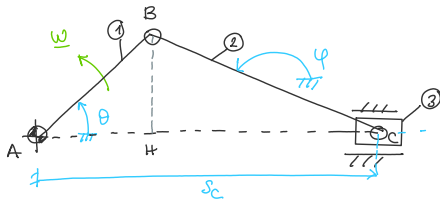


Eserc: An Cinem Posizione MDS

venerdì 22 novembre 2024 12:30

Nota : $AB = r = 68.1 \text{ mm}$
 $BC = l = 164 \text{ mm}$

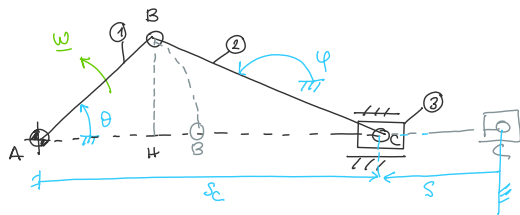
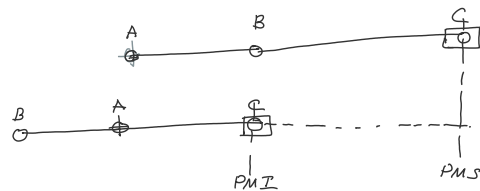
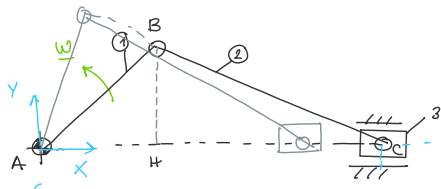


Nota $\theta(t), \dot{\theta}(t), \ddot{\theta}(t)$

↓ c.m. posiz.

Trovare $x(t), \dot{x}(t), \ddot{x}(t)$
 $s_c(t), \dot{s}_c(t), \ddot{s}_c(t)$ → $t = \bar{t}$

$$\left[\begin{array}{l} \theta(\bar{t}) = 45^\circ \\ \dot{\theta}(\bar{t}) = 6300 \text{ rpm} \approx 660 \text{ rad/s} \\ \ddot{\theta}(\bar{t}) = 0 \text{ rad/s}^2 \end{array} \right] \rightarrow \left[\begin{array}{l} \dot{s}_c(\bar{t}) \\ \ddot{s}_c(\bar{t}) \end{array} \right]$$



$E_P^{\text{ne chiusura}} \Rightarrow \varphi(t), s(t)$

$$\overrightarrow{AB}(t) + \overrightarrow{BC}(t) + \overrightarrow{CA}(t) = \mathbf{0}$$

$$\overrightarrow{AB}(t) = (r \cos \theta, r \sin \theta, 0)$$

$$\overrightarrow{BC}(t) = (-l \cos \varphi, -l \sin \varphi, 0)$$

$$\overrightarrow{CA}(t) = (-(r+l-s), 0, 0)$$

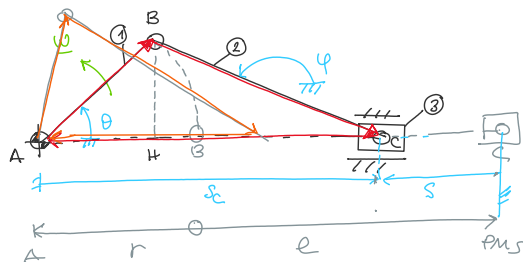
$$\begin{bmatrix} r \cos \theta \\ r \sin \theta \\ 0 \end{bmatrix} + \begin{bmatrix} -l \cos \varphi \\ -l \sin \varphi \\ 0 \end{bmatrix} + \begin{bmatrix} -(r+l-s) \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{array}{l} x: r \cos \theta - l \cos \varphi - (r+l-s) = 0 \\ y: r \sin \theta - l \sin \varphi = 0 \end{array}$$

$$\sin \varphi = \frac{r}{l} \sin \theta = \lambda \sin \theta \quad (1)$$

$$\lambda = \frac{r}{l}$$

0.1 - 1 (a)



$$\left\{ \begin{array}{l} s = r + l + l \cos \varphi - r \cos \theta \quad (2) \end{array} \right. \quad \boxed{\lambda} < 0.1 \quad (b)$$

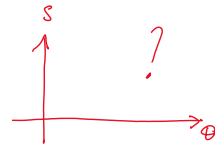
$$\cos \varphi = -\sqrt{1 - \sin^2 \varphi}$$

$$\stackrel{!}{=} -\sqrt{1 - \lambda^2 \sin^2 \theta}$$

$$\left\| \begin{array}{l} s(\theta) = s = r + l - l \sqrt{1 - \lambda^2 \sin^2 \theta} - r \cos \theta \\ \stackrel{!}{=} r \left[1 - \cos \theta + \frac{1}{\lambda} \left(1 - \sqrt{1 - \lambda^2 \sin^2 \theta} \right) \right] \end{array} \right\|$$

linearizziamo
-cos φ

SOLUZIONE
ESATTA DELLE
POSIZIONI DI C



$$\dot{s} = \frac{ds}{dt}$$

$$\ddot{s} = \frac{d\dot{s}}{dt}$$

$$(a) \quad \lambda = 0.1 - 1$$

$$x = -\lambda^2 \sin^2 \theta$$

$$x \rightarrow 0$$

$$\boxed{f(x)} = \sqrt{1+x} = (1+x)^{1/2} \quad \leftrightarrow \quad f'(\theta) = \sqrt{1 - \lambda^2 \sin^2 \theta}$$

$$x = x_0 = 0 \rightarrow \text{Sviluppo di serie di Taylor}$$

$$f(x) = f(x_0) + f'(x_0)(x-x_0) + \frac{f''(x_0)(x-x_0)^2}{2!} + o((x-x_0)^2)$$

$$f(x) = f(0) + f'(0)x + o(x)$$

$$f'(x) = \frac{1}{2} (1+x)^{-1/2}$$

$$\boxed{f(x)} = 1 + \frac{1}{2}x + o(x)$$

$$f(\theta) = 1 - \frac{1}{2} \lambda^2 \sin^2 \theta$$

$$s \approx r \left[1 - \cos \theta + \frac{1}{\lambda} \left(1 - 1 + \frac{1}{2} \lambda^2 \sin^2 \theta \right) \right]$$

$$\stackrel{!}{=} r \left[1 - \cos \theta + \frac{\lambda}{2} \sin^2 \theta \right]$$

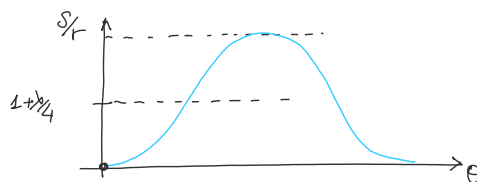
$$\sin^2 \theta = \frac{1 - \cos(2\theta)}{2}$$

$$\left\| \begin{array}{l} = r \left[1 + \frac{\lambda}{4} - \cos \theta - \frac{\lambda}{4} \cos(2\theta) \right] \end{array} \right\|$$

↓
VALORE MEDIO

$T_2 = 2\pi$ $T_1 = \pi$

SOL. APPROXIMATA
AL 2° ORDINE



$$\dot{s} = r \dot{\theta} \left[\sin \theta + \frac{\lambda}{2} \sin(2\theta) \right]$$

$$\ddot{s} = r \ddot{\theta} \left[\sin \theta + \frac{\lambda}{2} \sin(2\theta) \right] + r \dot{\theta}^2 [\cos \theta + \lambda \cos(2\theta)]$$

$$\ddot{s} (\dot{\theta} = 0) = r \dot{\theta}^2 [\cos \theta + \lambda \cos(2\theta)]$$

$$(b) \quad \lambda < 0.1$$

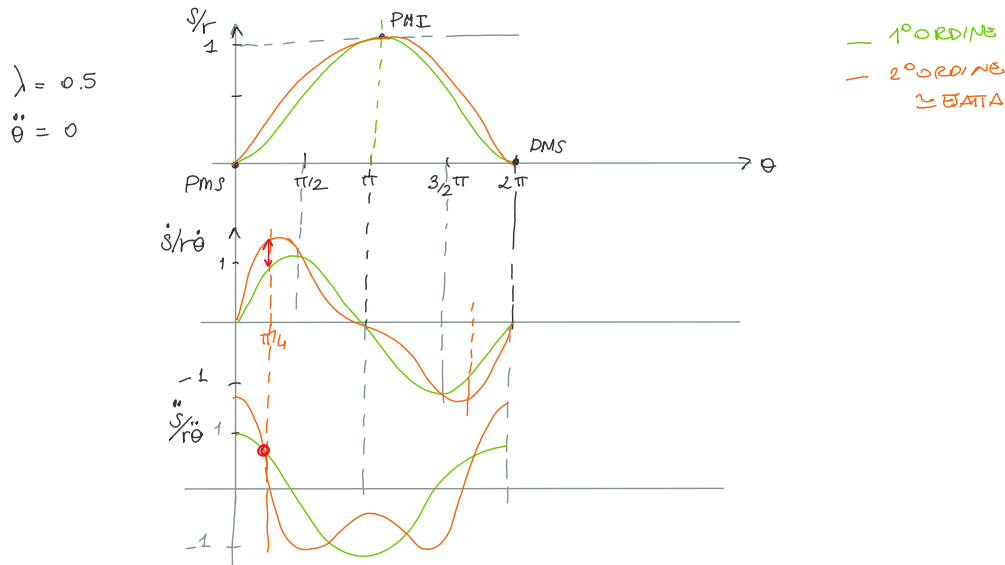
e) SVI. DER. TAYLOR \Rightarrow $f(x) \approx f(0)$
 $\cos x \approx -1$



$\lambda < 0.1$

$\frac{r}{l} < 0.1$

$s = r + l + l \cos \varphi - r \cos \theta$
 $\approx r - r \cos \theta$



$\theta = 45^\circ \leftarrow \boxed{t = \bar{t}}$
 $\hat{=} \pi/4$

s (m)

\dot{s} (m/s)

\ddot{s} (m/s²)

SOLU. BATA 4

0,0272

41,527

21566,4

SOLU. II ORD.

0,027 (0.7%)

41,097 (1%)

20959 (3%)

SOLU. I ORDIN.

0,0199 (27%)

31,769 (23%)

20959 (3%)

