightarrow S^{-1}x$$

Estimates:

$$\hat{\beta} = (X^T \Sigma^{-1} X)^{-1} X^T \Sigma^{-1} y$$
$$var(\hat{\beta}) = (X^T \Sigma^{-1} X)^{-1} \sigma^2$$

Employment Example

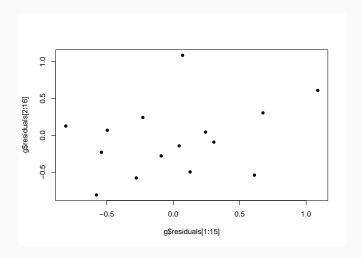
- Employment data from 1947 to 1962
- Response: number of people employed (yearly)
- Predictors: gross national product and population over 14

- Data collected over time: errors could be correlated
- One of the simplest correlation structures over time: the autoregressive model – here AR(1):

$$\epsilon_{i+1} = \phi \epsilon_i + \delta_i$$

where δ_i are i.i.d. $N(0, \tau^2)$.

Employment Example



```
## Fit GLS with AR(1) structure
> library(nlme)
> g <- gls(Employed ~ GNP + Population,
   correlation=corAR1(form=~Year), data=longley)
> summary(g)
Correlation Structure: AR(1)
 Formula: ~Year
 Parameter estimate(s):
     Phi 0.6441692
Coefficients:
             Value Std.Error t-value p-value
Intercept 101.85813 14.198932 7.173647 <.0001
           0.07207 0.010606 6.795485 <.0001
GNP
Population -0.54851 0.154130 -3.558778 0.0035
Residual standard error: 0.689207
Degrees of freedom: 16 total; 13 residual
```

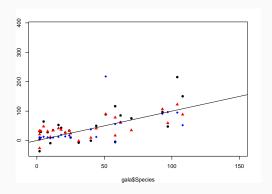
ANOVA Test

Lack of Fit: ANOVA test

How well does a model fit the data?

- If the model is correct, then $\hat{\sigma} \approx \sigma$.
- Otherwise, $\hat{\sigma} \gg \sigma$.

ANOVA test



Simulation Study: Polynomial Model

```
> lm_red = lm(v \sim x)
> lm full =lm(v \sim x + I(x^2))
> anova(lm red.lm full)
Analysis of Variance Table
Model 1: y ~ x
Model 2: y \sim x + I(x^2)
Res.Df RSS Df Sum of Sq F Pr(>F)
1 98 2273759
2 97 91 1 2273668 2426999 < 2.2e-16 ***
---
Signif. codes: 0 '*** 0.001 '** 0.01 '* 0.05 '.' 0.1 ' 1
> lm_red = lm(v \sim x + I(x^2))
> lm_full = lm(y ~ x + I(x^2) + I(x^3))
> anova(lm red.lm full)
Analysis of Variance Table
Model 1: v \sim x + I(x^2)
Model 2: v \sim x + I(x^2) + I(x^3)
Res.Df RSS Df Sum of Sq F Pr(>F)
1 97 90.872
2 96 88.859 1 2.0132 2.175 0.1435
```

Simulation Study: Polynomial Model

```
Coefficients:
Estimate Std. Error t value Pr(>|t|)
(Intercept) 99.614 15.411 6.464 3.99e-09 ***
       -3.986 1.498 -2.661 0.00911 **
x
Signif. codes: 0 '*** 0.001 '** 0.01 '* 0.05 '. '0.1 ' 1
Residual standard error: 152.3 on 98 degrees of freedom
Multiple R-squared: 0.06737, Adjusted R-squared: 0.05786
F-statistic: 7.08 on 1 and 98 DF, p-value: 0.009111
Coefficients:
Estimate Std. Error t value Pr(>|t|)
(Intercept) -0.0288700 0.1169616 -0.247 0.806
          0.0104287 0.0098592 1.058 0.293
x
I(x^2) 1.0006549 0.0006423 1557.883 <2e-16 ***
Signif. codes: 0 '*** 0.001 '** 0.01 '* 0.05 '. 0.1 ' 1
Residual standard error: 0.9679 on 97 degrees of freedom
Multiple R-squared: 1, Adjusted R-squared:
F-statistic: 1.301e+06 on 2 and 97 DF, p-value: < 2.2e-16
```

Simulation Study

```
Coefficients:
Estimate Std. Error t value Pr(>|t|)
(Intercept) -7.916e-02 1.212e-01 -0.653 0.515
x -9.183e-03 1.652e-02 -0.556 0.580
I(x^2) 1.001e+00 7.363e-04 1359.836 <2e-16 ***
I(x^3) 6.495e-05 4.404e-05 1.475 0.144
---
Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
Residual standard error: 0.9621 on 96 degrees of freedom
Multiple R-squared: 1,Adjusted R-squared: 1
F-statistic: 8.78e+05 on 3 and 96 DF, p-value: < 2.2e-16
```

Robust Regression

Main concern: heavy-tailed error distribution

- M-estimation
- Least trimmed squares

M-estimation

Definition:

• Find β to minimize

$$\sum_{i=1}^{n} L(y_i - x_i^T \beta)$$

 $L(\cdot)$ is called the loss function.

Possible loss functions:

• $L(z) = z^2$ least squares (LS)

$$\beta = \arg\min \sum_{i=1}^{n} (y_i - x_i^T \beta)^2$$

• L(z) = negative log likelihood.

M-estimation Continued

Possible loss functions:

• least absolute deviations (LAD), L(z) = |z|

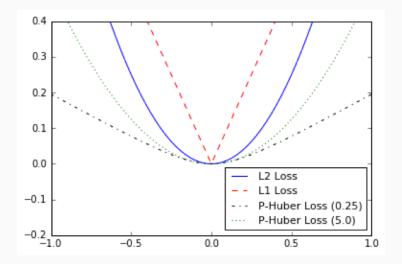
$$\beta = \arg\min \sum_{i=1}^{n} |y_i - x_i^T \beta|$$

Huber's method

$$L(z) = \begin{cases} z^2/2 & \text{if } |z| \le c \\ c|z| - c^2/2 & \text{otherwise} \end{cases}$$

c should be a robust estimate of σ , e.g., the median of $|\hat{\epsilon}_i|$.

LS vs LAD vs Huber



Gala Example

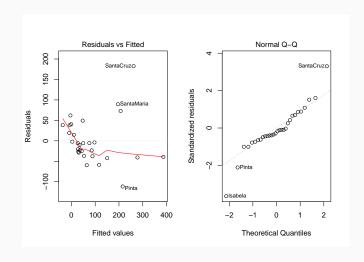
Recall from Ch. 2: Number of species of tortoise on the various Galapagos islands

- Response: number of species of tortoise
- Predictors: number of endemic species, area of the island, highest elevation of the island, distance from the nearest island, distance from Santa Cruz Island, area of the adjacent island

Gala Example: LSE

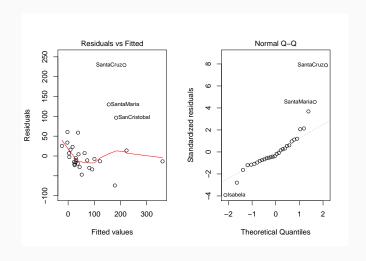
```
> data(gala)
## Least squares
> g <- lm(Species ~ Area + Elevation + Nearest
   + Scruz + Adjacent, data=gala)
> summary(g)
Coefficients:
           Estimate Std.Error t value Pr(>|t|)
(Intercept) 7.068221 19.154198 0.369 0.715351
Area
          -0.023938 0.022422 -1.068 0.296318
Elevation 0.319465 0.053663 5.953 3.82e-06
Nearest 0.009144 1.054136 0.009 0.993151
Scruz -0.240524 0.215402 -1.117 0.275208
Adjacent -0.074805 0.017700 -4.226 0.000297
Residual standard error: 60.98 on 24 degrees of freedom
Multiple R-Squared: 0.7658 Adjusted R-squared: 0.7171
F-statistic: 15.7 on 5 and 24 DF p-value: 6.838e-07
```

Gala Example: LSE Diagnostics



Gala Example: Huber

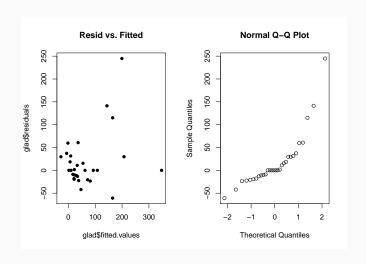
Gala Example: Huber Diagnostics



Gala Example: Least Absolute Deviations

```
## Least absolute deviations
> library(quantreg)
> glad <- rq(Species ~ Area + Elevation + Nearest
   + Scruz + Adjacent, data=gala)
> summary(glad)
Coefficients:
          coefficients lower bd
                              upper bd
(Intercept) 1.31445 -19.87777 24.37411
        -0.00306 -0.03185 0.52800
Area
Elevation 0.23211 0.12453 0.50196
Nearest 0.16366 -3.16339 2.98896
        -0.12314 -0.47987 0.13476
Scruz
Adjacent -0.05185
                      -0.10458
                                0.01739
```

Gala Example: LAD Diagnostics



Least Trimmed Squares (LTS)

LTS is a robust statistical method that fits a function to a set of data whilst not being unduly affected by the presence of outliers.

Minimize:

$$\sum_{i=1}^{m} \hat{\epsilon}_{(i)}^2$$

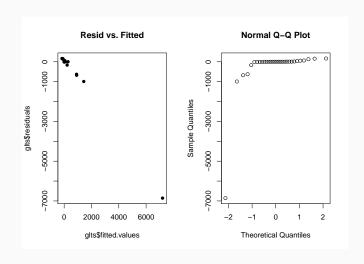
where m < n and (i) indicates sorting. Default m: $\lfloor n/2 \rfloor + \lfloor (p+1)/2 \rfloor$

- ignores largest residuals

Gala Example: LTS

```
## Least trimmed squares
> library(MASS)
> glts <- ltsreg(Species ~ Area + Elevation +
       Nearest + Scruz + Adjacent, data=gala)
> round(glts$coef, 3)
(Intercept) Area Elevation Nearest Scruz Adjacent
 8.975
       1.544 0.024 0.803 -0.117 -0.196
## Another try
> glts <- ltsreg(Species ~ Area + Elevation +
      Nearest + Scruz + Adjacent, data=gala)
> round(glts$coef, 3)
(Intercept) Area Elevation Nearest Scruz Adjacent
 9.321 1.512 0.032 0.559 -0.091 -0.196
 ## Exact solution - takes longer
 > glts <- ltsreg(Species ~ Area + Elevation +
 Nearest + Scruz + Adjacent, data=gala, nsamp = "exact")
 > glts$coef
  (Intercept)
                   Area Elevation Nearest
 9.38114511 1.54365847 0.02412458 0.81110889
 Scruz Adjacent
  -0.11773219 -0.19792333
```

Gala Example: LTS Diagnostics



Bootstrap

- We don't have the standard errors for the LTS regression coefficients.
- When we have no theory to compute SEs, can use bootstrap
- Fundamental idea: pretend the observed data is the population
- Resample observed data, create multiple samples
- From each sample, estimate parameters and assess variability

Bootstrap Continued

Simulation world:

- ullet Generate ϵ from the known error distribution
- Form $y = X\beta + \epsilon$ from the known β
- Compute $\hat{\beta}$
- useful for testing new methodology

Bootstrap world:

- Sampling with replacement from $\hat{\epsilon}_1, \dots, \hat{\epsilon}_n \Rightarrow \epsilon^*$
- Form $y^* = X\hat{\beta} + \epsilon^*$
- Compute $\hat{\beta}^*$ from (X, y^*)
- useful for assessing estimator uncertainty on real data when no theory is available

Gala Example: Inference

```
# extract matrix of predictors for ltsreg
> x <- gala[,3:7]
## bootstrap 1000 times
> bcoef <- matrix(0, nrow=1000, ncol=6)
> for (i in 1:1000) {
+      newy <- glts$fit + glts$resid[sample(30, rep=T)]
+      bcoef[i,] <- ltsreg(x, newy, nsamp="best")$coef
+ }

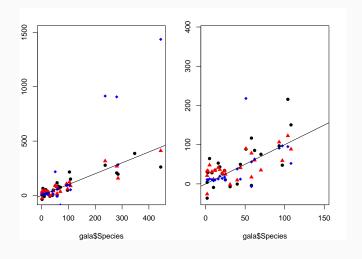
## 95% C.I. for Area
> quantile(bcoef[,2], c(0.025, 0.975))
      2.5% 97.5%
1.486674 1.689529
```

Gala Example

```
> g <- lm(Species ~ Area + Elevation + Nearest + Scruz + Adjacent, data=gala)
> which.max( cooks.distance(g) )
Isabela
16
## LS model w/o Isabela (the most influential point)
> gi <- lm(formula(g), data=gala,</pre>
subset=(row.names(gala) != 'Isabela'))
> gi$coef
(Intercept)
                Area Elevation
                                  Nearest
                                              Scruz
                                                      Adiacent
22.58614473 0.29574351 0.14039023 -0.25518223 -0.09010457 -0.06503051
> g$coef
(Intercept)
                       Elevation
                                     Nearest
                 Area
                                                  Scruz
                                                          Adiacent
7.068220709 -0.023938338 0.319464761 0.009143961 -0.240524230 -0.074804832
> glts$coef
(Intercept)
                 Area Elevation
                                     Nearest
                                                 Scruz
                                                          Adiacent
```

Gala Example

```
plot(gala$Species, g$fitted.values, pch = 16, ylim = c(-25,1500))
points(gala$Species[-16], gi$fitted.values, pch = 17, col="red")
points(gala$Species,glts$fitted.values, pch = 18, col="blue")
```



Remarks

- Two routes to the same goal:

Former more informative, but time-consuming; latter quick and suitable for large datasets.

• M-estimation failed to identify "Isabela"

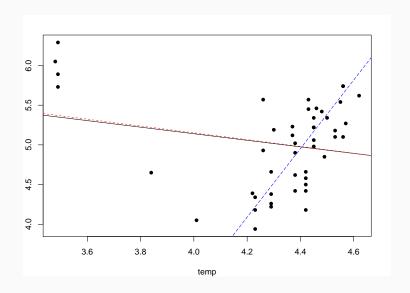
All models are wrong!

Star Example

- 47 stars in the star cluster CYG OB1
- Response: log of the light intensity
- Predictor: log of the surface temperature

```
## Compare LS, Huber and LTS
> data(star)
> plot(light ~ temp, data=star, xlab="temp", ylab="light")
> starls <- lm(light ~ temp, star)
> abline(starls$coef)
> starhuber <- rlm(light ~ temp, star)
> abline(starhuber$coef, lty=2)
> starlts <- ltsreg(light ~ temp, star, nsamp="exact")
> abline(starlts$coef, lty=5)
```

Star Example: LS vs Huber vs LTS



Summary: Robust methods

- Protect against outliers and heavy tails... but not misspecified structure (model or error)
- Theory not available for standard errors need bootstrap
- If robust and LS fits are very different, cause to worry
- Useful when automatic fitting is needed (no human intervention)