

MONASH INFORMATION TECHNOLOGY

FIT2004 Algorithms and Data Structures

Ian Wern Han Lim lim.wern.han@monash.edu

Referencing materials by Nathan Companez, Aamir Cheema, Arun Konagurthu and Lloyd Allison





Faculty of Information Technology, Monash University

COMMONWEALTH OF AUSTRALIA

Copyright Regulations 1969

This material has been reproduced and communicated to you by or on behalf of Monash University pursuant to Part VB of the Copyright Act 1968 (the Act). The material in this communication may be subject to copyright under the Act. Any further reproduction or communication of this material by you may be the subject of copyright protection under the Act. Do not remove this notice



Ready?

More shortest distance algorithms



- More shortest distance algorithms
 - Remember we can get the path through back tracking



- More shortest distance algorithms
 - Remember we can get the path through back tracking
- Bellman-Ford
- Floyd-Warshall



- More shortest distance algorithms
 - Remember we can get the path through back tracking
- Bellman-Ford
- Floyd-Warshall
 - Warshall's algorithm for transitive closure





Let us begin...

A recap



Let us recap Dijkstra

A recap



Shortest distance algorithm



- Shortest distance algorithm
 - Similar to BFS
 - Is BFS when the graph is unweighted



- Shortest distance algorithm
 - Similar to BFS
 - Is BFS when the graph is unweighted
 - Uses a priority queue
 - Implemented with a min-heap



- Shortest distance algorithm
 - Similar to BFS
 - Is BFS when the graph is unweighted
 - Uses a priority queue
 - Implemented with a min-heap
 - What is the complexity?



- Shortest distance algorithm
 - Similar to BFS
 - Is BFS when the graph is unweighted
 - Uses a priority queue
 - Implemented with a min-heap
 - What is the complexity? O(E log V)



- Shortest distance algorithm
 - Similar to BFS
 - Is BFS when the graph is unweighted
 - Uses a priority queue
 - Implemented with a min-heap
 - What is the complexity? O(E log V)
- Dijkstra is a...

A recap



Shortest distance algorithm

- Similar to BFS
 - Is BFS when the graph is unweighted
- Uses a priority queue
 - Implemented with a min-heap
- What is the complexity? O(E log V)

Dijkstra is a...

- Dynamic programming algorithm
- Greedy algorithm



- Shortest distance algorithm
 - Similar to BFS
 - Is BFS when the graph is unweighted
 - Uses a priority queue
 - Implemented with a min-heap
 - What is the complexity? O(E log V)
- Dijkstra is a...
 - Dynamic programming algorithm
 - Greedy algorithm

A recap



- Shortest distance algorithm
 - Similar to BFS
 - Is BFS when the graph is unweighted
 - Uses a priority queue
 - Implemented with a min-heap
 - What is the complexity? O(E log V)

store the distance from the source to target vertex by v.distance = u.distance + edge.w

- Dijkstra is a...
 - Dynamic programming algorithm
 - Greedy algorithm
 - Might not work when there is a negative edge





Questions?

cause negative edge would reduce overall distance due to the greedinnes of Dijkstra whihc would prefer the local optimum assuming no negative edge (that make v.distance lower than the u.distance) As A-> B shortes, B -> D shortes then A -> D shortest However in another path, A -> C is not shorest, but duev to the C-> D is a negative edge overall A -> C -> D is actually shortest not A -> B -> D from Dijkstra

Dijkstra would not consider C -> D if A -> C -> D has distance lower than A -> C , Dijkstra terminate due to reach the D which is destination

However, since C -> D is negative edge, A -> C -> D would actually give shortest path

Another shortest distance...



Bellman-Ford isn't greedy



- Bellman-Ford isn't greedy
 - Does that mean it will work for negative edges?



- Bellman-Ford isn't greedy
 - Does that mean it will work for negative edges?
 - Does that mean the complexity will increase?



- Bellman-Ford isn't greedy
 - Does that mean it will work for negative edges?
 - Does that mean the complexity will increase?
 - Yes, we consider all edges
 - But we overcome it via Dynamic Programming



- Bellman-Ford isn't greedy
 - Does that mean it will work for negative edges?
 - Does that mean the complexity will increase?
 - Yes, we consider all edges
 - But we overcome it via Dynamic Programming
- 2 main components



- Bellman-Ford isn't greedy
 - Does that mean it will work for negative edges?
 - Does that mean the complexity will increase?
 - Yes, we consider all edges
 - But we overcome it via Dynamic Programming
- 2 main components
 - Distance calculation
 - Check for negative cycle



- Distance calculation
- Check for negative cycle



- Distance calculation
- Check for negative cycle
 - Check if there's a negative cycle...

MONASH University

- Distance calculation
- Check for negative cycle
 - Check if there's a negative cycle... If we have a negative cycle, there won't be a shortest distance... Why?

Another shortest distance...



Negative cycle is bad...





Questions?

MONASH University

- Distance calculation
 - Here we loop |V| 1 times
- Check for negative cycle
 - Check if there's a negative cycle... If we have a negative cycle, there won't be a shortest distance... Why?

MONASH University

- Distance calculation
 - Here we loop |V| 1 times. Why?
- Check for negative cycle
 - Check if there's a negative cycle... If we have a negative cycle, there won't be a shortest distance... Why?



Another shortest distance...

Distance calculation

Here we loop |V| - 1 times. Why?
 This is the maximum number of jumps without a cycle in a graph.

Check for negative cycle

– Check if there's a negative cycle... If we have a negative cycle, there won't be a shortest distance... Why?



Another shortest distance...

Distance calculation

Here we loop |V| - 1 times. Why?
 This is the maximum number of jumps without a cycle in a graph.
 Going from vertex u to vertex v, you can only go through a maximum of |V| - 1 edges without a cycle...

Check for negative cycle

– Check if there's a negative cycle... If we have a negative cycle, there won't be a shortest distance... Why?

MONASH University

Another shortest distance...

Distance calculation

Here we loop |V| - 1 times. Why?
 This is the maximum number of jumps without a cycle in a graph.
 Going from vertex u to vertex v, you can only go through a maximum of |V| - 1 edges without a cycle...

Check for negative cycle

- Check if there's a negative cycle... If we have a negative cycle, there won't be a shortest distance... Why?
- Then here, we repeat the process ONE MORE TIME



Another shortest distance...

Distance calculation

Here we loop |V| - 1 times. Why?
 This is the maximum number of jumps without a cycle in a graph.
 Going from vertex u to vertex v, you can only go through a maximum of |V| - 1 edges without a cycle...

Check for negative cycle

- Check if there's a negative cycle... If we have a negative cycle, there won't be a shortest distance... Why?
- Then here, we repeat the process ONE MORE TIME. Why?



Another shortest distance...

Distance calculation

Here we loop |V| - 1 times. Why?
 This is the maximum number of jumps without a cycle in a graph.
 Going from vertex u to vertex v, you can only go through a maximum of |V| - 1 edges without a cycle...

negative circle: overal distance of the edges in cycle is negative

Check for negative cycle

- Check if there's a negative cycle... If we have a negative cycle, there won't be a shortest distance... Why?
- Then here, we repeat the process ONE MORE TIME. Why?
 If a cycle exist, this additional traversal will form the biggest cycle!



Questions?

MONASH University

Another shortest distance...

Let's look at the algorithm first, then I will explain from there...



Another shortest distance...

 Let's look at the algorithm first, then I will explain from there...

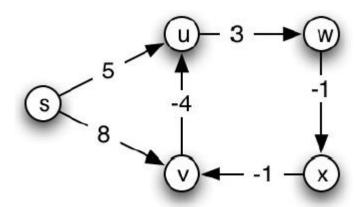
```
function BellmanFord(list vertices, list edges, vertex source)
   ::distance[],predecessor[]
  // This implementation takes in a graph, represented as
  // lists of vertices and edges, and fills two arrays
  // (distance and predecessor) with shortest-path
  // (less cost/distance/metric) information
  // Step 1: initialize graph
  for each vertex v in vertices:
      if v is source then distance[v] := 0
       else distance[v] := inf
       predecessor[v] := null
  // Step 2: relax edges repeatedly
  for i from 1 to size(vertices)-1:
      for each edge (u, v) with weight w in edges:
           if distance[u] + w < distance[v]:</pre>
               distance[v] := distance[u] + w
               predecessor[v] := u
  // Step 3: check for negative-weight cycles
  for each edge (u, v) with weight w in edges:
       if distance[u] + w < distance[v]:</pre>
           error "Graph contains a negative-weight cycle"
  return distance[], predecessor[]
```

```
function BellmanFord(list vertices, list edges, vertex source)
   ::distance[],predecessor[]
   // This implementation takes in a graph, represented as
   // lists of vertices and edges, and fills two arrays
   // (distance and predecessor) with shortest-path
   // (less cost/distance/metric) information
  // Step 1: initialize graph
   for each vertex v in vertices:
       if v is source then distance[v] := 0
       else distance[v] := inf
       predecessor[v] := null
  // Step 2: relax edges repeatedly
   for i from 1 to size(vertices)-1:
       for each edge (u, v) with weight w in edges:
           if distance[u] + w < distance[v]:</pre>
               distance[v] := distance[u] + w
               predecessor[v] := u
  // Step 3: check for negative-weight cycles
   for each edge (u, v) with weight w in edges:
       if distance[u] + w < distance[v]:</pre>
           error "Graph contains a negative-weight cycle"
   return distance[], predecessor[]
```

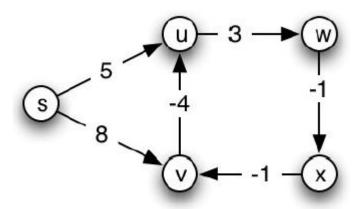
MONASH University

- Let's look at the algorithm first, then I will explain from there...
- Let us try with an example first...

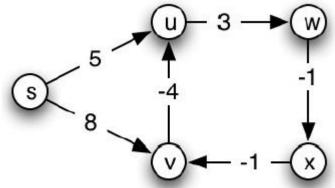
MONASH University



MONASH University



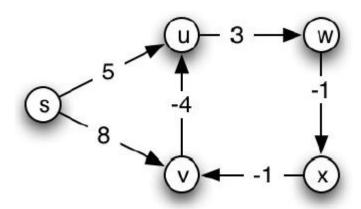
S	
u	
v	
w	
X	





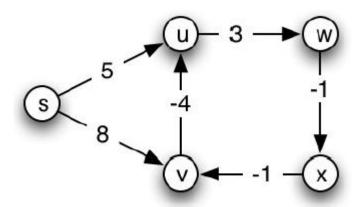






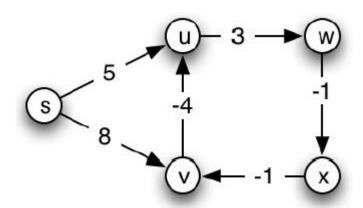
	i: numbee of egde	S
	i=0	
s	0	
u	inf	
V	inf	
w	inf	
X	inf	

MONASH University



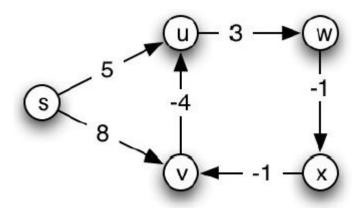
	i=0	i=1
S	0	0
u	inf	5s
v	inf	8s
W	inf	inf
х	inf	inf

MONASH University



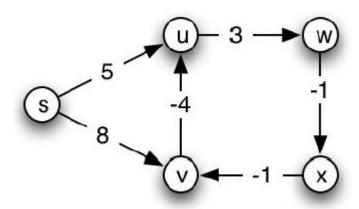
	I		allow 2 edges, u	= 4v as: s -> v. v -> u
	i=0	i=1	i=2	
s	0	0	0	
u	inf	5s	4v	
V	inf	8s	8s	
W	inf	inf	8u	
Х	inf	inf	inf	

MONASH University



	i=0	i=1	i=2	i=3
S	0	0	0	0
u	inf	5s	4v	4v
V	inf	8s	8 s	8s
w	inf	inf	8u	7u
Х	inf	inf	inf	7w
•				

MONASH University



	i=0	i=1	i=2	i=3	i=4
s	0	0	0	0	0
u	inf	5s	4v	4v	4v
V	inf	8s	8s	8s	6x
W	inf	inf	8u	7u	7u
X	inf	inf	inf	7w	6w

Another shortest distance...

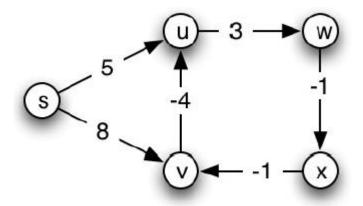
5

u

V

W

X



v - 1

inf

inf

inf

inf



7u

6w

I=0	I=1	1=2	I=3	I=4
0	0	0	0	0
inf	5s	4v	4v	4v
inf	8 s	8s	85	6x

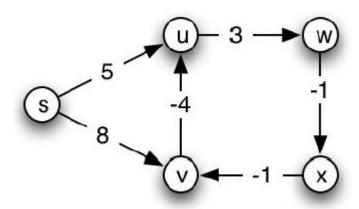
8u

inf

7u

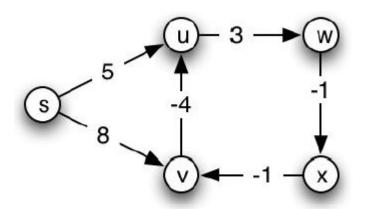
7w

MONASH University



	i=0	i=1	i=2	i=3	i=4	Checking	
S	0	0	0	0	0	0	
u	inf	5s	4v	4v	4v	2v	Break
v	inf	8 s	8s	8 s	бх	5x	Break too
W	inf	inf	8u	7u	7u	7 u	
X	inf	inf	inf	7w	6w	6w	







only use V - 1 edge at most, tree would only has traversal V - 1, so only V-1 edge in tree, otherwise form cycle i = V

	i=0	i=1	i=2	i=3	i=4	Checking	
s	0	0	0	0	0	0	
u	inf	5s	4v	4v	4v decr	ease tive cycle C xist	Break
v	inf	8 s	8s	8s	бх	5x	Break too
w	inf	inf	8u	7u	7u	7u	
Х	inf	inf	inf	7w	6w	бw	



Questions?

Another shortest distance...



What is our complexity here?





What is our complexity here?

```
function BellmanFord(list vertices, list edges, vertex source)
   ::distance[],predecessor[]
  // This implementation takes in a graph, represented as
  // lists of vertices and edges, and fills two arrays
  // (distance and predecessor) with shortest-path
  // (less cost/distance/metric) information
  // Step 1: initialize graph
   for each vertex v in vertices:
       if v is source then distance[v] := 0
       else distance[v] := inf
       predecessor[v] := null
  // Step 2: relax edges repeatedly
  for i from 1 to size(vertices)-1:
       for each edge (u, v) with weight w in edges:
           if distance[u] + w < distance[v]:</pre>
               distance[v] := distance[u] + w
               predecessor[v] := u
  // Step 3: check for negative-weight cycles
  for each edge (u, v) with weight w in edges:
       if distance[u] + w < distance[v]:</pre>
           error "Graph contains a negative-weight cycle"
   return distance[], predecessor[]
```



- What is our complexity here?
- Initialize
- Calculate distance
- Check negative cycle

```
function BellmanFord(list vertices, list edges, vertex source)
   ::distance[],predecessor[]
  // This implementation takes in a graph, represented as
  // lists of vertices and edges, and fills two arrays
  // (distance and predecessor) with shortest-path
  // (less cost/distance/metric) information
  // Step 1: initialize graph
   for each vertex v in vertices:
       if v is source then distance[v] := 0
       else distance[v] := inf
       predecessor[v] := null
  // Step 2: relax edges repeatedly
  for i from 1 to size(vertices)-1:
       for each edge (u, v) with weight w in edges:
           if distance[u] + w < distance[v]:</pre>
               distance[v] := distance[u] + w
               predecessor[v] := u
  // Step 3: check for negative-weight cycles
  for each edge (u, v) with weight w in edges:
       if distance[u] + w < distance[v]:</pre>
           error "Graph contains a negative-weight cycle"
   return distance[], predecessor[]
```



- What is our complexity here?
- Initialize
 - O(V)
- Calculate distance
- Check negative cycle

```
function BellmanFord(list vertices, list edges, vertex source)
   ::distance[],predecessor[]
  // This implementation takes in a graph, represented as
  // lists of vertices and edges, and fills two arrays
  // (distance and predecessor) with shortest-path
  // (less cost/distance/metric) information
  // Step 1: initialize graph
   for each vertex v in vertices:
       if v is source then distance[v] := 0
       else distance[v] := inf
       predecessor[v] := null
  // Step 2: relax edges repeatedly
  for i from 1 to size(vertices)-1:
       for each edge (u, v) with weight w in edges:
           if distance[u] + w < distance[v]:</pre>
               distance[v] := distance[u] + w
               predecessor[v] := u
  // Step 3: check for negative-weight cycles
  for each edge (u, v) with weight w in edges:
       if distance[u] + w < distance[v]:</pre>
           error "Graph contains a negative-weight cycle"
   return distance[], predecessor[]
```



- What is our complexity here?
- Initialize
 - O(V)
- Calculate distance
 - O(V) outer loop
- Check negative cycle

```
function BellmanFord(list vertices, list edges, vertex source)
   ::distance[],predecessor[]
  // This implementation takes in a graph, represented as
  // lists of vertices and edges, and fills two arrays
  // (distance and predecessor) with shortest-path
  // (less cost/distance/metric) information
  // Step 1: initialize graph
   for each vertex v in vertices:
       if v is source then distance[v] := 0
       else distance[v] := inf
       predecessor[v] := null
  // Step 2: relax edges repeatedly
   for i from 1 to size(vertices)-1:
       for each edge (u, v) with weight w in edges:
           if distance[u] + w < distance[v]:</pre>
               distance[v] := distance[u] + w
               predecessor[v] := u
  // Step 3: check for negative-weight cycles
   for each edge (u, v) with weight w in edges:
       if distance[u] + w < distance[v]:</pre>
           error "Graph contains a negative-weight cycle"
   return distance[], predecessor[]
```



- What is our complexity here?
- Initialize
 - O(V)
- Calculate distance
 - O(V) outer loop
 - O(E) inner loop
- Check negative cycle

```
function BellmanFord(list vertices, list edges, vertex source)
   ::distance[],predecessor[]
  // This implementation takes in a graph, represented as
  // lists of vertices and edges, and fills two arrays
  // (distance and predecessor) with shortest-path
  // (less cost/distance/metric) information
  // Step 1: initialize graph
  for each vertex v in vertices:
       if v is source then distance[v] := 0
       else distance[v] := inf
       predecessor[v] := null
  // Step 2: relax edges repeatedly
  for i from 1 to size(vertices)-1:
       for each edge (u, v) with weight w in edges:
           if distance[u] + w < distance[v]:</pre>
               distance[v] := distance[u] + w
               predecessor[v] := u
  // Step 3: check for negative-weight cycles
  for each edge (u, v) with weight w in edges:
       if distance[u] + w < distance[v]:</pre>
           error "Graph contains a negative-weight cycle"
   return distance[], predecessor[]
```



- What is our complexity here?
- Initialize
 - O(V)
- Calculate distance
 - O(V) outer loop
 - O(E) inner loop
- Check negative cycle
 - O(E) again one last time

```
function BellmanFord(list vertices, list edges, vertex source)
   ::distance[],predecessor[]
  // This implementation takes in a graph, represented as
  // lists of vertices and edges, and fills two arrays
  // (distance and predecessor) with shortest-path
  // (less cost/distance/metric) information
  // Step 1: initialize graph
   for each vertex v in vertices:
       if v is source then distance[v] := 0
       else distance[v] := inf
       predecessor[v] := null
  // Step 2: relax edges repeatedly
   for i from 1 to size(vertices)-1:
       for each edge (u, v) with weight w in edges:
           if distance[u] + w < distance[v]:</pre>
               distance[v] := distance[u] + w
               predecessor[v] := u
  // Step 3: check for negative-weight cycles
   for each edge (u, v) with weight w in edges:
       if distance[u] + w < distance[v]:</pre>
           error "Graph contains a negative-weight cycle"
   return distance[], predecessor[]
```



- What is our complexity here?
- Initialize
 - O(V)
- Calculate distance
 - O(V) outer loop
 - O(E) inner loop
- Check negative cycle
 - O(E) again one last time
- Total?

```
function BellmanFord(list vertices, list edges, vertex source)
   ::distance[],predecessor[]
  // This implementation takes in a graph, represented as
  // lists of vertices and edges, and fills two arrays
  // (distance and predecessor) with shortest-path
  // (less cost/distance/metric) information
  // Step 1: initialize graph
  for each vertex v in vertices:
       if v is source then distance[v] := 0
       else distance[v] := inf
       predecessor[v] := null
  // Step 2: relax edges repeatedly
  for i from 1 to size(vertices)-1:
       for each edge (u, v) with weight w in edges:
           if distance[u] + w < distance[v]:</pre>
               distance[v] := distance[u] + w
               predecessor[v] := u
  // Step 3: check for negative-weight cycles
  for each edge (u, v) with weight w in edges:
       if distance[u] + w < distance[v]:</pre>
           error "Graph contains a negative-weight cycle"
   return distance[], predecessor[]
```



- What is our complexity here?
- Initialize
 - O(V)
- Calculate distance
 - O(V) outer loop
 - O(E) inner loop
- Check negative cycle
 - O(E) again one last time
- Total? O(VE)

```
function BellmanFord(list vertices, list edges, vertex source)
   ::distance[],predecessor[]
  // This implementation takes in a graph, represented as
  // lists of vertices and edges, and fills two arrays
  // (distance and predecessor) with shortest-path
  // (less cost/distance/metric) information
  // Step 1: initialize graph
  for each vertex v in vertices:
      if v is source then distance[v] := 0
      else distance[v] := inf
      predecessor[v] := null
        only run v -1 times
  // Step 2: relax edges repeatedly
  for i from 1 to size(vertices)-1:
      for each edge (u, v) with weight w in edges:
          if distance[u] + w < distance[v]:</pre>
              distance[v] := distance[u] + w
              then updatee previous pmpevious round
  // Step 3: check for negative-weight cycles
  for each edge (u, v) with weight w in edges:
      if distance[u] + w < distance[v]:</pre>
          error "Graph contains a negative-weight cycle"
  return distance[], predecessor[]
```



- What is our complexity here?
- Initialize
 - O(V)
- Calculate distance
 - O(V) outer loop
 - O(E) inner loop
- Check negative cycle
 - O(E) again one last time







Questions?

Reachability



Given a graph G=(V,E)



- Given a graph G=(V,E)
- Transitive closure is another graph G'=(V,E')



- Given a graph G=(V,E)
- Transitive closure is another graph G'=(V,E')
 - Same vertices V



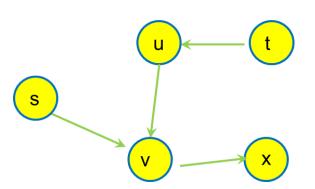
- Given a graph G=(V,E)
- Transitive closure is another graph G'=(V,E')
 - Same vertices V
 - Additional edges between vertex u and vertex v if there's a path between them



- Given a graph G=(V,E)
- Transitive closure is another graph G'=(V,E')
 - Same vertices V
 - Additional edges between vertex u and vertex v if there's a path between them
 - Concept of transitivity
 - A -> B, B -> C therefore A -> C

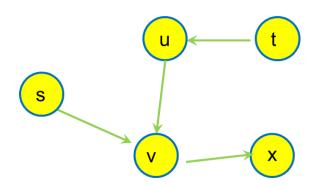


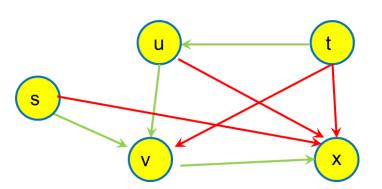
- Given a graph G=(V,E)
- Transitive closure is another graph G'=(V,E')
 - Same vertices V
 - Additional edges between vertex u and vertex v if there's a path between them
 - Concept of transitivity
 - A -> B, B -> C therefore A -> C





- Given a graph G=(V,E)
- Transitive closure is another graph G'=(V,E')
 - Same vertices V
 - Additional edges between vertex u and vertex v if there's a path
 between them
 - Concept of transitivity
 - A -> B, B -> C therefore A -> C virtual link







Questions?



- Given a graph G=(V,E)
- Transitive closure is another graph G'=(V,E')
 - Same vertices V
 - Additional edges between vertex u and vertex v if there's a path between them
 - Concept of transitivity
 - A -> B, B -> C therefore A -> C
- So how do you do this?

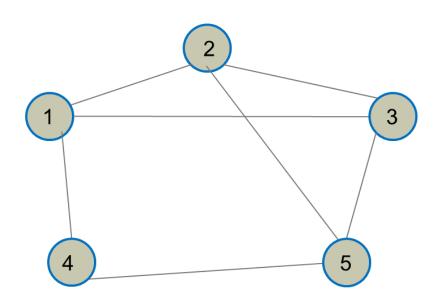


- Given a graph G=(V,E)
- Transitive closure is another graph G'=(V,E')
 - Same vertices V
 - Additional edges between vertex u and vertex v if there's a path between them
 - Concept of transitivity
 - A -> B, B -> C therefore A -> C
- So how do you do this?
 - Recall our adjacency matrix



- So how do you do this?
 - Recall our adjacency matrix

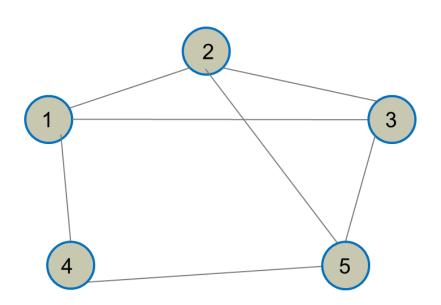
	1	2	3	4	5
1	F	Т	Т	Т	F
2	Т	F	Т	F	Т
3	Т	Т	F	F	Т
4	Т	F	F	F	Т
5	F	Т	Т	Т	F





- So how do you do this?
 - Recall our adjacency matrix
 - If matrix[1,2] = True and matrix [2,5] = True

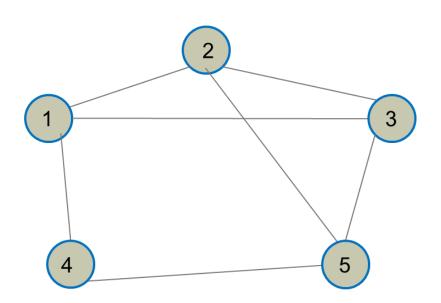
	1	2	3	4	5
1	F	Т	Т	Т	F
2	Т	F	Т	F	Т
3	Т	Т	F	F	Т
4	Т	F	F	F	Т
5	F	Т	Т	Т	F





- So how do you do this?
 - Recall our adjacency matrix
 - If matrix[1,2] = True and matrix [2,5] = True
 - Then matrix [1,5] = True

	1	2	3	4	5
1	F	Т	Т	Т	F
2	Т	F	Т	F	Т
3	Т	Т	F	F	Т
4	Т	F	F	F	Т
5	F	Т	Т	Т	F



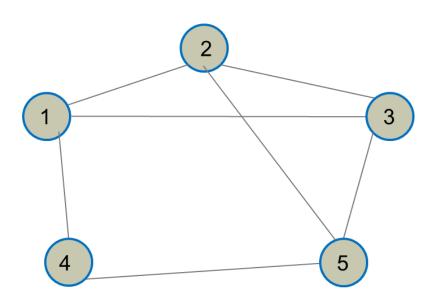
Reachability



So how do you do this?

- Recall our adjacency matrix
- If matrix[1,2] = True and matrix [2,5] = True
- Then matrix [1,5] = True
- If matrix[i,j] = True and matrix[j,k] = True then matrix[i,k] = True

	1	2	3	4	5
1	F	Т	Т	Т	F
2	Т	F	Т	F	Т
3	Т	Т	F	F	Т
4	Т	F	F	F	Т
5	F	Т	Т	Т	F





- So how do you do this?
 - Recall our adjacency matrix
 - If matrix[1,2] = True and matrix [2,5] = True
 - Then matrix [1,5] = True
 - If matrix[i,j] = True and matrix[j,k] = True then matrix[i,k] = True
- Can you code it?

Reachability



- So how do you do this?
 - Recall our adjacency matrix
 - If matrix[1,2] = True and matrix [2,5] = True
 - Then matrix [1,5] = True
 - If matrix[i,j] = True and matrix[j,k] = True then matrix[i,k] = True

Can you code it?

```
# warshall's

18  for k in range(count_vertex):

19  for i in range(count_vertex):

20  for j in range(count_vertex):

21  matrix[i][j] = matrix[i][j] or (matrix[i][k] and matrix[k][j])
```



Questions?

Reachability



Can you code it?

```
# warshall's

18  for k in range(count_vertex):

19  for i in range(count_vertex):

20  for j in range(count_vertex):

21  matrix[i][j] = matrix[i][j] or (matrix[i][k] and matrix[k][j])
```

either i,k (itself is already True) or Both (i,k = True and k,j = True)

- What is the complexity?
 - Time =
 - Space =

Reachability



Can you code it?

```
# warshall's
18  for k in range(count_vertex):
19  for i in range(count_vertex):
20  for j in range(count_vertex):
21  matrix[i][j] = matrix[i][j] or (matrix[i][k] and matrix[k][j])
```

- What is the complexity?
 - Time = $O(V^3)$
 - Space =

Reachability



Can you code it?

```
# warshall's

18  for k in range(count_vertex):

19  for i in range(count_vertex):

20  for j in range(count_vertex):

21  matrix[i][j] = matrix[i][j] or (matrix[i][k] and matrix[k][j])
```

- What is the complexity?
 - Time = $O(V^3)$
 - Space = $O(V^2)$ for the matrix



Questions?

Shortest distance



So we know the Warshall's algorithm



- So we know the Warshall's algorithm
 - A -> B and B -> C give us A -> C



- So we know the Warshall's algorithm
 - A -> B and B -> C give us A -> C
- Thus
 - Distance(A -> B) + Distance(B -> C) = Distance(A -> C)



- So we know the Warshall's algorithm
 - A -> B and B -> C give us A -> C
- Thus
 - Distance(A -> B) + Distance(B -> C) = Distance(A -> C)
 - So we can have the shortest distance from A to C, going through B



- So we know the Warshall's algorithm
 - A -> B and B -> C give us A -> C
- Thus
 - Distance(A -> B) + Distance(B -> C) = Distance(A -> C)
 - So we can have the shortest distance from A to C, going through B
 - And we do this for all vertex u and vertex v

Shortest distance



- So we know the Warshall's algorithm
 - A -> B and B -> C give us A -> C
- Thus

Bellman-Ford and Dijkstra always need source and destination

- Distance(A -> B) + Distance(B -> C) = Distance(A -> C) Floryd-Warshall only find shortest distance of pairs of verticesa
- So we can have the shortest distance from A to C, going through B
 - And we do this for all vertex u and vertex v
 - Thus, we have the shortest distance between all pairs!



- So we know the Warshall's algorithm
 - A -> B and B -> C give us A -> C
- Thus
 - Distance(A -> B) + Distance(B -> C) = Distance(A -> C)
 - So we can have the shortest distance from A to C, going through B
 - And we do this for all vertex u and vertex v
 - Thus, we have the shortest distance between all pairs!

All-Pair shortest distance



Why not Dijkstra?



- Why not Dijkstra?
 - Need to Dijkstra from every vertex. Complexity is?



- Why not Dijkstra?
 - Need to Dijkstra from every vertex. Complexity is?
 O(V) * O(E log V) = O(EV log V)



- Why not Dijkstra?
 - Need to Dijkstra from every vertex. Complexity is?
 O(V) * O(E log V) = O(EV log V) = O(V^3 log V)





- Why not Dijkstra?
 - Need to Dijkstra from every vertex.O(V) * O(E log V) = O(EV log V) = O(V^3 log V)
- Why not Bellman-Ford?
 - Need to Bellman-Ford from every vertex





- Why not Dijkstra?
 - Need to Dijkstra from every vertex.O(V) * O(E log V) = O(EV log V) = O(V^3 log V)
- Why not Bellman-Ford?
 - Need to Bellman-Ford from every vertex.
 O(V) * O(VE) = O(V^2 E) = O(V^4)



All-Pair shortest distance

- Why not Dijkstra? single-source algo
 - Need to Dijkstra from every vertex.O(V) * O(E log V) = O(EV log V) = O(V^3 log V)

if imutate the FW with Dijkstra, need to run Dijkstra on every vertex

- Why not Bellman-Ford? single-source algo
 - Need to Bellman-Ford from every vertex.
 O(V) * O(VE) = O(V^2 E) = O(V^4)
- Floyd-Warshall can do it quicker!

O(V^3)

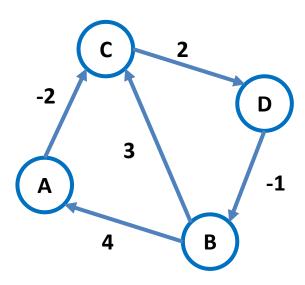


Questions?

All-Pair shortest distance



Now let us do it manually...

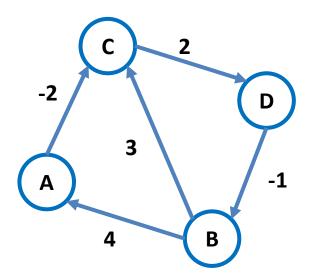






Now let us do it manually...

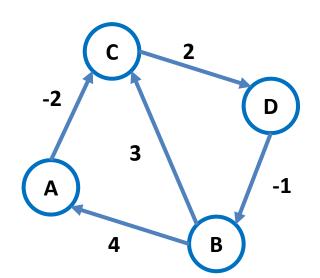
	Α	В	С	D
Α				
В				
С				
D				





- Now let us do it manually...
 - From itself back to itself is 0

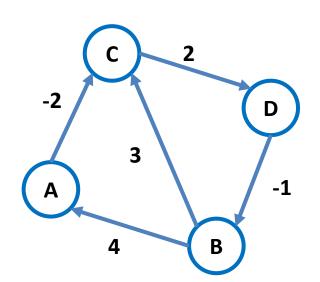
	Α	В	С	D
Α	0			
В		0		
С			0	
D				0





- Now let us do it manually...
 - From itself back to itself is 0
 - All of the edges are added

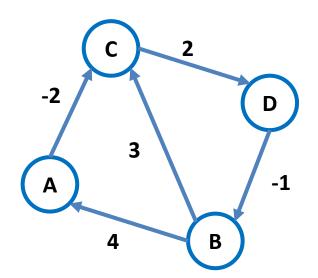
	Α	В	С	D
Α	0		-2	
В	4	0	3	
С			0	2
D		-1		0





- Now let us do it manually...
 - From itself back to itself is 0
 - All of the edges are added
 - Infinity for all of the non-edges

	Α	В	С	D
Α	0	inf	-2	inf
В	4	0	3	inf
С	inf	inf	0	2
D	inf	-1	inf	0





k: – Begin with vertex A, can we update the shortest distance of all vertices going through A?

– Begin with vertex B, can we update the shortest distance of all vertices going through B?

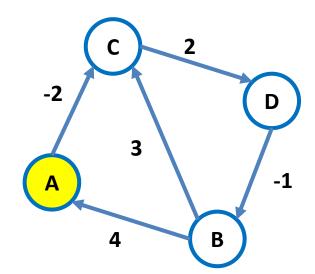
Questions?



- What is the algorithm?
 - Begin with vertex A, can we update the shortest distance of all vertices going through A?

do A column first with all rows, then B, C

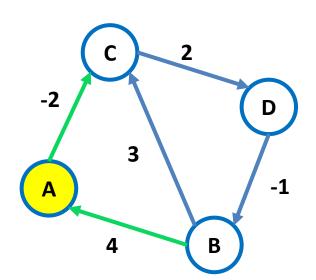
	Α	В	С	D
Α	0	inf	-2	inf
В	4	0	3	inf
С	inf	inf	0	2
D	inf	-1	inf	0





- What is the algorithm?
 - Begin with vertex A, can we update the shortest distance of all vertices going through A?

	Α	В	С	D
Α	0	inf	-2	inf
В	4	0	2	inf
С	inf	inf	0	2
D	inf	-1	inf	0



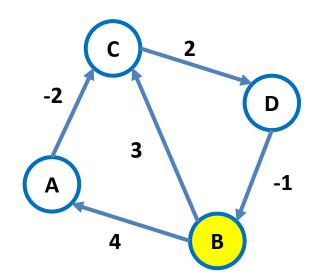




What is the algorithm?

- Begin with vertex A, can we update the shortest distance of all vertices going through A?
- Begin with vertex B, can we update the shortest distance of all vertices going through B?

	Α	В	С	D
Α	0	inf	-2	inf
В	4	0	2	inf
С	inf	inf	0	2
D	inf	-1	inf	0



All-Pair shortest distance



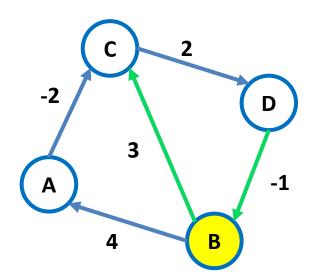
k: – Begin with vertex A, can we update the shortest distance of all vertices going through A

What is the algorithm?

i: B in this case, loop through the rows for column

- Begin with vertex A, can we update the shortest distance of all vertices going through A?
- Begin with vertex B, can we update the shortest distance of all vertices going through B?

	Α	В	С	D
Α	0	inf	-2	inf
В	4	0	2	inf
С	inf	inf	0	2
D	inf	-1	2	0



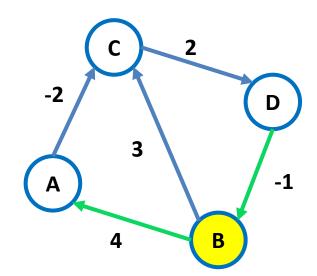




What is the algorithm?

- Begin with vertex A, can we update the shortest distance of all vertices going through A?
- Begin with vertex B, can we update the shortest distance of all vertices going through B?

	Α	В	С	D
Α	0	inf	-2	inf
В	4	0	2	inf
С	inf	inf	0	2
D	3	-1	2	0





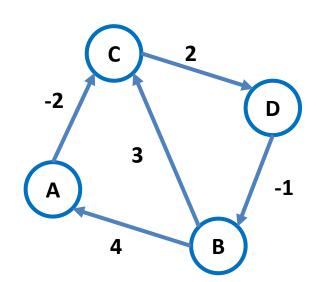
Questions?

All-Pair shortest distance



What is the algorithm?

	Α	В	С	D
Α	0	inf	-2	inf
В	4	0	3	inf
С	inf	inf	0	2
D	inf	-1	inf	0





- What is the algorithm?
 - Same as the Warshall's



- What is the algorithm?
 - Same as the Warshall's
 - Except we are now doing distance...



- What is the algorithm?
 - Same as the Warshall's
 - Except we are now doing distance...
 - If distance[i][j] > distance[i][k] + distance[k][j] then distance [i][j] = distance[i][k] + distance[k][j]



- What is the algorithm?
 - Same as the Warshall's
 - Except we are now doing distance...
 - If distance[i][j] > distance[i][k] + distance[k][j] then distance [i][j] = distance[i][k] + distance[k][j]

```
# floyd warshall's
for k in range(count_vertex):
for i in range(count_vertex):
for j in range(count_vertex):
matrix[i][j] = min(matrix[i][j], matrix[i][k]+matrix[k][j])
```

All-Pair shortest distance



- What is the algorithm?
 - Same as the Warshall's
 - Except we are now doing distance...
 - If distance[i][j] > distance[i][k] + distance[k][j] then distance [i][j] = distance[i][k] + distance[k][j]

```
# floyd warshall's
for k in range(count_vertex):
for i in range(count_vertex):
for j in range(count_vertex):
matrix[i][j] = min(matrix[i][j], matrix[i][k]+matrix[k][j])
```

— What is the meaning of the outer loop?

All-Pair shortest distance value = edge.w(B,A) + edge.w(A, C) which value must < Inf So matrix[A][A] can be changed

B -> A -> C. Even there is no edge from B to C (Inf the matrix) Flord-Warshall would give a B -> C vertual edge by assgin a



by matrix[B][A] + matrix[A][C] and more as there is negative cycle

i->k-> i B-> A-> C k: - Begin with vertex A, can we update the shortest distance of all vertices going through A

- What is the algorithm?
 - Same as the Warshall's

 - i: B in this case, loop through the rows for column A, take the value - matrix[i][k] = matrix[B][A], value is maintained for possible edge from B Except we are now doing distance.
 i. (next loop to search for v of the outgoing edge from A)
 i. j: C in this case, all possible edge from A
 Finally update matrix[i][j] = matrix[B][C]
 - If distance[i][j] > distance[i][k] + distance[k][j] then distance [i][j] = distance[i][k] + distance[k][j]

choose minimum one between (existing one and the updated one)

```
# floyd warshall's
□ for k in range(count vertex):
      for i in range(count vertex):
          for j in range(count vertex):
              matrix[i][j] = min(matrix[i][j], matrix[i][k]+matrix[k][j])
```

— What is the meaning of the outer loop?

going for vertex column

 As we increment, we find the minimum distance going through vertex k. Thus, we would have the minimum through every vertex, updating as needed!



Questions?

All-Pair shortest distance



What is the complexity?

```
# floyd warshall's
for k in range(count_vertex):
for i in range(count_vertex):
for j in range(count_vertex):
matrix[i][j] = min(matrix[i][j], matrix[i][k]+matrix[k][j])
```

All-Pair shortest distance



- What is the complexity?
 - Same as Warshall's

```
# floyd warshall's
for k in range(count_vertex):
for i in range(count_vertex):
for j in range(count_vertex):
matrix[i][j] = min(matrix[i][j], matrix[i][k]+matrix[k][j])
```

choose minimum one between (existing one and the updated one)



Questions?

All-Pair shortest distance



What about negative cycle?



- What about negative cycle?
 - We know about cycle by looking at the diagonal going from vertex u back to vertex u

All-Pair shortest distance



- What about negative cycle?
 - We know about cycle by looking at the diagonal going from vertex u back to vertex u
 - So if we have negative cycle, the diagonal will tell us!
 If the value is negative =(

if dagonal value is negative -> negative cycle all algori not useable, as forever going round the negative cycle



Questions?

Shortest Paths



Can you summarize it up?



- Can you summarize it up?
- Un-weighted graph?
- Weighted graph?



- Can you summarize it up?
- Un-weighted graph?
- Weighted graph?
 - Handle negative edge?



- Can you summarize it up?
- Un-weighted graph?
 - BFS
 - Dijkstra
- Weighted graph?
 - Handle negative edge?

Shortest Paths



k: - Begin with vertex A, can we update the shortest distance of all vertices

Can you summarize it up othrough A? going through B?

i: B

- Un-weighted graph?
 - BFS
 - Dijkstra
- Weighted graph?
 - Dijkstra
 - Handle negative edge?



- Can you summarize it up?
- Un-weighted graph?
 - BFS
 - Dijkstra
- Weighted graph?
 - Dijkstra
 - Handle negative edge?
 - Bellman-Ford
 - Floyd-Warshall (also all pairs)

Shortest Paths



- Un-weighted graph?
 - BFS
 - Dijkstra
- Weighted graph?
 - Dijkstra
 - Handle negative edge?
 - Bellman-Ford
 - Floyd-Warshall (also all pairs)
 - Handle negative cycle?

k: – Begin with vertex A, can we update the shortest distance of all vertices going through A

i: B in this case, loop through the rows for column

j: C

Shortest Paths



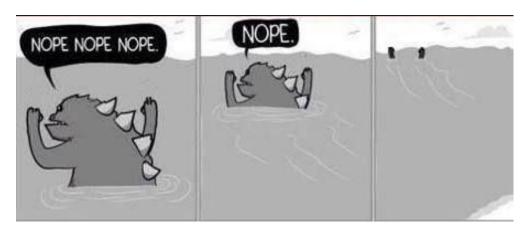
Un-weighted graph?

k: – Begin with vertex A, can we update the shortest distance of all vertices going through A?

- BFS
- Dijkstra
- Weighted graph?
 - Dijkstra
 - Handle negative edge?
 - Bellman-Ford
 - Floyd-Warshall (also all pairs)

i: B

– Handle negative cycle?





Questions?



Thank You