

Questions

1. Harmonic oscillator

An important system in physics and biology is the harmonic oscillator. The second-order linear differential equation is given by

$$\ddot{x} + \omega^2 x = 0, \quad \text{where} \quad \dot{x} = \frac{d^2x}{dt^2}.$$

By introducing the variable $y = \dot{x}$, this second-order equation can be rewritten as a system of two first-order equations:

$$\begin{aligned} \dot{x} &= y \\ \dot{y} &= -\omega^2 x \end{aligned} \quad \text{or} \quad \frac{d}{dt} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ -\omega^2 & 0 \end{pmatrix} \cdot \begin{pmatrix} x \\ y \end{pmatrix}$$

- Determine the general solution $x(t) = c_1 u_1 e^{\lambda_1 t} + c_2 u_2 e^{\lambda_2 t}$ by finding the eigenvalues $\lambda_{1/2}$ and eigenvectors $u_{1/2}$ of the matrix $A = \begin{pmatrix} 0 & 1 \\ -\omega^2 & 0 \end{pmatrix}$
- By writing the integration constants as the complex conjugate pair $c_1 = \frac{A}{2} e^{i\varphi}$ and $c_2 = \frac{A}{2} e^{-i\varphi}$, show that the general solution can be written as $x(t) = A \cos(\omega t + \varphi)$.
- How do amplitude A and phase shift φ depend on the initial conditions $x_0 = x(0)$ and $y_0 = y(0) = \dot{x}(0)$? (Hint: you will need that $\tan \varphi = \sin \varphi / \cos \varphi$ and $\cos^2 \varphi + \sin^2 \varphi = 1$)
- Show that the quantity $E = \frac{\dot{x}^2}{2} + \frac{\omega^2}{2} x^2$ is a conserved quantity. For this, show that $\frac{dE}{dt} = 0$. Hint: you *don't* need the solutions to the differential equations. The differential equation $\ddot{x} + \omega^2 x = 0$ is enough.

2. Damped oscillator

The harmonic oscillator is an idealisation. In reality, all systems lose energy due to friction. This is reflected by a term proportional to the velocity. Consider

$$\ddot{x} + 2\gamma \dot{x} + \omega^2 x = 0$$

with some positive γ .

- Rewrite the equation as a system of two linear equations.
 - Show that the characteristic polynomial is $\lambda^2 + 2\gamma\lambda + \omega^2$ and that for all $\gamma > 0$ the steady state is stable.
 - For $\gamma = \omega$ the system is degenerate and has two identical eigenvalues. Show that the function $x(t) = t \cdot e^{-\omega t}$ solves the equation $\ddot{x} + 2\omega \dot{x} + \omega^2 x = 0$. (This is called the *critically damped case*)
3. *Forced oscillator*

We now consider a harmonic oscillator with a periodic external force. The equation reads

$$\ddot{x} + 2\gamma \dot{x} + \omega^2 = f_0 \cos \Omega t.$$

This equation is much easier to solve in the complex number space.

- Make the assumption that the particular solution also describes an oscillation with frequency Ω and show that the function $x(t) = A e^{i(\Omega t - \varphi)}$ solves

$$\ddot{x} + 2\gamma \dot{x} + \omega^2 = f_0 e^{i\Omega t}$$

when

$$A(-\Omega^2 + 2i\gamma\Omega + \omega^2) = f_0 e^{i\varphi t}.$$

- Derive expressions how the amplitude A and the phase shift φ depend on the parameters and sketch these values as functions of the forcing period Ω for different values of γ .
- What happens in the case with no friction $\gamma = 0$ when the forcing frequency approaches the *eigenfrequency* ω ?

Submit your solutions by **Wednesday, April 26, 2023**.