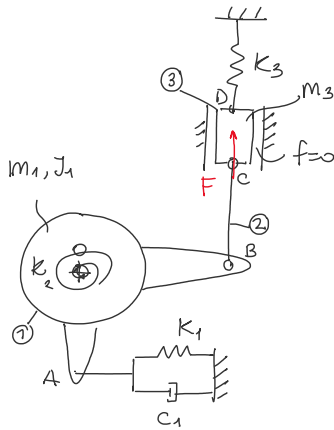


Esercizio oscillazioni forzate

venerdì 13 dicembre 2024 12:41



Nota:

$$\overline{OA} = a = 5 \text{ cm}$$

$$\overline{OB} = b = 10 \text{ cm}$$

$$J_1 = J_0 = 0,036 \text{ kg m}^2$$

$$O \equiv G_1$$

$$m_3 = 2 \text{ kg}$$

$$K_1 = 2 \text{ N/m}$$

$$K_2 = 0,05 \text{ N/m}$$

$$K_3 = 1 \text{ N/m}$$

$$C = 8,96 \text{ N s/m}$$

$$F = F_0 \cos(\omega t) \quad F_0 = 0,03 \text{ N}$$

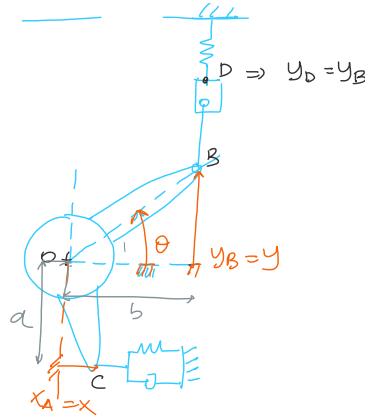
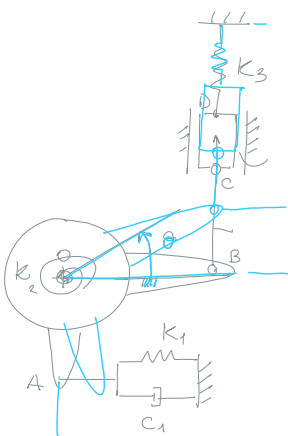
$$\omega = 1 \text{ rad/s}$$

Hp
piccole
oscillazioni

Valutare

- 1) Definire le coordinate + equi congruenza
- 2) Equazione moto
- 3) ω_n , ξ
- 4) legge oraria \Rightarrow diagramma ampiezza e fase
 \Downarrow
A REGIME

1) PROBLEMA A LQDL



$$\begin{aligned} x &= a \sin \theta \\ &\approx a \theta \\ y &= b \sin \theta \\ &\approx b \theta \end{aligned}$$

$\theta > 0, x > 0, y > 0$

$$\begin{cases} x = a \theta \\ \dot{x} = a \dot{\theta} \\ \ddot{x} = a \ddot{\theta} \end{cases} \quad \begin{cases} y = b \theta \\ \dot{y} = b \dot{\theta} \\ \ddot{y} = b \ddot{\theta} \end{cases}$$

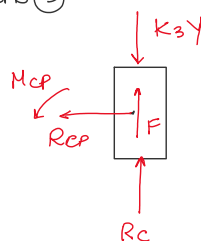
DCL

ASTA ②
SCALICA

$$R_C = R_B$$



CORPO ③



$$x: R_{CP} = 0$$

$$\sigma: M_{CP} = 0$$

$$-K_3 y + R_C + F = m \ddot{y} \quad \boxed{\text{Eq (1)}}$$

\downarrow

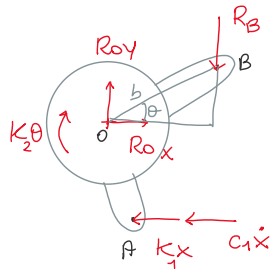
\downarrow

\downarrow

\downarrow

2 INCOGNITE

R_c, \ddot{y}



$R_{Ox}, R_{Ox}, R_B, \ddot{O}$
4 INCOG.

$$\text{Im} \langle \mathcal{D} | 0 \rangle = \underset{\substack{\parallel \\ R_e}}{R_B} b \cos \theta - (k_1 x + c_1 \dot{x}) a \cos \theta - k_2 \theta = J_0 \ddot{\theta}$$

$$\int -K_3 y + R_c + F = m_3 \ddot{y} \quad \text{Eq (1)}$$

$$\begin{cases} -K_3 y + R_c + F = m_3 \ddot{y} & \text{Eq (1)} \\ -R_c \overset{1}{b \cos \theta} - (\overset{1}{K_1 x + c_1 \dot{x}}) \overset{1}{a \cos \theta} - K_2 \theta = J_0 \ddot{\theta} & \text{Eq (2)} \end{cases}$$

$$\left\{ \begin{array}{l} R_c = m_3 \ddot{y} + k_3 y - F \\ -(m_3 \ddot{y} + k_3 y - F) b - (k_1 x + c_1 \dot{x}) a - k_2 \theta = I \ddot{\theta} \end{array} \right.$$

$$\underbrace{(J_0 + m_3 b^2)}_{J_{eq}} \ddot{\theta} + \underbrace{c a^2}_{C_{eq}} \dot{\theta} + \underbrace{(k_2 + k_1 a^2 + k_3 b^2)}_{K_{eq}} \theta = \underbrace{\frac{b F_0}{M_0}}_{M_0} \cos(\omega t) \quad ||$$

$$J_{eq} \ddot{\theta} + C_{eq} \dot{\theta} + K_{eq} \theta = M_0 \cos(\omega t)$$

$$\omega_n = \sqrt{\frac{k_{eq}}{y_{eq}}} = 1.077 \text{ rad/s} > \underline{\omega}$$

$$\xi = \frac{C_{eq}}{2 J_{eq} \omega_1} = 0,186 < 1 \Rightarrow \text{Osc. ПОТОМНОЕ. ПЕРИОДИЧЕ}$$

$$\theta(t) = \theta_{\text{cm}}(t) + \theta_p(t)$$

$$\theta_p(t) = \theta_0 \cos(-\omega t - \varphi)$$

$$\begin{cases} \vartheta_0 = 0,124 \text{ rad} \\ \varphi = 68^\circ \end{cases} \Rightarrow \vartheta_p(t) = 0,124 \cos(t - 68^\circ)$$

