# Logifold: A Geometric Fondation of Ensemble Machine Learning

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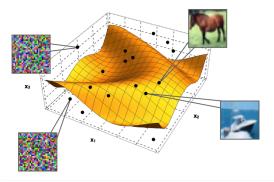
November 4

International Conference on Electrical, Computer, Communications and Mechatronics Engineering (ICECCME 2024)
4-5 November 2024, Male, Maldives

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#### "Manifold" in Data Science

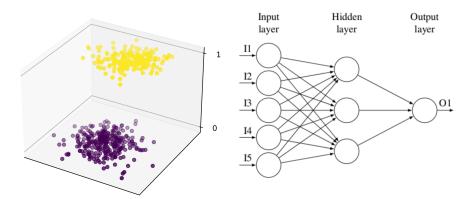
High-dimensional analogue of 2 dimensional surface in  $\mathbb{R}^N$ 



(Image from Sebastian Goldt, Marc Mézard, Florent Krzakala, and Lenka Zdeborová)

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#### Classification Dataset and Neural Network



 $f = \sigma_2 \circ L_2 \circ \sigma_1 \circ L_1$ 

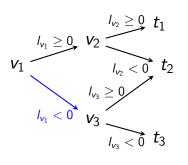
Classification with two classes

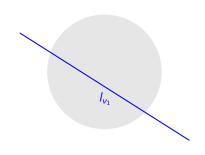
• Network models gain tremendous success in describing datasets

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Motivated from Neural Network.

Example: Directed graph G & Set of affine maps  $L = \{l_{v_1}, l_{v_2}, l_{v_3}\}, D \subset \mathbb{R}^2$ 



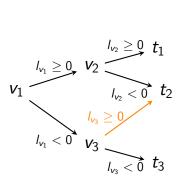


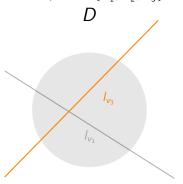
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Motivated from Neural Network.

Example: Directed graph G & Set of affine maps  $L = \{l_{v_1}, l_{v_2}, l_{v_3}\}$ ,  $D \subset \mathbb{R}^2$ 

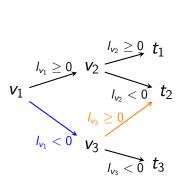


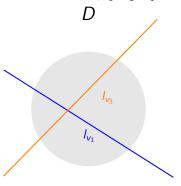


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Motivated from Neural Network.

Example: Directed graph G & Set of affine maps  $L = \{l_{v_1}, l_{v_2}, l_{v_3}\}$ ,  $D \subset \mathbb{R}^2$ 

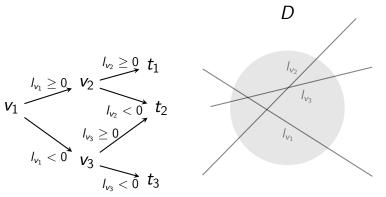




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Motivated from Neural Network.

Example: Directed graph G & Set of affine maps  $L=\{l_{v_1},l_{v_2},l_{v_3}\}$ ,  $D\subset\mathbb{R}^2$ 



 $f: D \to \{t_1, t_2, t_3\}$  is a function defined by G and L.

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- Measurable set  $D \subset \mathbb{R}^n$ , Finite set T.
- Directed finite graph G without cycle
- Affine maps

 $L = \{l_v : v \text{ is a vertex with more than one outgoing arrows}\}$ 

#### **Definition**

 $f_{G,L}:D\to T$  is a linear logical function of (G,L) if  $I_v\in L$  are affine linear functions whose chambers in D are one-to-one corresponding to the outgoing arrows of v.

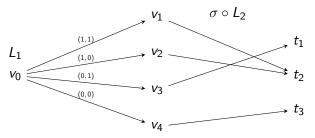
(G, L) is called a linear logical graph.

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#### Linear logical function: Example

 $f = \sigma \circ L_2 \circ s \circ L_1$  where

- $L_1: \mathbb{R}^n \to \mathbb{R}^2$  is affine map and s is a component-wise step function.
- $L_2: \mathbb{R}^2 \to \mathbb{R}^3$  is affine map and  $\sigma$  is the index-max map.



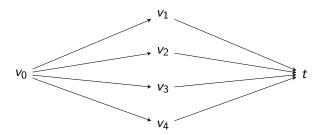
f is a linear logical function with the above graph G and  $L = \{L_1\}$ .

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# Fuzzy linear logical function: Example

 $f = \sigma \circ L_2 \circ s \circ L_1 : S^n \to S^3$  with SoftMax  $\sigma$  and ReLU s.

• *G* is a finite directed graph that has no oriented cycle with exactily one source vertex and target vertex *t*.

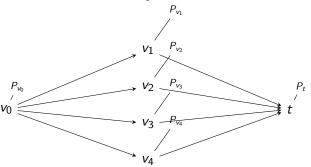


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#### Fuzzy linear logical function: Example

 $f = \sigma \circ L_2 \circ s \circ L_1 : S^n \to S^3$  with SoftMax  $\sigma$  and ReLU s.

• Each vertex v of G is equipped with a product of standard simplices  $P_v$ , with domain  $D = P_{v_0}$ .



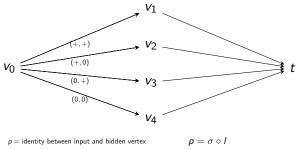
$$P_{v_0} = P_{v_1} = P_{v_2} = P_{v_3} = S^n, P_t = S^3$$

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#### Fuzzy linear logical function: Example

 $f = \sigma \circ L_2 \circ s \circ L_1 : S^n \to S^3$  with SoftMax  $\sigma$  and ReLU s.

• Arrow maps  $p_a: P_{s(a)} \to P_{t(a)}$  for each arrow a, and affine map  $I_v$ whose chambers in  $P_{\nu}$  are one-to-one corresponding to the outgoing arrows of v.



 $L_{v_0} = L_1$  and I is the restricted affine linear map on chambers made by  $L_{v_0}$  and the ReLU activation s.

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# Fuzzy linear logical function

- G is a finite directed graph that has no oriented cycle with exactily one source vertex and target vertices  $t_1, \ldots, t_K$ .
- Each vertex v of G is equipped with a product of standard simplices  $P_v$ , where simplex is a set of the form  $\{x \in \mathbb{R}^{d+1} : \sum x_i = 1\}$ . Domain D is a subset of  $P_{v_0}$ .
- Each arrow a is equipped with a continuous function

$$p_a:P_{s(a)}\to P_{t(a)}$$

where s(a), t(a) denote the source and target vertices respectively.

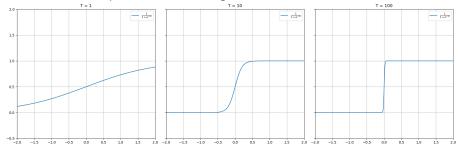
• Each vertex v that has more than one outgoing arrows is equipped with affine map  $I_v$  whose chambers in  $P_v$  are one-to-one corresponding to the outgoing arrows of v.

Given  $x \in D$ , L and  $p_a$  determine a path to a target, and  $f_{(G,L,P,p)}(x)$  is defined by the composition of arrow maps along the path.

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#### **Tropical limits**

Introduce formal parameter T to logistic functions.



$$\lim_{T \to \infty} \frac{1}{1 + T^{-x}} = \begin{cases} 1 & (x > 0) \\ 0 & (x < 0) \end{cases}$$

$$\operatorname{SoftMax}(x) \xleftarrow{T \to e} \left( \frac{T^{-x_k}}{\sum_i T^{-x_i}} \right) \xrightarrow{T \to 0^+} \operatorname{Argmax}(x)$$

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# Universality of Linear logical function

- $D \subset \mathbb{R}^N$  with  $\mu(D) < \infty$ , where  $\mu$  is the Lebesgue measure.
- T is finite

#### Theorem (I. Jung and S.C. Lau)

For any (Lebesgue) measurable function  $f: D \to T$ , we have a linear logical function that approximates to f.

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#### Corollary

There exists a family  $\mathcal{L}$  of linear logical functions  $L_i: D_i \to T$ , where  $D_i \subset D$  and  $L_i \equiv f|_{D_i}$ , such that  $D \setminus \bigcup_i D_i$  is measure zero set.

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# Fuzzy linear logical function and fuzzy linear logifold

#### Definition

A fuzzy linear logifold is a tuple  $(X, \mathcal{P}, \mathcal{U})$ , where  $(X, \mathcal{U})$  be a logifold and

- $\mathcal{U}$  is a collection of tuples  $(\rho_i, \phi_i, f_i)$
- ullet  $ho_i:X o [0,1]$  describe fuzzy subsets of X with  $\sum_i 
  ho_i \leq 1_X$
- $U_i = \{x \in X : \rho_i(x) > 0\}$  be the support of  $\rho_i$

In classification problems,

- $X = \mathbb{R}^n \times T$
- $\mathcal{P}: X \to [0,1]$  describes how likely an element of  $\mathbb{R}^n \times \mathcal{T}$  is classified as 'yes'
- ullet  $ho_i$  can be 'generalization performance', or 'constant'.

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# Example of logifold

 $f:(0,1]\to\{0,1\}$  be a function defined as

$$f(x) = \sum_{n=0}^{\infty} \left( \frac{(-1)^n + 1}{2} \right) I_{E_n}(x)$$

where  $E_n = (1 - 2^{-n}, 1 - 2^{-n-1}].$ The graph of  $f \subset [0, 1) \times \{0, 1\}$ 

with countably many 'jumps' or 'discontinuities' near at x = 0.

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In classification problems,  $X = \mathbb{R}^n \times T$  and each model  $g_i : X \to T$  with  $U_i = X$ . Define  $G_i : X \times T \to [0,1]$  by g such that  $G_i(x,t) = (g_i(x))_t$ . Let N be the total number of classifiers.

• If  $\rho_i = \frac{1}{N}$  for any i, then  $P: X \times T \rightarrow [0,1]$  is defined by

$$P(x,t) = \sum \rho_i(x) 1_{t_{i,0}(x)}(t)$$

, where  $t_{i,0}(x) = \arg \max G_i(x,t)$  denoting 'the answer of  $g_i$ ', and therefore the system employs majority voting.

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• If  $ho_i = \frac{1}{N}$  for any i, then  $P: X \times T \to [0,1]$  is defined by

$$P(x,t) = \sum G_i(x,t)$$

, which is simple average.

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• If  $\rho_i(x) = \frac{\max g_i(x)}{N}$  then  $P(x,t) = \sum \rho_i(x)G_i(x,t)$  be the weighted average.

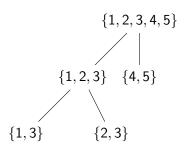
ICECCME2024 12 / 15 As our logifold formulation does not force to have X and T as domain/codomain of classifier, we allow classifier to have more flexibility in its target.

For instance, our classification problem is classifyting instances in X to  $\{1,2,3,4,5\}$ , and we have models  $g_1,\ldots,g_7$  such that

Models	Targets
g_1	{1,2,3}, {4,5}
$g_2, g_3$	{1,2,3,4,5}
g <sub>4</sub>	{1,2,3}
<b>g</b> 5	{1,3}
<b>g</b> 6	{2,3}

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As they can have various target, we make tree of targets. For instance, with  $\{1,2,3,4,5\},\{1,2,3\},\{1,3\},\{2,3\}$ , we have the following target tree.



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On validation dataset, define first certain domain of g under the certainty threshold  $\alpha$ .

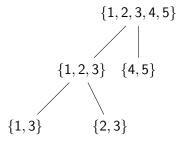
$$Certainty = \max g(x)$$

Certain domain = {certainty >  $\alpha$ },  $\alpha$  = threshold

Then compute accuracy (global, and in each target) of g. For instance,  $g_2$  has following fuzzy domain:

certainty threshold	Accuracy	Accuracy in each target
0	0.6	(0.7,0.8,0.45,0.5,0.45)
0.8	0.7	(0.7,0.9,0.5,0.7,0.6)
0.95	0.8	(0.8,0.9,0.75,0.8,0.75)

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- For a given instance x, we can compute weighted voting for x at node  $\{1,2,3,4,5\}$  according to the fuzzy domain of  $g_1,g_2,g_3$  in each target 1,2,3,4,5.
- If answer for 1, 2, 3 is dominant, then we pass it to  $\{1, 2, 3\}$  node. In this way, we have unique path in the target tree for each instance.
- On validation dataset, we can compute which (sub-)path and certainty threshold are optimal for best accuracy in each model.

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#### Experimental Result 1

Dataset: CIFAR10

Six Simple CNN structure models trained on CIFAR10 (56.45% in average)

ResNet20 structure model trained on CIFAR10 (85.96%)

Simple average: 62.55%

Majority voting provides 58.72%. Our logifold formulation: 84.86%

#### Experimental Result 2

dataset : CIFAR10, MNIST, Fashion MNIST (resized to 32\*32\*3 pixels)

- Filters are models classifying coarse targets. It only classify given data into three classes; CIFAR10, MNIST, and Fashion MNIST.
- Models only classifying either CIFAR10, MNIST, or Fashion MNIST.

Single model classifying 30 classes: 76.41% in average.

Simple average of models classifying 30 classes: 82.35%

Our logifold formulation: 94.94%.

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