

3.1) a) $G(s)$ berechnen

$$\dot{\vec{x}}_1 = \begin{pmatrix} -3 & 2 & -2 \\ -6 & 0 & 5 \\ -6 & 2 & 3 \end{pmatrix} \vec{x}_1 + \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} u_1$$

$$y_1 = (2 \ 0 \ 0) \vec{x}_1$$

Step 1: $\Phi(s) = (sE - A)^{-1}$

$$\begin{pmatrix} s+3 & -2 & 2 \\ 6 & s & -5 \\ 6 & -2 & s-3 \end{pmatrix}^{-1}$$

Inverse mit $\text{adj}(A)$:

$$A^{-1} = \frac{\text{adj} A}{\det A}$$

$$\text{adj} A = \begin{pmatrix} \tilde{a}_{11} & \tilde{a}_{12} & \tilde{a}_{13} \\ \tilde{a}_{21} & \tilde{a}_{22} & \tilde{a}_{23} \\ \tilde{a}_{31} & \tilde{a}_{32} & \tilde{a}_{33} \end{pmatrix}^T$$

$$\tilde{a}_{ij} = (-1)^{i+j} M_{ji}$$

$$\tilde{a}_{11} = s(s-3) - 10 \quad \tilde{a}_{12} = -6(s-3) + 36 \quad \tilde{a}_{13} = -12 - 6s \quad \tilde{a}_{21} = -2(s-3) + 4$$

$$\tilde{a}_{22} = (s+3)(s-3) - 12 \quad \tilde{a}_{23} = -(-2(s+3) + 12) \quad \tilde{a}_{31} = 10 - 2s \quad \tilde{a}_{32} = -(5(s+3) - 12)$$

$$\tilde{a}_{33} = s(s+3) + 12$$

$$\begin{aligned} \det A &= (s+3)s(s-3) + 60 - 24 - 12s + 12(s-3) - 10(s+3) \\ &= s^3 - 9s - 12s + 12s - 36 - 10s - 30 + 60 - 24 \\ &= s^3 - 19s - 30 \end{aligned}$$

nn: $60 - 24 - 36 - 30$
 $= -30$

$-9 - 12 + 12 - 10$
 $= -19$

$$\text{adj} A = \begin{pmatrix} s^2 - 3s - 10 & 2s - 10 & -2s + 10 \\ -6s - 18 & s^2 - 3^2 & -5s - 3 \\ -6s - 12 & 2s + 18 & s^2 + 3s + 12 \end{pmatrix}$$

$$\Phi(s) = \frac{1}{s^3 - 19s - 30} \begin{pmatrix} s^2 - 3s - 10 & 2s - 10 & -2s + 10 \\ -6s - 18 & s^2 - 3^2 & -5s - 3 \\ -6s - 12 & 2s + 18 & s^2 + 3s + 12 \end{pmatrix}$$

Step 2: $G(s) = C \Phi(s) B + \delta$

$$G(s) = \frac{1}{s^3 - 19s - 30} (2 \ 0 \ 0) \begin{pmatrix} s^2 - 3s - 10 & 2s - 10 & -2s + 10 \\ -6s - 18 & s^2 - 3^2 & -5s - 3 \\ -6s - 12 & 2s + 18 & s^2 + 3s + 12 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$$

$$G_1(s) = \frac{2(2s-10)}{(s^3-19s-30)}$$

Teiler fremd?

$$\frac{4(s-5)}{s^3-19s-30} \quad z(s) = 0$$

$$s = 5$$

$$h(5) = 5^3 - 19 \cdot 5 - 30 = 0$$

nicht TF

Polynom div:

$$s^3 + 0s^2 - 19s - 30 : s-5 = s^2 + 5s + 6 = (s+3)(s+2)$$

$$-(s^3 - 5s^2)$$

$$5s^2 - 19s - 30$$

$$-5s^2 + 25s$$

$$6s - 30$$

$$-6s + 30$$

$$0$$

linearfaktorzerlegung

$$\begin{array}{ccc} 1 & 5 & 6 \\ -3 & -3 & -6 \\ 1 & 2 & 0 \end{array}$$

$$G_1(s) = \frac{4}{(s+3)(s+2)}$$

Sprungfähigkeit: $\lim_{s \rightarrow \infty} \frac{4}{(s+3)(s+2)} = 0 \rightarrow$ nicht sprungfähig

BIBO: $\operatorname{Re}(s_i) < 0 \quad s_1 = -2; s_2 = -3 \rightarrow$ BIBO stabil

$$\dot{\vec{x}}_2 = \begin{pmatrix} 8 & -15 \\ 6 & -10 \end{pmatrix} \vec{x}_2 + \begin{pmatrix} 1 \\ 4 \end{pmatrix} u_2$$

$$y_2 = (2 \ 0) \vec{x}_2 + 4u_2$$

Step 1: $\Phi(s) = (sE - A)^{-1} \cdot M^{-1}$

$$= \begin{pmatrix} s-8 & +15 \\ -6 & s+10 \end{pmatrix}^{-1} = \frac{1}{\det M} \begin{pmatrix} m_{22} & -m_{12} \\ -m_{21} & m_{11} \end{pmatrix}$$

$$= \frac{1}{(s-8)(s+10) + 6 \cdot 15} \begin{pmatrix} s+10 & -15 \\ 6 & s-8 \end{pmatrix} = \frac{1}{s^2 + 2s + 10} \begin{pmatrix} s+10 & -15 \\ 6 & s-8 \end{pmatrix}$$

$$s^2 - 8s + 10s - 80 + 90 = s^2 + 2s + 10$$

viel Effizienter: $G(s) = C \Phi(s) B$

$$(2 \ 0 \ 0) \begin{pmatrix} s+3 & -2 & 2 \\ 6 & s & -5 \\ 6 & -2 & s-3 \end{pmatrix}^{-1} \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$$

$$\rightarrow 2 \Phi_{12} \quad \Phi_{12} = \frac{1}{\det A} \cdot \tilde{a}_{21} = 4(s-5)$$

$$G_1(s) = \frac{4(s-5)}{s^3-19s-30}$$

Step 2: $G(s) = C \Phi(s)^{-1} B + D = \frac{1}{s^2+2s+10} \begin{pmatrix} 2 & 0 \end{pmatrix} \begin{pmatrix} s+10 & -15 \\ 6 & s-8 \end{pmatrix} \begin{pmatrix} 1 \\ 4 \end{pmatrix} + 4 =$

$$= \frac{2}{s^2+2s+10} (s+10-15) \begin{pmatrix} 1 \\ 4 \end{pmatrix} + 4 = \frac{2}{s^2+2s+10} (s+10-60) + 4$$

$$\frac{2s-100}{s^2+2s+10} + \frac{(s^2+2s+10)4}{s^2+2s+10} = \frac{4s^2+8s+2s+40-100}{s^2+2s+10} = \frac{4s^2+10s-60}{s^2+2s+10}$$

Pole: $s^2+2s+10$ $s_{1,2} = -\frac{p}{2} \pm \sqrt{\left(\frac{p}{2}\right)^2 - q} = -\frac{2}{2} \pm \sqrt{\left(\frac{2}{2}\right)^2 - 10} = -1 \pm j9$

Sprungfähigkeit: $\lim_{s \rightarrow \infty} \frac{4s^2+10s-60}{s^2+2s+10} = 4 \neq 0 \rightarrow$ Sprungfähig

BIBO: $\operatorname{Re}(s_1) < 0$ $\operatorname{Re}(s_2) < 0$; $\operatorname{Re}(s_2) < 0 \rightarrow$ stabil